## Primer in Matrix Algebra

Giulio Rossetti\* giuliorossetti94.github.io January 16, 2025

\* email: giulio.rossetti.1@wbs.ac.uk

## What is a Matrix?

- A matrix is a rectangular set of numbers (i.e., range in Excel).
- Example:

$$A = egin{bmatrix} a & b \ c & d \ e & f \end{bmatrix}$$

Vectors are special cases of matrices with only one column:

$$x = \begin{bmatrix} a \\ c \\ e \end{bmatrix}$$

### Matrix Addition

Add matrices by adding corresponding elements:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad B = \begin{bmatrix} e & f \\ g & h \end{bmatrix}, \quad A + B = \begin{bmatrix} a + e & b + f \\ c + g & d + h \end{bmatrix}$$

Matrices must have the same shape to add.

## Matrix Multiplication

- Multiply matrices by combining rows of the left matrix with columns of the right matrix.
- Example:

$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}, \quad B = \begin{bmatrix} g & h \\ i & j \\ k & l \end{bmatrix}$$

$$AB = \begin{bmatrix} ag + bi + ck & ah + bj + cl \\ dg + ei + fk & dh + ej + fl \end{bmatrix}$$

Matrices must have compatible dimensions.

## Properties of Matrix Multiplication

- Distributive property: (A + B)C = AC + BC
- Non-commutative:  $AB \neq BA$

• Identity matrix: 
$$I=\begin{bmatrix}1&0&0\\0&1&0\\0&0&1\end{bmatrix}$$
 satisfies  $AI=IA=A$ .

## Transpose and Symmetric Matrices

Transpose: Swap rows and columns of a matrix.

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad A' = \begin{bmatrix} a & c \\ b & d \end{bmatrix}$$

• Symmetric matrix: A = A'.

$$A = \begin{bmatrix} a & d & e \\ d & b & f \\ e & f & c \end{bmatrix}$$

## Matrix Operations

Element-wise multiplication and division:

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad A = \begin{bmatrix} e & f \\ g & h \end{bmatrix}$$
$$A \cdot *B = \begin{bmatrix} ae & bf \\ cg & dh \end{bmatrix}, \quad A \cdot /B = \begin{bmatrix} \frac{a}{e} & \frac{b}{f} \\ \frac{c}{a} & \frac{d}{h} \end{bmatrix}$$

## Inner, Outer, and Quadratic Forms

Inner product: A row vector times a column vector gives a scalar.

$$x'y = \begin{bmatrix} a & b & c \end{bmatrix} \begin{bmatrix} d \\ e \\ f \end{bmatrix} = ad + cf + be$$

Outer product: A column vector times a row vector gives a matrix.

$$xy' = \begin{bmatrix} a \\ b \\ c \end{bmatrix} \begin{bmatrix} d & e & f \end{bmatrix} = \begin{bmatrix} ad & ae & af \\ bd & be & bf \\ cd & ce & cf \end{bmatrix}$$

### Inner, Outer, and Quadratic Forms

#### Cont'd

• Quadratic form: Combines a vector, a symmetric matrix, and another vector.

$$x'Ax = \begin{bmatrix} e & f \end{bmatrix} \begin{vmatrix} a & b \\ b & d \end{vmatrix} \begin{vmatrix} e \\ f \end{vmatrix} = ae^2 + df^2 + 2bef$$

### Matrix Inversion

- Inverse of A:  $A^{-1}$  satisfies  $AA^{-1} = A^{-1}A = I$ .
- · Conditions for inversion:
  - A must be square.
  - A must have full rank
- Example:

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix}^{-1} = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

# Applications of Matrices

### Linear Regression

### Roadmap:

- Linear regression model in matrix form
- Minimization problem
- Derivation of OLS estimate

• The linear regression model is:

$$Y = X\beta + \epsilon$$

Expanded notation:

$$\begin{bmatrix} y_1 \\ y_2 \\ \vdots \\ y_N \end{bmatrix} = \begin{bmatrix} x_{11} & x_{12} \\ x_{21} & x_{22} \\ \vdots & \vdots \\ x_{N1} & x_{N2} \end{bmatrix} \begin{bmatrix} \beta_1 \\ \beta_2 \end{bmatrix} + \begin{bmatrix} \epsilon_1 \\ \epsilon_2 \\ \vdots \\ \epsilon_N \end{bmatrix}$$

- If there is a constant in the regression, the first column of X is all 1s.
- OLS estimate:

$$\hat{\beta} = (X'X)^{-1}X'Y$$

- Where does  $\hat{\beta} = (X'X)^{-1}X'Y$  come from?
- Sum of squared residuals:

$$RSS = \sum_{i}^{N} \epsilon_{i}^{2} = \epsilon' \epsilon = (Y - X\beta)'(Y - X\beta)$$

• Minimize RSS with respect to  $\beta$ :

$$\hat{\beta} = \arg\min_{\beta} \epsilon' \epsilon$$

$$= \arg\min_{\beta} (Y - X\beta)' (Y - X\beta)$$

$$= \arg\min_{\beta} Q(\beta)$$

• rewrite  $Q(\beta)$ :

$$Q(\beta) = (y - X\beta)'(y - X\beta),$$

$$= (y' - \beta'X')(y - X\beta), \text{ since } (X\beta)' = \beta'X',$$

$$= y'y - \beta'X'y - y'X\beta + \beta'X'X\beta,$$

 $= y'y - 2y'X\beta + \beta'X'X\beta$ , since  $\beta'X'y = y'X\beta$ .

• differentiate  $Q(\beta)$  with respect to  $\beta$ 

$$\left. \frac{\partial Q(\beta)}{\partial \beta'} \right|_{\beta = \hat{\beta}} = -2(X'y)' + 2\hat{\beta}'X'X.$$

• FOC: set the k vector of partial derivatives to zero:

$$-2(X'y)' + 2\hat{\beta}'X'X = 0'_{K+1}$$

• rewrite the FOC:

$$X'X\hat{\beta}=X'y$$
 
$$\hat{\beta}=(X'X)^{-1}X'y$$
 
$$\hat{\beta}=(X'X)^{-1}X'y$$