

$$(2) \frac{\partial z}{\partial x} = e^x \cos y + \sin y (x+1) e^x = e^x [\cos y + (1+x) \sin y]$$

$$\frac{\partial z}{\partial y} = e^x (-\sin y + x \cos y)$$

$$\frac{\partial^2 z}{\partial x^2} = e^x [\cos y + (x+2) \sin y] \quad \frac{\partial^2 z}{\partial y^2} = e^x (-\cos y - x \sin y)$$

$$\frac{\partial^2 z}{\partial x \partial y} = \frac{\partial^2 z}{\partial y \partial x} = e^x [-\sin y + (1+x) \cos y]$$

$$(4) \frac{\partial^{p+q+r} u}{\partial x^p \partial y^q \partial z^r} = (x+p)(y+q)(z+r) e^{x+y+z}$$

$$(7) \text{ Let } s = x+y, \quad t = xy, \quad v = \frac{x}{y} \quad z = f(s, t, v)$$

$$z_x = \frac{\partial z}{\partial x} = \frac{\partial f}{\partial s} \frac{\partial s}{\partial x} + \frac{\partial f}{\partial t} \frac{\partial t}{\partial x} + \frac{\partial f}{\partial v} \frac{\partial v}{\partial x} = f_1' + y f_2' + \frac{1}{y} f_3'$$

$$z_{xx} = \frac{\partial}{\partial x} (f_1' + y f_2' + \frac{1}{y} f_3') = \frac{\partial f_1'}{\partial s} \frac{\partial s}{\partial x} + y \frac{\partial f_2'}{\partial t} \frac{\partial t}{\partial x} + \frac{1}{y} \frac{\partial f_3'}{\partial v} \frac{\partial v}{\partial x}$$

$$= \frac{\partial f_1'}{\partial x} + y \frac{\partial f_2'}{\partial x} + \frac{1}{y} \frac{\partial f_3'}{\partial x} = f_{11}'' + y f_{12}'' + \frac{1}{y} f_{13}'' + y(f_{21}'' + y f_{22}'' + \frac{1}{y} f_{23}'') + \frac{1}{y}(f_{31}'' + y f_{32}'' + \frac{1}{y} f_{33}'')$$

$$= f_{11}'' + y^2 f_{22}'' + \frac{1}{y^2} f_{33}'' + 2y f_{12}'' + \frac{2}{y} f_{13}'' + 2 f_{23}''$$

$$z_{xy} = \frac{\partial}{\partial y} (f_1' + y f_2' + \frac{1}{y} f_3') = \frac{\partial f_1'}{\partial y} + f_2' + y \frac{\partial f_2'}{\partial y} - \frac{1}{y^2} f_3' + \frac{1}{y} \frac{\partial f_3'}{\partial y}$$

$$= f_{11}'' + x f_{12}'' - \frac{x}{y^2} f_{13}'' + f_2' + y(f_{21}'' + x f_{22}'' - \frac{x}{y^2} f_{23}'') - \frac{1}{y^2} f_3' + \frac{1}{y}(f_{31}'' + x f_{32}'' - \frac{x}{y^2} f_{33}'')$$

$$= f_{11}'' + x y f_{22}'' - \frac{x}{y^3} f_{33}'' + (x+y) f_{12}'' + (\frac{1}{y} - \frac{x}{y^2}) f_{13}'' + f_2' - \frac{1}{y^2} f_3'$$

$$2. \frac{\partial u}{\partial r} = \frac{\partial u}{\partial x} \cos \theta + \frac{\partial u}{\partial y} \sin \theta, \quad \frac{\partial u}{\partial \theta} = \frac{\partial u}{\partial x} (-r \sin \theta) + \frac{\partial u}{\partial y} r \cos \theta$$

$$\frac{\partial^2 u}{\partial r^2} = \frac{\partial}{\partial r} \left( \frac{\partial u}{\partial x} \cos \theta + \frac{\partial u}{\partial y} \sin \theta \right)$$

$$= \frac{\partial^2 u}{\partial x^2} \cos^2 \theta + \frac{\partial^2 u}{\partial x \partial y} 2 \sin \theta \cos \theta + \frac{\partial^2 u}{\partial y^2} \sin^2 \theta$$

$$\frac{\partial^2 u}{\partial \theta^2} = \frac{\partial^2 u}{\partial x^2} r^2 \sin^2 \theta + \frac{\partial^2 u}{\partial y^2} r^2 \cos^2 \theta - 2 r^2 \sin \theta \cos \theta \frac{\partial^2 u}{\partial x \partial y} - r \cos \theta \frac{\partial u}{\partial x} - r \sin \theta \frac{\partial u}{\partial y}$$

$$\therefore \frac{\partial^2 u}{\partial r^2} + \frac{1}{r} \frac{\partial u}{\partial r} + \frac{1}{r^2} \frac{\partial^2 u}{\partial \theta^2} = \frac{\partial^2 u}{\partial x^2} + \frac{\partial^2 u}{\partial y^2}$$

$$4. \text{证明} \quad \frac{\partial V}{\partial x} = -\frac{1}{r^2} g \frac{\partial r}{\partial x} + \frac{1}{r} g' \cdot \left(-\frac{1}{c}\right) \frac{\partial r}{\partial x} = -\frac{x}{r^3} g - \frac{1}{c} \frac{x}{r^2} g'$$

$$\frac{\partial^2 V}{\partial x^2} = \frac{r^3 - 3x^2 - \frac{x}{c}}{r^6} g - \frac{x}{r^3} g' \cdot \left(-\frac{1}{c}\right) \frac{x}{r} - \frac{1}{c} \frac{r^2 - 3x^2 - \frac{x}{c}}{r^4} g' - \frac{1}{c} \frac{x}{r^2} g'' \cdot \left(-\frac{1}{c}\right) \frac{x}{r}$$

$$= \frac{3x^2 - r^2}{r^5} g + \frac{3x^3 - r^2}{cr^4} g' + \frac{x^2}{c^2 r^3} g''$$

$$\text{同理} \quad \frac{\partial^2 V}{\partial y^2} = \frac{3y^2 - r^2}{r^5} g + \frac{3y^3 - r^2}{cr^4} g' + \frac{y^2}{c^2 r^3} g''$$

$$\frac{\partial^2 V}{\partial z^2} = \frac{3z^2 - r^2}{r^5} g + \frac{3z^3 - r^2}{cr^4} g' + \frac{z^2}{c^2 r^3} g''$$

$$V_{xx} + V_{yy} + V_{zz} = \frac{1}{c^2 r} g'' = \frac{1}{c^2} V_{tt}$$



一 右稳定点;  $f: \mathbb{R}^n \rightarrow \mathbb{R}$ , 且  $f(x) = \phi(a \cdot x)$

$$\text{解: } f_x(0,0) = \lim_{x \rightarrow 0} \frac{f(x,0) - f(0,0)}{x-0} = \lim_{x \rightarrow 0} \frac{x^3}{x^3} = 1$$

$$f_y(0,0) = \lim_{y \rightarrow 0} \frac{f(0,y) - f(0,0)}{y-0} = \lim_{y \rightarrow 0} \left( \frac{-y^3}{y^3} \right) = -1$$

$$\lim_{\rho \rightarrow 0} \frac{[f - f_x(0,0)x - f_y(0,0)y]}{\rho} = \lim_{(x,y) \rightarrow (0,0)} \frac{x^2y - xy^2}{(x^2+y^2)^{\frac{3}{2}}}$$

$$\text{令 } y=x \quad \lim_{(x,y) \rightarrow (0,0)} \frac{x^2y - xy^2}{(x^2+y^2)^{\frac{3}{2}}} = 0 \quad y=2x \quad \lim_{(x,y) \rightarrow (0,0)} \frac{x^2y - xy^2}{(x^2+y^2)^{\frac{3}{2}}} = -\frac{2}{5\sqrt{5}}$$

极限不存在, 即  $f(x,y)$  在  $(0,0)$  不可微

$$\text{证明: (1) } \frac{\partial u}{\partial x_k} = \sum_{i=1}^{n-1} \begin{vmatrix} 1 & 1 & \dots & 1 & \dots & 1 \\ x_1 & x_2 & \dots & x_k & \dots & x_n \\ \vdots & \vdots & & \vdots & & \vdots \\ 0 & 0 & \dots & i x_k^{i-1} & \dots & 0 \\ \vdots & \vdots & & \vdots & & \vdots \\ x_1^{n-1} & x_2^{n-1} & \dots & x_k^{n-1} & \dots & x_n^{n-1} \end{vmatrix}$$

$$\sum_{k=1}^n \frac{\partial u}{\partial x_k} = \sum_{k=1}^n \sum_{i=1}^{n-1} \sum_{k=1}^n \begin{vmatrix} 1 & 1 & \dots & 1 & \dots & 1 \\ x_1 & x_k & \dots & x_n \\ \vdots & \vdots & & \vdots & & \vdots \\ 0 & i x_k^{i-1} & \dots & 0 \\ \vdots & \vdots & & \vdots & & \vdots \\ x_1^{n-1} & x_k^{n-1} & \dots & x_n^{n-1} \end{vmatrix} = \sum_{i=1}^{n-1} \begin{vmatrix} 1 & \dots & 1 & \dots & 1 \\ x_1^{i-1} & x_k^{i-1} & \dots & x_n^{i-1} \\ \vdots & \vdots & & \vdots & \\ i x_1^{i-1} & i x_k^{i-1} & \dots & i x_n^{i-1} \\ \vdots & \vdots & & \vdots & \\ x_1^{i+1} & x_k^{i+1} & \dots & x_n^{i+1} \\ \vdots & \vdots & & \vdots & \\ x_1^{n-1} & x_k^{n-1} & \dots & x_n^{n-1} \end{vmatrix}$$

= 0 (行列式中  $i$  与  $i+1$  行成比例, 所有行列式为 0)

$$(2) \sum_{k=1}^n x_k \frac{\partial u}{\partial x_k} = \sum_{i=1}^n \sum_{k=1}^n \begin{vmatrix} 1 & \dots & 1 & \dots & 1 \\ \vdots & & & & \vdots \\ 0 & \dots & i x_k^i & \dots & 0 \\ \vdots & & & & \vdots \\ x_1^{n-1} & & x_k^{n-1} & & x_n^{n-1} \end{vmatrix} = \sum_{i=1}^{n-1} i \cdot u = \frac{n(n-1)}{2} u$$

例 4. (1) 令  $x_1 = \sin x$ ,  $x_2 = \cos x$

$$(dg)'(x) = \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} \right) \begin{pmatrix} \frac{dx_1}{dx} \\ \frac{dx_2}{dx} \end{pmatrix} = (1, -1) \begin{pmatrix} \cos x \\ -\sin x \end{pmatrix} = \cos x + \sin x$$

(2) 令  $x = x_1 - x_2$

$$\begin{aligned} (g \circ f)'(x_1, x_2) &= \begin{pmatrix} \frac{\partial g}{\partial x} \\ \frac{\partial g}{\partial x} \end{pmatrix} \left( \frac{\partial f}{\partial x_1}, \frac{\partial f}{\partial x_2} \right) = \begin{pmatrix} \cos x \\ -\sin x \end{pmatrix} (1, -1) \\ &= \begin{bmatrix} \cos(x_1 - x_2) & -\cos(x_1 - x_2) \\ -\sin(x_1 - x_2) & \sin(x_1 - x_2) \end{bmatrix} \end{aligned}$$

(3) 令  $u = h(y) = (y_1, y_2, y_2 - y_1)^T$ ,

$y = h(x_1, x_2) = (x_1, x_2, x_2 - x_1)^T$ ,

$$(h \circ h)'(x_1, x_2) = \begin{pmatrix} \frac{\partial u_1}{\partial y_1} & \frac{\partial u_1}{\partial y_2} \\ \frac{\partial u_2}{\partial y_1} & \frac{\partial u_2}{\partial y_2} \end{pmatrix} \begin{pmatrix} \frac{\partial y_1}{\partial x_1} & \frac{\partial y_1}{\partial x_2} \\ \frac{\partial y_2}{\partial x_1} & \frac{\partial y_2}{\partial x_2} \end{pmatrix}$$

$$= \begin{pmatrix} y_2 & y_1 \\ -1 & 1 \end{pmatrix} \begin{pmatrix} x_2 & x_1 \\ -1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} x_2^2 - 2x_1x_2 & 2x_1x_2 - x_1^2 \\ -x_2 - 1 & -x_1 + 1 \end{pmatrix}$$

$$(4) \text{ 令 } u = S(y) = (y_1^2, 2y_2, y_2 + 4)^T$$

$$y = h(x_1, x_2) = (x_1, x_2, x_2 - x_1)^T$$

$$(Soh)'(x_1, x_2) = \begin{pmatrix} 2y_1 & 0 \\ 0 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_2 & x_1 \\ -1 & 1 \end{pmatrix} = \begin{bmatrix} 2x_1x_2^2 & 2x_1^2x_2 \\ -2 & 2 \\ -1 & 1 \end{bmatrix}$$

$$(5) u = t(y) = (y_1y_2y_3, y_1 + y_2 + y_3)^T$$

$$y = S(x_1, x_2) = (x_1^2, 2x_2, x_2 + 4)^T$$

$$(tos)'(x_1, x_2) = \begin{pmatrix} y_2y_3 & y_1y_3 & y_1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2x_1 & 0 \\ 0 & 2 \\ 0 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 4x_1x_2^2 + 16x_1x_2 & 8x_1^2 + 4x_1^2x_2 \\ 2x_1 & 3 \end{pmatrix}$$

$$(6) u = S(y) = (y_1^2, 2y_2, y_2 + 4)^T$$

$$y = t(x_1, x_2, x_3) = (x_1x_2x_3, x_1 + x_2 + x_3)^T$$

$$(Sot)'(x_1, x_2, x_3) = \begin{pmatrix} 2y_1 & 0 \\ 0 & 2 \\ 0 & 1 \end{pmatrix} \begin{pmatrix} x_2x_3 & x_1x_3 & x_1x_2 \\ 1 & 1 & 1 \end{pmatrix}$$

$$= \begin{pmatrix} 2x_1x_2^2x_3^2 & 2x_1^2x_2x_3^2 & 2x_1^2x_2^2x_3 \\ 2 & 2 & 2 \\ 1 & 1 & 1 \end{pmatrix}$$



5.  $(x, y)^T \mapsto (x, y, u)^T \mapsto (x, y, u, v)^T \mapsto w$ .

$$W'(x, y) = \left( \frac{\partial w}{\partial x}, \frac{\partial w}{\partial y}, \frac{\partial w}{\partial u}, \frac{\partial w}{\partial v} \right) \begin{pmatrix} \frac{\partial x}{\partial x} & \frac{\partial x}{\partial y} & \frac{\partial x}{\partial u} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} & \frac{\partial y}{\partial u} \\ \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} & \frac{\partial u}{\partial u} \\ \frac{\partial v}{\partial x} & \frac{\partial v}{\partial y} & \frac{\partial v}{\partial u} \end{pmatrix} \begin{pmatrix} \frac{\partial x}{\partial x} & \frac{\partial x}{\partial y} \\ \frac{\partial y}{\partial x} & \frac{\partial y}{\partial y} \\ \frac{\partial u}{\partial x} & \frac{\partial u}{\partial y} \end{pmatrix}$$

$$= \left( \frac{\partial h}{\partial x}, 1, \frac{\partial h}{\partial u}, \frac{\partial h}{\partial v} \right) \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \\ \frac{\partial g}{\partial x} & \frac{\partial g}{\partial y} & \frac{\partial g}{\partial u} \end{pmatrix} \begin{pmatrix} 1 & 0 \\ 0 & 1 \\ \frac{\partial f}{\partial x} & \frac{\partial f}{\partial y} \end{pmatrix}$$

$$= \left( \frac{\partial h}{\partial x} + \frac{\partial f}{\partial x} \frac{\partial h}{\partial u} + \frac{\partial h}{\partial v} \left( \frac{\partial g}{\partial x} + \frac{\partial f}{\partial x} \frac{\partial g}{\partial u} \right), \frac{\partial f}{\partial y} \frac{\partial h}{\partial u} + \frac{\partial h}{\partial v} \left( \frac{\partial g}{\partial y} + \frac{\partial f}{\partial y} \frac{\partial g}{\partial u} \right) \right)$$

P133 7. (2).  $f(x, y) = \frac{x}{y}$   $f(1, 1) = 1$   $f_x = \frac{1}{y}$   $f_x(1, 1) = 1$   $f_y = -\frac{x}{y^2}$   $f_y(1, 1) = -1$ .

$f_{xx} = 0$ ,  $f_{xx}(1, 1) = 0$   $f_{yy} = \frac{2x}{y^3}$   $f_{yy}(1, 1) = 2$   $f_{xy}(1, 1) = -1$

$f_{x^3}(1, 1) = 0$   $f_{x^2y}(1, 1) = 0$   $f_{xy^2}(1, 1) = 2$   $f_{y^3}(1, 1) = -6$

$f_{x^4} = 0$   $f_{x^2y^2} = 0$   $f_{xy^3} = -\frac{6}{y^4}$   $f_{y^4} = \frac{24x}{y^5}$

$x_0 = 1, y_0 = 1, x = 1+h, y = 1+k, n=3$

$f(x, y) = 1+h-h-hk+k^2+h|k^2-k^3 + \left[ -\frac{hk^3}{(1+k)^4} + \frac{1+0h}{(1+k)^5} k^4 \right] \quad (0 < 1)$

(3)  $x, y$  位置对称  $d_{x^i y^j}(0,0) = (-1)^{i+j-1} (i+j-1)!$

$$x_0=0, y_0=0 \quad x=h \quad y=k$$

$$\ln(1+x+y) = \sum_{r=0}^{\infty} \frac{1}{r!} \left( h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^r d(0,0) + \frac{1}{(n+1)!} \left( h \frac{\partial}{\partial x} + k \frac{\partial}{\partial y} \right)^{n+1} d(\theta h, \theta k)$$

$$= \sum_{r=1}^{\infty} (-1)^{r-1} \frac{(x+y)^r}{r} + (-1)^n \frac{(x+y)^{n+1}}{(n+1)(1+\theta h + \theta y)^{n+1}} \quad (0 < \theta < 1)$$

8. (1)  $\begin{cases} \frac{\partial Z}{\partial x} = 3ay - 3x^2 = 0 \\ \frac{\partial Z}{\partial y} = 3ax - 3y^2 = 0 \end{cases} \quad P_1(0,0) \quad P_2(a,a) \text{ 是驻点.}$

$$Z_{xx} = -6x \quad Z_{xy} = 3a \quad Z_{yy} = -6y$$

1)  $Z_{xx}(0,0) = 0 \quad Z_{xx}(0,0) \cdot Z_{yy}(0,0) - Z_{xy}^2(0,0) = -9a^2 < 0, \quad P_1(0,0) \text{ 非极值点}$

2)  $Z_{xx}(a,a) = -6a < 0 \quad Z_{xx}(a,a) \cdot Z_{yy}(a,a) - Z_{xy}^2(a,a) = 27a^2 > 0,$   
 $Z = 3axy - x^3 - y^3$  在  $P_2(a,a)$  取极大值  $a^3$ .

(2)  $\begin{cases} Z_x = e^{2x}(1+2x+4y+2y^2) = 0 \\ Z_y = e^x(2+2y) = 0 \end{cases} \quad P_0(\frac{1}{2}, -1) \text{ 为驻点.}$

$$Z_{xx}(\frac{1}{2}, -1) = e^{2x}(4+4x+8y+4y^2) = 2e > 0 \quad Z_{xy} = e^{2x}(4+4y) \quad Z_{yy} = 2e^{2x}$$

$$Z_{xx}(\frac{1}{2}, -1) \cdot Z_{yy}(\frac{1}{2}, -1) - Z_{xy}^2(\frac{1}{2}, -1) = 4e^2 > 0$$

$Z$  在  $P_0(\frac{1}{2}, -1)$  取极小值,  $Z(\frac{1}{2}, -1) = -\frac{1}{2}e$ .



$$9. (3) \begin{cases} dx' = \cos x - \cos(x+y) = 0 \\ dy' = \cos y - \cos(x+y) = 0 \end{cases} \quad \begin{cases} P_0(\frac{2}{3}\pi, \frac{2}{3}\pi) \text{ 为驻点} \end{cases}$$

$$f(P_0) = \frac{3}{2}\sqrt{3}.$$

1) 在  $y=0$  上,  $0 \leq x \leq 2\pi$   $z = \sin x - \sin x = 0$

2) 在  $x=0$  上,  $0 \leq y \leq 2\pi$   $z = 0$

3) 在  $x+y=2\pi$  上,  $0 \leq x \leq 2\pi$   $z = \sin x + \sin(2\pi - x) - \sin(2\pi) = 0$

最大值  $\frac{3}{2}\sqrt{3}$ , 最小值 0.

11.  $d(x, y) = x^2 + y^2 + \frac{1}{5}(x+2y-16)^2$

$$\begin{cases} dx' = 2x + \frac{2}{5}(x+2y-16) = 0 \\ dy' = 2y + \frac{4}{5}(x+2y-16) = 0 \end{cases}$$

$$P_0(\frac{8}{5}, \frac{16}{5}) \text{ 是驻点}$$

易知  $P_0$  就是  $d(x, y)$  的最小值点,  $d(P_0) = \frac{128}{5}$ .

$$5. \text{ 解 } \frac{\partial^2 \varphi}{\partial x^2} = \begin{vmatrix} 1 & 0 & 0 \\ d+z & e+x & f+y \\ g+y & h+z & k+x \end{vmatrix} + \begin{vmatrix} a+x & b+y & c+z \\ 0 & 1 & 0 \\ g+y & h+z & k+x \end{vmatrix} + \begin{vmatrix} a+x & b+y & c+z \\ d+z & e+x & f+y \\ 0 & 0 & 1 \end{vmatrix}$$

$$= (e+x)(k+x) - (f+y)(h+z) + (a+x)(k+x) - (c+z)(g+y)$$

$$+ (a+x)(e+x) - (b+y)(d+z)$$

$$\frac{\partial^2 \varphi}{\partial x^2} = k+x+e+x+a+x+k+x+a+x+e+x = 6x + 2(a+e+k)$$



7. 解, 首先证明 若  $f(x, y)$  在  $\mathbb{R}^2$  上连续,  $f_x(x, y) = 0$ , 则  $f(x, y) = \varphi(y)$

对  $\mathbb{R}^2$  上任意两点  $(x_1, y), (x_2, y)$  由中值定理

$$f(x_2, y) - f(x_1, y) = f_x(x_1 + \theta(x_2 - x_1), y)(x_2 - x_1) = 0$$

$$\therefore f(x_2, y) = f(x_1, y)$$

由  $(x_1, y), (x_2, y)$  对  $x$  任意性知  $f(x, y)$  与  $x$  无关  $f(x, y) = \varphi(y)$

$$u_{xy} = 0, \quad u_x = \varphi(x)$$

$$\frac{\partial}{\partial x}(u - \int \varphi(x) dx) = 0, \quad u - \int \varphi(x) dx = \varphi(y)$$

$$u = \int \varphi(x) dx + \varphi(y) = \Phi(x) + \varphi(y)$$

P298 8(2)  $f(x) = \frac{1}{2} x^T A x$  .  $A = \begin{pmatrix} -2 & 4 & 6 \\ 4 & -4 & -6 \\ 6 & -6 & 8 \end{pmatrix}$

黑塞矩阵  $f''(x) = A = \begin{pmatrix} -2 & 4 & 6 \\ 4 & -4 & -6 \\ 6 & -6 & 8 \end{pmatrix}$

稳定点  $x_0 = -A^{-1}b = - \begin{bmatrix} \frac{1}{2} & \frac{1}{2} & 0 \\ \frac{1}{2} & \frac{13}{34} & -\frac{3}{34} \\ 0 & -\frac{3}{34} & \frac{1}{17} \end{bmatrix} \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$

$A_{11} = -2 < 0$   $A_{22} = \begin{vmatrix} -2 & 4 \\ 4 & -4 \end{vmatrix} = -8 < 0$

黑塞矩阵负定,  $x_0$  不是极值点