Big data computing - 2019/2020

Homework 1

Due date: Sunday, November 10th, 11.59pm

Assignment 1

Suppose you are using Locality Sensitive Hashing for Jaccard similarity. I.e., each data point can be seen as a set of integer values. Assume, for the purpose of the analysis, that the hash functions you are using behave like an ideal, min-wise independent family. You are given the following constraints:

- You have two thresholds θ_1 and θ_2 , with $\theta_1 > \theta_2$. Two sets X and Y are considered "similar" (i.e., they are a *true positive pair*), whenever $Jaccard(X,Y) \geq \theta_1$, while they are not similar (i.e., a *true negative pair*), whenever $Jaccard(X,Y) < \theta_2$.
- Given a true positive pair (X, Y), you want the probability of considering them as a negative pair (false negative probability) to be at most a value p_1 .
- Given a true negative pair (X, Y), you want the probability of considering it as a positive pair (false positive probability) to be at most p_2 .
- We are not interested in the probability of misclassifying pairs with Jaccard similarity in the interval $[\theta_2, \theta_1)$.

Assume your signature matrix is going to have m rows.

- 1. Work out the equations that give the relationships between the parameters that describe the requirements you are given and the numbers r and b of rows and bands, so as to achieve false negative and false positive probabilities p_1 and p_2 respectively.
- 2. Assuming $\theta_1=0.7$, $\theta_2=0.5$, $p_1=p_2=0.01$, try to identify the minimum value of m that allows to meet these requirements. Given the strong non-linearity of the equations you are working with, you are advised to proceed numerically, by trial and error.

Assignment 2

The goal of this assignment is to highlight issues that arise in unsupervised classification (clustering) when the number of dimensions of the feature space is high (*the curse of dimensionality*), a topic we discussed in class. In the simplified scenario we consider here, we have a set of points that might be effectively clustered if they were first projected onto the right subspace. Unfortunately, finding the right subspace onto which to project is hard in general.

• To begin, consider n points in \mathbb{R}^d , each belonging to one of two possible clusters C_1 and C_2 . Let $a,b\in[0,1]$, with |a-b|>0. A point $\mathbf{x}\in C_1$ is generated as follows:

$$\mathbf{x}_j = \left\{egin{array}{l} a, \; j=i, \ ext{distributed u.a.r. in } [0,1], j
eq i \end{array}
ight.$$

Likewise, a point $\mathbf{y} \in C_2$ is generated in the same way, with the only difference that, this time $\mathbf{y}_i = b$. In words, the values along all dimensions but the i-th are distributed independently and uniformly at random in [0,1] for both points in C_1 and C_2 , while the value on the i-th dimension is deterministically d for points in d1 and d3 for points in d2.

Provide an answer (with convincing proofs) to the following questions:

- 1. What is the expected distance between two points from the same cluster?
- 2. What is the expected distance between two points from different clusters?
- 3. What do the results from points 1 and 2 suggest as regards the possibility that a clustering algorithm will effective identify the two clusters C_1 and C_2 ? Please elaborate.
- 4. Assume next that you know the dimension i. What would be an effective strategy to cluster the points in this case (assuming |a-b| is "not too small")? Assume you have a good clustering algorithm (such as k-means++) to use as a subroutine.
- Discuss why the strategy you identified in point 4 above may not be feasible in general.