

On sliding gradient

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2 ottobre 2015

From Lipschitz continuity we get:

$$f(y) \leq f(x) + \nabla f(x)^T (y - x) + \frac{L}{2} \|x - y\|^2, \quad (1)$$

which choosing $x = x_k$ and $y = x_{k+1} = x_k + t_k d_k$ becomes:

$$f(x_{k+1}) - f(x_k) \leq t_k \nabla f(x_k)^T d_k + t_k^2 \frac{L}{2} \|d_k\|^2. \quad (2)$$

The previous inequality can be rewritten as:

$$f(x_k) - f(x_{k+1}) \geq -t_k \nabla f(x_k)^T d_k \cdot \left(1 + t_k \frac{L}{2} \frac{\nabla f(x_k)^T d_k}{\|\nabla f(x_k)\|^2 \cos^2 \theta_k} \right) \quad (3)$$

where

$$\cos \theta_k = \frac{\nabla f(x_k)^T d_k}{\|\nabla f(x_k)\| \|d_k\|} \quad (4)$$

In a backtracking setting, as defined in algorithm 1, we search for a value of t_k such that:

$$f(x_k) - f(x_{k+1}) \geq \alpha t_k \nabla f(x_k)^T d_k. \quad (5)$$

When backtracking we have two possibilities: either $t_k = s$ satisfy inequality (5) or not. In the latter case it must hold:

$$f(x_k) - f(x_k + \frac{t_k}{\beta} d_k) < \alpha \frac{t_k}{\beta} \nabla f(x_k)^T d_k \quad (6)$$

Combining the latter with inequality 3 written for $t_k = \frac{t_k}{\beta}$ yields:

$$\alpha \frac{t_k}{\beta} \nabla f(x_k)^T d_k > -\frac{t_k}{\beta} \nabla f(x_k)^T d_k \cdot \left(1 + \frac{t_k}{\beta} \frac{L}{2} \frac{\nabla f(x_k)^T d_k}{\|\nabla f(x_k)\|^2 \cos^2 \theta_k} \right), \quad (7)$$

which in turn, being $\nabla f(x_k)^T d_k < 0$ since d_k is a descent direction, and $t_k, \beta > 0$, leads to:

$$t_k > \frac{2(\alpha + 1)\beta}{L} \frac{\|\nabla f(x_k)\|^2 \cos^2 \theta_k}{\nabla f(x_k)^T d_k} \quad (8)$$

$$= \frac{2(\alpha + 1)\beta}{L} \frac{\nabla f(x_k)^T d_k}{\|d_k\|^2} \quad (9)$$

If we impose

$$s \geq \gamma \frac{\nabla f(x_k)^T d_k}{\|d_k\|^2} \quad (10)$$

where γ is some positive constant, we can use 8 in 5 and get:

$$f(x_k) - f(x_{k+1}) > \alpha \cdot \min \left(\gamma, \frac{2(\alpha+1)\beta}{L} \right) \|\nabla f(x_k)\|^2 \cos^2 \theta_k. \quad (11)$$

Summing over k , if f is bounded below, say by f^* , and θ_k bounded away from 90 degrees we get:

$$f(x_0) - f^* \geq \sum_{k=0}^N f(x_k) - f(x_{k+1}) = f(x_0) - f(x_N) > C \sum_{k=0}^N \|\nabla f(x_k)\|^2. \quad (12)$$

Hence we have convergence at the same rate as gradient descent.

We have made the following assumptions along the way:

- $f(\cdot)$ is bounded below
- d_k is a descent direction bounded away from 90 degrees w.r.t $\nabla f(x_k)$
- the initial guess of the backtracking algorithm $s \geq \gamma \frac{\nabla f(x_k)^T d_k}{\|d_k\|^2}$ for some positive constant γ

Algorithm 1: Backtracking algorithm.

Data:

$s > 0$ initial step guess

$\alpha, \beta \in (0, 1)$

1 $t_k \leftarrow s$

2 **while** $f(x_k) - f(x_{k+1}) < \alpha t_k \nabla f(x_k)^T d_k$ **do**

3 $t_k \leftarrow t_k \beta$

4 **end**

5 **return** t_k
