

Seminar 5 Solutions

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Disclaimer

Full solutions are available on my.wbs. All exercises are examinable material, not just the ones we covered in the seminars.

Roadmap

Exercise 1

Exercise 3

Exercise 4

Exercise 6

Exercise 1

Q: The OLS estimator in a time-series setting is **unbiased** under the first three Gauss-Markov assumptions. *true*

1. *linearity in params*

2. *no multicollinearity*

3. $E[u_c | X] = 0$ *strict exogeneity*

$$E[\hat{\beta}] = \beta$$

Exercise 1

Q: The OLS estimator in a time-series setting is **unbiased** under the first three Gauss-Markov assumptions.

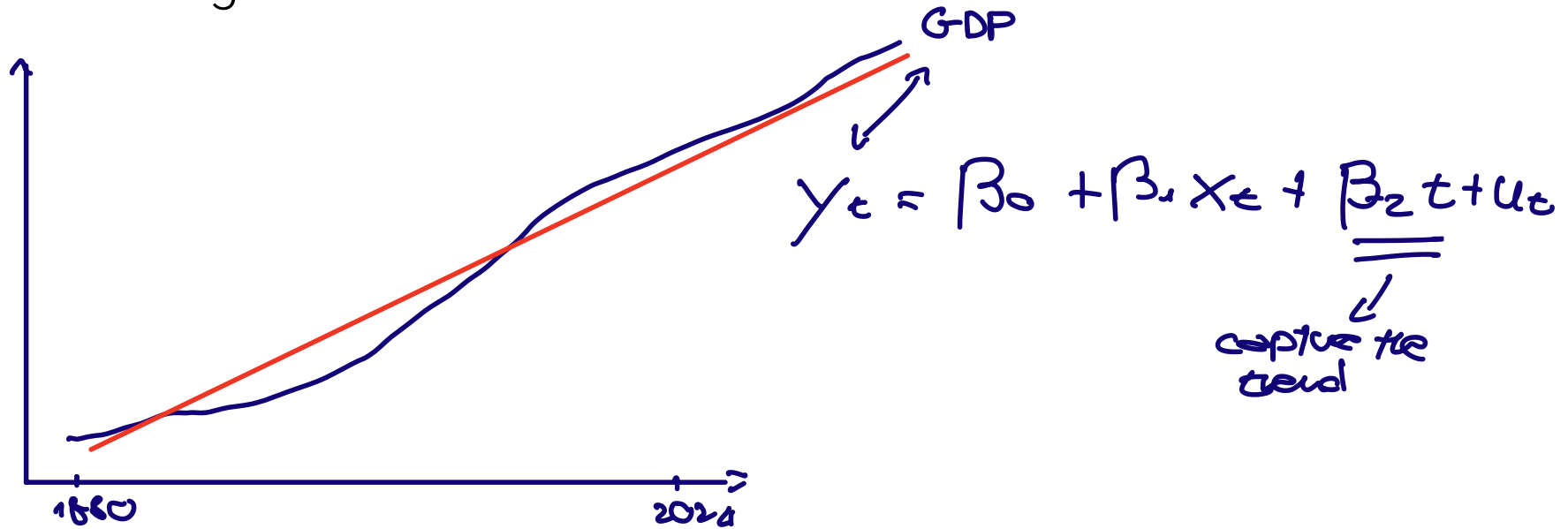
1. TS.1: Linearity in parameters
2. TS.2: No perfect collinearity
3. TS.3: **Strict** exogeneity/ Zero conditional mean

When we add the following two assumptions, the OLS estimator is also **BLUE**.

4. TS.4: Homoskedasticity $\text{var}(u_t | x) = \sigma^2$
5. TS.5: No serial correlation $\text{cov}(u_t, u_s) = 0 \quad t \neq s$

Exercise 1

Q: A trending variable cannot be used as a dependent variable in the multiple linear regression model. ~~false~~



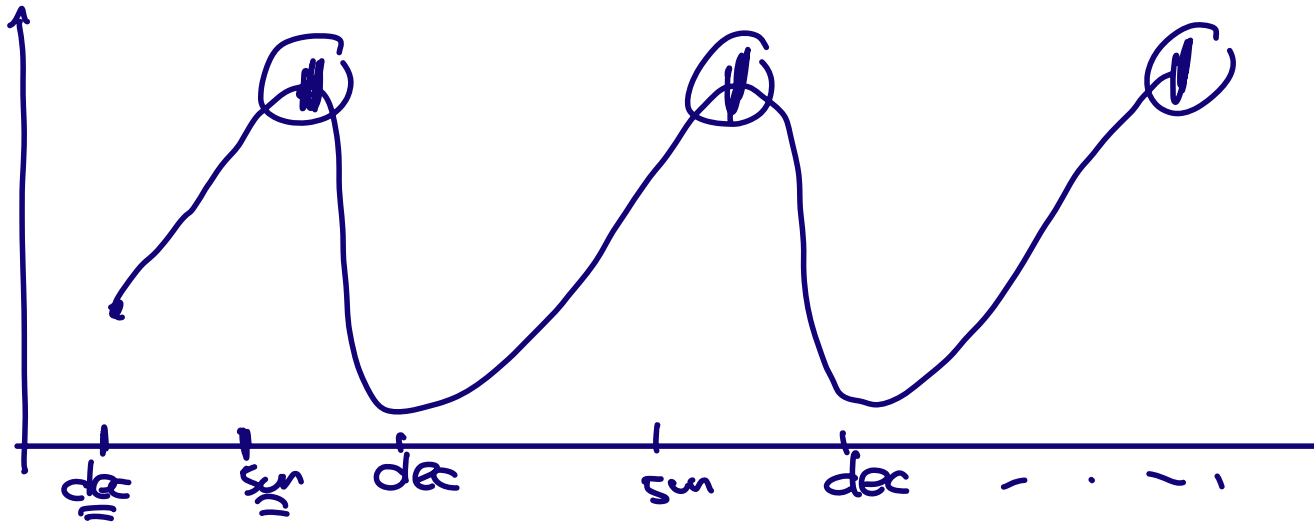
Exercise 1

Q: A trending variable cannot be used as a dependent variable in the multiple linear regression model.

- Trending variables *can* be used as dependent variables in a linear regression model.
- However, be cautious when interpreting the results:
 - **spurious relationship** between y_t and trending explanatory variables.
- Including a **time trend** in the regression is advisable when dependent and/or independent variables are trending.
- The usual R^2 measure can be **misleading** when the dependent variable is trending.

Exercise 1

Q: Seasonality is not an issue when using annual time-series observations. *true*



Exercise 1

Q: Seasonality is not an issue when using annual time-series observations.

- Each period represents a year and this is not associated with any season.

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Exercise 3

Weakly Stationary Process: Correlation

Let $\{x_t : t = 1, 2, \dots, T\}$ be a weakly stationary process.

Define $\gamma_h = \text{Cov}(\underline{x_t}, \underline{x_{t+h}})$ for $h \geq 0$. Then $\gamma_0 = \text{Var}(x_t)$. Show that

$$\underline{\text{Corr}(x_t, x_{t+h})} = \frac{\gamma_h}{\gamma_0}.$$

Weak (or covariance) Stationarity

A stochastic process $\{x_t : t = 1, 2, \dots\}$ is said to be **weakly stationary** if:

— $\mathbb{E}(x_t) = \mu, \quad \text{Var}(x_t) = \sigma^2, \quad \text{Cov}(x_t, x_{t+h}) = f(h).$

$E[x_t] = E[x_{t+h}] = \mu$

A weakly stationary process is uniquely determined by its mean, variance, and autocovariance function.

Derivation: $\rho(x, y) = \frac{\text{cov}(x, y)}{\text{std}(x) \text{std}(y)}$

$$\text{corr}(x_t, x_{t+h}) = \frac{\text{cov}(x_t, x_{t+h})}{\sqrt{\text{var}(x_t)} \sqrt{\text{var}(x_{t+h})}} = \frac{\gamma_h}{\sqrt{\gamma_0} \sqrt{\gamma_0}} = \frac{\gamma_h}{\gamma_0}$$

$$\gamma_h = \text{cov}(x_t, x_{t+h})$$

$$h=0$$

$$\gamma_0 = \text{cov}(x_t, x_{t+0}) = \text{cov}(x_t, x_t) = \text{var}(x_t)$$

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Exercise 4

Suppose that a time-series process $\{x_t : t = 1, 2, \dots, T\}$ is given by

$$x_t = z + \epsilon_t,$$

for all $t = 1, 2, \dots, T$, where ϵ_t is an i.i.d. sequence with mean zero and variance σ_ϵ^2 . The random variable z is constant over time, and it has mean zero and variance σ_z^2 . Furthermore, assume that ϵ_t is uncorrelated with z .

Exercise 4

$$E[X+Y] = E[X] + E[Y]$$

$$\text{Var}(X+Y) = \text{Var}(X) + \text{Var}(Y) + 2\text{Cov}(X, Y)$$

Q: Find the expected value and variance of x_t . Do your answers depend on t ? $E[x_t]$, $\text{Var}(x_t)$

$$x_t = z + \varepsilon_t$$

$$\varepsilon_t \stackrel{\text{iid}}{\sim} (\underline{0}, \underline{\sigma_\varepsilon^2}) \quad z \sim (\underline{0}, \underline{\sigma_z^2})$$

$$\text{Cov}(z, \varepsilon_t) = 0$$

$$\begin{aligned} \circ E[x_t] &= E[z + \varepsilon_t] \\ &= E[z] + E[\varepsilon_t] \\ &= 0 \end{aligned}$$

constant

$$\begin{aligned} \circ \text{Var}(x_t) &= \text{Var}(z + \varepsilon_t) \\ &= \text{Var}(z) + \text{Var}(\varepsilon_t) + 2\text{Cov}(z, \varepsilon_t) \\ &= \sigma_z^2 + \sigma_\varepsilon^2 \end{aligned}$$

constant

$$\text{COV}(X, Y) = E[XY] - E[X]E[Y] \quad \leftarrow$$

Exercise 4

$$\begin{aligned} \rightarrow X_t &= Z + \varepsilon_t \quad \dots \quad X_{t+h} = Z + \varepsilon_{t+h} \\ X_{t+1} &= Z + \varepsilon_{t+1} \end{aligned}$$

Q: Find $\text{Cov}(x_t, x_{t+h})$ for any t and h . Is x_t a weakly stationary process?

$$\begin{aligned} \text{COV}(x_t, x_{t+h}) &= E[x_t x_{t+h}] - E[x_t]E[x_{t+h}] \\ &= E[\underline{x_t} \underline{x_{t+h}}] \\ &= E[(Z + \varepsilon_t)(Z + \varepsilon_{t+h})] \\ &= E[Z^2 + Z\varepsilon_{t+h} + \varepsilon_t Z + \varepsilon_t \varepsilon_{t+h}] \\ &= E[Z^2] + E[Z\varepsilon_{t+h}] + E[\varepsilon_t Z] + E[\varepsilon_t \varepsilon_{t+h}] \\ &= E[Z^2] + \underbrace{E[Z\varepsilon_{t+h}]}_{\text{COV}(Z, \varepsilon_{t+h})} + \underbrace{E[\varepsilon_t Z]}_{\text{COV}(\varepsilon_t, Z)} + \underbrace{E[\varepsilon_t \varepsilon_{t+h}]}_{0} \\ \text{COV}(\varepsilon_t, Z) &= E[\varepsilon_t Z] - E[\varepsilon_t]E[Z] \\ &= E[\varepsilon_t Z] \\ &= E[Z^2] = \sigma_z^2 \\ \text{var}(Z) &= E[(Z - \bar{Z})^2] = E[Z^2] \end{aligned}$$

X_t is a weakly stationary process

Exercise 4

$$\begin{aligned} \text{COV}(X, Y) &= E[XY] - E[X]E[Y] \\ \text{COV}(Z, \varepsilon_{t+h}) &= E[Z\varepsilon_{t+h}] - E[Z]E[\varepsilon_{t+h}] \\ \text{COV}(Z, \varepsilon_{t+h}) &= E[Z\varepsilon_{t+h}] \end{aligned}$$

Q: Show that $\text{Corr}(x_t, x_{t+h}) = \frac{\sigma_z^2}{\sigma_z^2 + \sigma_\varepsilon^2}$ for any t and h .

$$\begin{aligned} \text{Corr}(x_t, x_{t+h}) &= \frac{\text{COV}(x_t, x_{t+h})}{\text{std}(x_t) \text{std}(x_{t+h})} = \frac{\text{COV}(x_t, x_{t+h})}{\text{var}(x_t)} \\ &= \frac{\sigma_z^2}{\sigma_z^2 + \sigma_\varepsilon^2} \end{aligned}$$

not correlated asymptotically

$$\lim_{h \rightarrow \infty} \frac{\sigma_z^2}{\sigma_z^2 + \sigma_\varepsilon^2} = \frac{\sigma_z^2}{\sigma_z^2 + \sigma_\varepsilon^2} \neq 0$$

$$\lim_{h \rightarrow \infty} \text{Corr}(x_t, x_{t+h}) = 0$$

$$\text{Corr}(x_t, x_{t+h}) = \frac{\sigma_z^2}{\sigma_z^2 + \sigma_\varepsilon^2} \times \frac{1}{h}$$

asymptotically uncorrelated process

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model $X_t = \beta_0 + \beta_1 X_{t-1} + u_t$ $|\beta_1| < 1 \Rightarrow$ stationary
 AR(1)

Return_t = $\beta_0 + \beta_1$ Return_{t-1} + u_t , $u_t \sim N(0, \sigma^2)$.

Source	SS	df	MS	Number of obs =	689
Model	10.6866231	1	10.6866231	F(1, 687) =	2.40
Residual	3059.73817	687	4.45376735	Prob > F	= 0.1218
Total	3070.42479	688	4.46282673	R-squared	= 0.0035
				Adj R-squared	= 0.0020
				Root MSE	= 2.1104

return	Coef.	Std. Err.	t	P> t	[95% Conf. Interval]
return_1	.0588984	.0380231	1.55	0.122	-.0157569 .1335538
_cons	.179634	.0807419	2.22	0.026	.0211034 .3381646

Figure: Predictive Model for Stock Returns

Q: Compute the unconditional mean and variance of the returns.

Exercise 6

- AR(1) model: $\text{Return}_t = \beta_0 + \beta_1 \text{Return}_{t-1} + u_t$.
- unconditional mean: $\mathbb{E}(\text{Return}_t) = \frac{\beta_0}{1-\beta_1}$.
- unconditional variance: $\text{Var}(\text{Return}_t) = \frac{\sigma^2}{1-\beta_1^2}$.
- use $\hat{\sigma}^2$ as an estimator of σ^2

$$\hat{\sigma}^2 = \frac{\hat{u}'\hat{u}}{T - k - 1}$$

$$x_t = \beta_0 + \beta_1 x_{t-1} + u_t \quad u_t \sim (0, \sigma^2)$$

$$\begin{aligned} \mathbb{E}[x_t] &= \mathbb{E}[\beta_0 + \beta_1 x_{t-1} + u_t] \\ &= \mathbb{E}[\beta_0] + \beta_1 \mathbb{E}[x_{t-1}] + \mathbb{E}[u_t] \end{aligned} \quad \parallel 0$$

$$\text{ws } \mathbb{E}[x_t] = \mathbb{E}[x_{t-1}]$$

$$\mathbb{E}[x_t] = \beta_0 + \beta_1 \mathbb{E}[x_t]$$

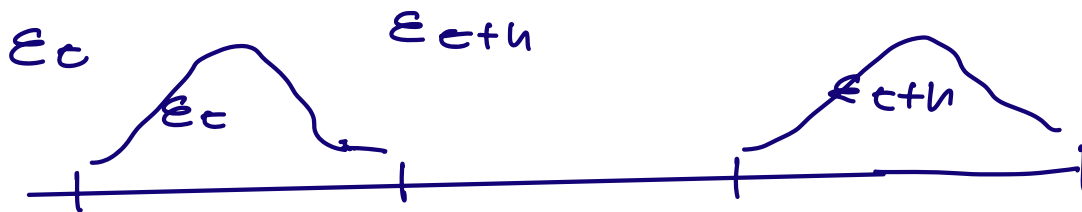
$$E[X_t] = \frac{\beta_0}{1 - \beta_1} = \frac{0.17}{1 - 0.058} = 0.19 = E[\text{return}]$$

$$\begin{aligned} \text{var}(x_t) &= \text{var}(\beta_0 + \beta_1 x_{t-1} + u_t) \\ &= \beta_1^2 \text{var}(x_{t-1}) + \sigma^2 \end{aligned}$$

$$\text{var}(x_t) = \text{var}(x_{t-1})$$

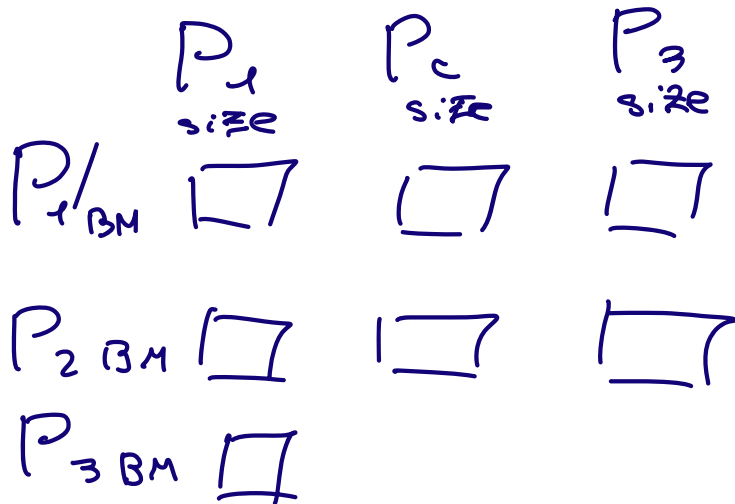
$$\begin{aligned} \text{var}(x_t) &= \frac{\sigma^2 \leftarrow}{1 - \beta_1^2} \\ &= \frac{4.45}{1 - 0.058^2} \\ &= 4.465 \end{aligned}$$

$$\begin{aligned} \sigma^2 &= \frac{\hat{u}'\hat{u}}{T - k - 1} \\ &= \frac{3059}{689 - 1 - 1} = 4.45 \end{aligned}$$



3x3

indep



conditional sorts

