



# ANALYSIS OF QUANTIZED MODELS

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## BACKGROUD AND MOTIVATION

#### **Quantized LSTM**

- BinaryConnect fails (Hou et al., 2017) on LSTM
- BWN, TWN, LAB, LAT perform much better, but sometimes inferior to the Spectral norm of quantized matrix full-precision network on some tasks (Ardakani et al. 2019)
- SOTA performance when training binarized/ternarized LSTMs with batch normalization (Ardakani et al. 2019)
- Why does batch normalization work for quantized LSTM?
- Does weight/layer normalization also help?

#### Recurrence of a LSTM

$$\begin{bmatrix} \mathbf{i}_t \\ \mathbf{f}_t \\ \mathbf{a}_t \\ \mathbf{o}_t \end{bmatrix} = \begin{bmatrix} \mathbf{W}_{xi} \mathbf{x}_t + \mathbf{W}_{hi} \mathbf{h}_{t-1} \\ \mathbf{W}_{xf} \mathbf{x}_t + \mathbf{W}_{hf} \mathbf{h}_{t-1} \\ \mathbf{W}_{xa} \mathbf{x}_t + \mathbf{W}_{ha} \mathbf{h}_{t-1} \\ \mathbf{W}_{xo} \mathbf{x}_t + \mathbf{W}_{ho} \mathbf{h}_{t-1} \end{bmatrix} + \begin{bmatrix} \mathbf{b}_i \\ \mathbf{b}_f \\ \mathbf{b}_a \\ \mathbf{b}_o \end{bmatrix},$$

$$\mathbf{c}_t = \sigma(\mathbf{i}_t) \odot \tanh(\mathbf{a}_t) + \sigma(\mathbf{f}_t) \odot \mathbf{c}_{t-1},$$

$$\mathbf{h}_t = \sigma(\mathbf{o}_t) \odot \tanh(\mathbf{c}_t).$$

- storage dominated by  $\mathbf{W}_{x*}, \mathbf{W}_{h*}$
- computation dominated by  $\mathbf{W}_{x*}\mathbf{x}_t + \mathbf{W}_{h*}\mathbf{h}_{t-1}$
- ullet ightarrow quantize  $\mathbf{W}_{x*}, \mathbf{W}_{h*}$

#### Our Findings

- Quantized LSTM is hard to train due to the exploding gradient problem
- popularly used weight/layer/batch normalization schemes can help stabilize the gradient magnitude in training quantized LSTMs

## EXPLODING GRADIENT IN LSTM

Proposition 1 
$$\left\| \frac{\partial \xi_m}{\partial \mathbf{h}_{t-1}} \right\| \leq \lambda_1 \left\| \frac{\partial \xi_m}{\partial \mathbf{h}_t} \right\| + \lambda_2 \left\| \frac{\partial \xi_m}{\partial \mathbf{c}_{t+1}} \right\|.$$

- $\lambda_1 = \frac{1}{4} \|\mathbf{W}_{hi}\|_2 + \frac{\gamma_1}{4} \|\mathbf{W}_{hf}\|_2 + \|\mathbf{W}_{ha}\|_2 + \frac{1}{4} \|\mathbf{W}_{ho}\|_2$   $\lambda_2 = \frac{1}{4} \|\mathbf{W}_{hi}\|_2 + \frac{\gamma_1}{4} \|\mathbf{W}_{hf}\|_2 + \|\mathbf{W}_{ha}\|_2$

**Corollary 1** When  $\lambda_2 = 0$ , a necessary condition for exploding gradients in the LSTM is

- empirically,  $\lambda_2$  is rarely zero
- upper bound of  $\|\frac{\partial \xi_m}{\partial \mathbf{h}_{\perp}}\|$  even larger, and gradient explode even more easily

## QUANTIZATION -> GRADIENT EASIER TO EXPLODE

 $\lambda_1, \lambda_2$  in the upper bound related to the spectral norm of weight matrix

• larger spectral norm  $\rightarrow$  more easily to explode

- For any  $\mathbf{W} \in \{-1, +1\}^{d \times d}$ ,  $\|\mathbf{W}\|_2 \ge \sqrt{d}$ .
- For any  $\mathbf{W} \in \{-B_k, \dots, -B_1, B_0, B_1, \dots, B_k\}^{d \times d}$  where  $0 = B_0 < B_1 < \dots < B_k$  $B_k$ ,  $\|\mathbf{W}\|_2 \ge (1-s)B_1\sqrt{d}$ , where s is the sparsity of W.

the gradient is more easily to explode when

- d is large
- number of bits is small

#### NORMALIZED LSTM

- Apply normalization as  $\mathcal{N}(\mathbf{W}_{x*}\mathbf{x}_t)$  and  $\mathcal{N}(\mathbf{W}_{h*}\mathbf{h}_{t-1})$
- $\bullet$   $\mathcal{N}$  can be weight, layer or batch normalization

$$\begin{bmatrix} \tilde{\mathbf{i}}_t \\ \tilde{\mathbf{f}}_t \\ \tilde{\mathbf{a}}_t \\ \tilde{\mathbf{o}}_t \end{bmatrix} = \begin{bmatrix} \mathcal{N}(\mathbf{W}_{xi}\mathbf{x}_t) + \mathcal{N}(\mathbf{W}_{hi}\mathbf{h}_{t-1}) \\ \mathcal{N}(\mathbf{W}_{xf}\mathbf{x}_t) + \mathcal{N}(\mathbf{W}_{hf}\mathbf{h}_{t-1}) \\ \mathcal{N}(\mathbf{W}_{xa}\mathbf{x}_t) + \mathcal{N}(\mathbf{W}_{ha}\mathbf{h}_{t-1}) \\ \mathcal{N}(\mathbf{W}_{xo}\mathbf{x}_t) + \mathcal{N}(\mathbf{W}_{ho}\mathbf{h}_{t-1}) \end{bmatrix} + \begin{bmatrix} \mathbf{b}_i \\ \mathbf{b}_f \\ \mathbf{b}_a \\ \mathbf{b}_o \end{bmatrix},$$

 $\mathbf{c}_t = \sigma(\tilde{\mathbf{i}}_t) \odot \tanh(\tilde{\mathbf{a}}_t) + \sigma(\tilde{\mathbf{f}}_t) \odot \mathbf{c}_{t-1},$ 

 $\mathbf{h}_t = \sigma(\tilde{\mathbf{o}}_t) \odot \tanh(\mathbf{c}_t).$ 

## WEIGHT NORMALIZATION:

decouples length and direction of the weight vector

• each row 
$$\mathbf{W}_{j,:}$$
 of  $\mathbf{W}$  ( $\mathbf{W}_{h*}$  or  $\mathbf{W}_{x*}$ ) is separately normalized as

$$\mathcal{WN}(\mathbf{W}_{j,:}\mathbf{x}) = g_j rac{\mathbf{W}_{j,:}}{\|\mathbf{W}_{j,:}\|}\mathbf{x}$$

•  $g_* = \max_{1 \le j \le d} g_j$ ;  $\mathbf{D}_* = \operatorname{diag}([\|(\mathbf{W}_{h*})_{1,:}\|, \|(\mathbf{W}_{h*})_{2,:}\|, \dots, \|(\mathbf{W}_{h*})_{d,:}\|]^\top)$ 

Proposition 2 With weight normalization,

$$\left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t-1}} \right\| \leq \left( \frac{g_{i}}{4} \left\| \mathbf{D}_{i}^{-1} \mathbf{W}_{hi} \right\|_{2} + \frac{\gamma_{1} g_{f}}{4} \left\| \mathbf{D}_{f}^{-1} \mathbf{W}_{hf} \right\|_{2} + g_{a} \left\| \mathbf{D}_{a}^{-1} \mathbf{W}_{ha} \right\|_{2} + \frac{g_{o}}{4} \left\| \mathbf{D}_{o}^{-1} \mathbf{W}_{ho} \right\|_{2} \right) \left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t}} \right\| + \left( \frac{g_{i}}{4} \left\| \mathbf{D}_{i}^{-1} \mathbf{W}_{hi} \right\|_{2} + \frac{\gamma_{1} g_{f}}{4} \left\| \mathbf{D}_{f}^{-1} \mathbf{W}_{hf} \right\|_{2} + g_{a} \left\| \mathbf{D}_{a}^{-1} \mathbf{W}_{ha} \right\|_{2} \right) \left\| \frac{\partial \xi_{m}}{\partial \mathbf{c}_{t+1}} \right\|.$$

• if  $\mathbf{W}_{h*}$  is scaled by a factor  $\alpha$ ,  $\mathbf{D}_{*}$  will also be scaled by  $\alpha \to \mathbf{D}_{*}^{-1}\mathbf{W}_{h*}$  not affected.

#### LAYER NORMALIZATION

normalizes activities in each layer

• input  $\mathbf{x} \in \mathbb{R}^d$  ( $\mathbf{W}_{x*}\mathbf{x}_t$  or  $\mathbf{W}_{h*}\mathbf{h}_{t-1}$ ) with mean  $\mu$  and standard deviation

$$\mathbf{y} = \mathcal{L}\mathcal{N}(\mathbf{x}) = \mathbf{g} \odot \mathbf{z} + \mathbf{b}, \text{where } \mathbf{z} = (\mathbf{x} - \mu \mathbf{1})/\sigma$$

• for  $\mathcal{LN}(\mathbf{W}_{h*}\mathbf{h}_{t-1})$ :  $g_* = g_k, \sigma_* = \sigma_k$ , where  $k = \arg\max_{1 \leq j \leq d} g_j$ 

Proposition 3 With layer normalization,

$$\left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t-1}} \right\| \leq \left( \frac{1}{4} \frac{g_{i}}{\sigma_{i}} \|\mathbf{W}_{hi}\|_{2} + \frac{\gamma_{1}}{4} \frac{g_{f}}{\sigma_{f}} \|\mathbf{W}_{hf}\|_{2} + \frac{g_{a}}{\sigma_{a}} \|\mathbf{W}_{ha}\|_{2} + \frac{1}{4} \frac{g_{o}}{\sigma_{o}} \|\mathbf{W}_{ho}\|_{2} \right) \left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t}} \right\|$$

$$+ \left( \frac{1}{4} \frac{g_{i}}{\sigma_{i}} \|\mathbf{W}_{hi}\|_{2} + \frac{\gamma_{1}}{4} \frac{g_{f}}{\sigma_{f}} \|\mathbf{W}_{hf}\|_{2} + \frac{g_{a}}{\sigma_{a}} \|\mathbf{W}_{ha}\|_{2} \right) \left\| \frac{\partial \xi_{m}}{\partial \mathbf{c}_{t+1}} \right\|.$$

• if the elements of  $\mathbf{W}_{h*}$  grow twice as large, the corresponding  $\sigma_*$  will be twice as large

## BATCH NORMALIZATION

operates on a minibatch (N samples in a batch)

- ullet  $\mathbf{H}_t = [\mathbf{h}_t^1, \dots, \mathbf{h}_t^N]^ op \in \mathbb{R}^{N imes d}; \mathbf{X}_t = [\mathbf{x}_t^1, \dots, \mathbf{x}_t^N]^ op \in \mathbb{R}^{N imes r}$
- input  $\mathbf{X} \in \mathbb{R}^{N \times d}$  ( $\mathbf{X}_t \mathbf{W}_{x*}^{\top}$  or  $\mathbf{H}_{t-1} \mathbf{W}_{h*}^{\top}$ ), with mean  $\mu_j$  and std  $\sigma_j$  for the jth column

$$\mathbf{y}_{:,j} = \mathcal{BN}(\mathbf{X}_{:,j}) = g_j \frac{\mathbf{X}_{:,j} - \mu_j \mathbf{1}}{\sigma_j} + b_j \mathbf{1}$$

• for  $\mathcal{BN}(\mathbf{H}_{t-1}\mathbf{W}_{h*}^{\top})$ :  $(\sigma_*, g_*) = \arg\max_{1 \leq j \leq d} \frac{g_j}{\sigma_j}$ 

Proposition 4 With batch normalization,

$$\sum_{k=1}^{N} \left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t-1}^{k}} \right\|^{2} \leq \left( \frac{1}{2} \frac{g_{i}^{2}}{\sigma_{i}^{2}} \|\mathbf{W}_{hi}\|_{2}^{2} + \frac{\gamma_{2}^{2}}{2} \frac{g_{f}^{2}}{\sigma_{f}^{2}} \|\mathbf{W}_{hf}\|_{2}^{2} + 8 \frac{g_{a}^{2}}{\sigma_{a}^{2}} \|\mathbf{W}_{ha}\|_{2}^{2} + \frac{1}{4} \frac{g_{o}^{2}}{\sigma_{o}^{2}} \|\mathbf{W}_{ho}\|_{2}^{2} \right) \sum_{k=1}^{N} \left\| \frac{\partial \xi_{m}}{\partial \mathbf{h}_{t}^{k}} \right\|^{2} + \left( \frac{1}{2} \frac{g_{i}^{2}}{\sigma_{i}^{2}} \|\mathbf{W}_{hi}\|_{2}^{2} + \frac{\gamma_{2}^{2}}{2} \frac{g_{f}^{2}}{\sigma_{f}^{2}} \|\mathbf{W}_{hf}\|_{2}^{2} + 8 \frac{g_{a}^{2}}{\sigma_{a}^{2}} \|\mathbf{W}_{ha}\|_{2}^{2} \right) \sum_{k=1}^{N} \left\| \frac{\partial \xi_{m}}{\partial \mathbf{c}_{t+1}^{k}} \right\|^{2}.$$

• if the elements of  $\mathbf{W}_{h*}$  grow twice as large, the corresponding  $\sigma_*$  will be twice as large

## EXPERIMENTS

#### Character-level Language Modeling

Rite Por Character (RPC) and ciza (in KR) of 1 lawer I CTM

<ul> <li>Bits Per Character (BPC) and size (in KB) of 1-layer LSTM.</li> </ul>										
preci-	quanti-	normali-	War and Peace		Penn Treebank		Text8			
sion	zation	zation	BPC	size	BPC	size	BPC	size		
full		_	1.72	4800	1.45	4504	1.46	63375		
		weight	1.73	4816	1.45	4520	1.48	63438		
	_	layer	1.69	4832	1.43	4536	1.45	63500		
		batch (shared)	1.72	4864	1.45	4568	1.46	63625		
		batch (separate)	1.72	8032	1.45	7736	1.46	86000		
1-bit	SBN	batch (separate)	1.78	3794	1.60	3785	1.54	27464		
		_	4.24	158	2.51	149	N/A	2011		
	Binary-	weight	1.74	174	1.50	165	1.50	2073		
	Connect	layer	1.69	<b>190</b>	1.49	181	1.47	2136		
		batch (shared)	1.72	222	1.51	213	1.47	2261		
		batch (separate)	1.72	3390	1.50	3381	1.48	24636		
2-bit	STN	batch (separate)	1.72	3944	1.60	3521	1.51	15303		
		-	6.35	308	5.84	289	N/A	3990		
	Ter-	weight	1.72	324	1.42	305	1.42	4053		
	Connect	layer	1.67	340	1.43	321	1.44	4115		
		batch (shared)	1.70	372	1.44	353	1.44	4240		
		batch (separate)	1.71	3540	1.45	3521	1.44	26615		

#### Word-level Language Modeling

• Test Perplexity and size (in KB) of 1-layer LSTM with d hidden units

			a = 500		a = 000	
precision	quantlization	normalization	PPL	size	PPL	size
full		_	91.5	2817	87.6	13213
	SBN	batch (separate)	92.2	852	87.2	2068
	_	-	8247.4	93	1244.2	423
		weight	87.6	102	84.8	443
	BinaryConnect	layer	89.4	111	82.3	463
		batch (shared)	92.4	130	84.8	504
1-bit		batch(separate)	91.9	767	85.6	1885
	alternating LSTM	_	103.1	180	_	_
	STN	batch (separate)	90.7	940	86.1	2481
		-	113.8	180	113.8	835
		weight	86.5	190	84.9	856
	TerConnect	layer	88.2	199	82.5	876
2-bit		batch (shared)	90.6	218	85.8	917
<b>4-DI</b>		batch (separate)	91.6	855	86.5	2298

#### **Observations**

- Vanilla BinaryConnect and TerConnect fail, but normalized versions work
- Normalized quantized LSTM is comparable to the full-precision baseline
- Applying weight/layer/batch (shared) normalization perform similarly or better than SBN and STN (Ardakani et al., 2019), while being much smaller

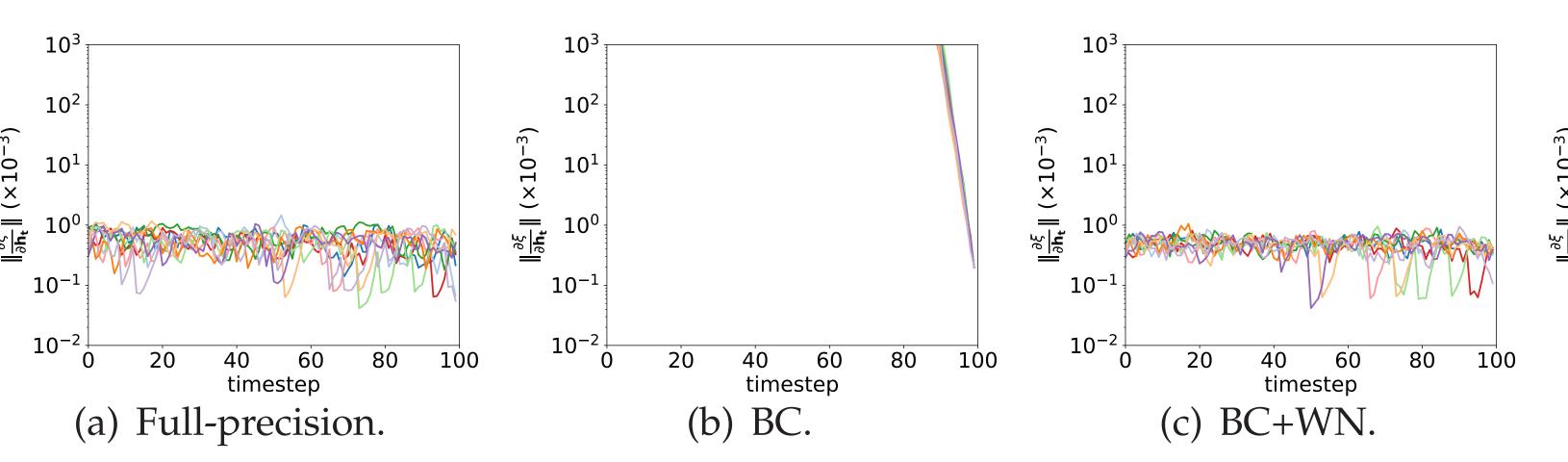
More experiments in the paper!

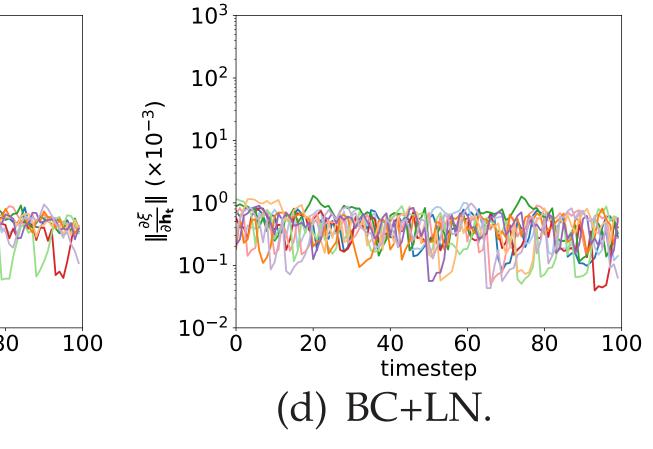
## CONCLUSION

- WHY: Quantization tends to increase spectral norm of weights in LSTM, making the exploding gradient problem much more severe than its full-precision counterpart.
- HOW: By using normalization, backpropagation of  $\left\| \frac{\partial \xi_m}{\partial \mathbf{h}_t} \right\|$  in the quantized LSTM is not affected by the possibly large scaling of the weight matrix caused by quantization, and the exploding gradient problem can be alleviated.
- CODE: https://github.com/houlu369/Normalized-Quantized-LSTN

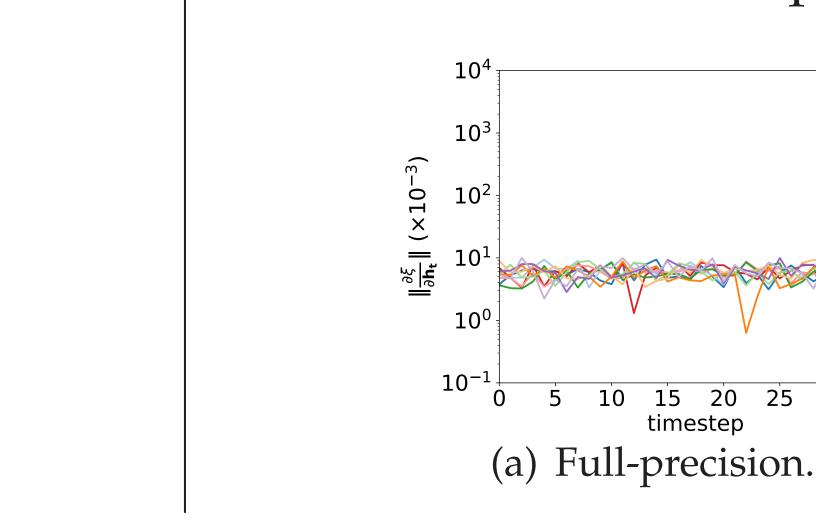
# OBSERVATIONS

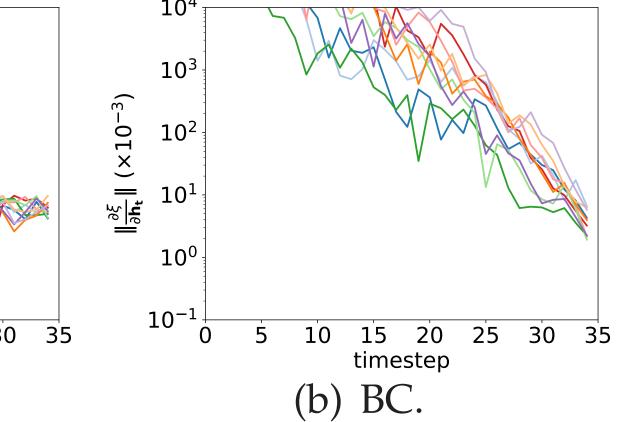
Figure 1: Gradient norms of character-level language modeling on Penn Treebank dataset.

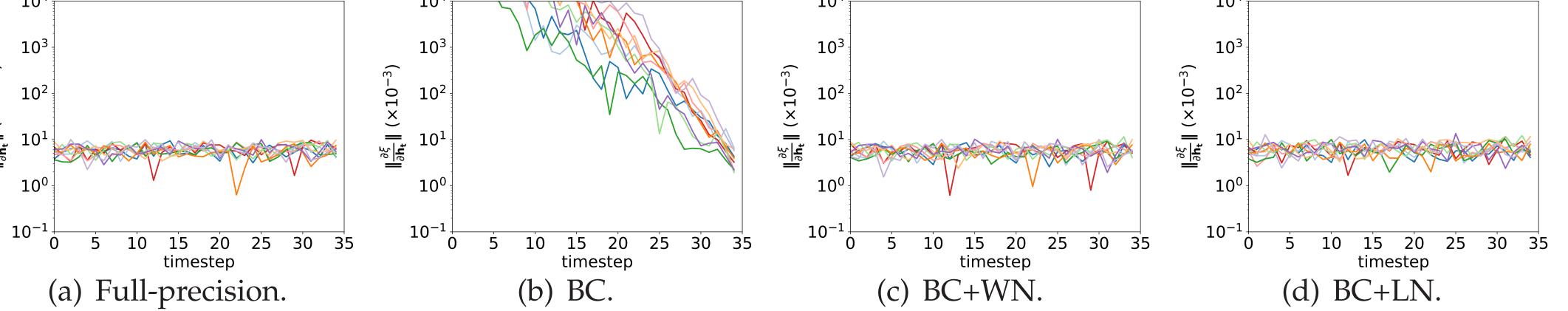




(e) BC+BN (shared).







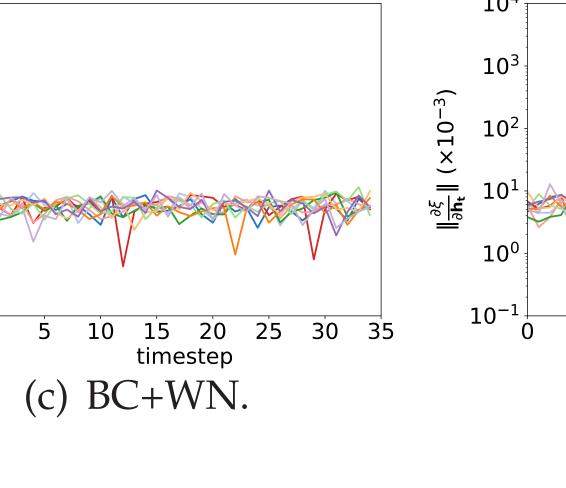


Figure 2: Gradient norms of word-level language modeling on Penn Treebank dataset.

