Code in the function

In [124]:

```
import matplotlib
import numpy as np
import matplotlib.cm as cm
import matplotlib.pyplot as plt

base_length = list(np.meshgrid(np.linspace(0, 3, 50)))
angles = list(np.linspace(0, np.pi/2, 50))

Y, X = np.meshgrid(angles, base_length)
Area = lambda t,b:(b+ np.cos(t))*(0.5*(3-b))*(0.5*(3-b))*np.sin(t)
Z = Area(Y,X)
```

Contour plot

In [167]:

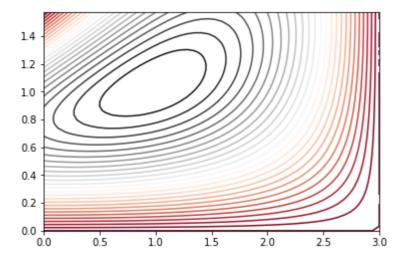
```
f = lambda x, y : 1.5*x*np.sin(y) - 1.5*x*np.sin(y)*np.cos(y) + 2.25*np.sin(y)*np.c

# plot
X, Y = np.meshgrid(np.linspace(0, 3, 50), np.linspace(0, np.pi/2, 50))
Z = f(X,Y)
plt.figure()
plt.contour(X, Y, f(X,Y), 25, cmap='RdGy')

plt.xlim(0, 3)
plt.ylim(0, np.pi/2)
```

Out[167]:

(0, 1.5707963267948966)

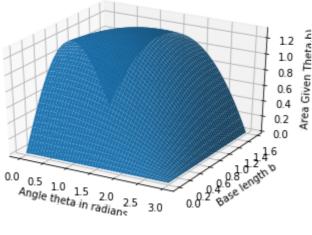


Surface plot

In [170]:

```
from mpl_toolkits.mplot3d import Axes3D
fig = plt.figure()
ax = fig.add_subplot(111, projection='3d')
ax.plot_surface(X, Y, Z)
ax.set_ylabel('Base length b')
ax.set_zlabel('Area Given Theta,b)')
ax.set_xlabel('Angle theta in radians')
ax.set_title('SURFACE PLOT OF THE AREA FUNCTION')
plt.show()
print(Area(1, 1.1))
```

SURFACE PLOT OF THE AREA FUNCTION



1.2456907840231282

Gradient descent with line search. This is a modificattion of the code we had in class for session 6.1. I worked with Fabian on this.

M

In [165]:

```
import numpy as np
import matplotlib.pyplot as plt
x, y = np.meshgrid(np.linspace(0, 3, 100), np.linspace(-np.pi / 2, np.pi / 2, 100))
#Define our functions, their graadient and the hessian
def f(inputvector):
    x, y = inputvector[0], inputvector[1]
    return 1.5 * x * np.sin(y) - 1.5 * x * np.sin(y) * np.cos(y) + 2.25 * np.sin(y)
        y) + 0.25 * x * x * np.sin(y) * np.cos(y)
def fbar(inputvector):
    x, y = inputvector[0], inputvector[1]
    return np.array([1.5 * np.sin(y) - 1.5 * np.sin(y) * np.cos(y) - x * np.sin(y)
                     1.5 * x * np.cos(y) - 0.25 * x * x * (np.sin(y)) ** 2 + 0.25 *
                         np.cos(y)) ** 2 - 1.5 * x * (np.cos(y)) ** 2 + 1.5 * x * (
                         np.cos(y)) - 2.25 * (np.sin(y)) ** 2 + 2.25 * (np.cos(y))
def fbarbar(inputvector):
    x, y = inputvector[0], inputvector[1]
    return np.array([[0.5 * np.cos(y) * np.sin(y) - np.sin(y),
                      -x * np.cos(y) - 0.5 * np.cos(2 * y) - 1.5 * np.cos(2 * y) +
                     [0.5 * x + 1.5 + 1.5 * np.cos(y) - x * np.cos(y),
                      -1.5 * x * np.sin(y) - x * x * np.cos(y) * np.sin(y) + 0.5 *
                          y) * np.sin(y)]])
def H prime(x, a):
    result = np.matmul(np.transpose(fbar(x - (a * fbar(x)))), -fbar(x))
    return result
#Use bisection to determine the step size
def bisection(x):
    low, high, tol = 0, 1, 10 ** (-4)
    a = None
    while H prime(x, high) < 0:
        high = high * 2
   while high - low > tol:
        a = np.mean([low, high])
        if H prime(x, a) > 0:
            high = a
        if H prime(x, a) < 0:
            low = a
    return a
def gradient_descent(x):
    history = []
    steps = 0
    rel change = float("inf")
    f_val = f(x)
    tol = 10 ** (-6)
```

```
while rel_change > tol and steps < 10 ** 4:</pre>
                      step = fbar(x)
                      step *= bisection(x)
                     x = x - step
                     new f val = f(x)
                      rel change = abs(new f val - f val)
                      f val = new f val
                     history.append(x)
                      steps += 1
           return x, np.array(history)
initial = [0, 0.5]
minimum, history = gradient descent(initial)
print("minimum is", abs(minimum), "steps", len(history))
print(history)
z = 1.5 * x * np.sin(y) - 1.5 * x * np.sin(y) * np.cos(y) + 2.25 * np.sin(y) * np.cos(y) * np.c
          y) + 0.25 * x * x * np.sin(y) * np.cos(y)
x, y = np.meshgrid(np.linspace(0, 3, 100), np.linspace(-np.pi / 2, np.pi / 2, 100))
plt.figure()
plt.contour(x, y, z, 50, cmap='coolwarm')
for i in range(len(history) - 1):
           plt.plot([abs(history[i][0]), abs(history[i + 1][0])],
                                   [abs(history[i][1]), abs(history[i + 1][1])], k-1, marker=1, marker
plt.title('Optimal value: (x,y) = (\{\},\{\})'.format(round(history[-1][0], 3),
                                                                                                                                       -round(history[-1][1], 3)))
plt.show()
minimum is [0.99929982 1.04698721] steps 11
[[-0.09117841 -0.75908674]
  [ 0.80412419 -0.82390308]
  [ 0.79236451 -0.9863495 ]
  [ 0.95394475 -0.99805324]
   [ 0.95143627 -1.03269144]
  [ 0.98885541 -1.03538859]
   [ 0.98825801 -1.04367581]
  [ 0.99727628 -1.04432039]
  [ 0.99713219 -1.04633634]
  [ 0.99933521 -1.0464946 ]
```

[0.99929982 -1.04698721]]

