

start $t=0$ $x_0 = 0$

\downarrow

$t=1$ $x_1 = x_0 + a_1$ generate $a_1 \sim (0, 1)$

0.045

$x_0 = 0$ $x_1 = 0 + 0.045 = 0.045$

$t=2$ $x_2 = x_1 + a_2$ generate $a_2 \sim (0, 1)$

0.045 -0.20

$= 0.045 - 0.2$

AR(1)

$\hat{\rho} \rightarrow t$ test

$\varepsilon_t \sim N(0, \sigma_\varepsilon^2)$

$$x_t = \alpha + \underbrace{\rho}_{\text{test}} x_{t-1} + \varepsilon_t$$

$$|\rho| = 1 \rightarrow x_t = \alpha + x_{t-1} + \varepsilon_t \quad \text{RW}$$

$\alpha \neq 0 \Rightarrow \text{RW w/drift}$

$H_0: |\rho| = 1 \Rightarrow \text{non stationary}$

$H_1: |\rho| < 1 \Rightarrow \text{stationarity}$

Under H_0 $x_t, x_{t-1} \rightarrow \text{RW}$

$$\downarrow$$
$$* \quad x_t - \underline{x_{t-1}} = \alpha + (\rho - 1)x_{t-1} + \varepsilon_t$$

$$\underbrace{x_t - \underline{x_{t-1}}}_{\Delta x_t} = \alpha + \underbrace{(\rho - 1)}_{\theta} x_{t-1} + \varepsilon_t$$

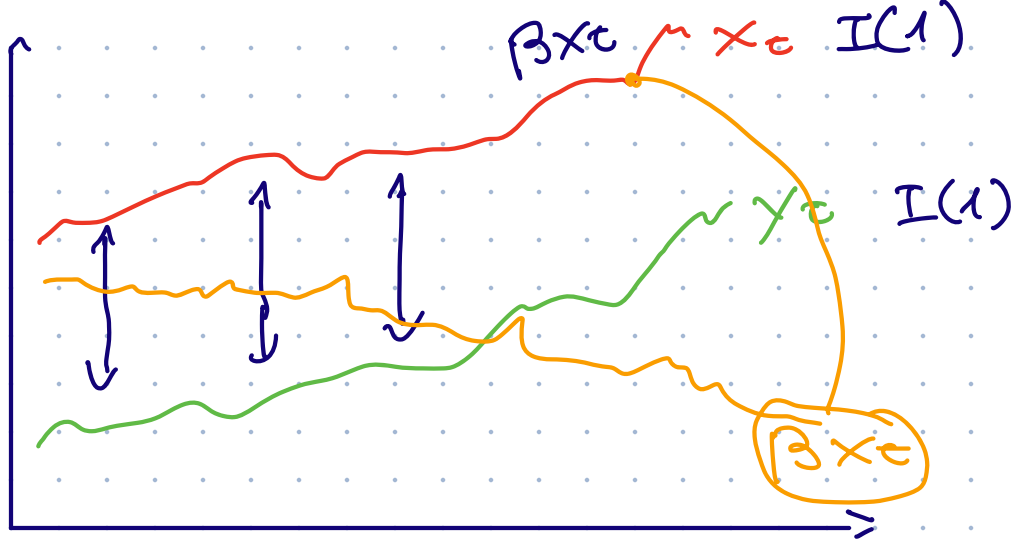
$$\Delta x_t = \alpha + \theta x_{t-1} + \varepsilon_t$$

$H_0: \rho = 1 \Rightarrow \theta = 0 \quad \underline{\Delta x_t} = \alpha + \varepsilon_t$

$H_1: \rho < 1 \Rightarrow \underline{\Delta x_t} = \alpha + \underbrace{\theta}_{< 0} x_{t-1} + \varepsilon_t$

$\hat{\theta} \rightarrow \text{compute } t\text{-stat}$

$t_{\text{stat}} < t_{\text{crit.}}$ DF distribution



$$y_t - \beta x_t \Rightarrow I(0)$$

* \hookrightarrow stationary $\rightarrow \beta$ scaling factor such that distance b/w y_t βx_t is constant = stationary

β exists $\rightarrow y_t$ x_t cointegrated

need estimate of β

$$LS \rightarrow y_t = \hat{\alpha} + \hat{\beta} x_t + \hat{u}_t$$

$$\hat{u}_t = y_t - \hat{\alpha} - \hat{\beta} x_t$$

$\hat{u}_t \rightarrow I(0)$ DF test \hat{u}_t

$$\rightarrow \Delta \hat{u}_t = \delta_0 + \delta_1 \hat{u}_{t-1} + \dots + \delta_p$$