

RPi.GPIO Module Usage

Import the module:

import RPi.GPIO (as “whatever” if desired - **as IO** is assumed in the following)

Pin numbering: a choice is required to specify channel designations:

IO.setmode(IO.BOARD)

...Or...

(see reverse side for diagram)

IO.setmode(IO.BCM)

Setup: every channel that is to be used:

IO.setup(channel, IO.IN)

IO.setup(channel, IO.OUT)

You can specify an initial state for the pin:

IO.setup(channel, IO.OUT, initial=IO.HIGH)

Or setup a bunch at a time:

chan_list = [11,12] add multiple channels

can use tuples instead i.e.: **chanlist = (11,12)**

IO.setup(chan_list, IO.OUT)

Read or write (set) pins: (NOTE: a “pin” is the same as a “channel”)

IO.input(channel) (0=False=IO.Low,1=True=IO.High)

IO.output(channel, state) (states same as above)

Can output to several channels with one command:

chanlist = [11,12] <- this also works with tuples

IO.output(chanlist, IO.LOW) <- this sets all to IO.LOW

IO.output(chanlist, (IO.HIGH, IO.LOW)) <- this sets first HIGH and the second LOW

Environmental information:

GPIO.RPI_INFO about your RPi

GPIO.RPI_INFO['P1_REVISION'] Raspberry Pi board revision

GPIO.VERSION RPi.GPIO version number

Find the function of a channel:

func = IO.gpio_function(pin)

will return a value from:

IO.IN, IO.OUT, IO.SPI, IO.I2C, IO.HARD_PWM, IO.SERIAL,

IO.UNKNOWN

Pull UP / Pull DOWN:

Unconnected pins float.

Default values (High or Low) can be set in **software** or with **hardware**

Hardware:

Pull Up:

Input channel -> 10K resistor -> 3.3V

Pull Down:

Input channel -> 10K resistor -> 0V

Software:

IO.setup(channel, IO.IN, pull_up_down = IO.PUD_UP) or

IO.PUD_DOWN) or

IO.PUD_OFF)

Edge detection: change of state event — 3 ways to handle

1. wait_for_edge() function - stops everything until an edge is detected.

IO.wait_for_edge(channel, IO.RISING)

can detect edges of type IO.RISING, IO.FALLING or IO.BOTH

2. event_detected() function - use in a loop with other activity — event triggers priority response. Example:

IO.add_event_detect(channel, IO.RISING) activity detection on a channel

[your loop activity here]

if **IO.event_detected(channel)**:

print('Button pressed')

3. threaded callbacks - RPi.GPIO runs a second thread for callback functions. This means that callback functions can be run at the same time as your main program, in immediate response to an edge. For example:

def my_callback(channel):

print('Edge detected on channel %s'%channel')

print('This is run in a different thread to your main program')

IO.add_event_detect(channel, IO.RISING, callback=my_callback) add rising edge detection on a channel

...the rest of your program...

If you want more than one callback function:

def my_callback_one(channel):

print('Callback one')

def my_callback_two(channel):

print('Callback two')

IO.add_event_detect(channel, IO.RISING)

IO.add_event_callback(channel,

my_callback_one)

IO.add_event_callback(channel,

my_callback_two)

Note that in this case, the callback functions are run sequentially, not concurrently. This is because there is only one thread used for callbacks, in which every callback is run in the order in which they have been defined.

Switch debounce: solutions to a button event causing multiple callbacks

Hardware: add a 0.1uF capacitor across your switch.

Software: add the bouncetime= parameter to a function where you specify a callback function. bouncetime= should be specified in milliseconds.

IO.add_event_detect(channel, IO.RISING, callback=my_callback, bouncetime=200)

or

IO.add_event_callback(channel,

my_callback, bouncetime=200)

Remove Event Detection:

IO.remove_event_detect(channel)

Cleanup: resets all channels and clears pin numbering system at the end of a program - just do it.

IO.cleanup()

Or cleanup just select pins:

IO.cleanup(channel)

IO.cleanup(channel1, channel2) <-tuple

IO.cleanup([channel1, channel2]) <-or list

Raspberry Pi Model B+			
1	3V Power	1	2
2	GPIO2 SDA1 12C	3	4
3	GPIO3 SCL1 12C	5	6
4	GPIO4	7	8
5	Ground	9	10
6	GPIO17	11	12
7	GPIO27	13	14
8	GPIO22	15	16
9	3V Power	17	18
10	GPIO10 SPI0-MOSI	19	20
11	GPIO9 SPI0-MOSO	21	22
12	GPIO11 SPI0-SCLK	23	24
13	Ground	25	26
14	ID_SD 12C ID EEPROM	27	28
15	GPIO5	29	30
16	GPIO6	31	32
17	GPIO13	33	34
18	GPIO11 PCM-FS	35	36
19	GPIO26	37	38
20	Ground	39	40

SERIAL PERIPHERAL INTERFACE PINS
 19 MOSI-master output, slave input
 21 MISO-master input, slave output
 23 SCK-serial clock 24 & 26-slave select pins
 UART - UNIVERSAL ASYNCHRONOUS
 RECEIVER/TRANSMITTER pins
 8 UART-TDX & 10 UART-RDX

PWM in RPi.GPIO is an analog signal, **P**ulse **W**idth **M**odulation - available **ONLY** on **one** of the Pi's pins:
 board #12 = BCM #18 ; used mostly for audio

To create a **software** instance of PWM on any in/out pin:

p = IO.PWM(channel, frequency)

To start PWM: **p.start(dc)** where dc is the duty cycle (0.0 <= dc <= 100.0)

To change the frequency:

p.ChangeFrequency(freq) freq is the new frequency in Hz*

To change the duty cycle:

p.ChangeDutyCycle(dc) where 0.0 <= dc <= 100.0

To stop PWM:

p.stop()

Shown below: 3600 Ω with 2% tolerance

1st Digit	2nd Digit	Multiplier	Tolerance
0	0	1	
1	1	10	1%
2	2	100	2%
3	3	1 K	
4	4	10 K	
5	5	100 K	
6	6	1 M	
7	7	10M	
8	8		5% gold
9	9		10% silver

270 Ω -> red, purple, brown
 330 Ω -> orange, orange, brown
 10K Ω -> brown, black, yellow

Note: RPi maximum current to a single pin is 16ma, to all pins is 50ma

