

GO TO DEXIT is almost always generated since a branch may not exist to allow normal exit from the DT. DEXIT is the normal return from the decision table if the DT is operated as a closed COBOL subroutine. If it is not, the last action performed by any rules-action string must be an unconditional GO TO, and the "GO TO DEXIT" will not be generated.

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A Method for Finding Hamilton Paths and Knight's Tours

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The use of Warnsdorff's rule for finding a knight's tour is generalized and applied to the problem of finding a Hamilton path in a graph. A graph-theoretic justification for the method is given.

1. Introduction

A path in a graph is a Hamilton path if and only if it goes through each node of the graph once and only once [1]. These paths were named for Sir William Hamilton who invented and analyzed a game to find these paths through the vertices of a regular dodecahedron. A problem of this type is the classic knight's tour problem (Figure 1) on a chessboard. The knight is placed on a square and must cover the whole board, moving to each square once and only once.

Many mathematicians¹ proposed specialized methods for finding a knight's tour,² but general methods for Hamilton paths on graphs and similarly for knight's tours on any shape or size board are lacking. In 1823, H. Warnsdorff proposed the following rule for knight's tours:

Select the move which connects with the fewest number of further moves, providing this number is not 0. If a tie occurs it may be broken arbitrarily.

This rule proved unusually successful and generally applicable³ until a few carefully constructed counterexamples showed that in case of ties some of the options failed to find knight's tours. However, not much was done in analyzing the rule and its failures because of the large computational effort involved in using the rule. The rule

¹ Euler, Vandermonde, de Moivre, Roget, and others.

² For general material on the knight's tour problem see [2].

³ It was called inelegant by many mathematicians because of its computational nature.

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3. EGLER, J. F. A procedure for converting logic table conditions into an efficient sequence of test instructions. *Comm. ACM* 6, 9 (Sept. 1963), 510-515.

was justified on the common sense grounds that it eliminated bad squares as quickly as possible, leaving many possibilities for success.

2. Problems and Background

The finding of a Hamilton path in a graph is generally attacked with combinatoric methods, which for large richly connected graphs are not feasible. Warnsdorff's rule is a simple computational rule for finding knight's tours. It presents an attractive method for finding Hamilton paths in richly connected graphs. In understanding the reasons for its successes and failures an improved generalization of the rule has been devised and implemented, and the general theory of the method has been examined.

The problem of a knight's tour can be displayed as a graph for which the connections (edges) are knight's moves. Consider a 3×3 board (Figure 2). It is readily described as a graph with the center square unconnected. Therefore, there can be no tour even though the remainder of the graph is two-connected⁴ and has a path.

The 4×4 board is more complicated, involving 16

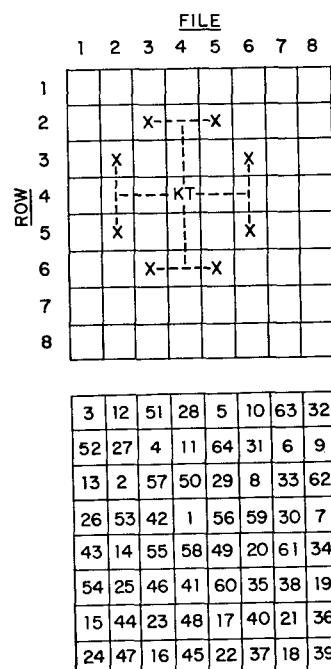


FIG. 1. Top, legal knight moves; bottom, a knights tour

squares and 48 connections. Although all the squares are at least two-connected (Figure 3(a)) and the graph is richly connected, the graph has no Hamilton path. The graph may be broken into 4 factors:

{(1, 1), (2, 3), (4, 4), (3, 2)}, {(1, 4), (3, 3), (4, 1), (2, 2)}, {(4, 2), (2, 1), (1, 3), (3, 4)}, {(2, 4), (4, 3), (3, 1), (1, 2)}.

However, there are only enough transition squares to link three of them. The maximum path is 15 squares (Figure 3(b)) and Warnsdorff's rule does indeed find it.

The first nontrivial square board to have a tour is a 5 × 5 on which the knight must start on a square such that

(row number) + (file number) = (even integer) because of parity.⁵ Traditionally the 8 × 8 board or ordinary chessboard has gotten the most attention. First let us look at the number of connections from each square of the board (Figure 4). They range from two to eight, totaling 336 connections, and giving an average of slightly

over five connections per square. This average increases asymptotically to eight as the board size increases, but the corner squares remain two-connected.

Warnsdorff's rule maximizes the number of connections remaining at the current point in the path. A knight's tour is a path on the chessboard which maximizes the number of connections at the 63rd move; i.e., there is one remaining move and there can be at most one at this point. The move tree of the various paths of the knight is exponential in nature, and maximization at the 63rd level is not computationally possible. Maximizing the current level propagates down the move tree, and therefore is likely to maximize the later levels. Warnsdorff's rule is just an approximation to the algorithm of searching the complete tree for a connection at the 63rd level.

In implementing Warnsdorff's rule on a B5500 in extended ALGOL, the rule was tried starting from each square of an 8 × 8 board and found to fail at least once for each of five fixed orderings⁶ of moves. In fact, the rule failed twelve times with a median of three failures for a given move ordering.⁷ This high rate of failure was a disappointment as it seemed that for some fixed ordering of moves Warnsdorff's rule could generate a knight's tour from each square of the board. Initially, the rule was investigated with a view to correcting these failures.

3. Generalization and Analysis

To improve on Warnsdorff's arbitrary selection in case of ties, the following tie-breaking method was proposed and tested. For each tie move, sum the number of moves available to it at the next level and pick the one yielding a minimum. In theory this can be carried through as many levels as necessary for tie-breaking. For computational purposes the breaking of ties of the ordinary Warnsdorff's rule (first level minimization) was only carried one more level (second level tie-breaking). In symmetric positions, ties cannot be broken at any level. In unsymmetric positions, many-level tie-breaking methods are not computationally practical because of exponential

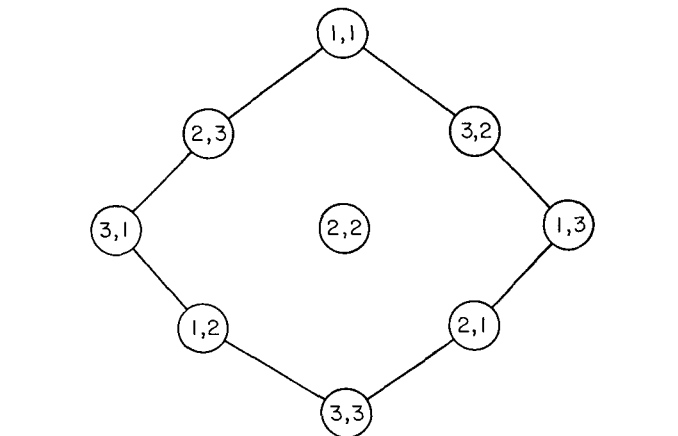


FIG. 2. Graph of a 3 × 3 board

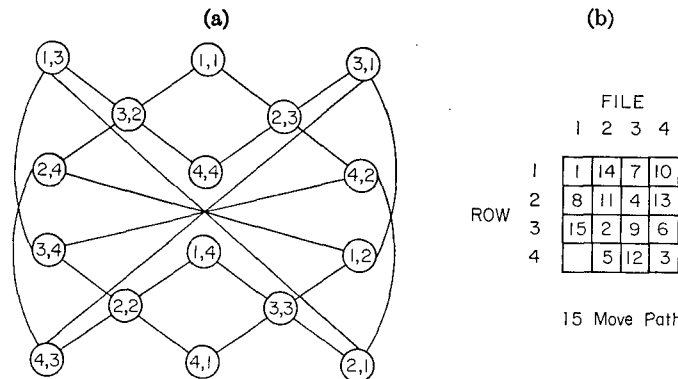


FIG. 3 (a). Graph of a 4 × 4 board; (b), a 15-move path

⁴ Two-connected means that in one move from a square, two other squares may be reached. It corresponds to the degree of a node in an undirected graph without multiple edges [1].

⁵ A board is ordinarily thought of as having white and black squares. On boards of odd length one color has to have an extra square. Knight moves alternate between colors, and therefore on a board with an odd number of squares the knight must start on a square of the majority color to be able to complete a tour.

2	3	4	4	4	4	3	2
3	4	6	6	6	6	4	3
4	6	8	8	8	8	6	4
4	6	8	8	8	8	6	4
4	6	8	8	8	8	6	4
3	4	6	6	6	6	4	3
2	3	4	4	4	4	3	2

FIG. 4. Connectivity of a chess board for a knight

⁶ In cases where more than one minimum exists, the order in which the squares are evaluated determines the next move. The first square encountered with the minimum value is used.

⁷ Ball remarks, "it would require exceptionally bad luck to happen accidentally, [failures of Warnsdorff's rule] on such a route" [2, p. 181].

growth of the move tree. The second-level method always yielded a knight's tour from all squares of the 8×8 board. The generalized method was tried with several of the positions and move orderings which had previously failed and it was successful in each case. The ordinary Warnsdorff's rule on the chessboard had occasionally failed and the improvement brought complete success for the knight's tour problem.

This modification to Warnsdorff's rule is a generalization of the original concept. In terms of the connections of the unreached squares it is again a maximizing rule, with sufficient power always to work with a knight on a chessboard. The generalized rule (for method of order k) is:

Consider all paths of k moves and count the remaining number of connections for each path. Select the first move of the path whose number is maximum, providing this path is not a dead end. Ties are broken by going to $k + 1$ moves.

In our case k has been 1.

The argument for Warnsdorff's rule has previously been an appeal to common sense. However, the maximization of connectivity at the first level as an approximation to a full search of the move tree is a firmer explanation and yet is not enough. While mathematicians have searched for a proof of Warnsdorff's conjecture, modified to account for any solution from a tie point, the rule may only be justified as above. A graph-theoretic proof would have to account for Warnsdorff's rule working in general, which it does not. A typical counterexample is Figure 5, a graph with a Hamilton path which cannot be found by application of Warnsdorff's rule. To find it would require the generalized rule with $k = 9$. Certain nodes in a graph⁸ independently of their connectivity play crucial roles as transition squares between otherwise independent components of the graph. (To see this, re-examine the 4×4 graph in Figure 3(a).)

4. Conclusions

Warnsdorff's generalized rule is a powerful yet practical method of finding a Hamilton path in a graph. In terms of a knight's tour on a chessboard, a random generation of moves has virtually no chance of success, but the second

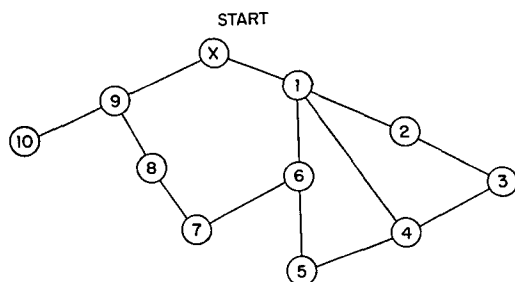


FIG. 5. Counterexample for the generalized graph application of Warnsdorff's rule. Warnsdorff's rule selects node 9 which would make a Hamilton path impossible.

level tie-breaking program was always successful. The program was also used to find several Hamilton paths in an especially tricky regular graph⁹ of degree 3 with 46 nodes, proposed by W. Tutte. In Figure 6 the nodes are labeled by their move number in a Hamilton path found by the program.

The time needed to find a path is directly proportional to the total number of edges in the graph. In contrast an enumeration procedure would be impossibly long and some recent methods [1, p. 115] using Boolean connection matrices and linear systems of equations are useful only for sparse graphs. The modified Warnsdorff's method has proved so powerful in practice that it has generated solutions for 20×20 and 40×40 boards. The method may be viewed as an approximation to a full search on the move tree. The higher the order of the method, the better the approximation but the longer the computation.

There is much to be explored theoretically and empirically in using maximizing methods in graph theory. Certainly other tie-breaking modifications warrant attention. One could check the next level for the square with minimum connectivity instead of the sum as used in the program (see *RecurNumofmov* in Appendix). Alternatively one could use a hybrid method in which the sum would be used unless a square is two-connected, in which case this path would be followed. A further possibility is to try Warnsdorff's rule and, if it fails, backtrack to where it is practical to derive the rest of the solution by using the Boolean system of equations for the graph. At this point the remaining unreached subgraph should be sparse. Some order of the generalized method outlined above is a useful basis method for finding Hamilton paths in graphs.

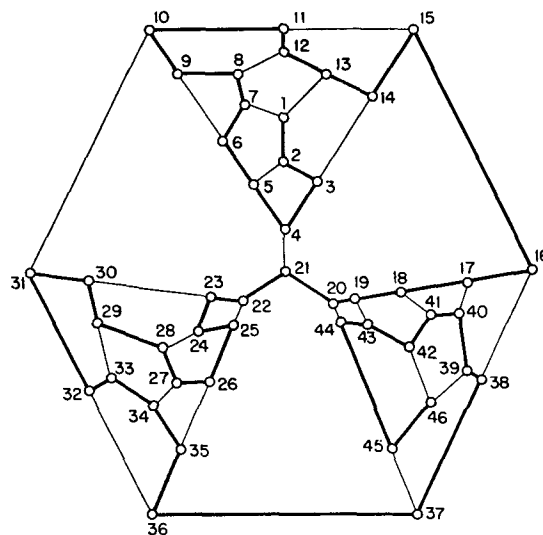


FIG. 6. Tutte's graph planar of degree 3

⁸ Certain nodes in a graph may be *articulation points*. These are nodes that, if removed from the graph, leave an unconnected subgraph. In Figure 5, node 9 is an articulation point.

⁹ A regular graph is a graph where all the nodes have the same degree. In terms of squares, each square has the same number of connections.

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APPENDIX

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procedure HAMILTONPATH (BOARD, ROW, FILE);
  value ROW, FILE; integer ROW, FILE;
  integer array BOARD;
  comment BOARD is a collection of nodes through which is
    generated a Hamilton path (connection of all the nodes pass-
    ing through each node once and only once). The path is started
    at the node specified by BOARD [ROW, FILE];
begin
  integer i, j, nummov, move, min, T1, T2, T2L1, T2L2;
  boolean flg;
  integer array NextR, NextF [1:8];
  comment The Hamilton paths to be found will be knight's
    tours where 8 is the maximum number of moves (connections);
  procedure Listofmov (CR, CF, XR, XF, II);
    value CR, CF; integer CR, CF, II;
    integer array XR, XF;
    comment From the current position specified by CR, CF this
      procedure generates in XR[i], XF[i] a list of the coordinates
      of the possible moves and their number II. The B5500 program
      used a CASE statement which for ALGOL 60 purposes is trans-
      lated to a switch list;
  begin
    integer i, rr, ff;
    switch case := L1, L2, L3, L4, L5, L6, L7, L8;
    II := 0;
    for i := 1 step 1 until 8 do
      begin
        go to case [i];
        L1: rr := CR - 1; ff := CF + 2; go to check;
        L2: rr := CR - 1; ff := CF - 2; go to check;
        L3: rr := CR + 1; ff := CF + 2; go to check;
        L4: rr := CR + 1; ff := CF - 2; go to check;
        L5: rr := CR + 2; ff := CF + 1; go to check;
        L6: rr := CR + 2; ff := CF - 1; go to check;
        L7: rr := CR - 2; ff := CF + 1; go to check;
        L8: rr := CR - 2; ff := CF - 1;
        check: comment check whether a legal connection or move;
          if BOARD [rr, ff] = 0 then
            begin II := II + 1; XR[II] := rr; XF[II] := ff end
          end loop i
      end procedure Listofmov;
  integer procedure Numofmov (CR, CF);
    value CR, CF; integer CR, CF;
    comment This procedure is a simplification of Listofmov for
      efficiency. It is used only to obtain number of legal moves;
  begin
    integer i, ii, rr, ff;
    switch case := L1, L2, L3, L4, L5, L6, L7, L8;
    ii := 0;
    for i := 1 step 1 until 8 do
      begin
        go to case [i];
        L1: rr := CR - 1; ff := CF + 2; go to check;
        L2: rr := CR - 1; ff := CF - 2; go to check;

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        L3: rr := CR + 1; ff := CF + 2; go to check;
        L4: rr := CR + 1; ff := CF - 2; go to check;
        L5: rr := CR + 2; ff := CF + 1; go to check;
        L6: rr := CR + 2; ff := CF - 1; go to check;
        L7: rr := CR - 2; ff := CF + 1; go to check;
        L8: rr := CR - 2; ff := CF - 1;
        check: if BOARD [rr, ff] = then ii := ii + 1
          end loop i;
        Numofmov := ii
      end procedure Numofmov;
  integer procedure RecurNumofmov (CR, CF, Level);
    value CR, CF, Level; integer CR, CF, Level;
    comment This is a recursive routine to the depth Level for
      counting the nodes of the move tree;
  begin
    integer tt, i, nn;
    integer array ra, fa [1:8];
    BOARD [CR, CF] := 1;
    if Level = 1 then RecurNumofmov := Numofmov (CR, CF)
    else
      begin
        Listofmov (CR, CF, ra, fa, nn);
        tt := 0;
        for i := 1 step 1 until nn do
          tt := tt + RecurNumofmov (ra[i], fa[i], Level-1);
        RecurNumofmov := tt
      end; BOARD [CR, CF] := 0
    end procedure RecurNumofmov;
  comment The program deals with knight's tours on a chess-
    board. Warnsdorff's rule is applied and the improvement of
    reapplying the rule to resolve ties is used and is sufficient for
    generating knight's tours on chessboards;
  for i := -1, 0, 9, 10 do
    for j := -1 step 1 until 10 do
      begin BOARD [i, j] := BOARD [j, i] := -1 end;
    comment Initializing the boundaries of the BOARD to -1
      prevents moving there. The BOARD proper is initialized to 0;
    for i := 1 step 1 until 8 do
      for j := 1 step 1 until 8 do BOARD [i, j] := 0;
    comment Initialize the starting position;
    min := 0; T2 := 1; BOARD [ROW, FILE] := move := 1;
    for move := 2 step 1 while min ≠ 99 do
      begin
        min := 99;
        Listofmov (ROW, FILE, NextR, NextF, nummov);
        for i := 1 step 1 until nummov do
          begin
            T1 := Numofmov (NextR [i], NextF [i]);
            if (min > T1) ∧ (T1 ≠ 0) then
              begin flg := true; T2 := i; min := T1 end
            else comment Above is Warnsdorff's rule;
              begin comment Here is the improvement;
                T2L1 := RecurNumofmov (NextR [i], NextF [i], 2);
                if flg then
                  T2L2 := RecurNumofmov (NextR [i], NextF [i], 2);
                  if (T2L2 > T2L1) ∧ (T2L1 ≠ 0) then
                    begin T2L2 := T2L1; flg := false; T2 := i end
                  end tie breaking improvement;
              end loop i;
              if min ≠ 99 then
                begin
                  ROW := NextR [T2]; FILE := NextF [T2];
                  BOARD [ROW, FILE] := move; move := move + 1
                end
              end loop move;
              OUTPUT (BOARD);
              comment Use an output procedure to print results;
            end procedure HAMILTONPATH alias the knight's tour;

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