

On consensus

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Algorithm 1 shows a Gauss-Seidel like decomposition method which optimizes a function $f(\cdot)$ w.r.t a block of variables i in a iteratively fashion. It can be shown that the algorithm converges if \mathcal{L}_0 is compact.

Algorithm 1: Gauss-Seidel like decomposition method

Data:
 $x^0 \in \mathbb{R}^m$: candidate solution
 $\lambda_i > 0, \quad i = 1, \dots, m$
1 $k \leftarrow 0$
2 **while** *stop criterion* **do**
3 **for** $i = 1, \dots, m$ **do**
4 $d_i^k \leftarrow -\nabla_i f(x^k)$
5 compute α_i^k with line search
6 $x_i^{k+1} = x_i^k + \alpha_i^k d_i^k$
7 **end**
8 $k \leftarrow k + 1$
9 **end**

In the case fo RNNs we would, ideally, in a consesum inspired way, solve

$$\begin{aligned} \min_{W, W^i} \quad & f(W, W^i, i = 1 \dots, T) \\ \text{subject to} \quad & W_i = W, \quad i = 1, \dots, T \end{aligned}$$

considering only W^{rec} for easiness. The Lagrangian can then be written as:

$$\min_{\tilde{W}, W^i} g(\cdot) = f(\tilde{W}, W^i, i = 1 \dots, T) + \lambda(W^i - \tilde{W}) \quad (1)$$

The blocks of variables are, hence, $W^i, i = 1, \dots, T$ where T is the length of the sequence, and \tilde{W} the master variable. However we cannot have T of such matrix in memory so we have to devise a modification of the algorithm like I tried to do in Algorithm 2

The idea is not to store all the matrices, computing gradients for each block separately but using an iteratively update rule, like is done at line 7.

Algorithm 2: RNN consensus-decomposition method

Data:

$W^i = \tilde{W} = W^0, \quad i = 1, \dots, T$: candidate solution

1 $k \leftarrow 0$

2 **while** *stop criterion* **do**

3 **for** $i = 1, \dots, m$ **do**

4 $d_i^k \leftarrow -\nabla_i g(x^k)$

5 compute α_i^k with line search

6 $\tilde{W} = W_i^k + \alpha_i^k d_i^k$

7 $W_j^{k+1} = \tilde{W}, \quad j = 1, \dots, i$

8 **end**

9 $k \leftarrow k + 1$

10 **end**
