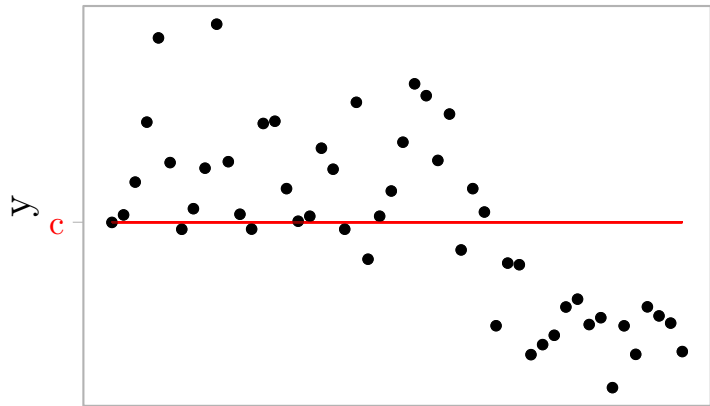
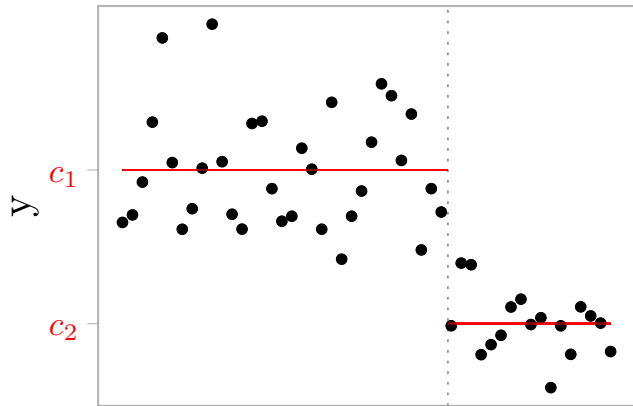


$\mathcal{N}$  $x_j$  $\mathcal{N}_1$  $\mathcal{N}_2$  $x_j$  $t$