

1. KORELACIJSKA MATRICA

a) $M = b_1 \cdot a_1^T + b_2 \cdot a_2^T + b_3 \cdot a_3^T$

$$= \begin{bmatrix} 6 \\ 2 \end{bmatrix} [-2 \ 2 \ 1] + \begin{bmatrix} -1 \\ 2 \end{bmatrix} [1 \ 2 \ -2] + \begin{bmatrix} 4 \\ 2 \end{bmatrix} [2 \ 1 \ 2]$$

$$= \begin{bmatrix} -12 & 12 & 6 \\ -4 & 4 & 2 \end{bmatrix} + \begin{bmatrix} -1 & -2 & 2 \\ 2 & 4 & -4 \end{bmatrix} + \begin{bmatrix} -8 & -4 & -8 \\ 4 & 2 & 4 \end{bmatrix} = \underline{\begin{bmatrix} -21 & 6 & 0 \\ 2 & 10 & 2 \end{bmatrix}}$$

b) $\|a_1\| = \sqrt{4+4+1} = \sqrt{9} = 3 \neq 1$

$$a_1 \cdot a_2 = -2 \cdot 1 + 2 \cdot 2 - 1 \cdot 2 = 0 \quad \checkmark$$

$$\|a_2\| = \sqrt{1+4+4} = \sqrt{9} = 3 \neq 1$$

$$a_1 \cdot a_3 = -2 \cdot 2 + 2 \cdot 1 + 1 \cdot 2 = 0 \quad \checkmark$$

$$\|a_3\| = \sqrt{4+1+4} = \sqrt{9} = 3 \neq 1$$

$$a_2 \cdot a_3 = 1 \cdot 2 + 2 \cdot 1 - 2 \cdot 2 = 0 \quad \checkmark$$

$$b) \|a_1\| = \sqrt{4+4+1} = \sqrt{9} = 3 \neq 1$$

$$a_1 \cdot a_2 = -2 \cdot 1 + 2 \cdot 2 - 1 \cdot 2 =$$

$$\|a_2\| = \sqrt{1+4+6} = \sqrt{9} = 3 \neq 1$$

$$a_1 \cdot a_3 = -2 \cdot 2 + 2 \cdot 1 + 1 \cdot 2 =$$

$$\|a_3\| = \sqrt{4+1+4} = \sqrt{9} = 3 \neq 1$$

$$a_2 \cdot a_3 = 1 \cdot 2 + 2 \cdot 1 - 2 \cdot 2 =$$

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$$c) a_1 = \frac{a_1}{\|a_1\|} = \frac{1}{3} [-2 \quad 2 \quad 1]^T$$

$$a_2 = \frac{a_2}{\|a_2\|} = \frac{1}{3} [1 \quad 2 \quad -2]^T$$

$$a_3 = \frac{a_3}{\|a_3\|} = \frac{1}{3} [2 \quad 1 \quad 2]^T$$

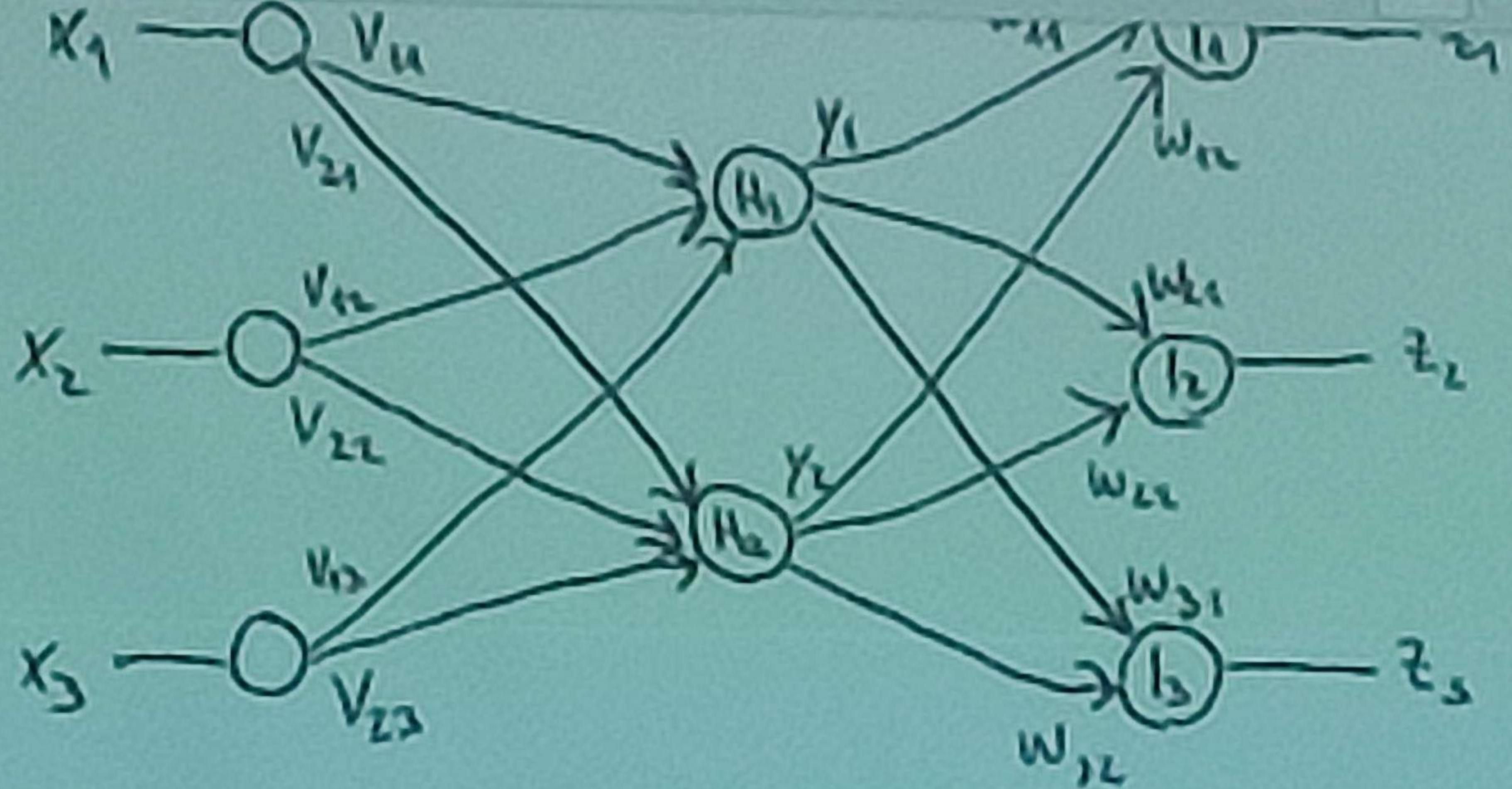
d)

$$\|a_4\| = \sqrt{\frac{100}{225} + \frac{121}{225} + \frac{4}{225}} = \sqrt{\frac{225}{225}} = 1 \quad \checkmark$$

$$a_1 \cdot a_4 = \frac{1}{3} \cdot \frac{1}{15} (-2 \cdot 10 + 2 \cdot 11 + 1 \cdot 2) = \frac{1}{45} \cdot 4 \quad \times$$

$$a_2 \cdot a_4 = \frac{1}{3} \cdot \frac{1}{15} (1 \cdot 10 + 2 \cdot 11 - 2 \cdot 2) = \frac{1}{45} \cdot 28 \quad \times$$

$$a_3 \cdot a_4 = \frac{1}{3} \cdot \frac{1}{15} (2 \cdot 10 + 1 \cdot 11 + 2 \cdot 2) = \frac{1}{45} \cdot 35 \quad \times$$



$$v_1 = \begin{bmatrix} 1 \\ -2 \end{bmatrix} \quad v_2 = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

$$w_1 = \begin{bmatrix} -1 \\ -3,5 \end{bmatrix} \quad w_2 = \begin{bmatrix} 0,5 \\ -1,2 \end{bmatrix} \quad w_3 = \begin{bmatrix} -0,5 \\ 0,6 \end{bmatrix}$$

- SIGMOIDA, DENG BIASA, ULUR $u = [1 \ 1 \ 0]^\top$

$$f(x) = \frac{1}{1+e^{-x}}$$

$$y_1 = f(h_1) = f(v_1^\top \cdot u) = f([-2 \ 2 \ -2] \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}) = f(0) = \frac{1}{1+e^0} = \boxed{\frac{1}{2}}$$

$$y_2 = f(h_2) = f(v_2^\top \cdot u) = f([1 \ 1 \ -1] \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}) = f(2) \cdot \frac{1}{1+e^2} = \boxed{0,88}$$

$$z_2 = f(l_2) = f(w_2^\top \cdot h) = f([0,5 \ -1,2] \begin{bmatrix} 0,5 \\ 0,88 \end{bmatrix}) = f(-0,806) = \frac{1}{1+e^{-0,806}} = \boxed{0,31}$$

$$\vec{z} = \begin{bmatrix} 0,83 \\ 0,26 \\ 0,56 \end{bmatrix}$$

$$w_{12} = -3,5$$

$$w_{22} = -1,2$$

$$w_{32} = 0,6$$

$$\gamma_2 = 0,6$$

$$\lambda = [0,68 \quad 0,26 \quad 0,56]^T$$

$$\eta = 0,03$$

$$\Delta w_{12} = \eta \cdot \delta_1 \cdot \gamma_2$$

$$\delta_1 = e_1 \cdot f'(l_1) = (t_1 - z_1) \cdot z_1(1-z_1)$$

$$\delta_1 = (-0,15) \cdot 0,83 \cdot 0,17 = -0,02417$$

~~Δw₁₂ = 0,03 · (-0,02417) · 0,6 = -0,00038~~

$$\Delta w_{12} = 0,03 \cdot (-0,02417) \cdot 0,6 = -0,00038$$

$$\Rightarrow w_{12}^1 = w_{12} + \Delta w_{12} = \boxed{-3,50038}$$

$$\Delta w_{22} = \eta \cdot \delta_2 \cdot \gamma_2$$

$$\delta_2 = e_2 \cdot f'(l_2) = (t_2 - z_2) \cdot z_2(1-z_2) = 0$$

$$\Delta w_{22} = 0$$

$$\boxed{w_{22}^1 = -1,2}$$

$$\Delta w_{32} = \eta \cdot \delta_3 \cdot \gamma_2$$

$$\delta_3 = e_3 \cdot f'(l_3) = (t_3 - z_3) \cdot z_3(1-z_3) = 0$$

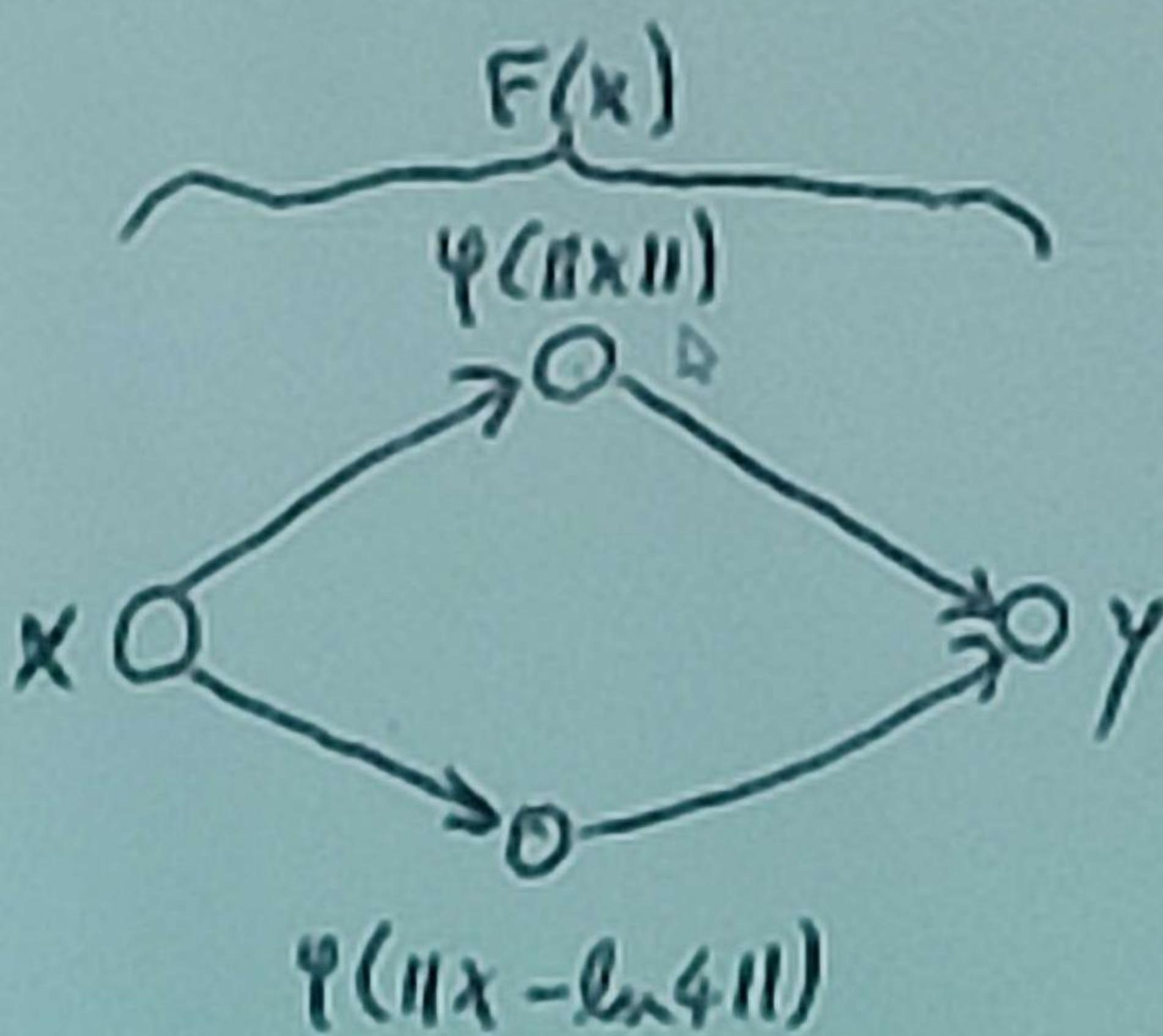
$$\Delta w_{32} = 0$$

$$\boxed{w_{32}^1 = 0,6}$$

3. RADIJALNE MRČEC

$$F(0) = 3$$

$$F(\ln(4)) = -4 \quad \Psi(\pi) = \frac{1}{e^{\pi/2}}$$



$$F(x) = \sum_{k=1}^n w_k \Psi(||x-x_k||)$$

$$F(x) = w_1 \Psi(||x||) + w_2 \Psi(||x-\ln 4||)$$

$$F(0) = w_1 \Psi(0) + w_2 \Psi(\ln 4)$$

$$F(\ln 4) = w_1 \Psi(\ln 4) + w_2 \Psi(0)$$

$$\Psi(0) = \frac{1}{e^0} = 1$$

$$\Psi(\ln 4) = \frac{1}{e^{\frac{\ln 4}{2}}} = \frac{1}{e^{\ln 4^{\frac{1}{2}}}} = \frac{1}{4^{\frac{1}{2}}} = \frac{1}{2}$$

$$\begin{bmatrix} 1 & \frac{1}{2} \\ \frac{1}{2} & 1 \end{bmatrix} \begin{bmatrix} w_1 \\ w_2 \end{bmatrix} = \begin{bmatrix} 3 \\ -4 \end{bmatrix}$$

$$w_1 + \frac{1}{2}w_2 = 3 \quad | \cdot 2 \quad \left. \begin{array}{l} \\ \end{array} \right\} -$$

$$\frac{1}{2}w_1 + w_2 = -4$$

$$\frac{3}{2}w_1 = 10$$

$$w_1 = \frac{20}{3}$$

$$\frac{20}{3} + \frac{1}{2}w_2 = 3$$

$$\frac{1}{2}w_2 = -\frac{11}{3}$$

4. STROJ S PÓTPORNÍM VĚKTORIEM

a) $w_0^T x + b_0 = 0$

$$[w_{01} \ w_{02}] \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + b_0 = 0$$

$$5w_{01} + 6w_{02} + b_0 = 1$$

$$2w_{01} + 3w_{02} + b_0 = -1$$

$$\underline{7w_{01} + 5w_{02} + b_0 = -1}$$

$$-2w_{01} - 2w_{02} = 0$$

$$w_{01} = -w_{02}$$

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$$w_{02} + b_0 = 1$$

$$-7w_{01} + 5w_{02} + 1 - w_{02} = -1$$

$$\underline{-3w_{02} = -2}$$

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$$-2w_{o1} - 2w_{o2} = 0$$

$$w_{o1} = -w_{o2}$$

$$\downarrow \quad \downarrow$$

$$w_{o2} + b_o = 1$$

$$b_o = 1 - w_{o2}$$

$$-7w_{o2} + 5w_{o2} + 1 - w_{o2} = -1$$

$$-3w_{o2} = -2$$

$$w_{o2} = \frac{2}{3}$$

$$w_{o1} = -\frac{2}{3}$$

$$b_o = \frac{1}{3}$$

b) $\rho = L_{NT} = \frac{2}{||\omega_0||} = \frac{2}{\sqrt{\frac{4}{3} + \frac{4}{3}}} = \frac{2}{\frac{2\sqrt{2}}{3}} = \frac{3}{\sqrt{2}} = \boxed{\frac{3\sqrt{2}}{2}}$