

# Network Formation Games

# Network Formation Games

- NFGs model distinct ways in which *selfish* agents might create and evaluate networks
- We'll see two models:
  - Global Connection Game
  - Local Connection Game
- Both models aim to capture two competing issues: players want
  - to minimize the cost they incur in building the network
  - to ensure that the network provides them with a high quality of service

# Motivations

- NFGs can be used to model:
  - social network formation (edge represent social relations)
  - how subnetworks connect in computer networks
  - formation of networks connecting users to each other for downloading files (P2P networks)

# Setting

- What is a stable network?
  - we use a NE as the solution concept
  - we refer to networks corresponding to Nash Equilibria as being *stable*
- How to evaluate the overall quality of a network?
  - we consider the *social cost*: the sum of players' costs
- **Our goal**: to bound the efficiency loss resulting from stability

# Global Connection Game

E. Anshelevich, A. Dasgupta, J. Kleinberg, E. Tardos, T. Wexler, T. Roughgarden,  
The Price of Stability for Network Design with Fair Cost Allocation, FOCS'04

# The model

- $G=(V,E)$ : directed graph
- $c_e$ : non-negative cost of the edge  $e \in E$
- $k$  players
- player  $i$  has a source node  $s_i$  and a sink node  $t_i$
- player  $i$ 's goal: to build a network in which  $t_i$  is reachable from  $s_i$  while paying as little as possible
- Strategy for player  $i$ : a path  $P_i$  from  $s_i$  to  $t_i$

# The model

- Given a strategy vector  $S$ , the constructed network will be  $N(S) = \cup_i P_i$
- The cost of the constructed network will be shared among all players as follows:

$$\text{cost}_i(S) = \sum_{e \in P_i} c_e / k_e(S)$$

$k_e(S)$ : number of players whose path contains  $e$

sometimes we write  $k_e$  instead of  $k_e(S)$   
when  $S$  is clear from the context

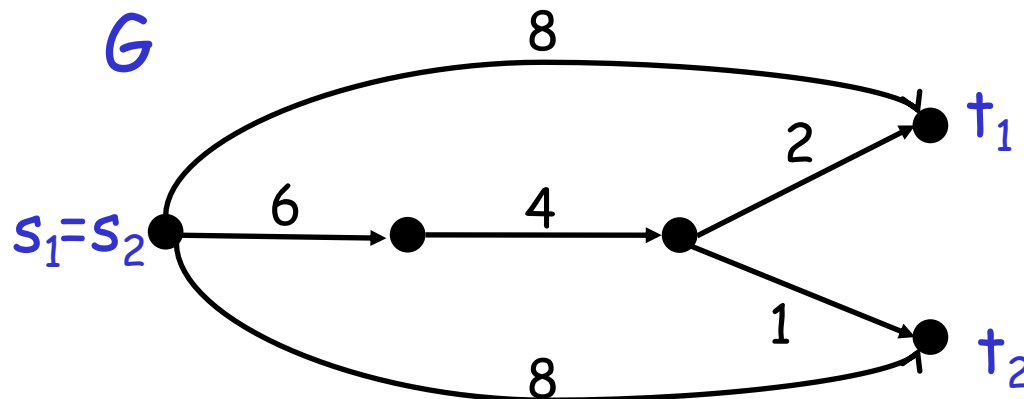
this cost-sharing scheme is called  
*fair* or *Shapley cost-sharing mechanism*

# Remind

- We use **Nash equilibrium** (NE) as the solution concept
- A strategy vector  $S$  is a NE if no player has convenience to change its strategy
- Given a strategy vector  $S$ ,  $N(S)$  is **stable** if  $S$  is a NE
- To evaluate the overall quality of a network, we consider the **social cost**, i.e. the sum of all players' costs

$$\text{cost}(S) = \sum_i \text{cost}_i(S)$$

- a network is **optimal** or **socially optimal** if it minimizes the social cost



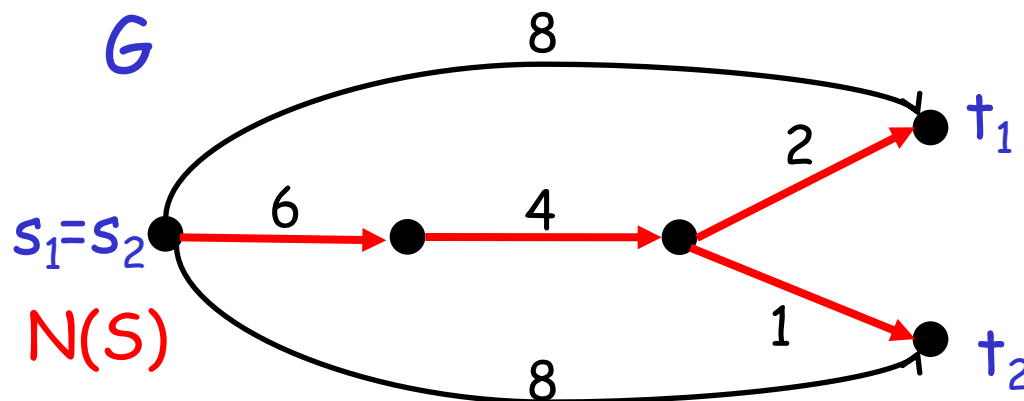
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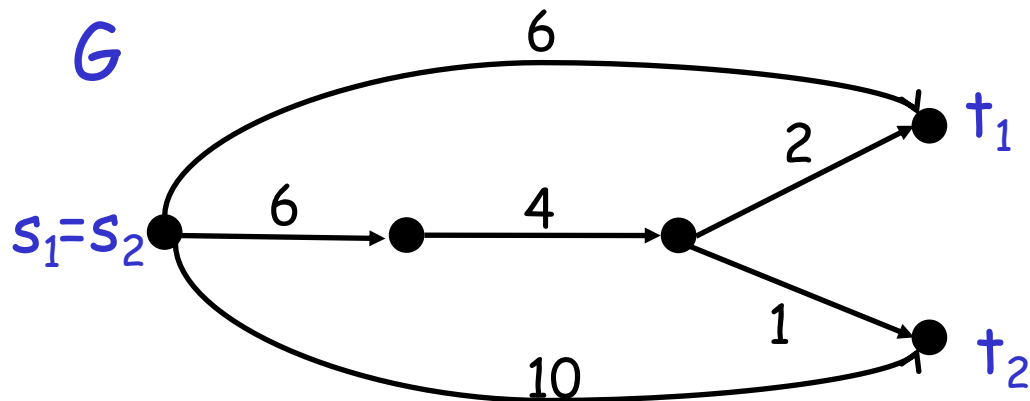
**Notice:**  $\text{cost}(S) = \sum_{e \in N(S)} c_e$



the **optimal network** is a **cheapest subgraph** of  $G$  containing a path from  $s_i$  to  $t_i$ , for each  $i$

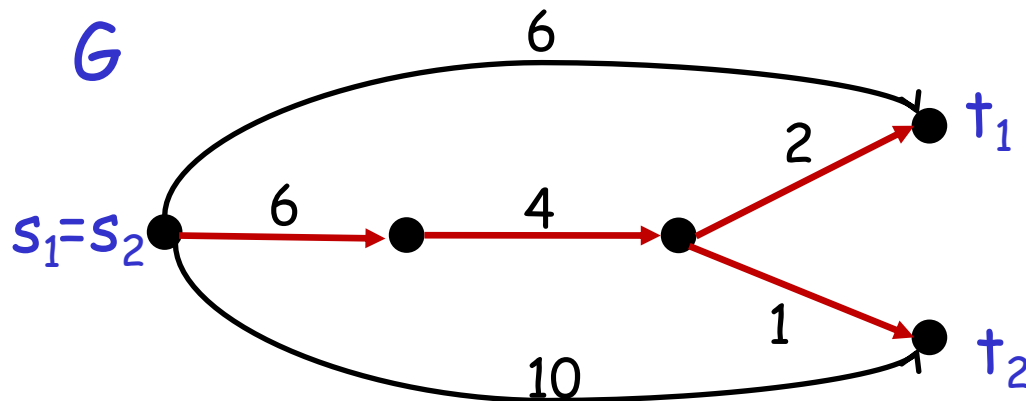
$$\begin{aligned} \text{cost}_1 &= 7 \\ \text{cost}_2 &= 6 \end{aligned}$$

# an example



what is the socially  
optimal network?

# an example



$\text{cost}_1=7$   
 $\text{cost}_2=6$

social cost  
of the network  
**13**

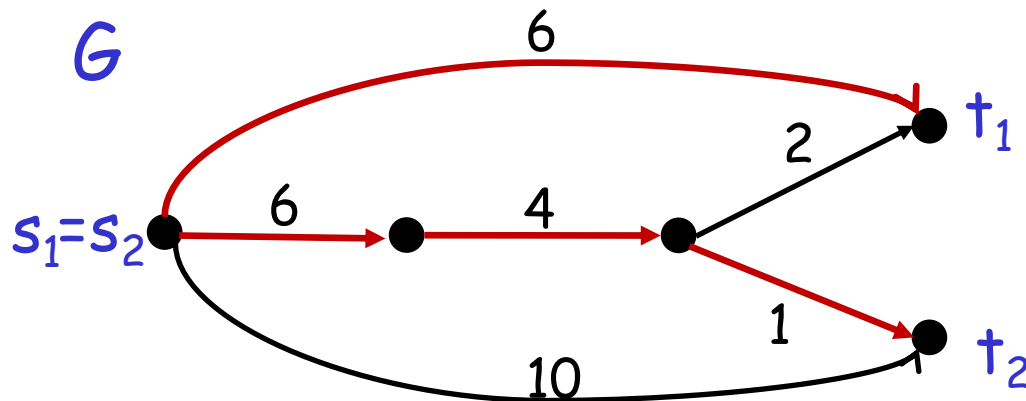
what is the socially  
optimal network?

cost of the social  
optimum: **13**

is it stable?

...no!

# an example



$\text{cost}_1 = 6$   
 $\text{cost}_2 = 11$

social cost  
of the network  
**17**

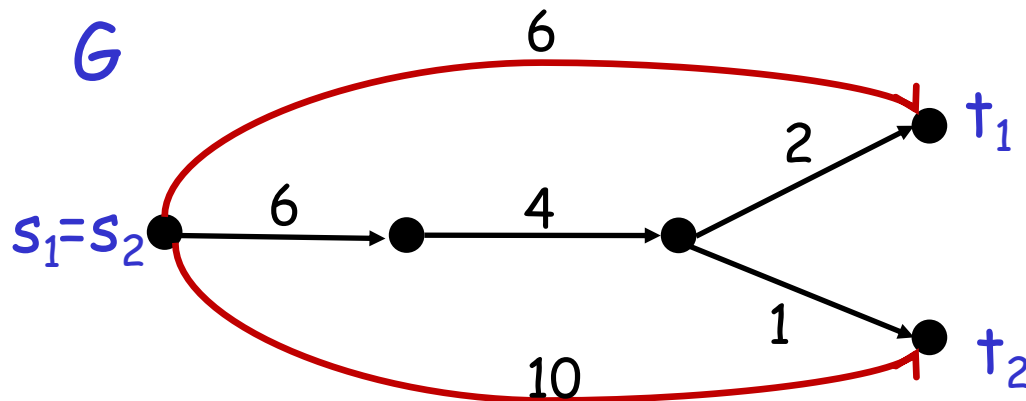
what is the socially  
optimal network?

cost of the social  
optimum: **13**

is it stable?

...no!

# an example



$\text{cost}_1 = 6$   
 $\text{cost}_2 = 10$

social cost  
of the network  
**16**

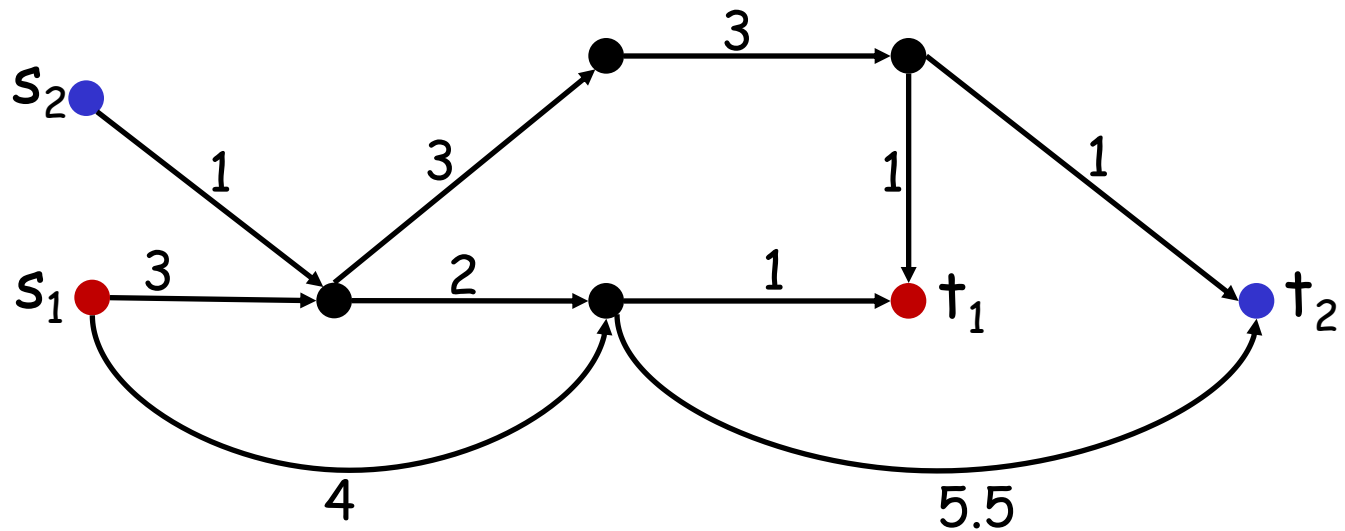
what is the socially  
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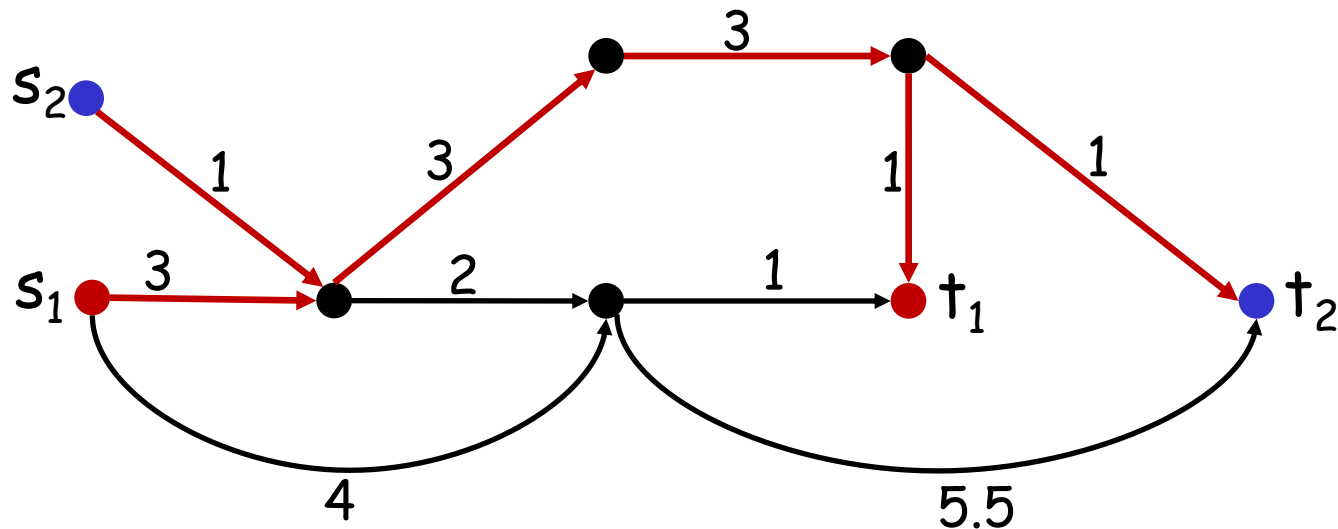
is it stable?

...yes!

one more example



# one more example

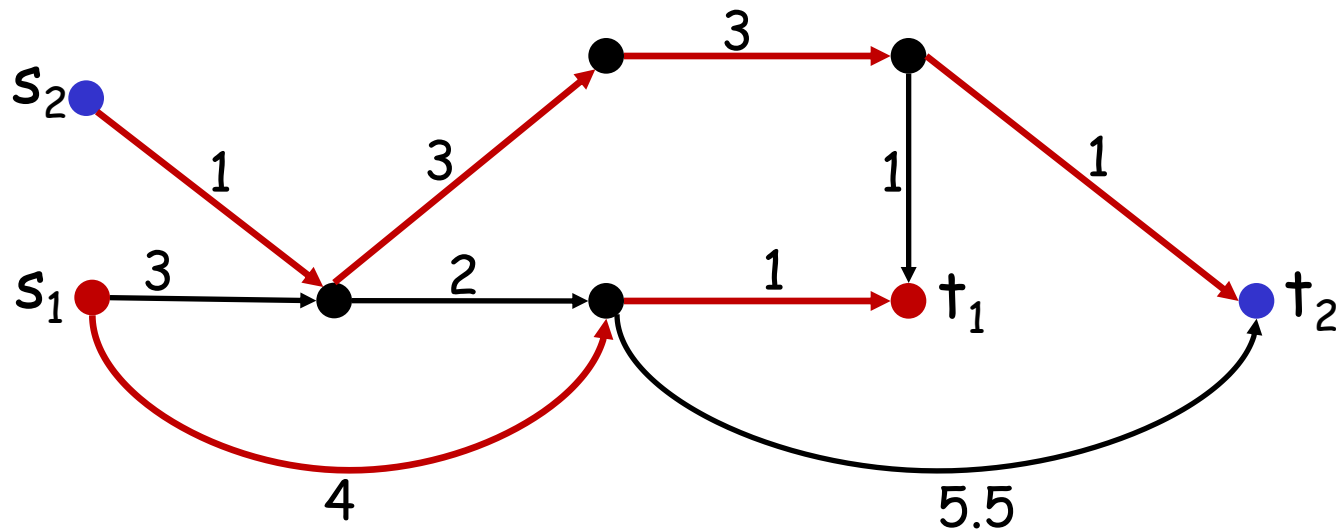


optimal network has cost 12

$\text{cost}_1=7$   
 $\text{cost}_2=5$

is it stable?

# one more example



...no!, player 1 can decrease its cost

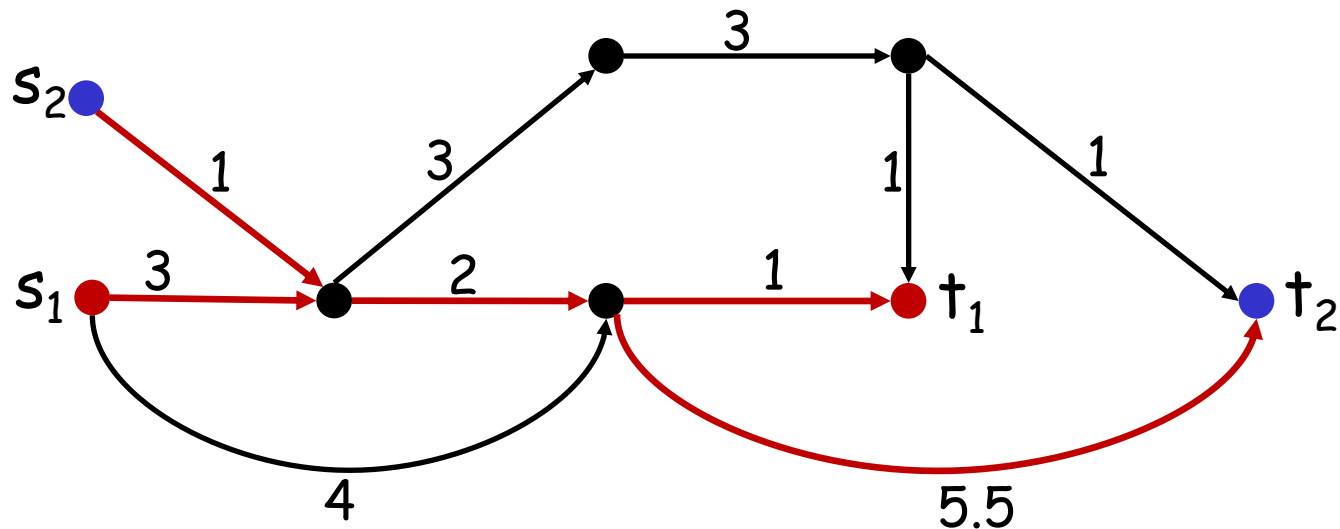
$\text{cost}_1 = 5$

$\text{cost}_2 = 8$

is it stable? ...yes!

the social cost is 13

# one more example



...a better NE...

$$\begin{aligned} \text{cost}_1 &= 5 \\ \text{cost}_2 &= 7.5 \end{aligned}$$

the social cost is 12.5

# Addressed issues

- Does a stable network always exist?
- Can we bound the price of anarchy (PoA)?
- Can we bound the price of stability (PoS)?
- Does the repeated version of the game always converge to a stable network?

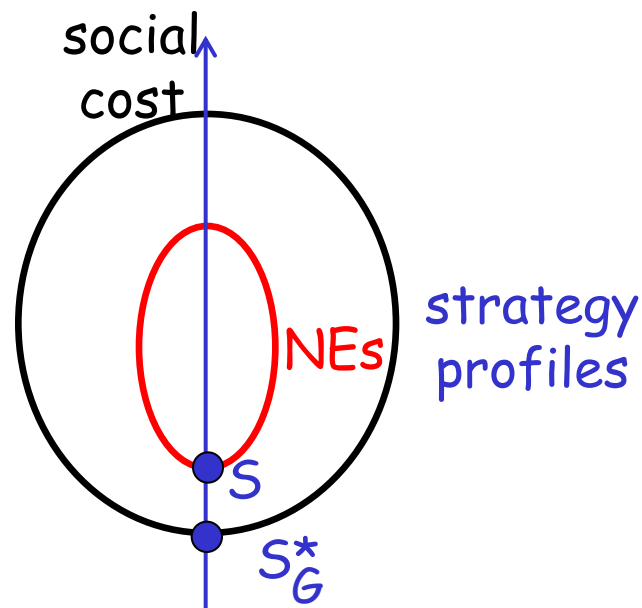
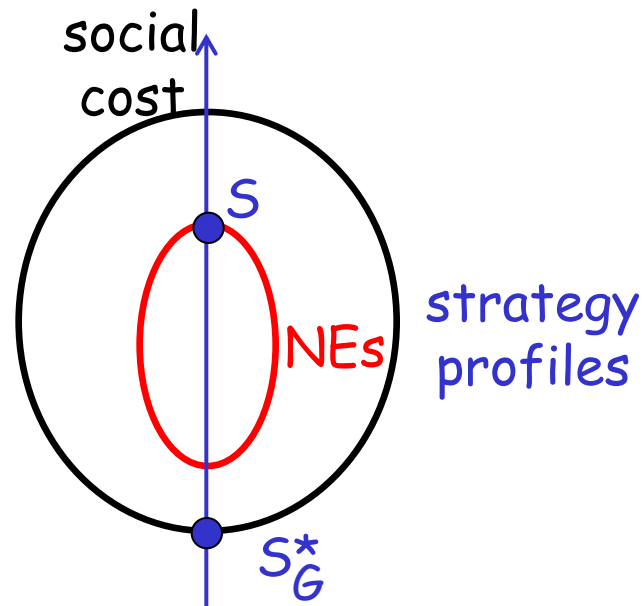
# PoA and PoS

$S_G^*$  : socially optimum for  $G$

for a given network  $G$ , we define:

$$\text{PoA of the game in } G = \max_{\substack{S \text{ s.t.} \\ S \text{ is a NE}}} \frac{\text{cost}(S)}{\text{cost}(S_G^*)}$$

$$\text{PoS of the game in } G = \min_{\substack{S \text{ s.t.} \\ S \text{ is a NE}}} \frac{\text{cost}(S)}{\text{cost}(S_G^*)}$$



# PoA and PoS

we want to bound PoA and PoS in the worst case:

$$\text{PoA of the game} = \max_G \text{PoA in } G$$

$$\text{PoS of the game} = \max_G \text{PoS in } G$$

# some notations

we use:

$$x = (x_1, x_2, \dots, x_k); \quad x_{-i} = (x_1, \dots, x_{i-1}, x_{i+1}, \dots, x_k); \quad x = (x_{-i}, x_i)$$

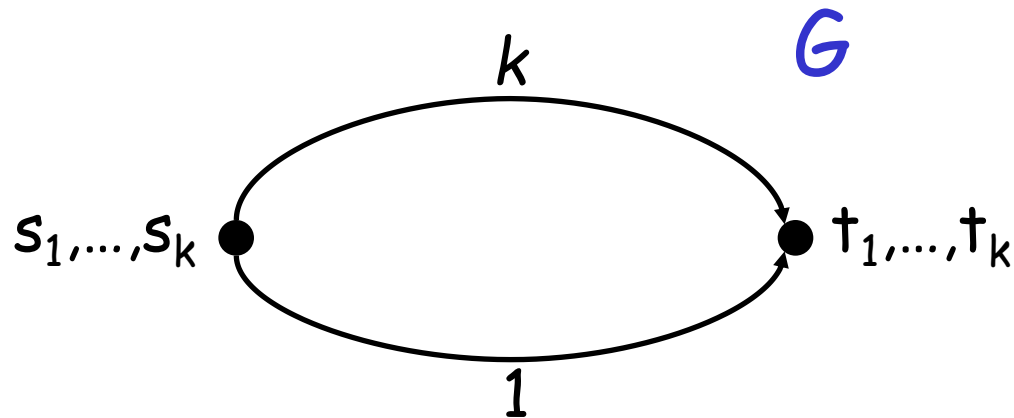
$G$ : a weighted directed network

cost or length of a path  $\pi$  in  $G$  :  $\sum_{e \in \pi} c_e$   
from a node  $u$  to a node  $v$

$d_G(u, v)$ : distance in  $G$  from a node  $u$  to a node  $v$  ; length of any shortest path in  $G$  from  $u$  to  $v$

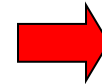
# Price of Anarchy

# Price of Anarchy: a lower bound



optimal network has cost  $1$

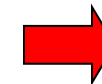
best NE: all players use the lower edge



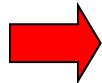
PoS in  $G$  is  $1$



worst NE: all players use the upper edge



PoA in  $G$  is  $k$



PoA of the  
game is  $\geq k$

# Theorem

The price of anarchy in the global connection game with  $k$  players is **at most**  $k$

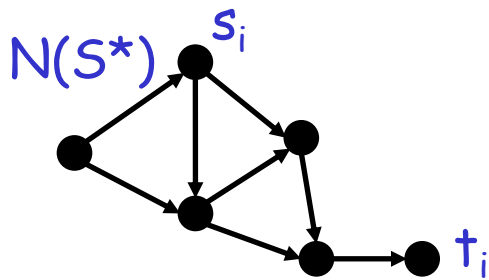
proof

$S$ : a NE                       $S^*$ : a strategy profile minimizing the social cost  
for each player  $i$ ,

let  $\pi_i$  be a shortest path in  $G$  from  $s_i$  to  $t_i$

we have

$$\text{cost}_i(S) \leq \text{cost}_i(S_{-i}, \pi_i) \leq d_G(s_i, t_i) \leq \text{cost}(S^*)$$



# Theorem

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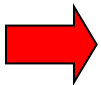
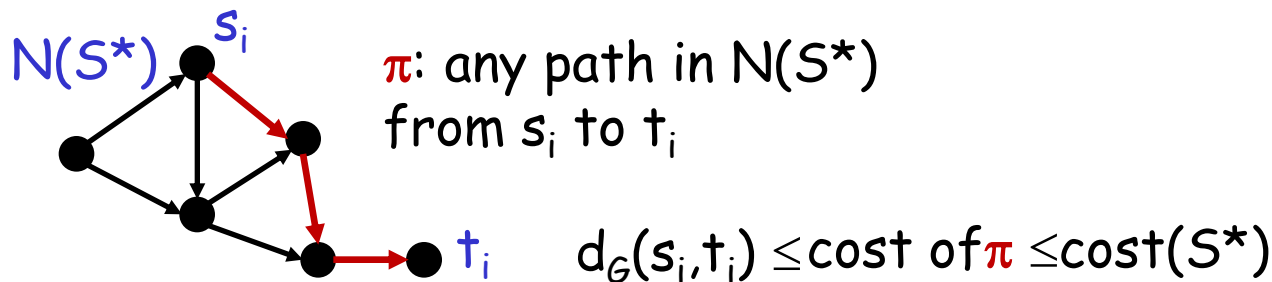
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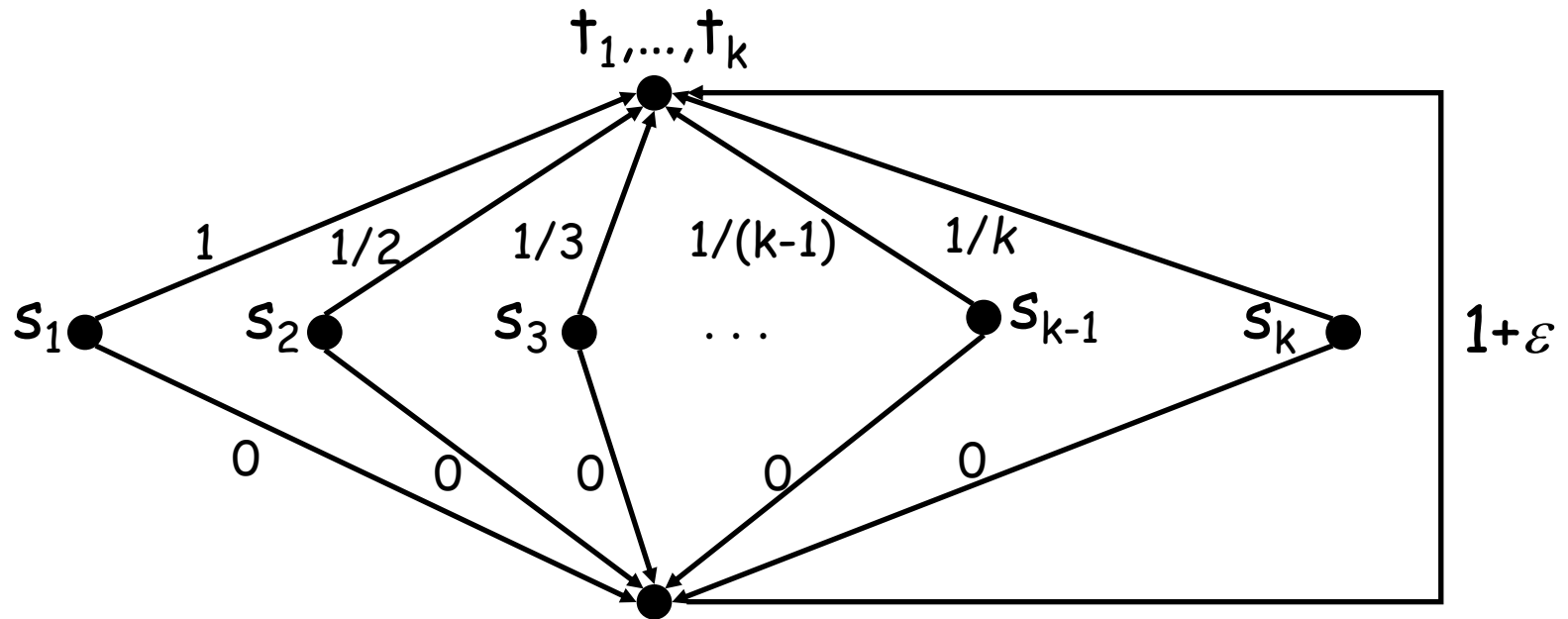


$$\text{cost}(S) = \sum_i \text{cost}_i(S) \leq k \text{cost}(S^*)$$

# Price of Stability & potential function method

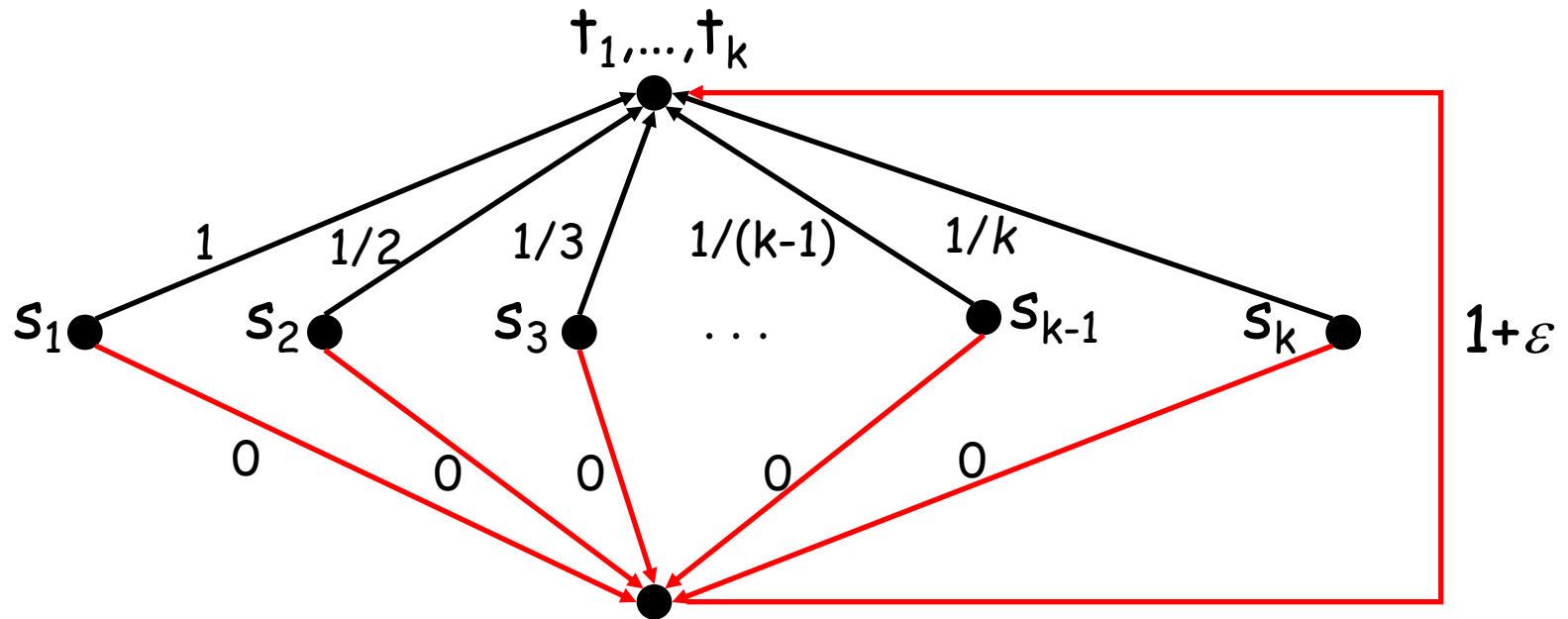
# Price of Stability: a lower bound

$\varepsilon \rightarrow 0$ : small value



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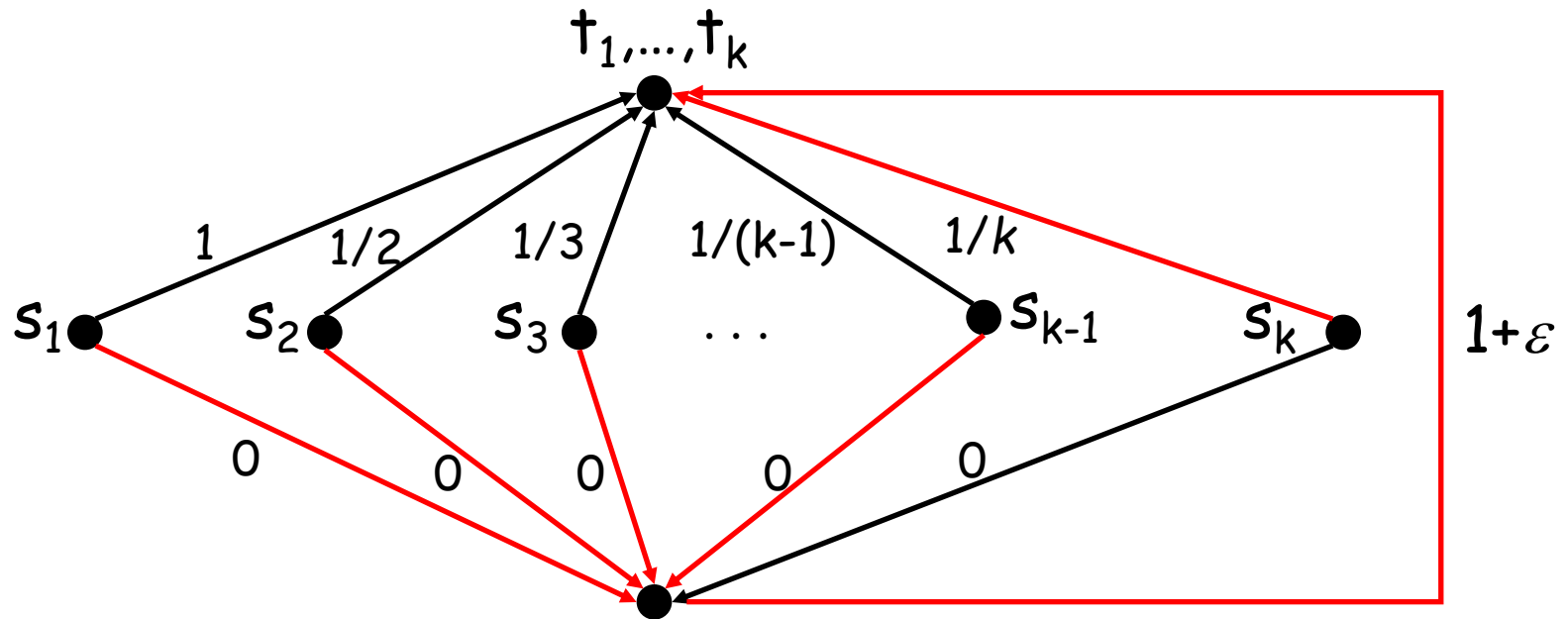


The **optimal** solution has a cost of  $1+\varepsilon$

is it stable?

# Price of Stability: a lower bound

$\varepsilon > 0$ : small value

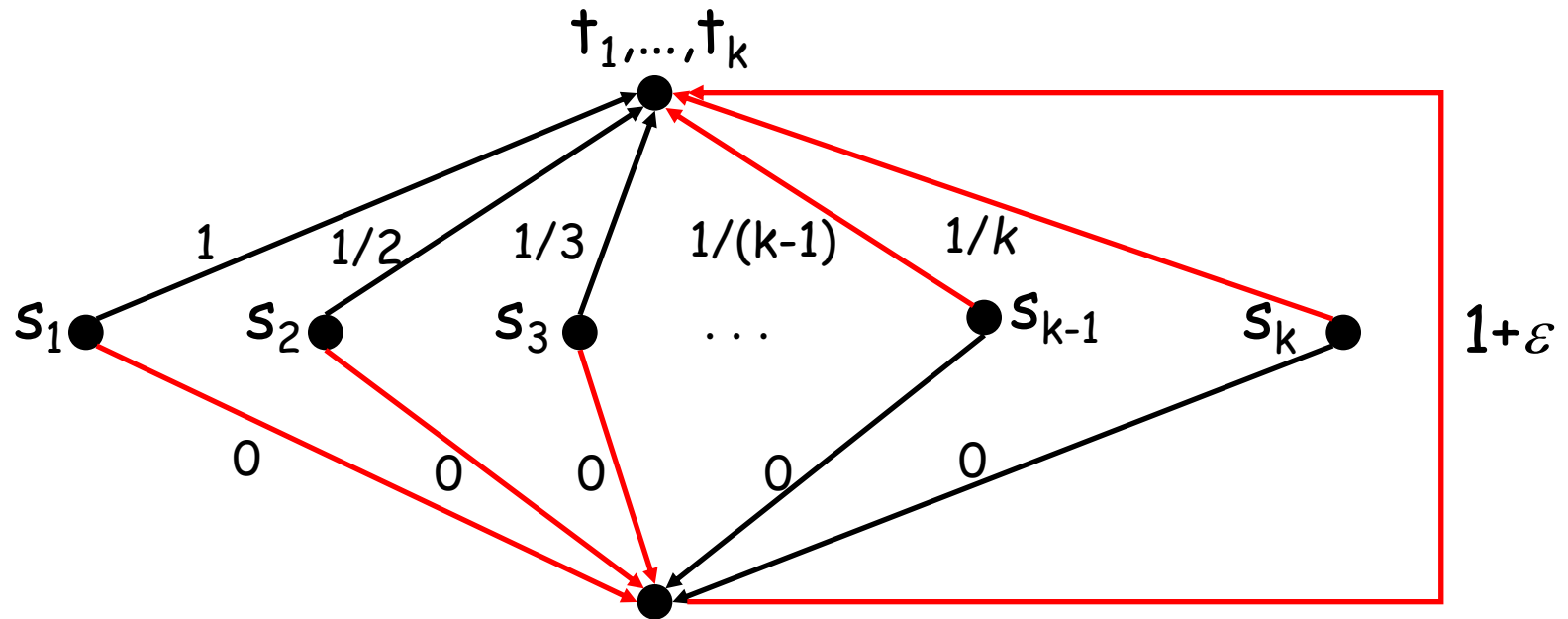


...no! player  $k$  can decrease its cost...

is it stable?

# Price of Stability: a lower bound

$\varepsilon \rightarrow 0$ : small value

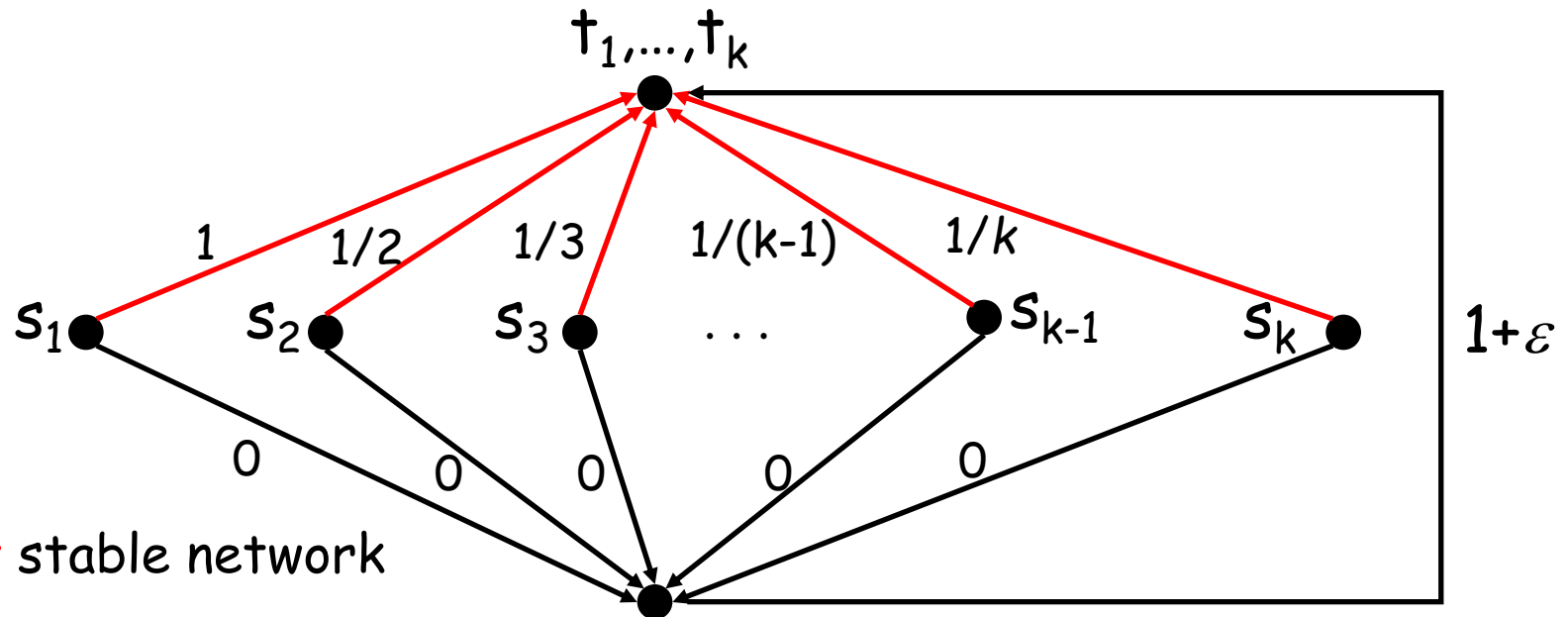


...no! player  $k-1$  can decrease its cost...

is it stable?

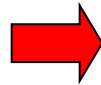
# Price of Stability: a lower bound

$\varepsilon > 0$ : small value



social cost:  $\sum_{j=1}^k 1/j = H_k \leq \ln k + 1$        $k$ -th *harmonic number*

the **optimal** solution  
has a cost of  $1+\varepsilon$



PoS of the  
game is  $\geq H_k$

## Theorem

Any instance of the global connection game has a pure Nash equilibrium, and better response dynamic always converges

## Theorem

The price of stability in the global connection game with  $k$  players is at most  $H_k$ , the  $k$ -th harmonic number

To prove them we use the  
*Potential function method*

## Notation:

$$x=(x_1,x_2,\dots,x_k); \quad x_{-i}=(x_1,\dots,x_{i-1},x_{i+1},\dots,x_k); \quad x=(x_{-i},x_i)$$

## Definition

For any finite game, an *exact potential function*  $\Phi$  is a function that maps every strategy vector  $S$  to some real value and satisfies the following condition:

$\forall S=(S_1,\dots,S_k), S'_i \neq S_i$ , let  $S'=(S_{-i},S'_i)$ , then

$$\Phi(S)-\Phi(S') = \text{cost}_i(S)-\text{cost}_i(S')$$

A game that possesses an exact potential function is called *potential game*

# Theorem

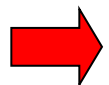
Every potential game has at least one pure Nash equilibrium, namely the strategy vector  $S$  that minimizes  $\Phi(S)$

proof

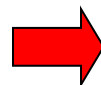
consider any move by a player  $i$  that results in a new strategy vector  $S'$

we have:

$$\underbrace{\Phi(S) - \Phi(S')}_{\leq 0} = \text{cost}_i(S) - \text{cost}_i(S')$$



$$\text{cost}_i(S) \leq \text{cost}_i(S')$$



player  $i$  cannot decrease its cost, thus  $S$  is a NE



# Theorem

In any finite potential game, better response dynamics always converge to a Nash equilibrium

## proof

better response dynamics simulate local search on  $\Phi$ :

1. each move strictly decreases  $\Phi$
2. finite number of solutions



**Note:** in our game, a best response can be computed in polynomial time

# Theorem

Suppose that we have a potential game with potential function  $\Phi$ , and assume that for any outcome  $S$  we have

$$\text{cost}(S)/A \leq \Phi(S) \leq B \text{ cost}(S)$$

for some  $A, B > 0$ . Then the price of stability is at most  $AB$

## proof

Let  $S'$  be the strategy vector minimizing  $\Phi$

Let  $S^*$  be the strategy vector minimizing the social cost

we have:

$$\text{cost}(S')/A \leq \Phi(S') \leq \Phi(S^*) \leq B \text{ cost}(S^*)$$



# ...turning our attention to the global connection game...

Let  $\Phi$  be the following function mapping any strategy vector  $S$  to a real value:

$$\Phi(S) = \sum_{e \in E} \Phi_e(S)$$

where

$$\Phi_e(S) = c_e H_{k_e(S)}$$

$$H_k = \sum_{j=1}^k 1/j \quad \text{k-th harmonic number}$$

[we define  $H_0 = 0$ ]

## Lemma 1

Let  $S=(P_1,\dots,P_k)$ , let  $P'_i$  be an alternative path for some player  $i$ , and define a new strategy vector  $S'=(S_{-i},P'_i)$ . Then:

$$\Phi(S) - \Phi(S') = \text{cost}_i(S) - \text{cost}_i(S')$$

## Lemma 2

For any strategy vector  $S$ , we have:

$$\text{cost}(S) \leq \Phi(S) \leq H_k \text{cost}(S)$$

...from which we have:

PoS of the  
game is  $\leq H_k$

## Lemma 2

For any strategy vector  $S$ , we have:

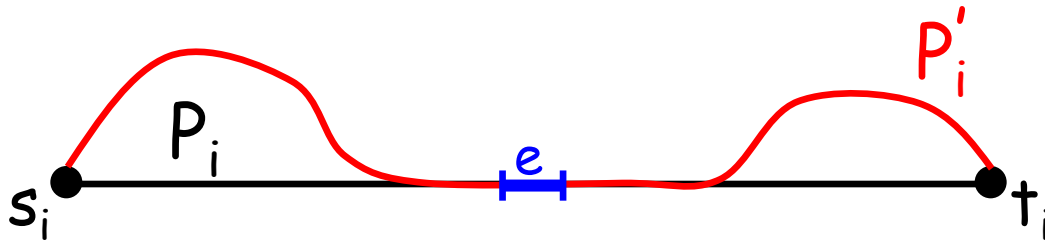
$$\text{cost}(S) \leq \Phi(S) \leq H_k \text{cost}(S)$$

proof

$$\begin{aligned} \text{cost}(S) \leq \Phi(S) &= \sum_{e \in E} c_e H_{k_e(S)} \\ &= \sum_{e \in N(S)} c_e H_{k_e(S)} \leq \sum_{e \in N(S)} c_e H_k = H_k \text{cost}(S) \end{aligned}$$

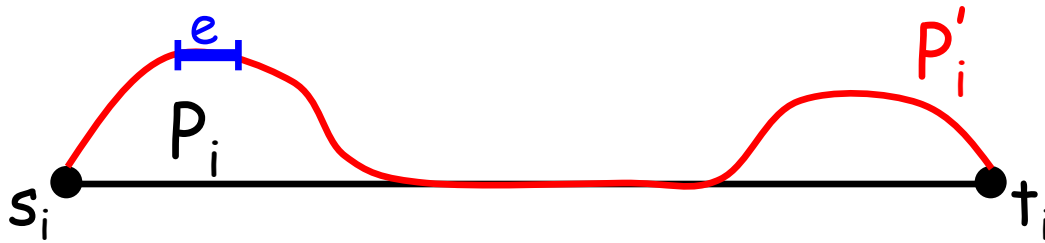
$$1 \leq k_e(S) \leq k \quad \text{for } e \in N(S)$$





for each  $e \in P_i \cap P'_i$

term  $e$  of  $\text{cost}_i()$  & potential  $\Phi_e$  remain the same

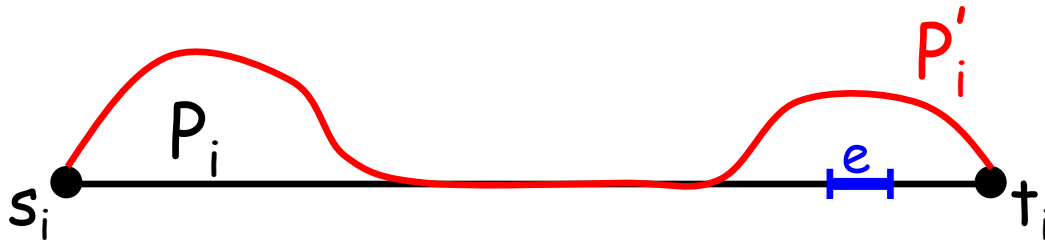


for each  $e \in P_i' \setminus P_i$

term  $e$  of  $\text{cost}_i()$  increases by  $c_e/(k_e(S)+1)$

potential  $\Phi_e$  increases from  $c_e \left(1 + \frac{1}{2} + \dots + \frac{1}{k_e(S)}\right)$   
to  $c_e \left(1 + \frac{1}{2} + \dots + \frac{1}{k_e(S)} + \frac{1}{k_e(S)+1}\right)$

$$\Rightarrow \Delta\Phi_e = c_e/(k_e(S)+1)$$



for each  $e \in P_i \setminus P'_i$

term  $e$  of  $\text{cost}_i()$  decreases by  $c_e / k_e(S)$

potential  $\Phi_e$  decreases from  $c_e \left( 1 + \frac{1}{2} + \dots + \frac{1}{k_e(S)-1} + \frac{1}{k_e(S)} \right)$   
to  $c_e \left( 1 + \frac{1}{2} + \dots + \frac{1}{k_e(S)-1} \right)$

$$\Rightarrow \Delta \Phi_e = -c_e / k_e(S)$$



# Theorem

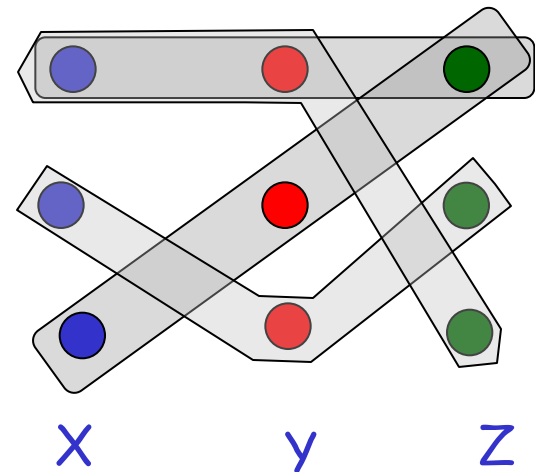
Given an instance of a *GC Game* and a value  $C$ , it is NP-complete to determine if a game has a Nash equilibrium of cost at most  $C$ .

proof

Reduction from 3-dimensional matching problem

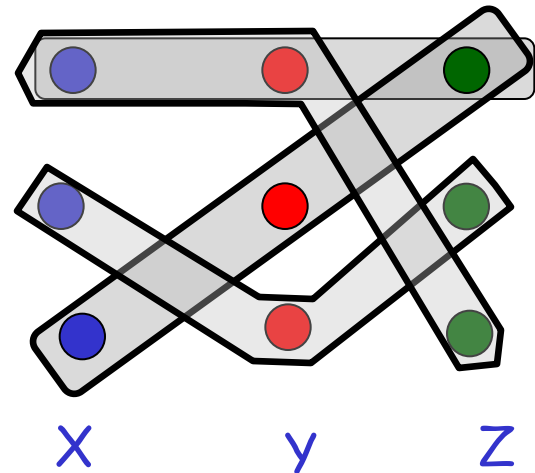
# 3-dimensional matching problem

- Input:
  - disjoint sets  $X, Y, Z$ , each of size  $n$
  - a set  $T \subseteq X \times Y \times Z$  of ordered triples
- Question:
  - does there exist a set of  $n$  triples in  $T$  so that each element of  $X \cup Y \cup Z$  is contained in exactly one of these triples?

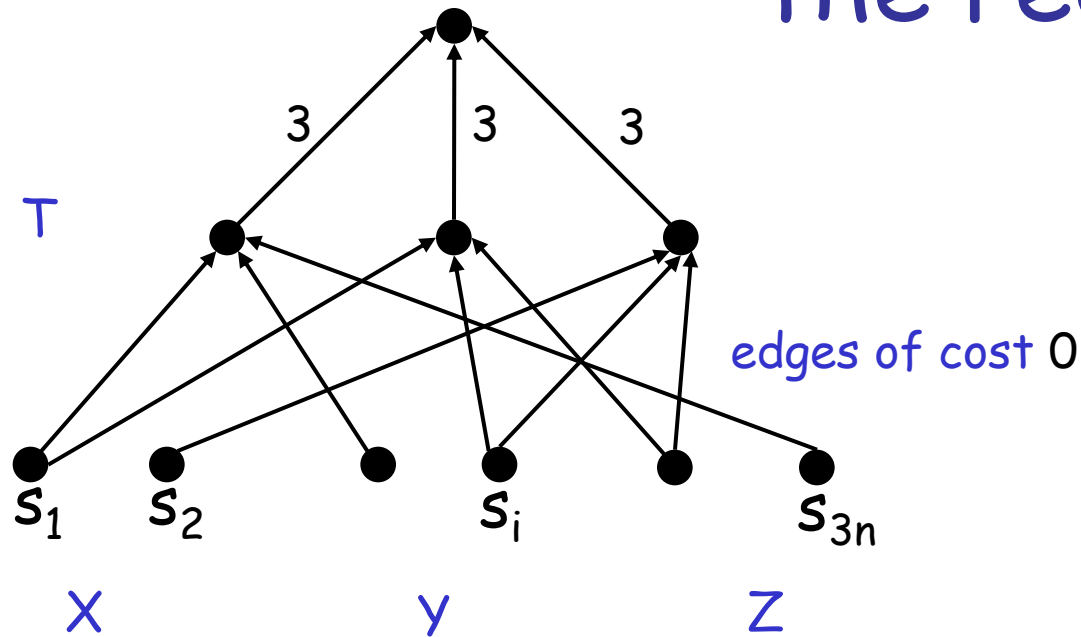


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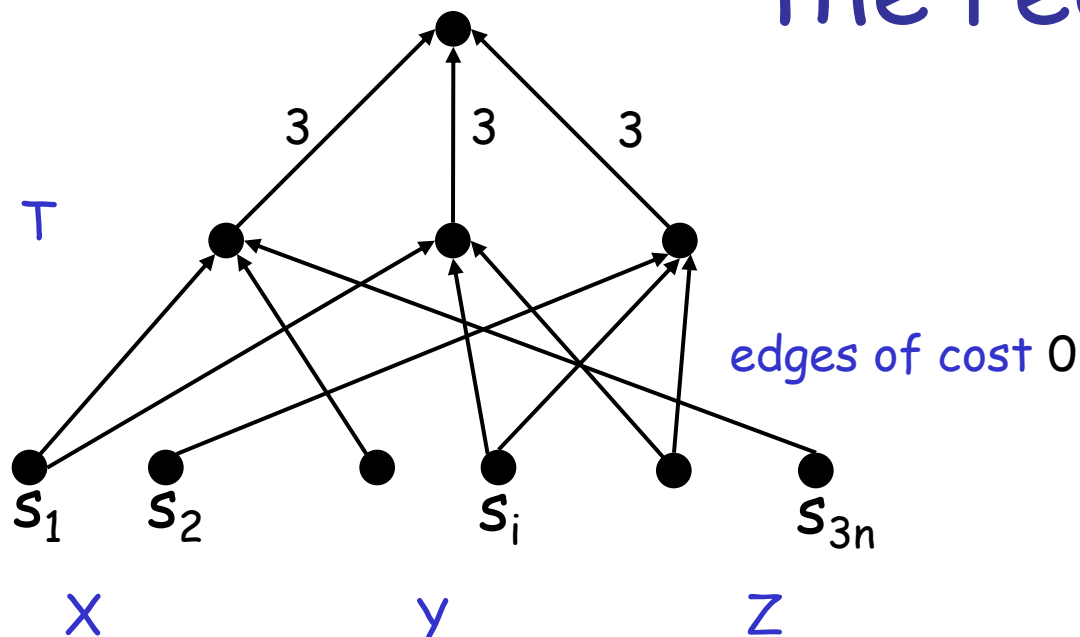


# the reduction



There is a 3D matching if and only if there is a NE of cost at most  $C=3n$

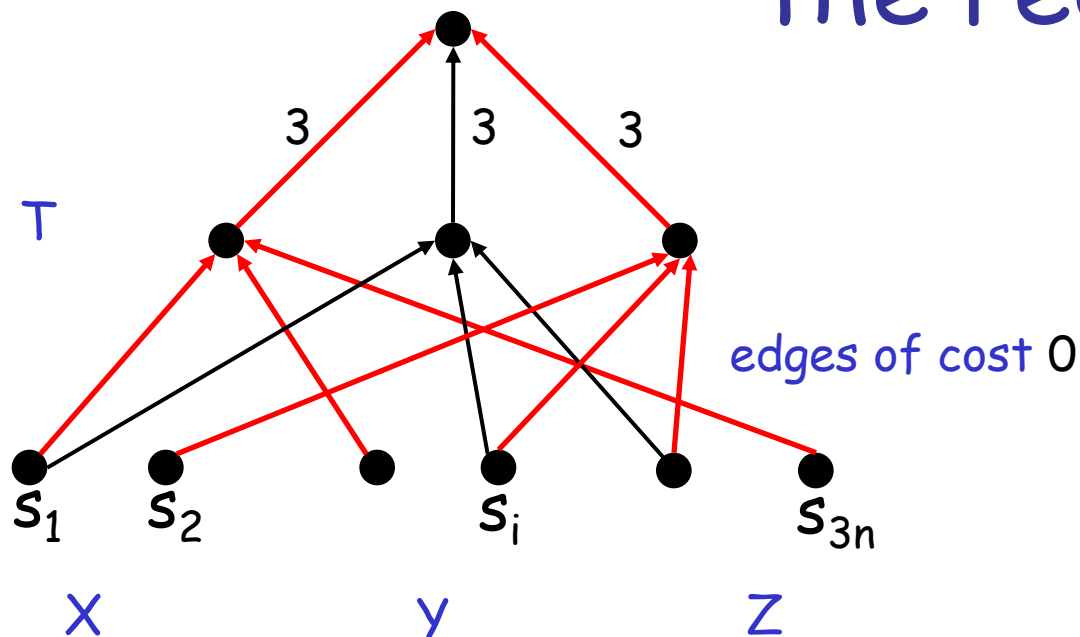
# the reduction



Assume there is a 3D matching.

$S$ : strategy profile in which each player choose a path passing through the triple of the matching it belongs to

# the reduction



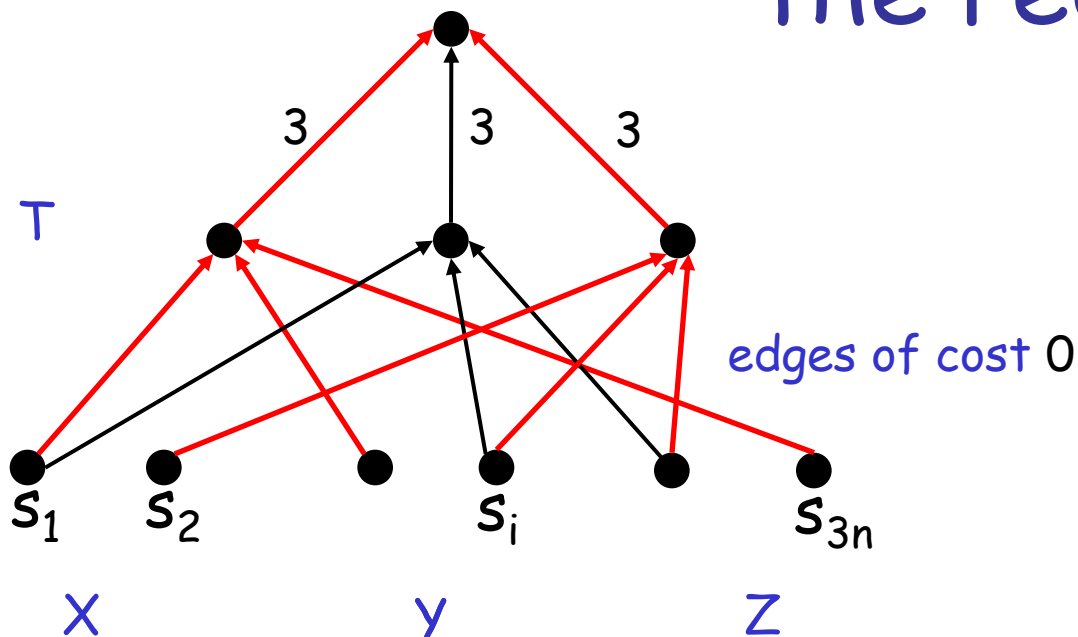
Assume there is a 3D matching.

$S$ : strategy profile in which each player choose a path passing through the triple of the matching it belongs to

$$\text{cost}(S) = 3n$$

$S$  is a NE

# the reduction



Assume there is a NE of cost  $\leq 3n$

$N(S)$  uses at most  $n$  edges of cost 3

each edge of cost 3 can "serve" at most 3 players

then, the edge of cost 3 are exactly  $n$

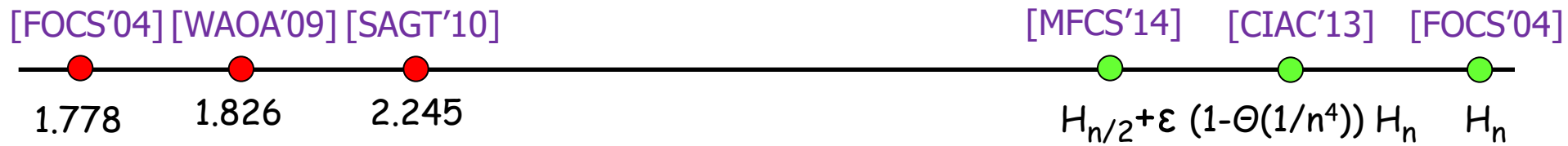
...and they define a set of triples that must be a 3D-matching



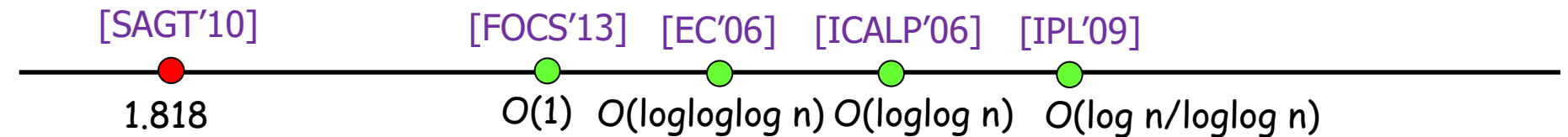
What is the PoS of the  
game for *undirected*  
networks?

# PoS for undirected graphs: State of the art

● UB ● LB

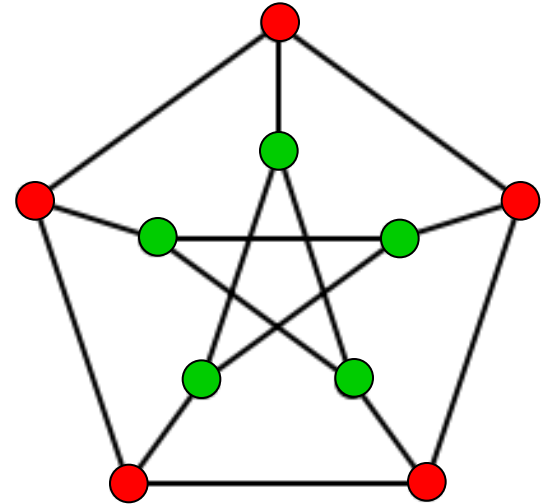


one single terminal (multicast)  
+ all sources (broadcast)



# Max-cut game

- $G=(V,E)$ : undirected graph
- Nodes are (selfish) players
- Strategy  $S_u$  of  $u$  is a color {red, green}
- player  $u$ 's payoff in  $S$  (to maximize):
  - $p_u(S) = |\{(u,v) \in E : S_u \neq S_v\}|$

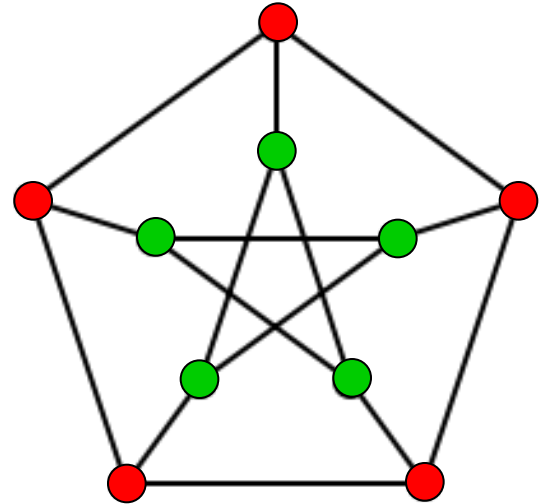


social welfare of  
strategy vector  $S$   
 $\sum_u p_u(S) =$   
2 #edges crossing  
the red-green cut

# Max-cut game

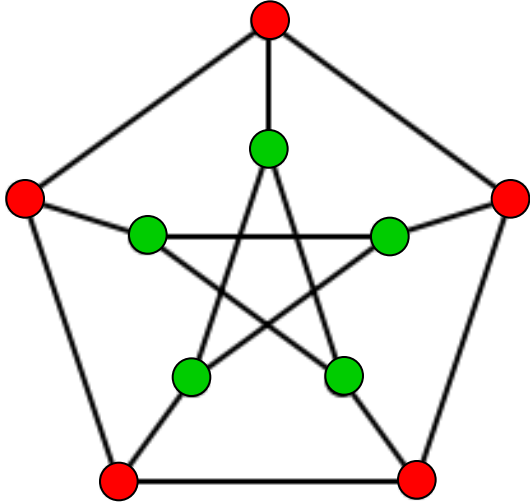
does a Nash Equilibrium  
always exist?

how bad a Nash  
Equilibrium  
Can be?



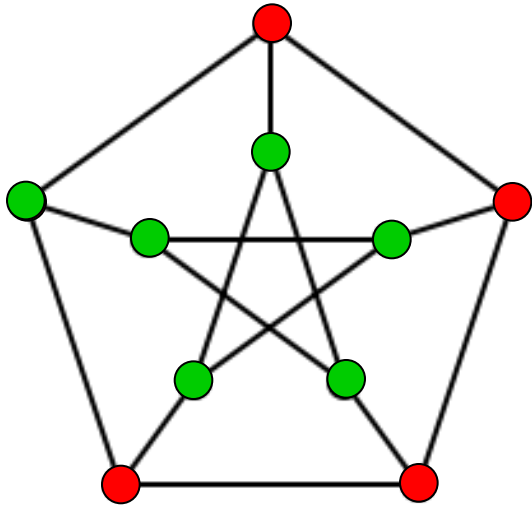
does the repeated  
game always  
converge to a  
Nash Equilibrium?

...let's play **Max-cut game**  
on Petersen Graph



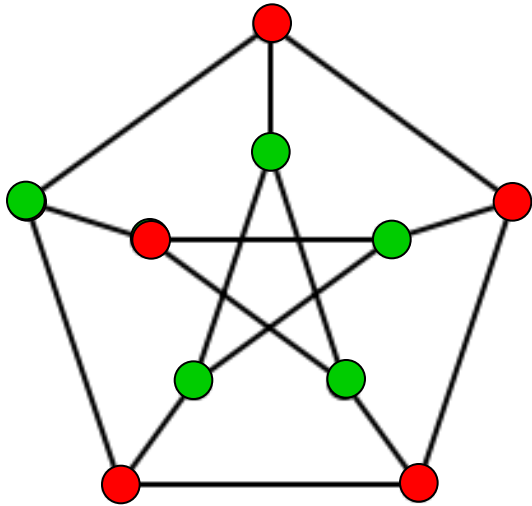
...is it a NE?

...let's play **Max-cut game**  
on Petersen Graph



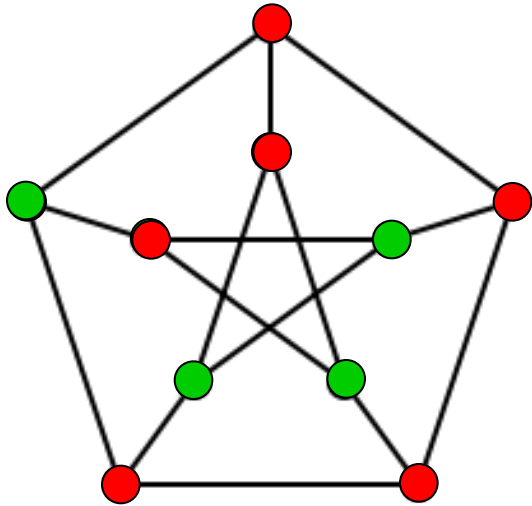
...is it a NE?

...let's play **Max-cut game**  
on Petersen Graph



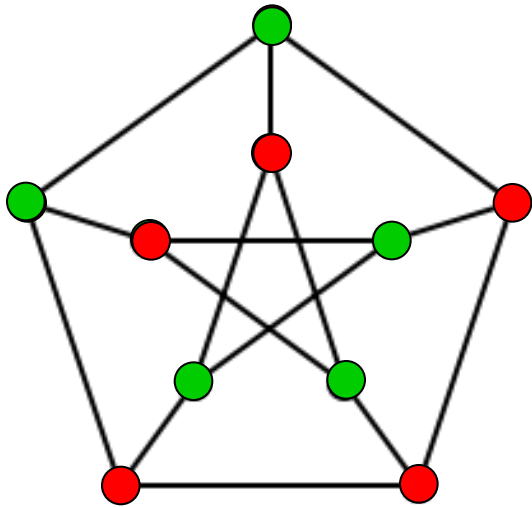
...is it a NE?

...let's play **Max-cut game**  
on Petersen Graph



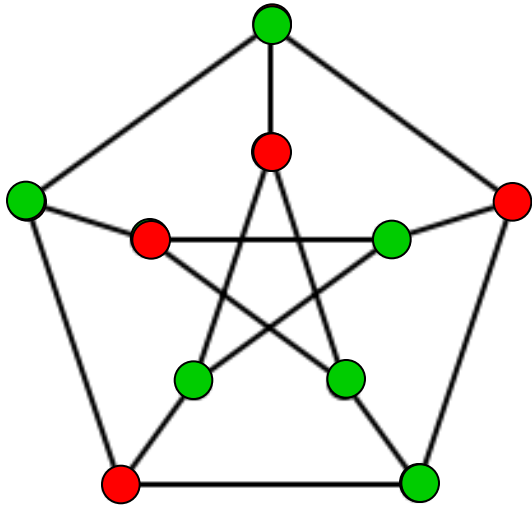
...is it a NE?

...let's play **Max-cut game**  
on Petersen Graph



...is it a NE?

...let's play **Max-cut game**  
on Petersen Graph



...is it a NE?

...yes!

# of edges crossing  
the cut is **12**

# Exercise

Show that:

- (i) **Max-cut** game is a potential game
- (ii) PoS is 1
- (iii)  $\text{PoA} \geq \frac{1}{2}$
- (iv) there is an instance of the game having a NE with social welfare of  $\frac{1}{2}$  the social optimum