

Project 1

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Task 2.0:

The momentum equation is a parabolic equation since, if we compute the $\Delta = B^2 - 4AC$ from the general form of the partial differential equations:

$$A \frac{\partial^2 u}{\partial x^2} + B \frac{\partial^2 u}{\partial x \partial y} + C \frac{\partial^2 u}{\partial y^2} + D \frac{\partial u}{\partial x} + E \frac{\partial u}{\partial y} + Fu + G = 0 \quad (1)$$

we get $\Delta = 0$, which means that the equation is parabolic.

We now define the additional boundary conditions:

- $u(0, y) = 1$
- $u(1, y) = 1$
- $v(0, y) = 0$
- $v(1, y) = 0$
- $v(x, \infty) = 0$

Task 2.1:

The discretization applied to the x-momentum equation takes into account the parabolic nature of the equation. The discretization is performed using the central difference scheme for the y-direction and the backward difference scheme for the x-direction. The discretized equation is as follows:

$$u_{i,j} \frac{u_{i,j} - u_{i-1,j}}{\Delta x} + v_{i,j} \frac{u_{i,j+1} - u_{i,j-1}}{2\Delta y} = \frac{1}{Re} \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{\Delta y^2}$$

Such equation is a steady-state equation and thus it doesn't require any time-stepping algorithm. For this reason, the constraints for convergence are only applied on the spatial discretization.

Task 2.2:

This system is solved using a GMRES iterative solver, which allows us to solve the system for a non-symmetric \mathbf{A} and the non linearities of the x-momentum. The solver updates the values of u and v at each iteration, denoted as $u^{(k+1)}$ and $v^{(k+1)}$, by utilizing the values from the previous iteration, $u^{(k)}$ and $v^{(k)}$, to handle the non-linear terms effectively. The system of partial differential equations is: The continuity equation is discretized using the backward difference scheme (BDS) along the x-direction and the central difference scheme (CDS) along the y-direction. The discretized continuity equation is given by:

$$\begin{cases} \frac{u_{i,j} - u_{i-1,j}}{\Delta x} + \frac{v_{i,j+1} - v_{i,j-1}}{2\Delta y} = 0 \\ u_{i,j} \frac{u_{i,j} - u_{i-1,j}}{\Delta x} + v_{i,j} \frac{u_{i,j+1} - u_{i,j-1}}{2\Delta y} = \frac{1}{Re} \frac{u_{i,j+1} - 2u_{i,j} + u_{i,j-1}}{\Delta y^2} \end{cases}$$

To solve this, we construct a linear system of equations in the form $\mathbf{Ax} = \mathbf{b}$, where \mathbf{A} is a $2n^2 \times 2n^2$ matrix, \mathbf{b} is a $2n^2$ vector, and \mathbf{x} is also a $2n^2$ vector. The structure of \mathbf{x} is as follows:

$$\mathbf{x} = \begin{bmatrix} u_{1,1} \\ u_{1,2} \\ \vdots \\ u_{n,n} \\ v_{1,1} \\ v_{1,2} \\ \vdots \\ v_{n,n} \end{bmatrix}$$

The structure of the matrix \mathbf{A} is as follows:

$$A = \begin{bmatrix} \frac{1}{\Delta x} & \cdots & -\frac{1}{\Delta x} & \cdots & 0 & \cdots & 0 & \cdots \\ \cdots & \frac{u_{i,j}}{\Delta x} - \frac{2}{Re} \left(\frac{1}{\Delta x^2} + \frac{1}{\Delta y^2} \right) & \cdots & \frac{1}{Re\Delta x^2} & \cdots & 0 & \cdots & 0 & \cdots \\ \cdots & \frac{u_{i,j}}{\Delta x} & \cdots & \frac{1}{Re\Delta x^2} & \cdots & 0 & \cdots & 0 & \cdots \\ 0 & \cdots & 0 & \cdots & \frac{1}{\Delta y} & \cdots & -\frac{1}{\Delta y} & \cdots \\ 0 & \cdots & 0 & \cdots & \frac{v_{i,j}}{2\Delta y} & \cdots & -\frac{Re\Delta y^2}{2} & \cdots \\ 0 & \cdots & 0 & \cdots & \frac{v_{i,j}}{2\Delta y} & \cdots & -\frac{Re\Delta y^2}{2} & \cdots \end{bmatrix}$$

In addition, the boundary conditions are applied to the matrix \mathbf{A} and the vector \mathbf{b} to solve the system of equations. The boundary conditions are applied to the cells of \mathbf{b} and \mathbf{A} as follows:

1. For $u(0, y) = 1$:
 - Set $b_{(j-1)n+1} = 1$
 - Set $A_{(j-1)n+1, (j-1)n+1} = 1$
2. For $u(1, y) = 1$:
 - Set $b_{(j-1)n+n} = 1$
 - Set $A_{(j-1)n+n, (j-1)n+n} = 1$
3. For $v(0, y) = 0$:
 - Set $b_{n^2+(j-1)n+1} = 0$
 - Set $A_{n^2+(j-1)n+1, n^2+(j-1)n+1} = 1$
4. For $v(1, y) = 0$:
 - Set $b_{n^2+(j-1)n+n} = 0$
 - Set $A_{n^2+(j-1)n+n, n^2+(j-1)n+n} = 1$
5. For $v(x, \infty) = 0$:
 - Set $b_{n^2+(n-1)n+i} = 0$
 - Set $A_{n^2+(n-1)n+i, n^2+(n-1)n+i} = 1$

Task 2.3:

```
import numpy as np
import scipy.sparse.linalg as spla
M2 = spla.spilu(A)
x = spla.gmres(A,b,M=M2)
```

References

- [1] *CFD Repository*,
Available at: <https://github.com/GiuseppePisante/CFD.git>
- [2] *GitHub Copilot*,
GitHub. Available at: <https://github.com/features/copilot>