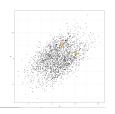
Introduction to Machine Learning

Introduction: Data



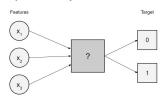


Learning goals

- Features and target
- Labeled/unlabeled
- Data generating process

DATA IN MACHINE LEARNING

- The data we deal with in machine learning usually consists of observations on different aspects of objects:
 - Target variable(s): the attribute(s) of interest
 - Features: measurable properties that provide a concise description of the object
 - Both features and target variables may be of different data types (categorical, numeric, ...).
- We assume some kind of relationship between the features and the target, in a sense that the value of the target variable can be explained by a combination of the features.



	Target y			
Sepal.Length	Sepal.Width	Petal.Length	Petal.Width	Species
4.3	3.0	1.1	0.1	setosa
5.0	3.3	1.4	0.2	setosa
7.7	3.8	6.7	2.2	virginica
5.5	2.5	4.0	1.3	versicolor

DATA LABELS

- We distinguish two basic forms our data may come in:
 - For labeled data we have already observed the target values (labels).
 - For unlabeled data these remain unknown.
- It is easy to see how labeled data are vastly more informative.
- In practice, however, we will much more frequently encounter the unlabeled sort.

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ed	5.9	3.0	5.1	1.8	?
Ì	4.4	3.2	1.3	0.2	?

unlabeled

labele

NOTATION FOR DATA

In formal notation, the data sets we are given are of the following form:

$$\mathcal{D} = \left\{ \left(\boldsymbol{x}^{(1)}, y^{(1)}\right), \dots, \left(\boldsymbol{x}^{(n)}, y^{(n)}\right) \right\} \subset \left(\mathcal{X} \times \mathcal{Y}\right)^{n}.$$

We call

- \mathcal{X} the input space with $p = \dim(\mathcal{X})$ (for now: $\mathcal{X} \subset \mathbb{R}^p$),
- \mathcal{Y} the output / target space,
- the tuple $(\mathbf{x}^{(i)}, y^{(i)}) \in \mathcal{X} \times \mathcal{Y}$ the *i*-th observation,
- $\mathbf{x}_j = \left(x_j^{(1)}, \dots, x_j^{(n)}\right)^T$ the j-th feature vector.

DATA-GENERATING PROCESS

ullet We assume the observed data ${\mathcal D}$ to be generated by a process that can be characterized by some probability distribution

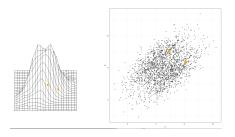
$$\mathbb{P}_{xy}$$
,

defined on $\mathcal{X} \times \mathcal{Y}$.

- Depending on the context, we denote the random variables following this distribution by x and y.
- It is important to understand that the true distribution is essentially unknown to us.

DATA-GENERATING PROCESS

- Usually we assume the data to be drawn *i.i.d.* from the joint probability density function (pdf) / probability mass function (pmf) $p(\mathbf{x}, y)$.
 - i.i.d. stands for independent and identically distributed.
 - We presuppose that all samples are drawn from the same distribution and are mutually independent – the *i*-th realization does not depend on the previous i – 1 ones.
 - It is a strong yet crucial assumption that is precondition to many theoretical implications (e.g., the Central Limit Theorem).



DATA-GENERATING PROCESS

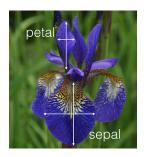
Remarks:

- With a slight abuse of notation we write random variables, e.g., x and y, in lowercase, as normal variables or function arguments.
 The context will make clear what is meant.
- Often, distributions are characterized by a parameter vector θ ∈ Θ. We then write p(x, y | θ).
- This lecture mostly takes a frequentist perspective. Distribution parameters θ appear behind the | for improved legibility, not to imply that we condition on them in a probabilistic Bayesian sense.
 So, strictly speaking, p(x|θ) should usually be understood to mean p_θ(x) or p(x, θ) or p(x; θ).

IRIS DATASET

The iris dataset was introduced by the statistician Ronald Fisher and is one of the most frequent used datasets.

- 150 iris flowers.
- 3 different species (50 setosa, 50 versicolor, 50 virginica).
- Sepal length / width and petal length / width in [cm].



 $Source: https://holgerbrandl.github.io/kotlin4ds_kotlin_night_frankfurt//krangl_example_report.html$