

## PROJECT PRESENTATION

## Artificial Intelligence Fundamentals

Academic year 2022/2023

#### THE SNAKERS TEAM



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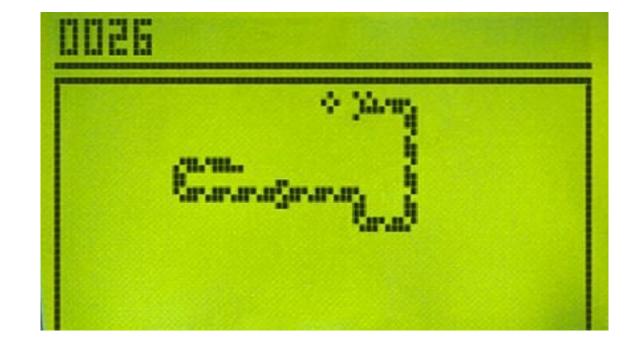
Luca Marini



Irene Testa

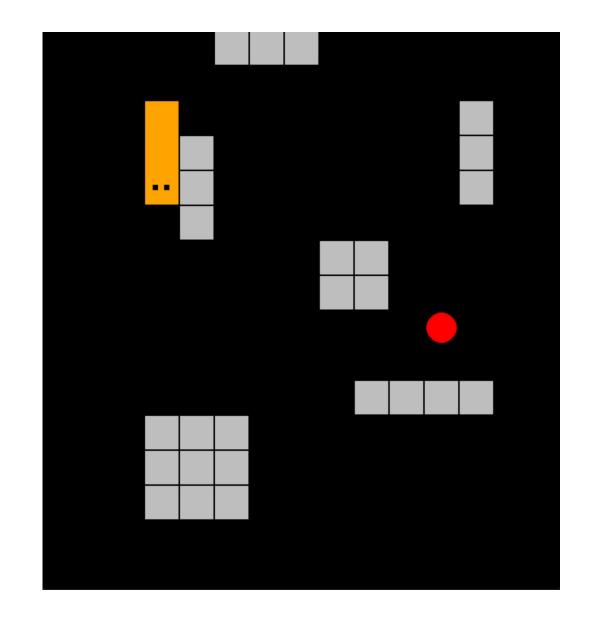
# HISTORY OF THE GRME SNAKE

- Snake was inspired by the arcade game *Blockade*, in 1976.
- The first single-player version was introduced in 1982.

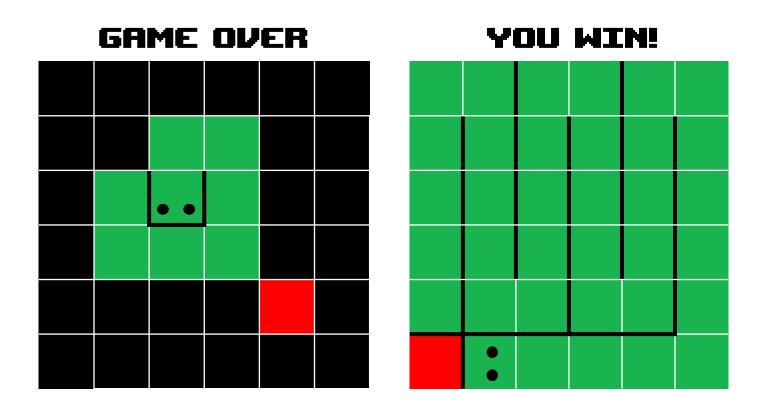


## AIM OF THE GAME

• Starting from a prefixed position, try to eat apples as much as possible in order to cover all the grid (when the snake eats an apple its body lengthens by one unit)

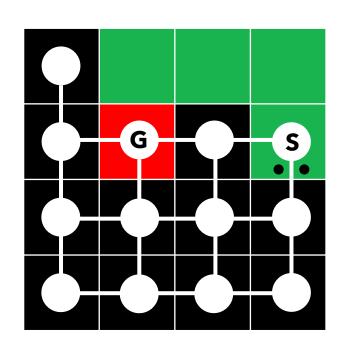


## RULES OF THE GAME



• To survive, the snake must not hit neither the obstacles in the grid, the frame of the grid nor its own body

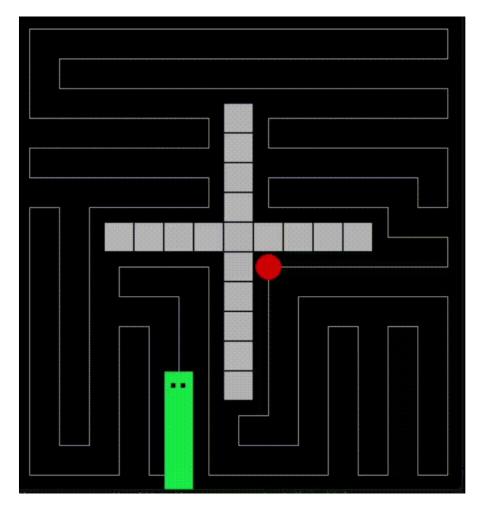
## GAME SPACE: A GRAPH



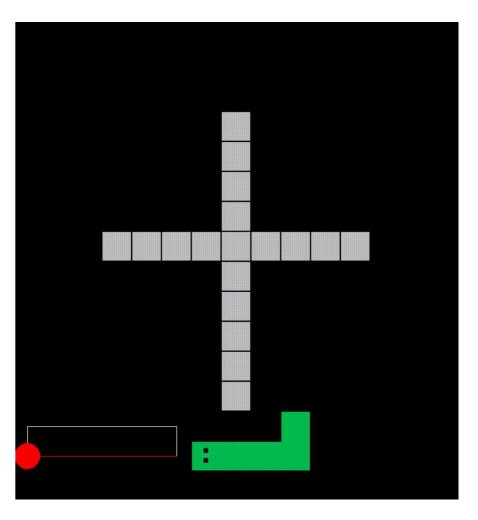
- Self-contained problem where all possible events and outcomes are known. Ideal to apply the Al methodologies we have seen in the course.
- The grid in which the snake moves is actually a solid graph. Each block corresponds to a node in the graph.

S: start, G: goal

## STRATEGIES



Hamilton strategy

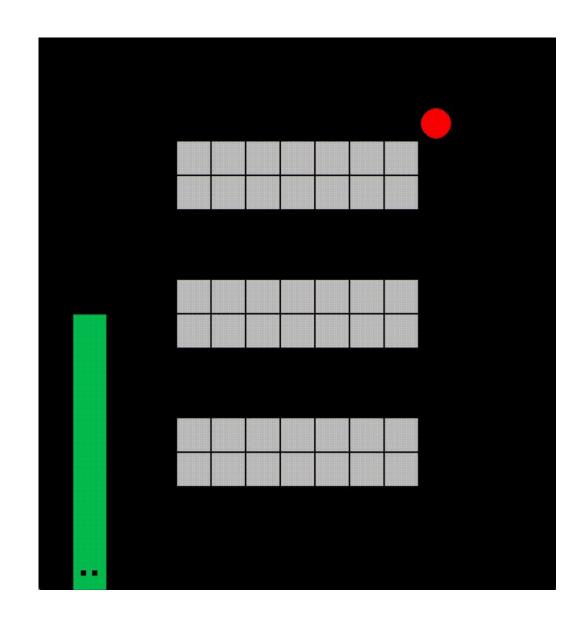


Greedy strategy

# GREEDY STRATEGY

### - WHY?

- the easiest to implement but probably the hardest to perfect
- suitable for any type of grid and obstacle configuration
- requires little computational time
- takes full advantage of search algorithms



## 3 SUB-STRATEGIES



Full greedy approach



Big improvement in the late stages of the game

time

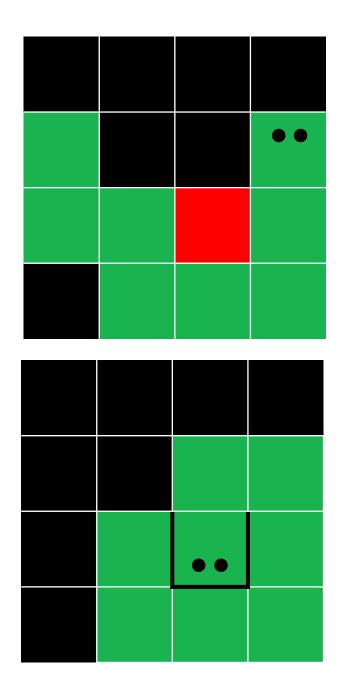
Increase of the survival time

Added "Safe path"

Now

## PATH TO FOOD

- Every game tick the snake tries to find a path between its head and the food
- Obvious problem of early death

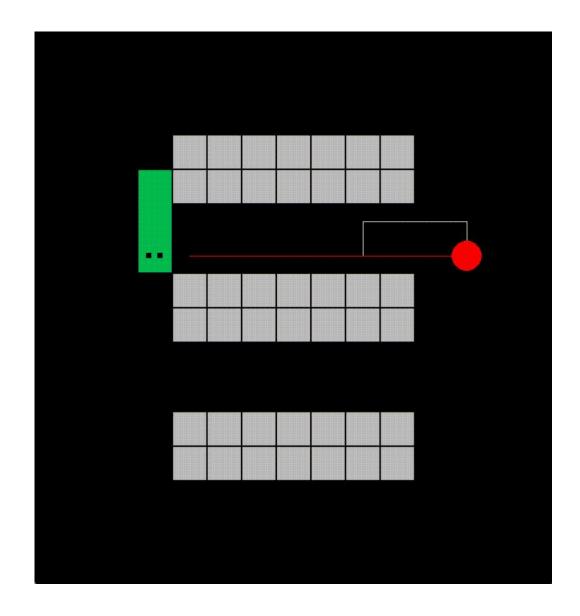


## SAFE PATH

After having computed the path to the food, the algorithm checks if there is a safe cycle

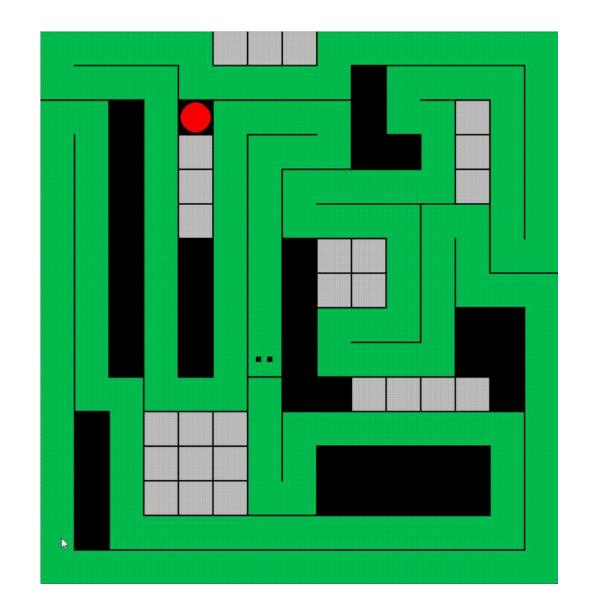
• Red line: "Path to Food"

Yellow line: "Safe Path"



## SAFE PATH

- Due to the lack of attention to the snake's position, the grid tends to become full of small scattered empty spaces
- In this situation the bot is stuck in an infinite loop

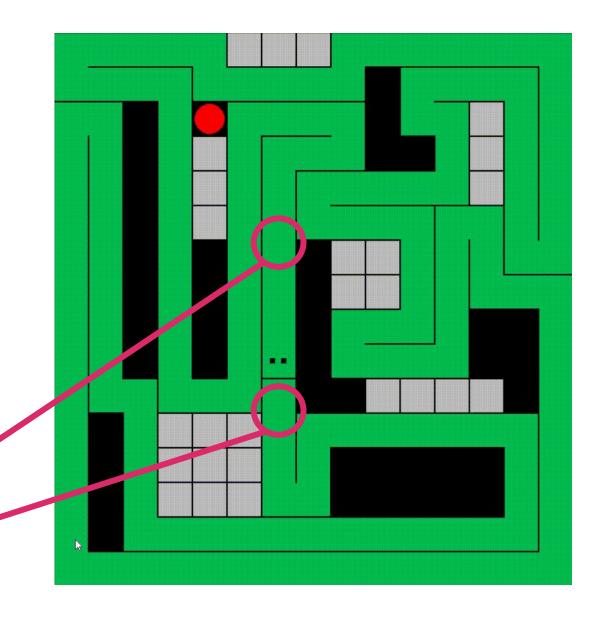


# SPACE OPTIMIZATION

 Every time the bot can't find the shortest path to the food, it tries to optimize the safe path it is following checking for the next optimizable cell and computing the longest path between that cell and the next choke point

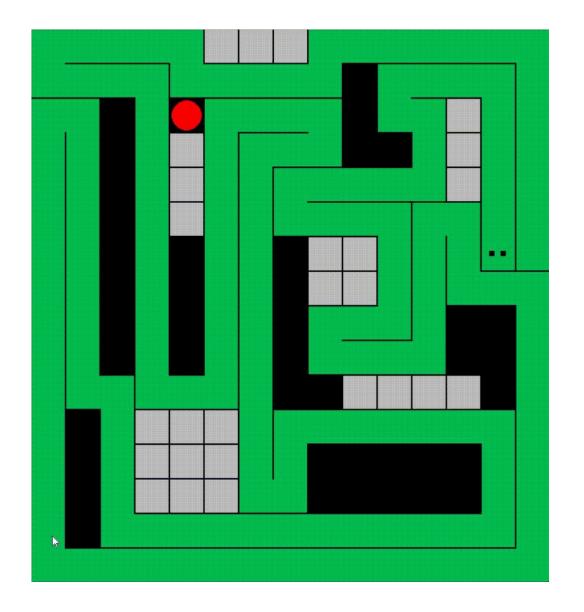
Optimizable cell

Chokepoint



## SPACE OPTIMIZATION

- Longest path ≠ Hamiltonian cycle
- With this optimization the bot always reaches "pseudo-terminal" states



## USED ALGORITHMS

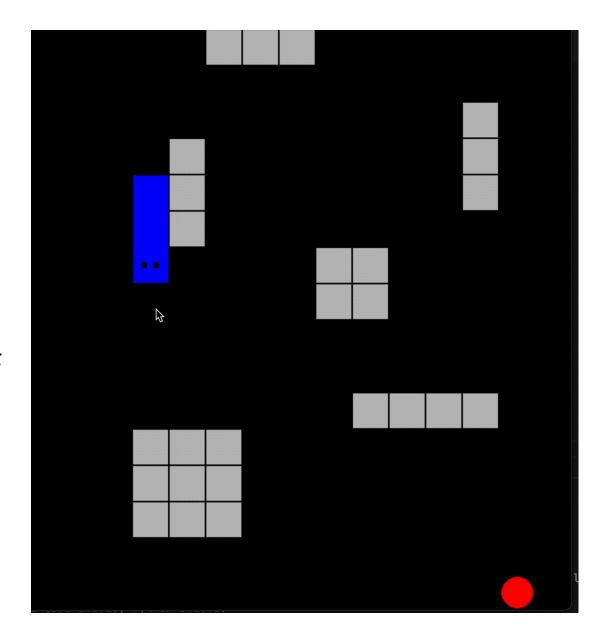
- •A\*
- Longest Path



 Manhattan distance as the main heuristic (best underestimation + avoids zigzagging paths)

• Min-turns: storing the direction of the snake in each node

• Save space: expanding first the nodes with less neighbors

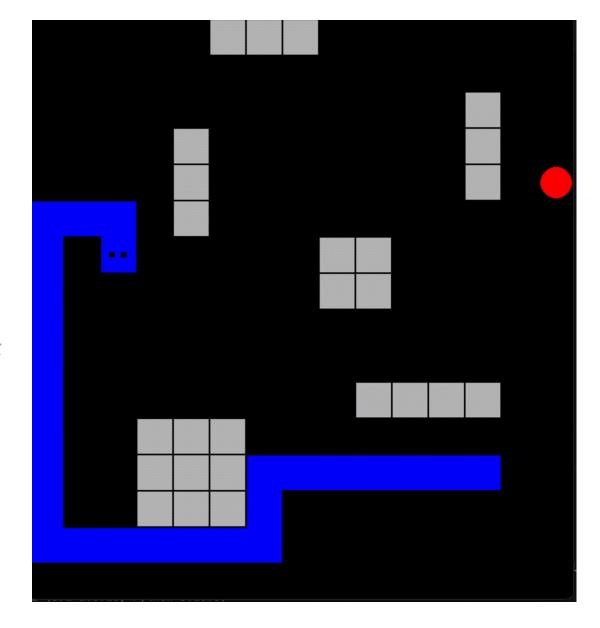




 Manhattan distance as the main heuristic (best underestimation + avoids zigzagging paths)

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## LONGEST PATH PROBLEM

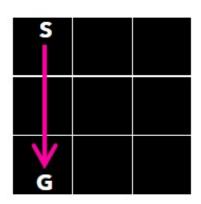
• Find a simple path of maximum lenght

• NP-complete :(

Longest Path Heuristic algorithm

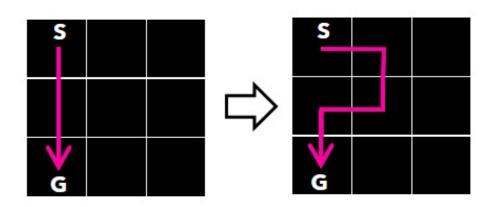
## LONGEST PATH HEURISTIC ALGORITHM

1. Find the shortest path (A\*)



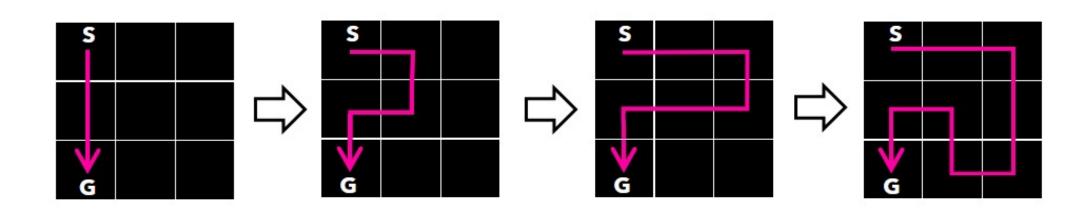
#### LONGEST PATH HEURISTIC ALGORITHM

- 1. Find the shortest path (A\*)
- 2. Extend a pair of path pieces with another pair which is not currently included in the path



### LONGEST PATH HEURISTIC ALGORITHM

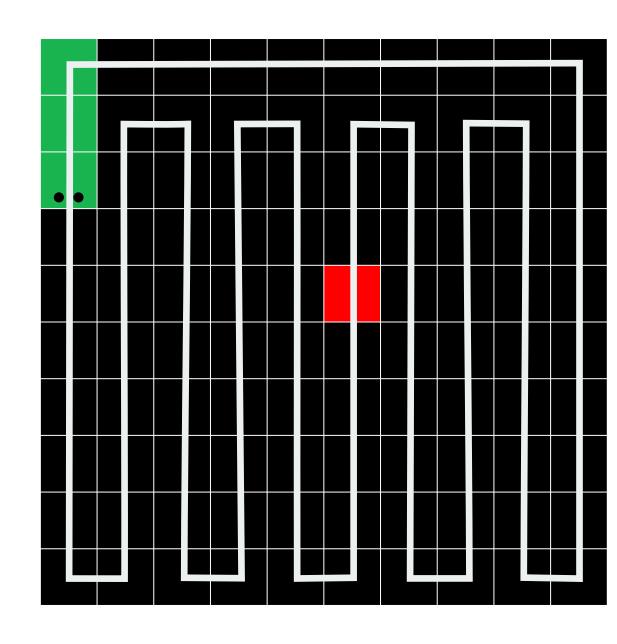
- 1. Find the shortest path (A\*)
- 2. Extend a pair of path pieces with another pair which is not currently included in the path
- 3. Iterate until no extensions can be found

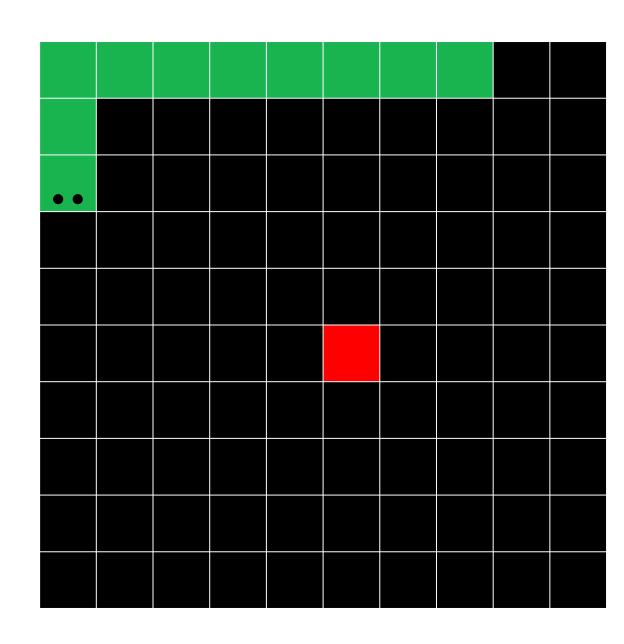


# TRIVIAL WINNING STRATEGY

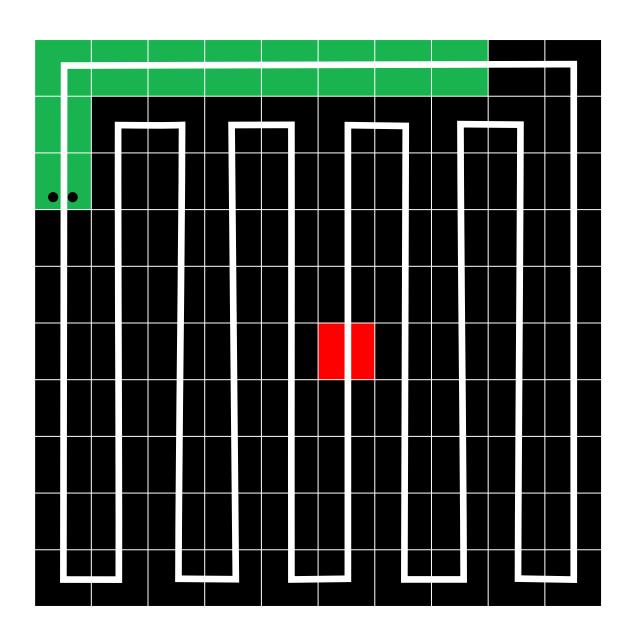
Keep following a hamiltonian cycle, i.e. a cycle that passes through every point of the board exactly once.

- + always leads to a win
- completing the game requires a high number of moves (to eat an apple the snake visits on average half of the nodes)





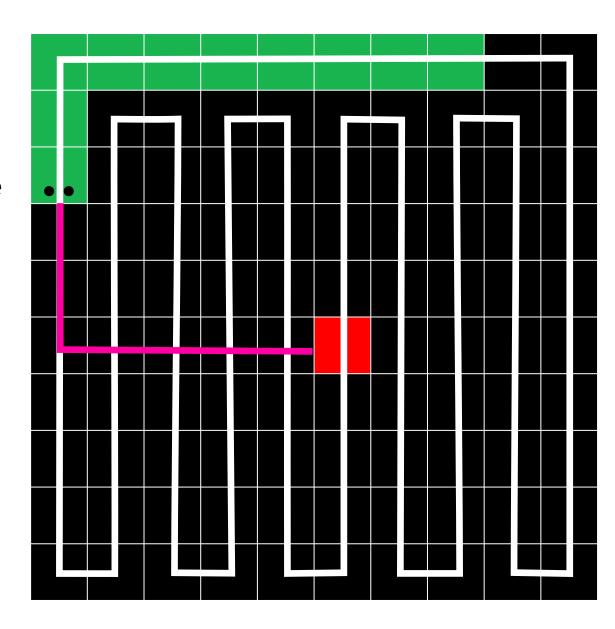
Compute a hamiltonian cycle on the grid.



Compute a hamiltonian cycle on the grid.

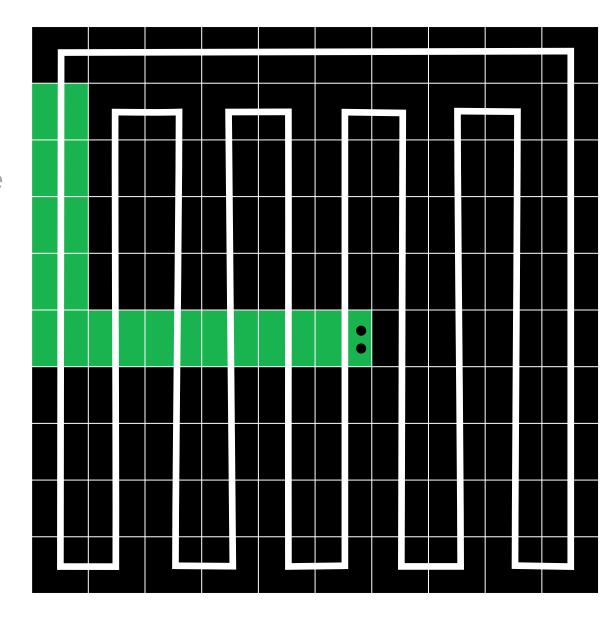
For each step of the game:

Compute the shortest path to the apple



Compute a hamiltonian cycle on the grid. For each step of the game:

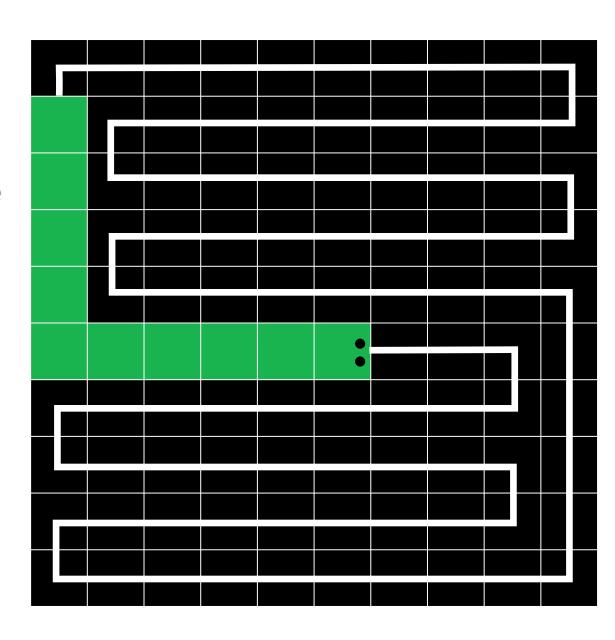
Compute the shortest path to the apple and the position of the snake once it has reached the apple through that path.



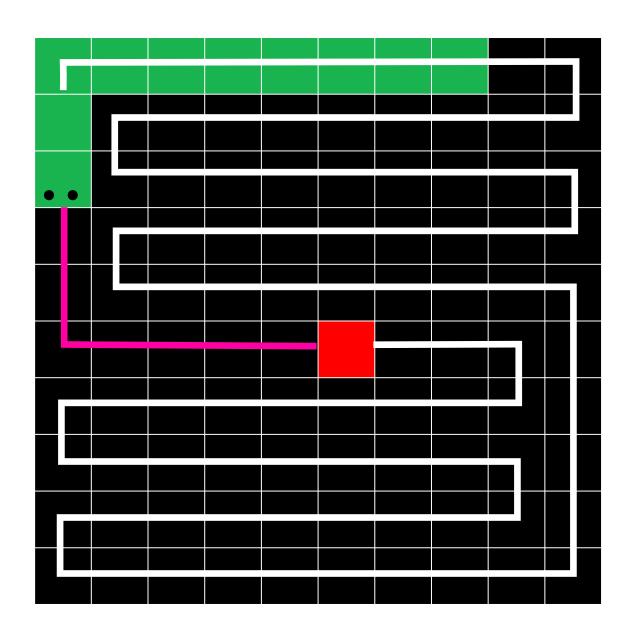
Compute a hamiltonian cycle on the grid. For each step of the game:

Compute the shortest path to the apple and the position of the snake once it has reached the apple through that path.

If there exists a hamiltonian path from the apple to the position of the tail of the snake once it has eaten the apple, then follow the shortest path and save the computed hamiltonian cycle. Otherwise follow the hamiltonian cycle previously computed.



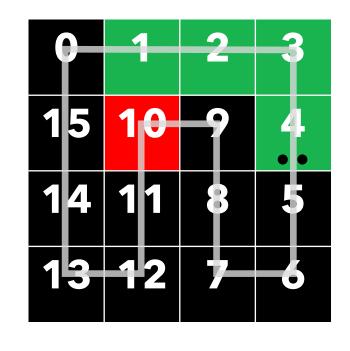
- + gets to the apple faster
- not scalable on arbitrary wide grids (deciding whether a graph contains a hamiltonian path is an NP-complete problem)

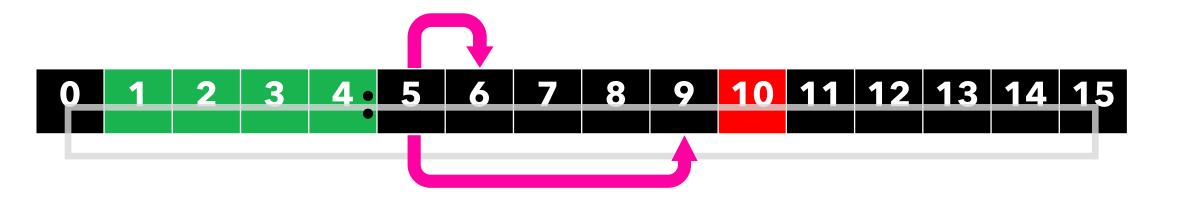


Compute a hamiltonian cycle once and try to skip sections of the cycle to reach the apple faster.

#### How to take shortcuts?

If all the positions occupied by the snake's body on the hamiltonian cycle are between its tail and its head, the snake will never crash into itself.

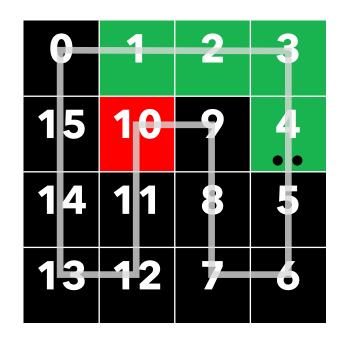


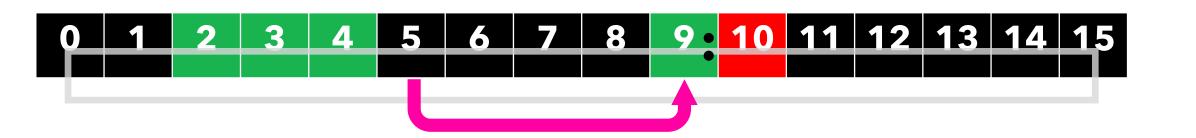


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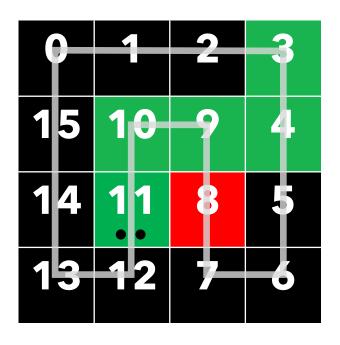
#### How to take shortcuts?

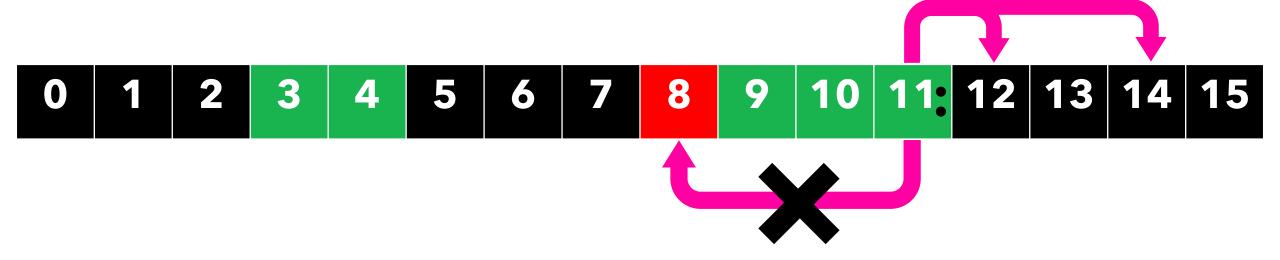
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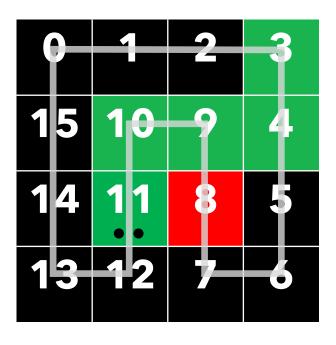


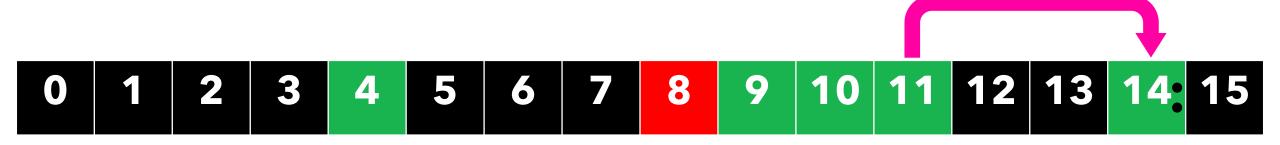
Another step of the game.



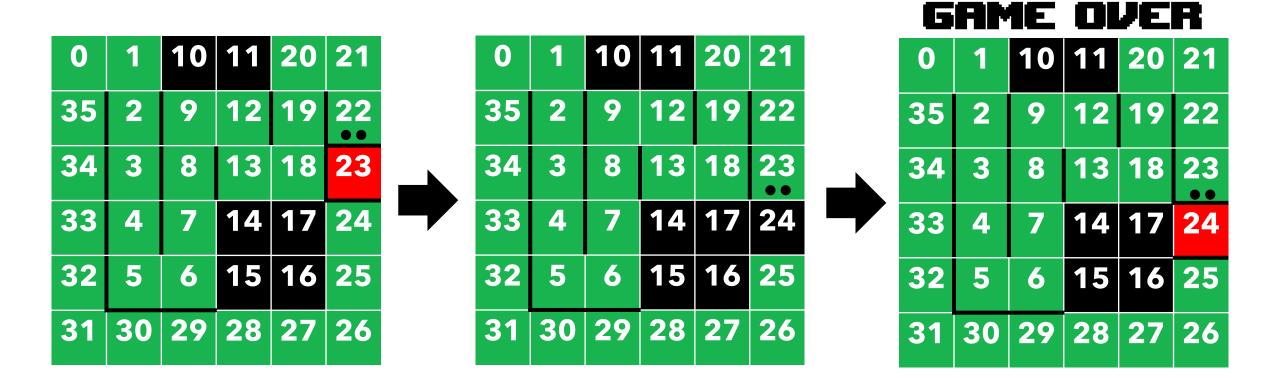


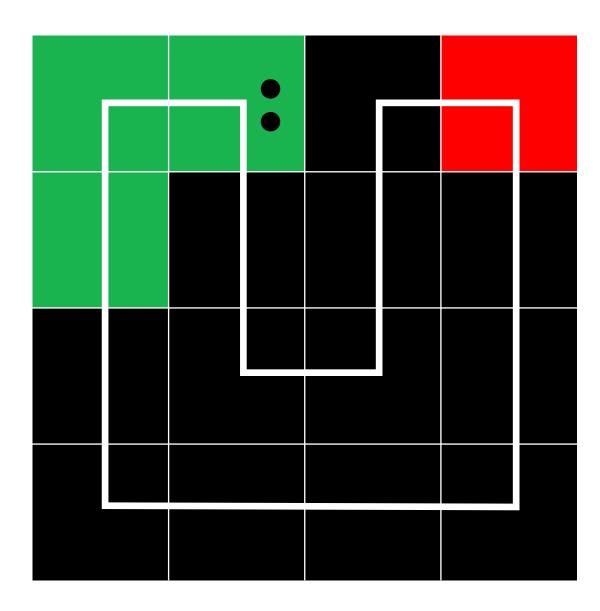
Another step of the game.



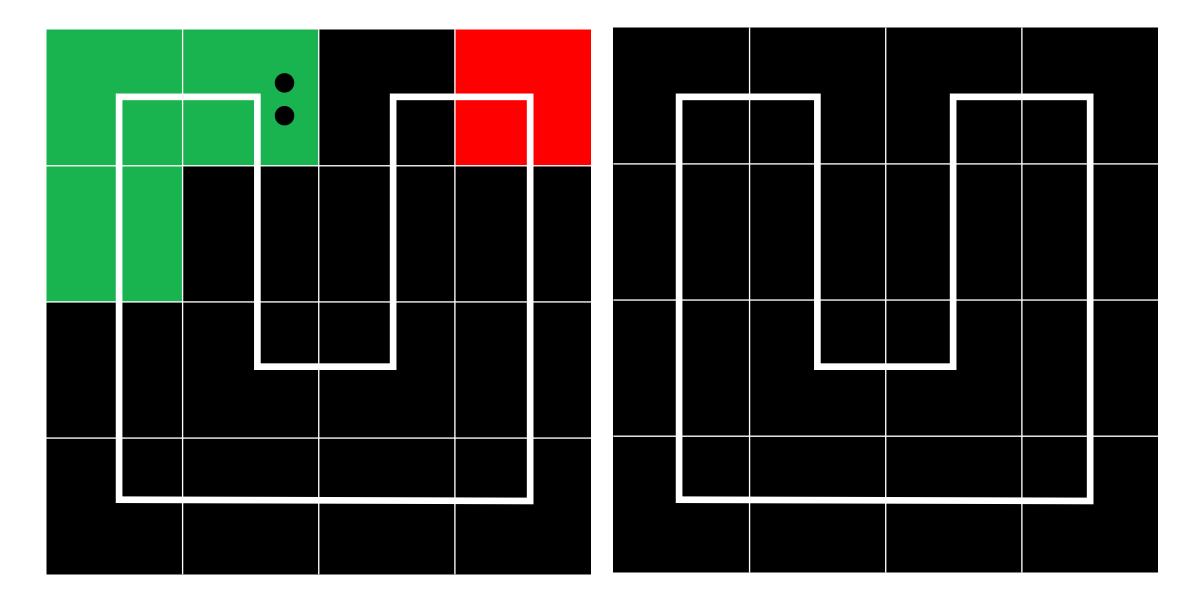


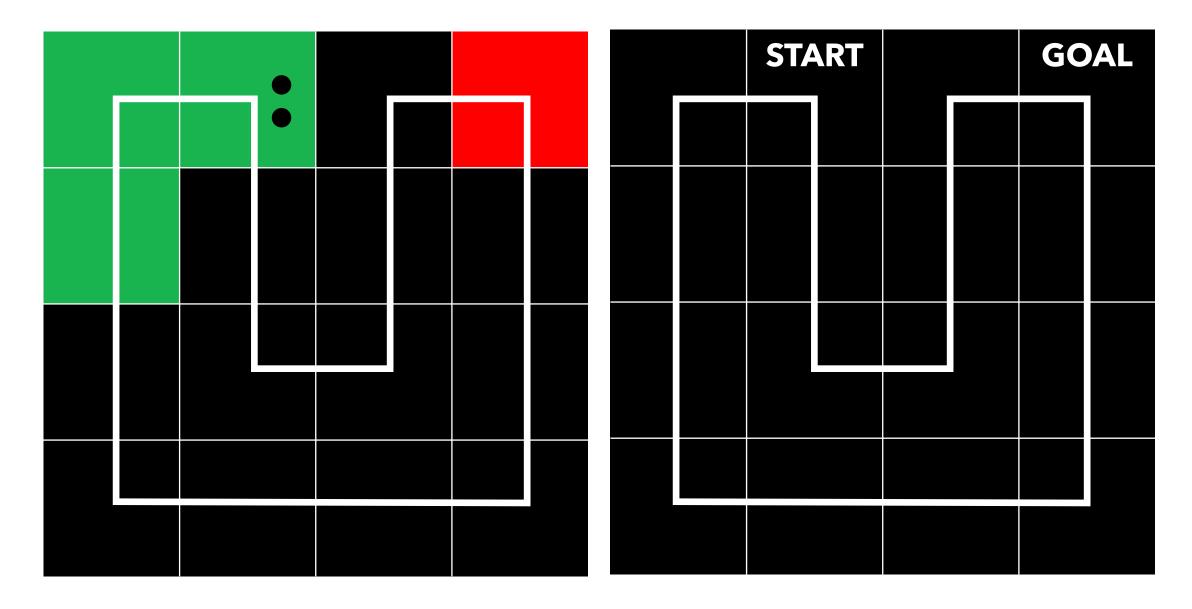
- + taking shortcuts reduces the number of steps to reach the apple
- + deciding the next move requires constant time (few modular arithmetic operations)
- taking shortcuts in the late stages of the game can occasionally lead the snake to crash into itself 🖒 the snake stops taking shortcuts when it gets long

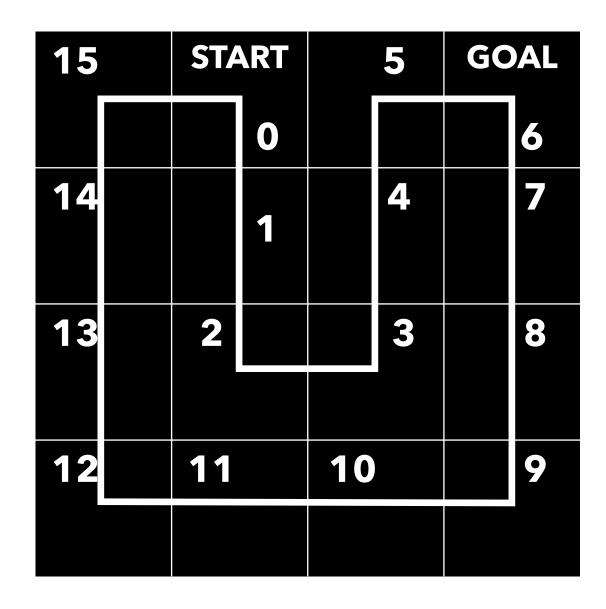




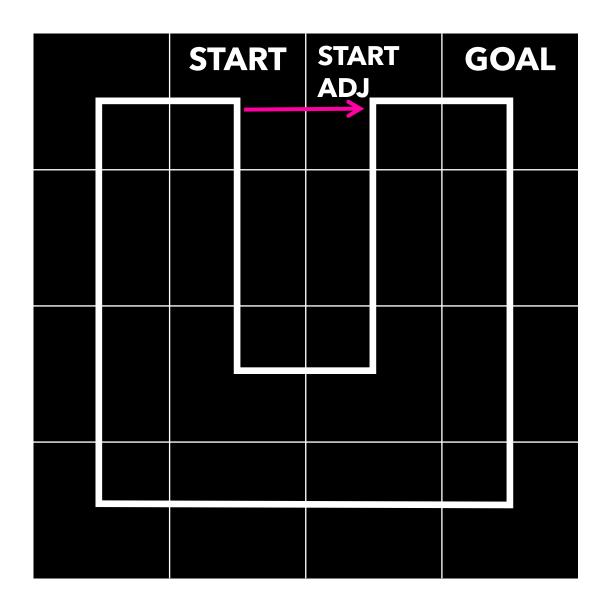
Compute a hamiltonian cycle at every iteration such that the distance between the snake's head and the food is less than the one in the previous cycle.



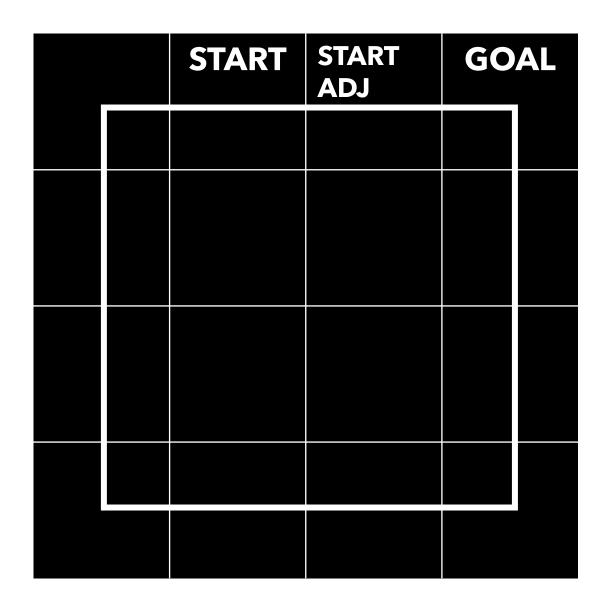




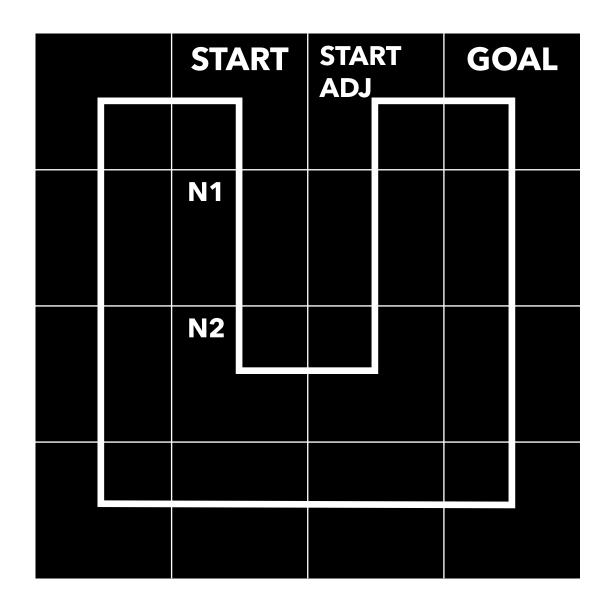
Assign a value to each node following the cycle.



START\_ADJ.VALUE in (START.VALUE + 2, GOAL.VALUE)



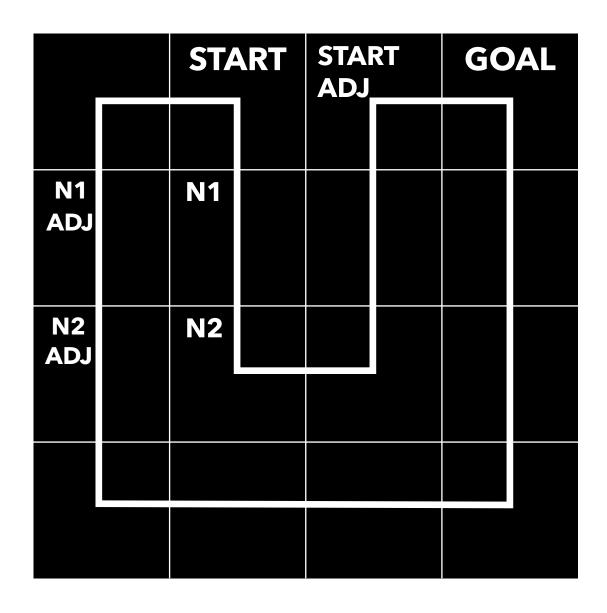
How to insert the excluded nodes in the new cycle?



N1.VALUE, N2.VALUE in (START.VALUE, START\_ADJ.VALUE)

and

N2.VALUE == N1.VALUE +1



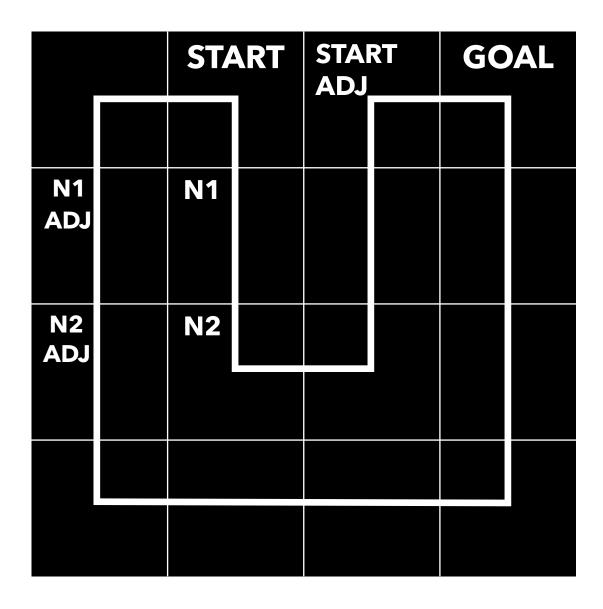
N1\_ADJ.VALUE, N2\_ADJ.VALUE in (GOAL.VALUE, START.VALUE)

and

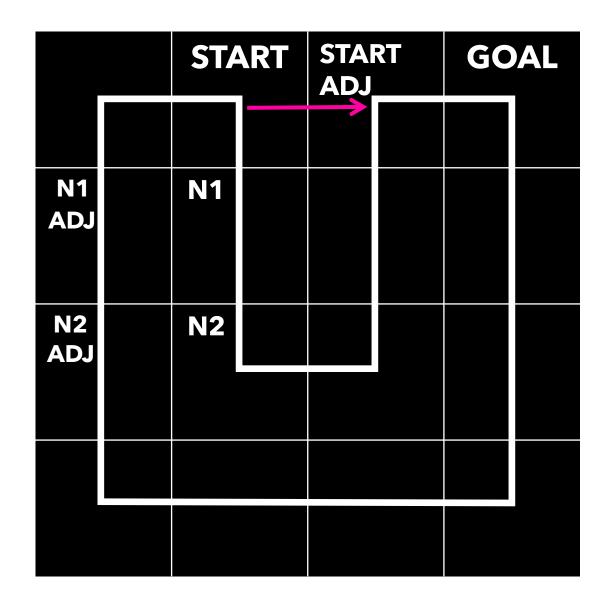
N1\_ADJ adjacent to N1 in the grid graph N2\_ADJ adjacent to N2

and

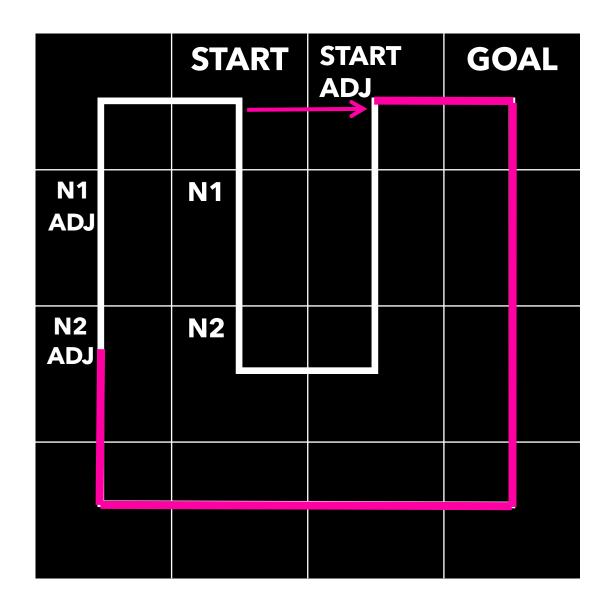
N2\_ADJ.VALUE == N1\_ADJ.VALUE - 1



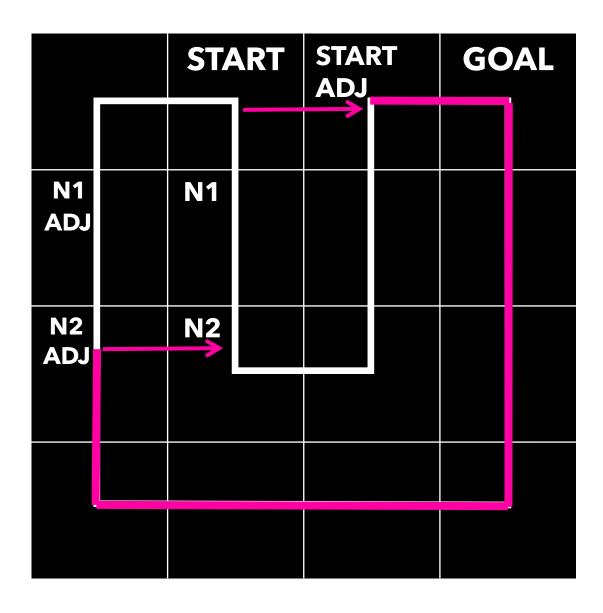
Compute the new cycle.



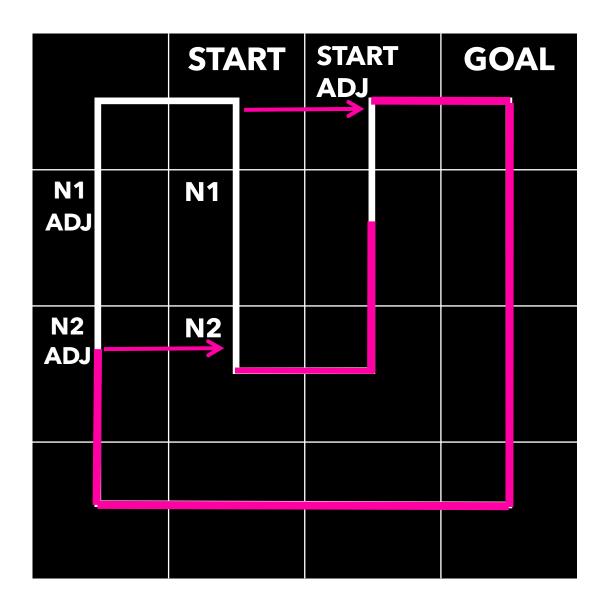
Connect START with START\_ADJ.



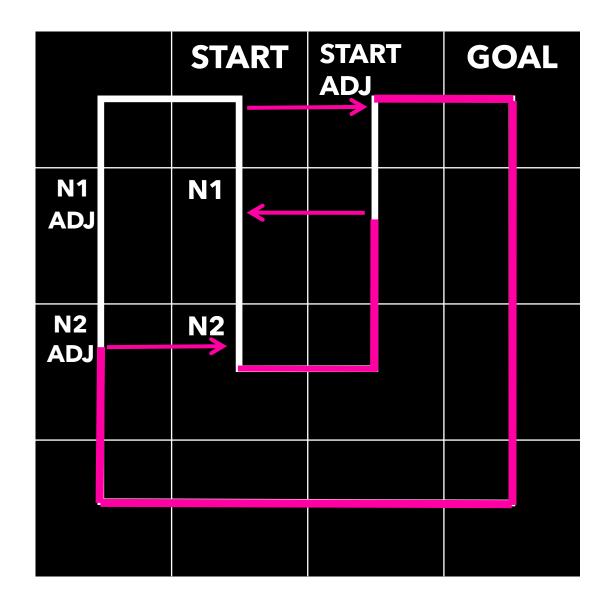
Follow the cycle from START\_ADJ to N2\_ADJ.



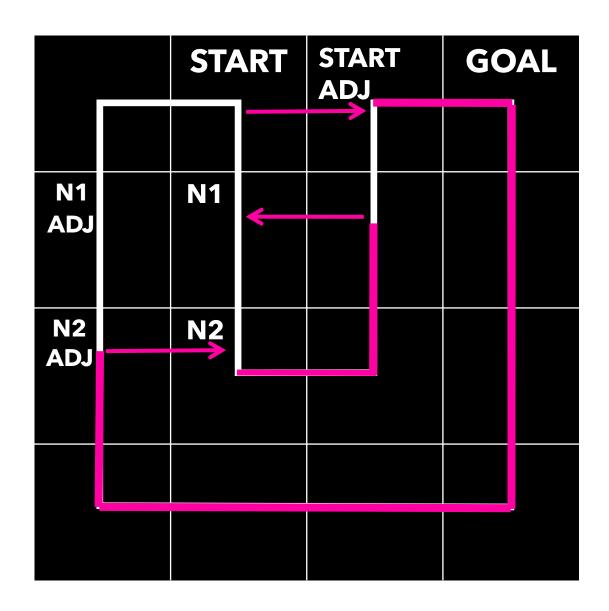
Connect N2\_ADJ to N2.



Follow the cycle from N2 to the node before START ADJ.

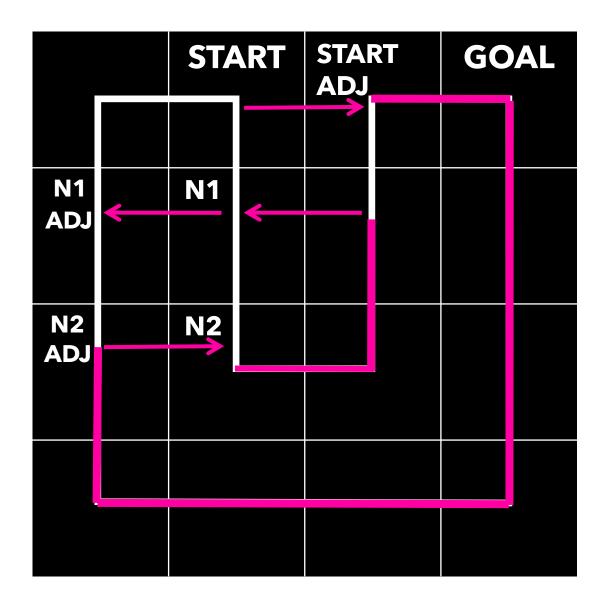


Connect to the node following START.

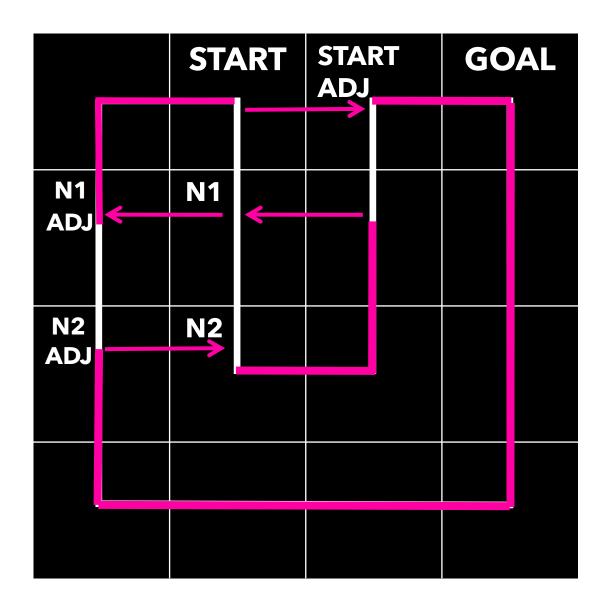


Connect to the node following START.

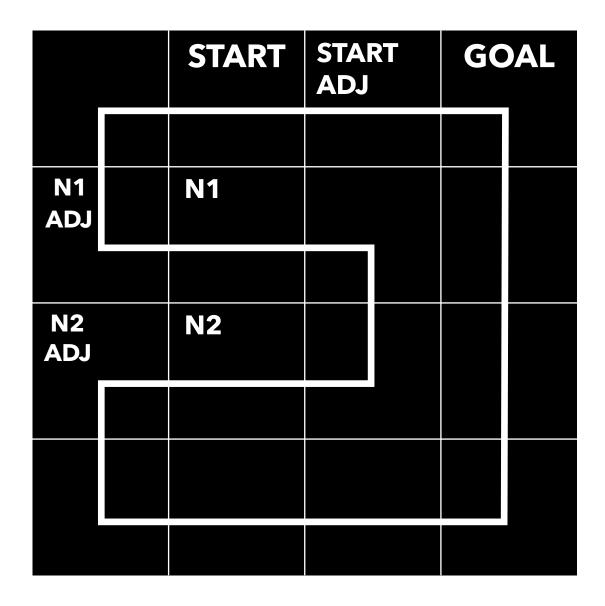
Follow the cycle in the reverse way until N1.



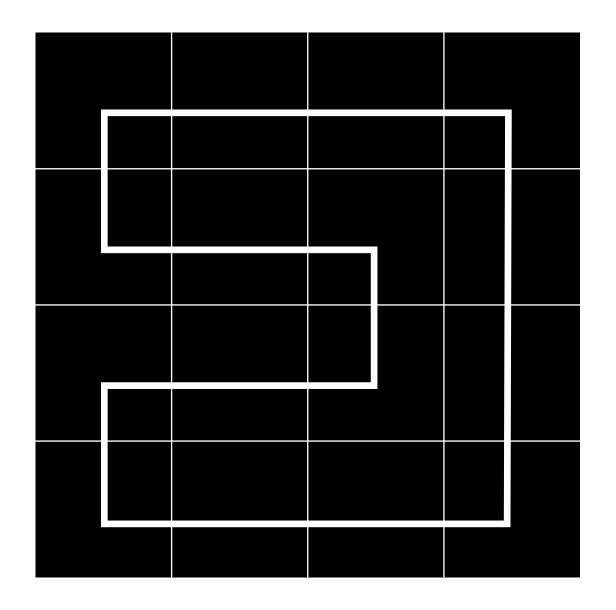
Connect N1 to N1\_ADJ.

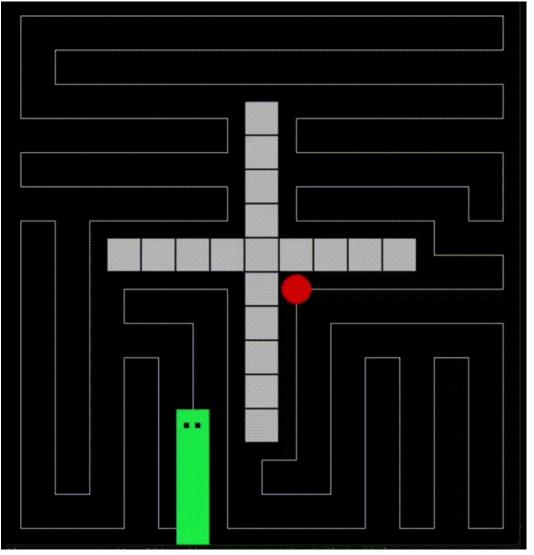


Follow the cycle from N1\_ADJ to START.



Connect all the nodes.





#### REFERENCES

- ☐ Snake (history of the game)
- ☐ Hamiltonian shortcuts strategy
- ☐ Longest path heuristic
- ☐ Hamiltonian cycle change strategy

#### SOFTWARE



aimacode/aimapython



Python implementation of algorithms from Russell And Norvig's "Artificial Intelligence - A Modern Approach"

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Contributors

☆ 7k

**∜** 3k Forks

# THANK YOU FOR YOUR ATTENTION!

