

Manual for C2 sample O3D3xx M03023

Version 1.1



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1. Primary note

This document is used for the quick bring up of a C2 sample O3D3xx (high resolution camera) of the company ifm syntron gmbh.

For detailed information the contact person is your ifm sales contact.

2. Safety instructions

Please read this manual before activating the unit.

The violation of application advice or technical data could lead to personal or property damage.

These units are development prototypes (Prototype C2 samples). Later releases of the O3D3xx (including its interfaces) could be different to the current version.

For this sample release no safety certification exists nor will be applied for. This will change for later releases.

Additional to this document a deviation list exists which refers to the maturity level of the C2 samples. Please consider it as part of the manual as well.

Operating the camera at high frame rates with high exposure times will lead to high temperatures. It is the customer's responsibility to provide adequate cooling.

The maximum recommended settings for medium dynamic range without external cooling are:

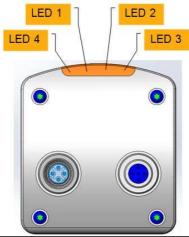
- 2ms exposure time at 15Hz frame rate
- 5ms exposure time at 5Hz frame rate

When operating, the camera emits pulsed infrared LED light of nominally 850nm wavelength from the upper and lower front windows. Do not stare into those windows.



3. Control and indicating element

3.1. LED display



| Process | LED status |
|---------------------|------------------------------------|
| Startup of the unit | Sequence flashing lights (LED 1-3) |
| Standard operation | LED 1 (green) is active |
| Ethernet Connection | LED 4 flashing |



4. Manual for mounting

4.1. Electric connection

ATTENTION!

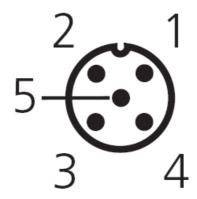
The unit must be installed by a electrically qualified person.

The plant must be volt-free before installing the unit.

The unit has to be connected with the crossover-cable to the PC. Supply the unit with power over the power supply.

4.2. Pin configuration





| Power supply (right) | |
|----------------------|--------------|
| Pin 1 | V++ (18-30V) |
| Pin 2 | n.a. |
| Pin 3 | GND |
| Pin 4 | n.a. |
| Pin 5 | n.a. |
| Ethernet plug (left) | |
| | |



5. Network communication between the O3D3XX sample and a PC

Attention: The C" sample O3D3xx and the PC have to be in the same IP-Address area.

5.1. Networkparameter

| | Networkaddress | Stationaddress |
|------------------|----------------|----------------------------------|
| C2 sample O3D3xx | 192.168.0. | 69 (Can be changed if necessary) |
| | = | ≠ |
| PC | 192.168.0. | e.g. 60 |



5.2. Connection between software "ifmVisionAssistant" (GUI) and the camera

To connect the camera and the GUI, the software has to establish communication. The following steps will show a first connection and a edit of an application.

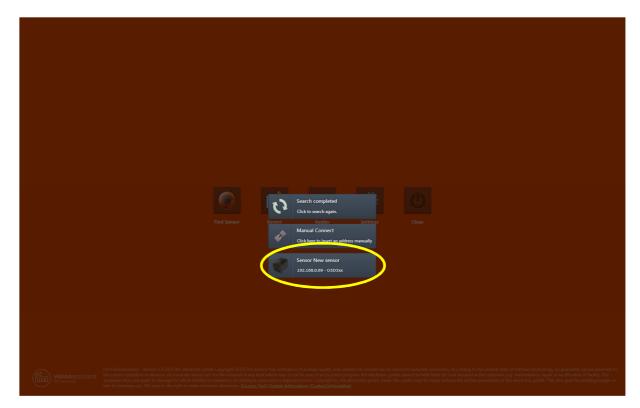
5.2.1. "Find Sensor"

The software will at first search automatically the camera in the network over UDP. If no camera was found the user can type in the IP-Address manually.





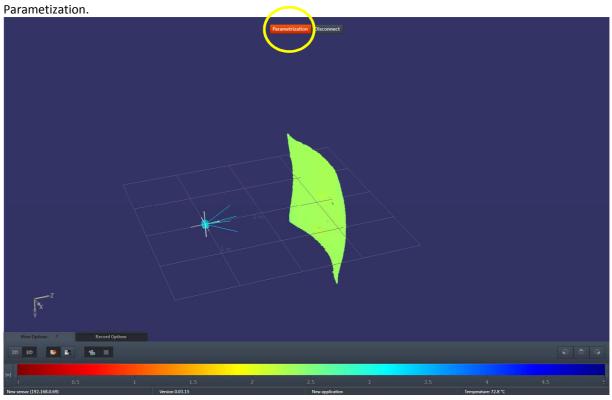
A found camera will be listed after the search process. By clicking on it the software will connect to the camera.





5.2.2. "Monitor mode"

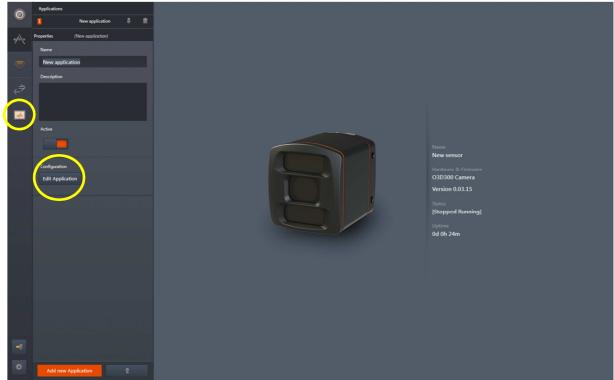
After the connection is established the "ifmVisionAssistant" will switch to the Monitor mode. In this mode the user can see the actual image and activated application. To edit the saved configuration click on





5.2.3. "Edit Application"

With "Edit Application" the actual marked Application will be configured. To come back to the "Monitor mode" use the button on the left side called "Monitor"

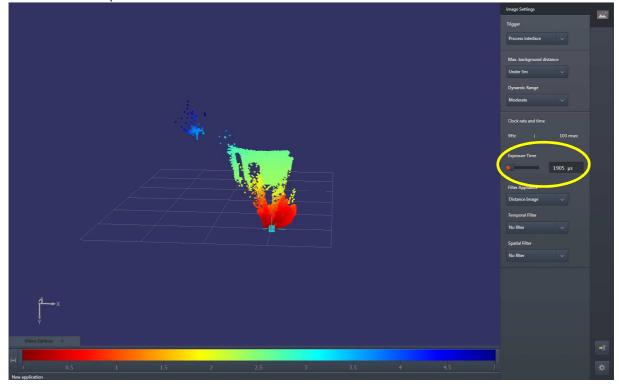




5.2.4. "Configurate the application"

In this mode the application can be changed.

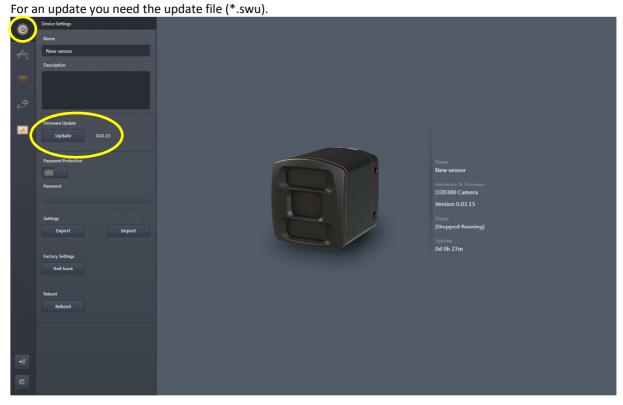
- Trigger: It is possible to switch the triggertype from "Process Interface" (Software) to "Continuous".
- Dynamic Range: Switch between:
 - o Low: Single exposure time.
 - o Moderate: Dual exposure time. The ratio of the exposure times is fixed at 40:1. The setting controls the longer exposure time.
 - High: Triple exposure time. In the "High" mode it is not possible to change the exposure time.
- Max. Framerate: Please see 2. Safety instructions for operating the camera at high framerates. The actual displayed framerate is not necessarily the real framerate.
- Exposure Time: Changes the illumination time/power. To get a better image.
- Filter Appliance: Fixed on Distance Image
- Temporal Filter: Will be supported in future versions
- Spatial Filter: Fixed on "No Filter" and "Median".



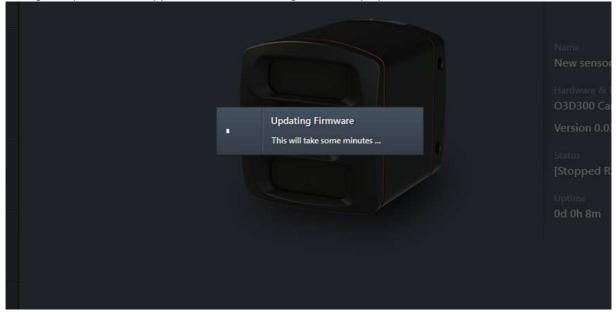


5.2.5. Device Settings

It is possible to upgrade the camera with an update file over the button "Update".



During the update it will happen that an error message will be displayed.







Wait 2 min. after the error message until you try to connect the GUI to the camera. Don't install the firmware again, boot the camera into the recovery mode. This will start the camera with the new firmware version.

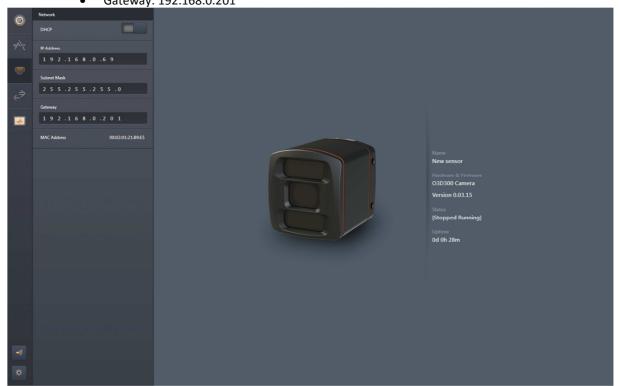




5.2.6. Network settings

It is possible to change the Networkparameters. Default parameter:

IP Address: 192.168.0.69Subnet Mask: 255.255.255.0Gateway: 192.168.0.201





6. XML-RPC Interface

The O3D3xx can be configured by the XML-RPC interface. Note: general information about XML-RPC is found on the website http://xmlrpc.scripting.com/spec

To send a command over the XML-RPC interface the command has to be on a special layout. In this command, linefeeds and carriage returns are essential.

Several commands will use different URL in the XML-RPC header.

6.1. Sample XML-RPC command

POST /RPC2 HTTP/1.0

All following XML-RPC commands will have this type of layout:

User-Agent: Frontier/5.1.2 (WinNT)
Host: betty.userland.com
Content-Type: text/xml
Content-length: 181

<?xml version="1.0"?>
<methodCall>
<methodName>examples.getStateName</methodName>
<params>
<param>
<value><i4>41</i4></value>
</param>
</params>

release date: 18Aug2014

</methodCall



Following example contains one command of the O3D3xx C2-sample:

POST /api/rpc/v1/com.ifm.efector/ User-Agent: Frontier/5.1.2 (WinNT)

Host: 192.168.0.69 Content-Type: text/xml Content-length: 94

- <?xml version="1.0"?>
- <methodCall>
- <methodName>getParameter</methodName>
- </methodCall>



6.2. Main-Object:

Object-URI: /api/rpc/v1/com.ifm.efector/

This is the main-object of RPC, it allows to access some basic information and contains methods for activating edit-mode.

6.3. SessionObject

Object-URI e.g.: /api/rpc/v1/com.ifm.efector/session_d21c80db5bc1069932fbb9a3bd841d0b/

6.4. EditMode-Object

Object-URI e.g.: /api/rpc/v1/com.ifm.efector/session_d21c80db5bc1069932fbb9a3bd841d0b/edit/

This object is only available if the device is in edit-OperatingMode. Index of Applications must be between 1 and 32. The device must only support 32 applications and the indexes must start at 1.

6.5. DeviceConfig-Object

Object-URI e.g.: /api/rpc/v1/com.ifm.efector/session_d21c80db5bc1069932fbb9a3bd841d0b/edit/device/

6.6. Device/NetworkConfig-Object

Object-URI e.g.:

/api/rpc/v1/com.ifm.efector/session_d21c80db5bc1069932fbb9a3bd841d0b/edit/device/network/

6.7. ApplicationConfig-Object (editable application)

Object-URI e.g.: /api/rpc/v1/com.ifm.efector/session d21c80db5bc1069932fbb9a3bd841d0b/edit/application/

6.8. App./ImagerConfig-Object (O3D3xx)

Object-URI e.g.:

/api/rpc/v1/com.ifm.efector/session d21c80db5bc1069932fbb9a3bd841d0b/edit/application/imager 001/

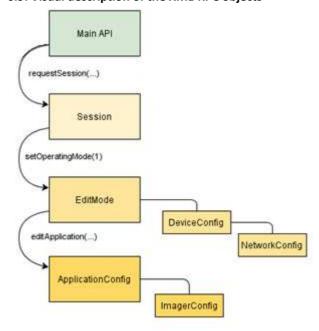
As there is only one imger-config on O3D3xx, the ID must be fixed to "001". Data of this object is persistent saved, when calling "save" on ApplicationConfig-object. The imager config RPC-object has multiple sub-types. Only parameters relevant for a specific type are available while it is active. They are based on frequency (extending the distance) and integration-intervals (extending the measure-details).

type-names, based on GUI-draft (under 5 meter->single Frequency, up to 30 meter-> double Freq., more than 30 Meter -> 3Freq.):

under5m_low under5m_moderate under5m_high



6.9. Visual description of the XML-RPC objects



Note: It could be necessary to send heartbeats so that there will be no session-timeout.



7. Process Interface

7.1. Sending commands

For sending commands over the process interface, the commands have to be send with a special protocol and as strings. This protocol conforms to the version 3 of the O2V/O2D products.

Structure of the protocol:

<Ticket><length>CR LF <Ticket><contents>CR LF

| Abbreviation | Description | ASCII code (dec) |
|--------------|---|------------------|
| CR | Carriage Return | 13 |
| LF | Linefeed | 10 |
| <> | Marking of a placeholder (e.g. <code> is a placeholder for code)</code> | |
| [] | Optional argument (possible but not required) | |

<contents> is the command to the device (e.g. trigger the unit).

<ticket> is a character string of 4 digits 0-9, to be interpreted as decimal

number. If a message with a specific ticket is sent to the device, its

reply will contain the same ticket

<length> is a character string beginning with the letter 'L' followed by 9 digits

to be interpreted as decimal number. This figure indicates the length

of the following data (<ticket><contents>CR LF) in bytes.

| Version | input format | output format |
|---------|--|--|
| V1 | <content>CR LF</content> | as input |
| V2 | <ticket><content>CR LF</content></ticket> | as input |
| V3 | <ticket><length>CR+LF<ticket><content>CR LF</content></ticket></length></ticket> | as input |
| V4 | <content>CR LF</content> | <length>CR LF<content>CR LF</content></length> |

The default protocolversion is "V3". Do not use the other versions for the C2 sample.



7.2. Receiving images

For receiving the image data there has to be a TCP/IP socket communication established. This communication works on the Port 50010. After opening the socket communication the O3D3XX sample will automatically (if the unit is in free run mode) send the image data through this socket to the TCP/IP client (PC).

PCIC output per frame. The following data shall be submitted in this sequence:

| Component | Content | |
|---|-----------------------------------|--|
| Ticket and length information | Please see chapter 0 7.1. Sending | |
| | commands | |
| Ticket | "0000" | |
| Start sequence | String "star" (4 bytes) | |
| normalized amplitude image | 1 image | |
| output format: 16 Bit Unsigned Integer. | | |
| distance image | 1 image | |
| output format: 16 Bit Unsigned Integer. Unit is mm. | | |
| x-image | 1 image | |
| output format: 16 Bit Signed Integer. Unit ist mm. | | |
| y-image | 1 image | |
| output format: 16 Bit Signed Integer. Unit ist mm. | | |
| z-image | 1 image | |
| output format: 16 Bit Signed Integer. Unit ist mm. | | |
| Confidence image | 1 image | |
| output format: 8 Bit Unsigned Integer | | |
| Diagnostic data | | |
| Stop sequence | String "stop" (4 bytes) | |
| Ticket finish | <cr><lf></lf></cr> | |

Diagnostic data output has the following structure:



| Illumination Temperature | 32-bit signed int | 4 bytes |
|--------------------------|-------------------------|---------|
| Frontend Temperature 1 | 32-bit signed int | 4 bytes |
| Frontend Temperature 2 | 32-bit signed int | 4 bytes |
| i.mx6 Temperature | 32-bit signed int | 4 bytes |
| processing time in ms | 32-bit unsigned integer | 4 bytes |

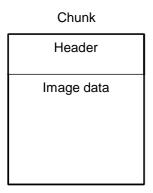
All temperature values have the unit 0.1 °C, invalid temperatures have the value 0x7FFF (32767).

Illumination Temperature and Frontend Temperature 2 are not measured in C2 sample. Therefor these temperatures have the value 0x7FFF (32767).



7.3. Image data

For every image there will be a separate chunk. The chunk is a part of the response frame data from the process interface. The image data layout of the response is separated to these points:



The header of each chunk contains different kind of information. This information is separated into Bytes. The information contains e.g. the kind of image which will be in the "PIXEL_DATA" and the size of the chunk.

Chunk type:

| Offset | Name | Description | Size [Byte] |
|--------|----------------|---|-------------|
| 0x0000 | CHUNK_TYPE | Defines the type of the chunk. For each distinct chunk type a own type has to be defined. | 4 |
| 0x0004 | CHUNK_SIZE | Size of the whole image chunck in bytes. After this count of bytes the next chunk starts. | 4 |
| 0x0008 | HEADER_SIZE | Number of bytes starting from 0x0000 until PIXEL_DATA | 4 |
| 0x000C | HEADER_VERSION | Version number of the header | 4 |
| 0x0010 | IMAGE_WIDTH | Image width in pixel | 4 |
| 0x0014 | IMAGE_HEIGTH | Image height in pixel | 4 |
| 0x0018 | PIXEL_FORMAT | Pixel-Format | 4 |
| 0x001C | TIME_STAMP | Timestamp in uS | |
| 0x0020 | FRAME_COUNT | Frame count according to algorithm output | |
| 0x0024 | PIXEL_DATA | The pixel data in the given type and dimension of the image. Padded to 4-Byte boundary. | |



Pixel format:

| Constant | Value | Description |
|------------|-------|--------------------------------|
| FORMAT_8U | 0 | 8bit unsigned integer |
| FORMAT_8S | 1 | 8bit signed integer |
| FORMAT_16U | 2 | 16 bit unsigned integer |
| FORMAT_16S | 3 | 16bit signed integer |
| FORMAT_32U | 4 | 32bit unsigned integer |
| FORMAT_32S | 5 | 32bit signed integer |
| FORMAT_32F | 6 | 32bit floating point number |
| FORMAT_64U | 7 | 64bit unsigned integer |
| FORMAT_64F | 8 | 64bit floating point number |



7.4. Additional information for image data

| Image type | Unit | Invalid | Data interpretation |
|------------|--------------|--------------|--|
| Distance | Milimeter | pixel 0.0 | Each pixel of the distance matrix denotes the |
| Distance | Willimiteter | mm | distance between the optical center of the |
| | | | camera and appropriate object in the scene |
| Amplitude | Digits | 0.0 | Each pixel of the amplitude matrix denotes the |
| | | | amount of light which is reflected by the |
| | | | appropriate object. Due to the double |
| | | | exposure time the lack of normalization may |
| | | | lead to inhomogeneous amplitude image |
| | | | impression |
| Intensity | Digits | 0.0 | Each pixel of the intensity matrix denotes the |
| | | | sum of light reflected by the appropriate |
| | | | object. Due to the double exposure time the |
| | | | lack of normalization may lead to |
| | | | inhomogeneous intensity image impression |
| Confidence | Digits | | See table bellow |
| X,Y,Z | Milimeter | | The X,Y,Z matrices denote the appropriate |
| | | | component of the Cartesian coordinate of a |
| | | | PMD 3D measurement. |
| | | | +X: to the right |
| | | | +Y: down |
| | | | +Z: forward |



Further information for the Confidence image

| Bit | Value | Description |
|-----|--|---|
| 0 | 1 = pixel invalid | Pixel invalid (NV) The pixel is invalid. To determine, whether a pixel is valid or not only this bit needs to be checked. For a reason why the bit is invalid the other confidence bits may be checked. |
| 1 | 1 = pixel saturated | Pixel is saturated (SA) Contributes to pixel validity: yes |
| 2 | 1 = bad A-B symmetry | A-B pixel symmetry (SY) The A-B symmetry value of the four phase measurements is above threshold. Remark: This symmetry value is used to detect motion artefacts. Noise (e.g. due to strong ambient light or very short integration times) or PMD interference may also contribute. Contributes to pixel validity: yes |
| 3 | 1 = amplitude below minimum amplitude threshold | Amplitude limits (AM) The amplitude value is below minimum amplitude threshold. Contributes to pixel validity: yes |
| 4+5 | Bit 5, Bit 4 0 0 unused 0 1 shortest exposure time (only used in 3 exposure mode) 1 0 middle exposure time in 3 exposure mode, short exposure in double exposure mode 1 1 longest exposure time (always 1 in single exposure mode) | Exposure time indicator The two bits indicate, which exposure time was used in a multiple exposure measurement. Contributes to pixel validity: no |
| 6 | 1= motion artefact compensated | Not implemented for C2 sample O3D3xx |
| 7 | 1 = pixel suspect/defect | Suspect pixel (SU) This pixel has been marked as "suspect" or "defect" and values have been replaced by interpolated values from the surrounding. Contributes to pixel validity: no |



8. Set up PMDSDK2

8.1. Purpose

The purpose of the PMDSDK2 is to provide an environment for a code example of the interface of the O3D3xx. To visualize results the PC-Software "LightVis" can be used. "LightVis" originally has been developed by **pmd**technologies. The PMDSDK2 provides sample code to demonstrate the O3D interface. However, ifm electronic gmbh excludes liability for demonstrational sample codes.

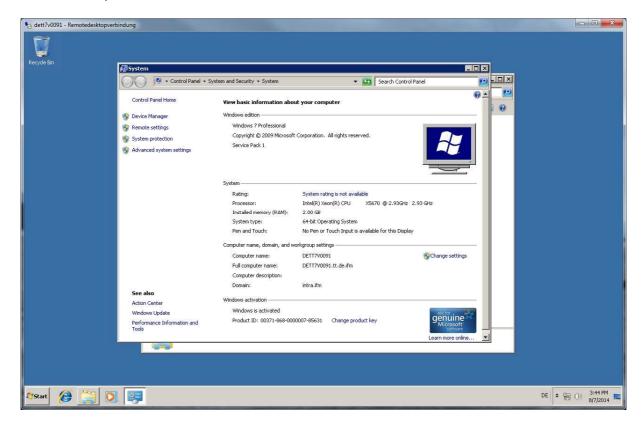
All sample codes are provided in the PMDSDK2. To set up the SDK follow these steps:

The following software has to be installed on the PC before you can build the library

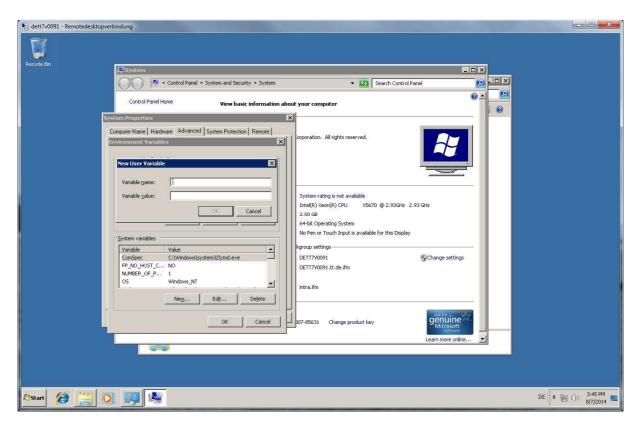
1) CMake (version 2.8.9 or higher from http://cmake.org/cmake/resources/software.html)
When the software asks you for the path use all users

2)Boost (version 1.54.0 or higher from http://www.boost.org/users/download/)

- after download, go to the boost root folder over with the console
- start "bootstrap"
- start "b2.exe --with-regex --with-date_time --with-system --with-thread" (copy/paste this command, files are found at "stage/lib")
- add system variable to boost root directory: e.g.: BOOST_ROOT = "D:\boost_1_54_0\" (see pictures bellow)









The following software is needed to build the Doxygen documentation -

- 1) Doxygen (version 1.8.7 or higher from http://www.stack.nl/~dimitri/doxygen/download.html)
- 2) Graphviz (version 2.38 or higher from http://www.graphviz.org/Download.php)
- 3) Miktex (version 2.9 or higher from http://miktex.org/download) this is required only if the documentation is as PDF required.

NOTE: We have built and tested the code with the versions mentioned above. Higher versions should also work seamlessly, but this is not guranteed.

Download the source code from ifm official site. Or use the provided ones.

The source code folder shall contain code related files for "O3D3xx plugin development" project.

It mainly consists of O3D3xx source and processing plugin, along with dependent code and third party tools, test suites etc.

The folder structure looks like this:

Base Folder

- "processing_plugin" (the files needed to build the processing plugin)
- "source_plugin" (the files needed to build the source plugin)
- "samples" (all the sample codes)
- "tests" (all the unit test codes)
- "third_party" (all the third party code)



8.2. Process for building the Source Code:

- Open the CMake GUI (Start Menu -> All Programs -> CMake 2.8 -> CMake (cmake-gui)).
- Type into "Where is the Source code", the point to the location of the source code (only the path to the folder /code).
- In the "Where to build the binaries" area, point to the location where you want to build the binaries.
- It is recommended that a separate folder called as "build" (this name can be changed)be created in a separate location on the PC for this purpose.
- Click on "Configure". Select the Visual Studio (VS) compiler version that you have installed on your PC. Please note the following mapping to be used:

VS 2008 --> Visual Studio 9

VS 2010 --> Visual Studio 10

VS 2012 --> Visual Studio 11

VS 2013 --> Visual Studio 12

There are a couple of options in CMake which can be selected if required:

| O3D3XX_SAMPLE_CODES_BUILD_ALL | This option if selected (default ON),generates the sample code project |
|---------------------------------------|--|
| O3D3XX_UNIT_TESTS_BUILD_ALL | This option if selected (default ON), generates the unit test and Gtest projects. |
| O3D3XX_DOXYGEN_DOCUMENTATION_GENERATE | If selected this option (default OFF), generates the doxygen documentation. For this option, please have a look at the software required for doxygen described in the section above. |
| O3D3XX_DOXYGEN_DOCUMENTATION_CHM | If selected this option (default ON), generates the doxygen documentation. For this option, please have a look at the software required for doxygen described in the section above. |
| O3D3XX_DOXYGEN_DOCUMENTATION_PDF | If selected this option (default OFF), generates the doxygen documentation. For this option, please have a look at the software required for doxygen described in the section above. |

- Click on "Generate".
- This will build a VS solution in the "build" folder.
- Open the VS Solution in VS.
- In VS is now a list "pf projects" which are created as –

ALL_BUILD - CMake project; do not touch

ZERO_CHECK - CMake project; do not touch
gtest - part of the gtest library
gtest_main - part of the gtest library
libxmlrpc - part of the open source XML-RPC library
libxmlrpc_client - part of the open source XML-RPC library
libxmlrpc_util - part of the open source XML-RPC library
libxmlrpc_xmlparse - part of the open source XML-RPC library
libxmlrpc_xmltok - part of the open source XML-RPC library
03D3xxCamera - Source plugin for the O3D3xx Camera
O3D3xxProc - Processing plugin for the O3D3xx Camera
SampleO3D3xxCamera - Sample code for using the O3D3xxCamera Class directly

You are now ready to build all the projects.



- After successful compilation of code,
 - i. If the doxygen documentation generation is selected, the technical reference document named "O3D3xx_Plugin.chm" and / or "O3D3xx_Plugin.pdf" shall be available at, "build/docs".
 - ii. The generated binaries shall be available at, "build/bin/<configuration_folder>".
 <configuration_folder> denotes the configuration by which you build the solution eg: Debug,
 Release etc.

NOTE:

For compiling boost library, make sure that your environment variables contain the path for following binaries.

i."cl.exe" - Generally found at " $(WIN_DIR)\Program Files\Microsoft Visual Studio 9.0\VC\bin\" folder. ii."mspdb80.dll" - Generally found at "<math>(WIN_DIR)\Program Files\Common Files\microsoft shared\VSA\9.0\VsaEnv" folder.$



8.3. Sample C code - shows usage of class functions via C code.

User application can directly access O3D3xx plugin class functions to connect/communicate to the camera. A sample C/C++ code is given to demonstrate the usage of O3D3xx plugin class functions.

8.3.1. Steps to use sample code:

- If your camera ip is 192.168.0.69, xmlrpc port is 80 and pcic port is 50010, then directly go to step 4.
- In solution window, open file "o3d3xx_camera_sample_usage_code.cpp" listed under "SampleO3D3xxCamera" project.
- Steps to change default camera ip address, xmlrpc port number and pcic port number
- If your camera ip address is not 192.168.0.69, then find following line of code: #define IP_ADDRESS_OF_CAMERA "192.168.0.69" then replace "192.168.0.69" with your camera's IP-Address.
- If your xmlrpc port number is not 80, then find following line of code: #define XMLRPC_PORT 80 then replace "80" with your xmlrpc port number.
- If your pcic port number is not 50010, then find following line of code, #define PCIC_PORT 50010 then replace "50010" with your pcic port number. After this save the solution.
- Compile the solution.
- After successfull compilation of project, the executable for sample C code shall be generated by name "SampleO3D3xxCamera.exe" at "build/bin/<configuration_folder>".<configuration_folder> denotes the configuration by which you build the solution. It could be Debug, Release etc.
- Double click at the executable. It shall demonstrate the configuration of the camera and receiving frames and image data.



9. XML-RPC command references

9.1. Main-Object

"getParameter"

| Method Name | getParameter |
|----------------------|--|
| Description | Getter for the device-global parameters |
| Input Parameters | Name of a device-parameter :string |
| Output Parameters | Value of the requested parameter :string |

"getAllParameters"

| Method Name | getAllParameters |
|----------------------|--|
| Description | Getter for the parameters described here: This is an additional getter outside of Edit-Sessions, so it is possible to read device informations without login. |
| Input Parameters | none |
| Output Parameters | Struct (name contains parameter-name, value the stringified parameter-value) |

"getSWVersion"

| Method Name | getSWVersion |
|----------------------|--|
| Description | Returns version-information of all software componenents |
| Input Parameters | none |
| Output Parameters | 1. Struct of strings (e.g. { "IFM_Software": "0.01.07", "Frontend": "01.05.02", }) *mandatory keys: "IFM_Software" "Linux" "Main_Application" "Diagnostic_Controller" "Algorithm_Version" "Calibration_Version" "Calibration_Device" |



"getHWInfo"

| Method Name | getHWInfo |
|-------------------|---|
| Description | Returns hardware-information of all components |
| Input Parameters | none |
| Output Parameters | Struct of strings (e.g. { "MACAddress": "00:02:01:40:06:C9", "Frontend": "#!01_F340_001", }) *mandatory keys: "MACAddress" "Connector" "Diagnose" "Frontend" "Illumination" "Mainboard" |

"getApplicationList"

| Method Name | |
|-------------------|--|
| | getApplicationList |
| Description | Delivers basic information of all Application stored on the device. This should be available before password-session, so the CombiGUI could display Sensor-screen before login. |
| Input Parameters | none |
| Output Parameters | 1. Array of structs (Index: int, Id: int, Name: string, Description: string) |



"requestSession"

| Method Name | requestSession |
|-------------------|---|
| Description | Request a session-object for access to the configuration and for changing device operating-mode. This should block parallel editing and allows to put editing behind password. The ID could optionally be defined from the external system, but it must be the defined format (32char "hex"). If it is called with only one parameter, the device will generate a SessionID. The session will start with a default timeout("SessionTimeout" device-parameter), the timeout can be extended by calling "heartbeat". The device will stay in RUN-mode. If password is disabled on the device, the value given as password-parameter is ignored. |
| Input Parameters | Password: string SessionID: string (optional) |
| Output Parameters | 1. SessionID: string |

"reboot"

| Method Name | reboot |
|----------------------|--|
| Description | Reboot system, parameter defines which mode/system will be booted |
| Input Parameters | type of system that should be booted after shutdown :int productive-mode recovery-mode |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"systemCommand"

| Method Name | systemCommand |
|----------------------|---|
| Description | Performs a generic command on the device. |
| Input Parameters | 1. Command :string 2. Parameter :string |
| Output Parameters | 1. Output :string |



9.2. Session-Object

"heartbeat"

| Method Name | heartbeat |
|-------------------|--|
| Description | Extend the live time of edit-session If the given value is outside the range of "SessionTimeout", the saved default timeout will be used. |
| Input Parameters | 1. requested timeout-interval till next heartbeat, in seconds :int |
| Output Parameters | 1. the used timeout-interval, in seconds :int |

"cancelSession

| Method Name | |
|--------------------------|---|
| | cancelSession |
| Description | Explicit stopping this session If an application is still in edit-mode, it will implicit do the same as "stopEditingApplication". |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"exportConfig"

| Method Name | |
|-------------------|--|
| | exportConfig |
| Description | exports the whole configuration of the sensor-device |
| Input Parameters | none |
| Output Parameters | 1. configuration as one data-blob :binary/base64 |



"importConfig"

| Method Name | |
|-------------------|---|
| | importConfig |
| Description | import whole configuration, with the option to skip specific parts |
| Input Parameters | 1. configuration as one data-blob :binary/base64 2. flags which parts should be loaded: 0x0001: Include Globale-Configuration (Name, Description, Location,) 0x0002: Include Network-Configuration (IP, DHCP,) 0x0010: Include All Application-Configurations |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"exportApplication"

| Method Name | |
|-------------------|---|
| | exportApplication |
| Description | exports one application-config |
| Input Parameters | 1. Application Index |
| Output Parameters | 1. application-config as one data-blob :binary/base64 |

"importApplication"

| Method Name | importApplication |
|-------------------|--|
| Description | imports an application-config and creates a new application with it. The name of the application should be based on the one stored in the exported-config. If the name should be unique, the sensor must generate an suffix in case of a naming conflict. The device will give a new ID, if there is an ID inside the config-data it must be ignored. The device will put the new application on the first free Index. |
| Input Parameters | 1. application-config as one-data-blob: binary/base64 |
| Output Parameters | 1. Index of new application |

"setOperatingMode"

| Method Name | setOperatingMode |
|-------------------|--|
| Description | Changes the operation mode of the device. Setting this to "edit" will enable the "EditMode"-object on RPC. |
| Input Parameters | 1. mode :int 0: run mode 1: edit mode |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |



9.3. EditMode-Object

"factoryReset"

| Method Name | |
|-------------------|---|
| | factoryReset |
| Description | sets all configurations back to "werkseinstellungen" |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

Note: A factory reset will delete all applications which are saved on the camera.

"editApplication"

| Method Name | editApplication |
|-------------------|---|
| Description | Puts a specified Application into edit-status. This will attach an application-object to the RPC interface. The name of the object will be application independent. This does not change the "ActiveApplication"-parameter. |
| Input Parameters | 1. Application index :int |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"stopEditingApplication"

| Method Name | |
|-------------------|--|
| | stopEditingApplication |
| Description | Tells the device that editing this application was finished. Unsaved changed should be discard. HINT: The device must also call this implicit, when a edit-session timed out or was closed by "cancelSession". |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"createApplication"

| Method Name | createApplication |
|--------------------------|---|
| Description | Creates an "empty" application. The embedded side should initialize all needed parameters and structures. Such an application might be in an non-activatable state, this means it could be saved on the device, but not set as active application. |
| Input Parameters | none |
| Output Parameters | 1. Index of new application :int |



"copyApplication"

| Method Name | |
|-------------------|--|
| | copyApplication |
| Description | Creates a new application by copying the configuration of another application. The device will generate an ID for the new application and put it on a free Index. |
| Input Parameters | 1. Index of the application which should be copied :int |
| Output Parameters | 1. Index of new application :int |

"deleteApplication"

| Method Name | deleteApplication |
|-------------------|---|
| Description | Deletes the application form sensor If the deleted application was the active one, the sensor will have no active application anymore until the user picks one. (O2V-behavior) |
| Input Parameters | 1. Index of application :int |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"changeNameAndDescription" must be implemented in Edit-API

| Method Name | changeNameAndDescription |
|-------------------|--|
| Description | |
| Input Parameters | Application index :int new name of the application: string(utf8, max. 64 character) new description of the application: string(utf8, max. 500 character) |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"moveApplications" must be implemented in Edit-API

| Method Name | moveApplications |
|-------------------|--|
| Description | Moves applications to other Index. There must be all applications in the new list, none of them duplicated and no Index used twice. The ID is a fixed value that stays the same as long as the application stays on the sensor. The Index could be changed and is used to address the application via PCIC, XML-RPC and Digital-IO. |
| Input Parameters | 1. Array of structs (Id :int, Index :int) |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |



9.4. DeviceConfig-Object

"activatePassword"

| Method Name | activatePassword |
|-------------------|---|
| Description | Set a password and activate it for the next edit-session. Making this change presistant requires to call "save" on the DeviceConfig. |
| Input Parameters | 1. Password :string |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"disablePassword"

| Method Name | disablePassword |
|-------------------|---|
| Description | Disables the password-protection. Making this change presistant requires to call "save" on the DeviceConfig. |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"save"

| Method Name | |
|-------------------|--|
| | save |
| Description | Store current configuration in persistent memory. If this is not called after changing device-parameters (via setParameter), changes will get lost on reboot. |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |



9.4.1 Parameters

Parameters of DeviceConfig

Methods for parameter access are defined here:

| Parameter Name | Data Type | Description | |
|---------------------------|--------------------|---|--|
| Name | string (utf8) | User defined name of the device. (max. 64 characters) | |
| Description | string (utf8) | User defined description of the device. (max. 500 characters) | |
| ActiveApplication | int *has limits | Index of active Application This effects only RUN-mode: * defines the application active on startup (if static-application-switching is disabled) * contains the current active application (could also be changed via PCIC-command) * 0 means there is no application active (see SYRS 660606-3530) | |
| PcicTcpPort | int | TCP/IP-Port for PCIC-connections. | |
| PcicProtocolVersion | int *has limits | Sub Protocol of PCIC, see specification of PCIC: | |
| IOLogicType | int *has limits | Defines logic-type of all digital-pins. Allowed values: 0: NPN 1: PNP | |
| IODebouncing | bool | Applies to all inputs | |
| IOExternApplicationSwitch | int *has limits | Allowed values: 0: off 1: static via I/O 2: pulse driven via I/O 3: pulse driven via trigger | |
| SessionTimeout | int *has limits | number of seconds which a session stays before a call to "heartbeat"-method is needed | |
| ExtrinsicCalibTransX | double | Extrinsic calibration, Transition in X direction | |
| ExtrinsicCalibTransY | double | Extrinsic calibration, Transition in Y direction | |
| ExtrinsicCalibTransZ | double | Extrinsic calibration, Transition in Z direction | |
| ExtrinsicCalibRotX | double | Extrinsic calibration, Rotation around X-axis | |
| ExtrinsicCalibRotY | double | Extrinsic calibration, Rotation around Y-axis | |
| ExtrinsicCalibRotZ | double | Extrinsic calibration, Rotation around Z-axis | |
| IPAddressConfig | int | readonly, The GUI requires to know if the device is on a Discovery-IP-address for multiple usecases. This information was extended to reflect all kinds of IP-address situations. Allowed values: 0: static (IP-address explicit defined inside the device) 1: DHCP (using a DHCP-server in the network) 2: LinkLocal (configured to DHCP, but no server which provided an address) 3: Discovery (changed by IP4Discovery mechanism) | |



| PasswordActivated | bool | readonly, is true if the password-protection is enabled |
|-------------------------|--------|---|
| OperatingMode | int | readonly, mode of device (RUN, EDIT) see "setOperatingMode" (the setter is outside of edit-mode, but inside of session) |
| DeviceType | string | readonly, Delivers a type description, unique by imager, evaluation-logic and device-interface Format could be like this: "[VendorID]:[TypeID]" e.g. "1:42" |
| ArticleNumber | string | readonly, Official catalog-number |
| ArticleStatus | string | readonly, Official two-letter status code |
| UpTime | double | readonly, Hours since last reboot |
| ImageTimestampReference | int | readonly, The image-data contains a timestamp (32bit int, μ s) This should return the current timestamp as a reference to the images received. |
| TemperatureFront1 | double | readonly , Temperature measured in the device, value is in degree Celsius. Measured by first sensor on imager board. |
| TemperatureFront2 | double | readonly , Temperature measured in the device, value is in degree Celsius. Measured by second sensor on imager board. |
| TemperatureIMX6 | double | readonly , Temperature measured in the device, value is in degree Celsius. Measured inside the main CPU. |
| TemperatureIllu | double | readonly , Temperature measured in the device, value is in degree Celsius. Measured on the illumination board. |

^{*}has limits: parameters with this marker are listed in the reply of getAllParameterLimits-method

Default values of DeviceConfig parameters

The default values of the device configuration parameters are:

| Parameter Name | Data Type | Default Value |
|---------------------------|------------------|---------------|
| Name | string (utf8) | "New sensor" |
| Description | string (utf8) | "" |
| ActiveApplication | int | 0 |
| PcicTcpPort | int | 50010 |
| PcicProtocolVersion | int | 3 |
| IOLogicType | int | 1 |
| | | |
| IODebouncing | bool | true |
| IOExternApplicationSwitch | int | 0 |
| SessionTimeout | int | 30 |



| ExtrinsicCalibTransX | double | 0.0 |
|----------------------|--------|-------|
| ExtrinsicCalibTransY | double | 0.0 |
| ExtrinsicCalibTransZ | double | 0.0 |
| ExtrinsicCalibRotX | double | 0.0 |
| ExtrinsicCalibRotY | double | 0.0 |
| ExtrinsicCalibRotZ | double | 0.0 |
| IPAddressConfig | int | 0 |
| PasswordActivated | bool | false |
| OperatingMode | int | 0 |

For all other DeviceConfig parameters there are no defined default values because they are either device-dependent (DeviceType, ArticleNumber, ArticleStatus) or volatile (UpTime, ImageTimestampReference).



Minimum and maximum values of DeviceConfig parameters

The minimum and maximum values of the device configuration parameters are:

| Parameter Name | Minimum Value | Maximum Value |
|---------------------------|---------------|---------------|
| ActiveApplication | 0 | 32 |
| PcicProtocolVersion | 1 | 4 |
| IOLogicType | 0 | 1 |
| IOExternApplicationSwitch | 0 | 3 (C2: 0) |
| SessionTimeout | 5 | 300 |



9.5. Device/NetworkConfig-Object

"saveAndActivateConfig"

| Method Name | saveAndActivateConfig |
|-------------------|--|
| Description | Reinitialize the network interface so that it uses the configuration which was set by the other RPC-methods. There will be no XMLRPC-replay, because the network-interface is instantly reset. This must also close the session, as there is no clean way of closing it. |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

9.6. ApplicationConfig-Object

"save"

| Method Name | save |
|--------------------------|---|
| Description | stores current configuration in persistent memory. This should also be possible if the application is not yet in an "activatable" status. |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"forceTrigger"

| Method Name | |
|-------------------|---|
| | forceTrigger |
| Description | Do a software-trigger of current active application |
| Input Parameters | none |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |



9.6.1. Parameters

Parameters of Application

Methods for parameter access are defined here:

| Parameter Name | Data Type | Description |
|----------------------------|-----------------------|--|
| Name | string (utf8) | User defined name of the application. (max. 64 characters) |
| Description | string (utf8) | User defined description of the application. (max. 500 characters) |
| TriggerMode | int *has limits | Allowed values: 1: free run 2: process interface |
| PcicTcpResultOutputEnabled | bool | Allows to disable the automatic output of results via PCIC. If it is false, PCIC-commands could be used to access the data again. |
| PcicTcpResultSchema | string | The Schema defines which images and result-data will be send. It will also define the order of data-elements and additional separators. Contains single-enabling/-disabling of AmplitudeImage, IntensityImage, DistanceImage, XImage, YImage, ZImage, ConfidenceImage, DiagnosticData |

^{*}has limits: parameters with this marker are listed in the reply of getAllParameterLimits-method

Default values of application parameters

The default values of application parameters are:

| Parameter Name | Data Type | Default Value |
|----------------------------|------------------|-------------------|
| Name | string (utf8) | "New application" |
| Description | string (utf8) | ···· |
| TriggerMode | int | 1 |
| PcicTcpResultOutputEnabled | bool | true |
| PcicTcpResultSchema | string | ···· |



Minimum and maximum values of application parameters
The minimum and maximum values of application parameters are:

| Parameter Name | Minimum Value | Maximum Value |
|----------------|---------------|---------------|
| TriggerMode | 1 | 4 (C2: 2) |



9.7. App./ImgagerConfig-Object

"changeType"

| Method Name | |
|-------------------|---|
| | changeType |
| Description | Changes the type of imager-configuration. This changes the set of available parameters and might also change available RPC-methods. |
| Input Parameters | 1. type :string |
| Output Parameters | 1. empty-string (compatibility for classic XmIRPC-Client) |

"availableTypes"

| Method Name | |
|-------------------|---|
| | availableTypes |
| Description | Lists all available imager-configuration types. |
| Input Parameters | none |
| Output Parameters | 1. Array of strings |



9.7.1. Parameters

Parameters of all types of Application-ImagerConfig

Methods for parameter access are defined here:

| Parameter Name | Data Type | Description | |
|--------------------------|--------------------|--|--|
| Туре | string | readonly, Type of Imager-Configuration, see changeType method | |
| FrameRate | double *has limits | Target frame rate in frames per second for free run mode. | |
| ClippingLeft | int *has limits | Clipping-Area lower value in width-dimension | |
| ClippingTop | int *has limits | Clipping-Area lower value in height-dimension | |
| ClippingRight | int *has limits | Clipping-Area upper value in width-dimension | |
| ClippingBottom | int *has limits | Clipping-Area upper value in height-dimension | |
| ReduceMotionArtifacts | bool | enables a filtering for motion-artifacts. Not implemented for C2 samples. | |
| SpatialFilterType | int *has limits | Allowed values: 0: off 1: Median-filter | |
| AverageFilterNumPictures | int *has limits | Number of pictures to use for average filter Filter will be active if is unique 1. | |

^{*}has limits: parameters with this marker are listed in the reply of getAllParameterLimits-method

Default values of common ImagerConfig parameters. The default values of the common imager configuration parameters are:

| Parameter Name | Data Type | Default Value |
|--------------------------|-----------|---------------|
| Туре | string | "under5m_low" |
| FrameRate | double | 5.0 |
| ClippingLeft | int | 0 |
| ClippingTop | int | 0 |
| ClippingRight | int | 175 |
| ClippingBottom | int | 131 |
| ReduceMotionArtifacts | bool | false |
| SpatialFilterType | int | 0 |
| AverageFilterNumPictures | int | 1 |



Minimum and maximum values of common ImagerConfig parameters

The minimum and maximum values of the common imager configuration parameters are:

| Parameter Name | Minimum Value | Maximum Value |
|--------------------------|------------------|---------------|
| FrameRate | 0.0167 | 100.0 |
| ClippingLeft | 0 | 175 (C2: 0) |
| ClippingTop | 0 | 131 (C2: 0) |
| ClippingRight | 0 (C2: 175) | 175 |
| ClippingBottom | 0 (C2: 131) | 131 |
| SpatialFilterType | 0 | 4 (C2: 1) |
| AverageFilterNumPictures | 1 | 25 (C2: 1) |

Parameters only in "under5m_low"-type of Application-ImagerConfig

| Parameter Name | Data Type | Description |
|----------------|--------------------|-----------------------|
| ExposureTime | int *has limits | Time for the Exposure |

Default values of the "under5m_low" mode parameters

| Parameter Name | Data Type | Default Value |
|----------------|-----------|---------------|
| ExposureTime | int | 1905 |
| Channel | int | 0 |

Minimum and maximum values of the "under5m_low" mode parameters

| Parameter Name | Minimum Value | Maximum Value |
|----------------|---------------|---------------|
| ExposureTime | 0 | 17476 |
| Channel | -1 (C2 0) | 3 (C2 0) |

Parameters only in "under5m_moderate"-type of Application-ImagerConfig

| Parameter Name | Data Type | Description |
|----------------|-----------------|--|
| ExposureTime | int *has limits | Time for the long Exposure The 2nd ExposureTime will be calculated based on the first one. |

Default values of the "under5m_moderate" mode parameters

| Parameter Name | Data Type | Default Value |
|----------------|-----------|---------------|
| ExposureTime | int | 1905 |
| Channel | int | 0 |



Minimum and maximum values of the "under5m_moderate" mode parameters

| Parameter Name | Minimum Value | Maximum Value |
|----------------|---------------|---------------|
| ExposureTime | 0 | 17476 |
| Channel | -1 (C2 0) | 3 (C2 0) |



10. Process Interface command reference

Note: All received messages which are send because of the following commands, will be send without "start"/"stop" at the beginning or ending of the string.

t command

| command | t | | |
|-------------|--|--|--|
| description | execute trigger and send process data asynchronously | | |
| type | action | | |
| reply | * | trigger was executed, the device captures an image and evaluates the result | |
| | ! | device is busy with an evaluation device is in an invalid state for this command, e.g. configuration mode device is set to a different trigger source no active application | |

I? command

| command | I <image-id>?</image-id> | |
|-------------|--|---|
| description | request last image taken | |
| type | request | |
| reply | <length><image data=""/></length> | |
| | ! | no image availablewrong ID |
| | ? | invalid command length |
| note | <image-id> </image-id> 2 digits for the image type <length> </length> char string with exact 9 digits as decimal number for the image data size in bytes <image data=""/> image data | Valid image ID: ID O1: Amplitude image O2: not fully implemented O3: Distance image O4: Distance cartesian x image O5: Distance cartesian y image O6: Distance cartesian z image O7: not fully implemented O8: not fully implemented O9: not fully implemented O9: not fully implemented |



| | 11: not fully implemented |
|--|---------------------------|
| | |

p command

| command | p <state></state> | |
|-------------|---|---|
| description | turns the PCIC output on or off, no images will be send from the camera in free run mode or as an answer of a trigger | |
| type | action | |
| reply | * | |
| | ! | <state> contains wrong value</state> device is in an invalid state for this command, e.g. configuration mode |
| | ? | invalid command length |
| note | <state> 1 digit</state>0 deactivate1 activate | at device restart the value configured within the application is essential for the output of data |

V? command

| command | V? |
|-------------|--|
| description | request current protocol version |
| type | request |
| reply | <pre><current version=""><emtpy><min version=""><emtpy><max version=""></max></emtpy></min></emtpy></current></pre> |
| note | <ur> <current version=""> 2 digits for the current set version</current> <empty> space sign: 0x20</empty> <min max="" version=""> 2 digits for the min and max available version to set</min> </ur> |



v command

| command | v <version></version> | |
|-------------|---|-----------------|
| description | set the current protocoll verstion. The device configuration is not afected | |
| type | action | |
| reply | * | |
| | ! | invalid version |
| note | <version></version>2 digits for the protocol version | |

Note: The default protocolversion is "V3". Do not use the other versions for the C2 sample.



G? command

| command | G? | |
|-------------|--|--|
| description | request device information | |
| type | request | |
| reply | <vendor><t><article number><t><name><t><location><t><description><t><ip> <subnet mask><t><gateway><t><mac><t><dhcp><t><port number></port </t></dhcp></t></mac></t></gateway></t></subnet </ip></t></description></t></location></t></name></t></article </t></vendor> | |
| note | <vendor> IFM ELECTRONIC</vendor> <t> Tabulator (0x09)</t> <article number=""> e.g. O3D300</article> <name> UTF8 Unicocde string</name> <location> UTF8 Unicocde string</location> <description> UTF8 Unicocde string</description> <ip> IP-Adresse des Geräts als ASCII-Zeichenkette</ip> <subnet mask=""> subnet mask of the device as ASCII</subnet> <gateway> Gateway> Gateway of the device as ASCII</gateway> <mac> MAC of the device as ASCII</mac> <dhcp> ASCII string "0" for off and "1" for on</dhcp> | |

H? command

| command | H? | |
|-------------|---|--|
| description | returns a list with available commands | |
| type | request | |
| reply | H? - show this list t - execute Trigger T? - execute Trigger and wait for data I <image-id>? - get last image of defined type V? - get current protocol version v<version> - set protocol version G? - show device information</version></image-id> | |