

1. Description

1.1. Project

Project Name	ldrfixedDiscoveryF4
Board Name	STM32F407G-DISC1
Generated with:	STM32CubeMX 6.12.1
Date	01/09/2025

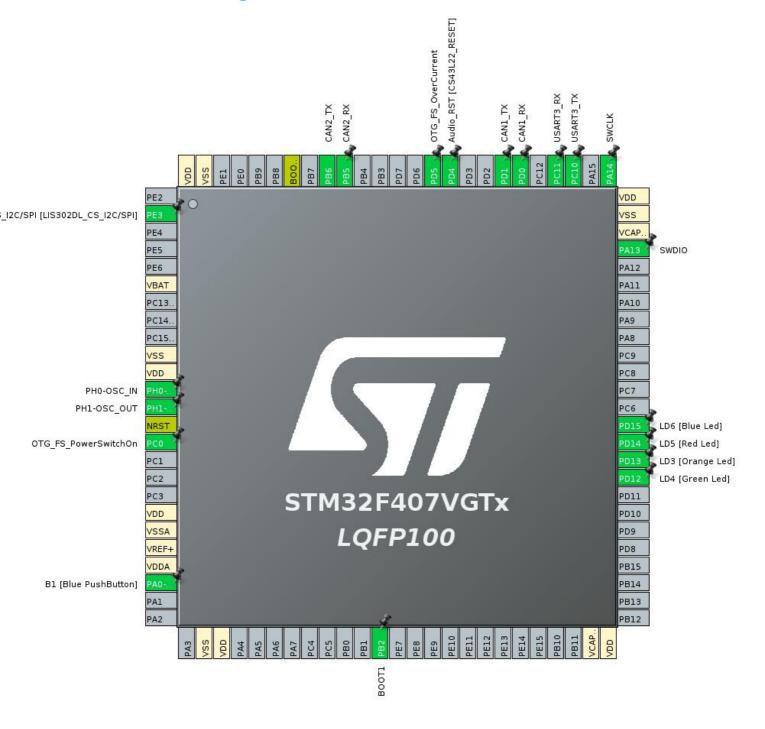
1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F407/417
MCU name	STM32F407VGTx
MCU Package	LQFP100
MCU Pin number	100

1.3. Core(s) information

Core(s)	Arm Cortex-M4

2. Pinout Configuration



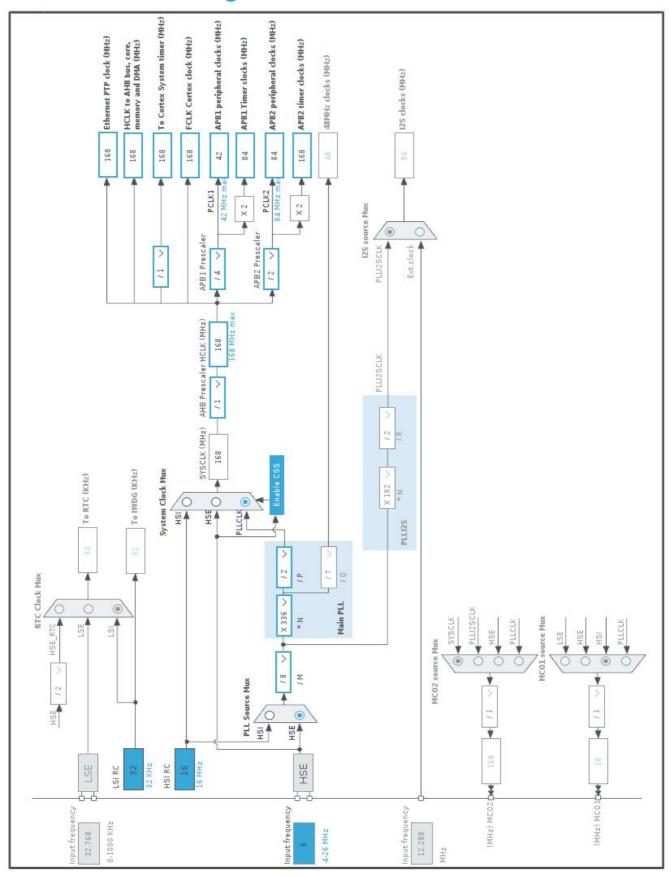
3. Pins Configuration

Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP100	(function after		Function(s)	
	reset)		(0)	
2	PE3 *	I/O	GPIO_Output	CS_I2C/SPI
2	1 23	1/0	Of 10_Output	[LIS302DL_CS_I2C/SPI]
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
12	PH0-OSC_IN	I/O	RCC_OSC_IN	PH0-OSC_IN
13	PH1-OSC_OUT	I/O	RCC_OSC_OUT	PH1-OSC_OUT
14	NRST	Reset		
15	PC0 *	I/O	GPIO_Output	OTG_FS_PowerSwitchOn
19	VDD	Power		
20	VSSA	Power		
21	VREF+	Power		
22	VDDA	Power		
23	PA0-WKUP	I/O	GPIO_EXTI0	B1 [Blue PushButton]
27	VSS	Power		
28	VDD	Power		
37	PB2 *	I/O	GPIO_Input	BOOT1
49	VCAP_1	Power		
50	VDD	Power		
59	PD12 *	I/O	GPIO_Output	LD4 [Green Led]
60	PD13 *	I/O	GPIO_Output	LD3 [Orange Led]
61	PD14 *	I/O	GPIO_Output	LD5 [Red Led]
62	PD15 *	I/O	GPIO_Output	LD6 [Blue Led]
72	PA13	I/O	SYS_JTMS-SWDIO	SWDIO
73	VCAP_2	Power		
74	VSS	Power		
75	VDD	Power		
76	PA14	I/O	SYS_JTCK-SWCLK	SWCLK
78	PC10	I/O	USART3_TX	
79	PC11	I/O	USART3_RX	
81	PD0	I/O	CAN1_RX	
82	PD1	I/O	CAN1_TX	
85	PD4 *	I/O	GPIO_Output	Audio_RST [CS43L22_RESET]
86	PD5 *	I/O	GPIO_Input	OTG_FS_OverCurrent
91	PB5	I/O	CAN2_RX	
	-		-	•

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
92	PB6	I/O	CAN2_TX	
94	воото	Boot		
99	VSS	Power		
100	VDD	Power		

^{*} The pin is affected with an I/O function

4. Clock Tree Configuration



1. Power Consumption Calculator report

1.1. Microcontroller Selection

Series	STM32F4
Line	STM32F407/417
MCU	STM32F407VGTx
Datasheet	DS8626_Rev8

1.2. Parameter Selection

Temperature	25
Vdd	3.3

1.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

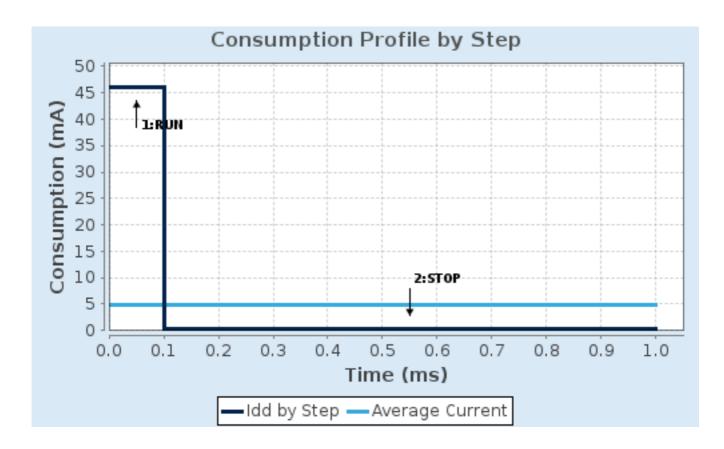
1.4. Sequence

Step	Step1	Step2
Mode	RUN	STOP
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	FLASH	n/a
CPU Frequency	168 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	46 mA	280 μΑ
Duration	0.1 ms	0.9 ms
DMIPS	210.0	0.0
Ta Max	98.47	104.96
Category	In DS Table	In DS Table

1.5. Results

Sequence Time	1 ms	Average Current	4.85 mA
Battery Life	29 days, 4 hours	Average DMIPS	210.0 DMIPS

1.6. Chart



2. Software Project

2.1. Project Settings

Name	Value
Project Name	ldrfixedDiscoveryF4
Project Folder	/home/deh/GliderWinchItems/CANloader1/ldrfixedDiscoveryF4
Toolchain / IDE	Makefile
Firmware Package Name and Version	STM32Cube FW_F4 V1.28.1
Application Structure	Advanced
Generate Under Root	No
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

2.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power consumption)	No
Enable Full Assert	No

2.3. Advanced Settings - Generated Function Calls

Rank	Function Name	Peripheral Instance Name
1	SystemClock_Config	RCC
2	MX_GPIO_Init	GPIO
3	MX_CAN1_Init	CAN1
4	MX_USART3_UART_Init	USART3
5	MX_CAN2_Init	CAN2
6	MX_CRC_Init	CRC
7	MX_WWDG_Init	WWDG

3. Peripherals and Middlewares Configuration

500000 *

3.1. CAN1

mode: Activated

3.1.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 12 *

Time Quantum 285.7142857142857 *

Time Quanta in Bit Segment 1 5 Times *

Time Quanta in Bit Segment 2 1 Time
Time for one Bit 2000 *

ReSynchronization Jump Width 1 Time

Basic Parameters:

Baud Rate

Time Triggered Communication Mode

Automatic Bus-Off Management

Automatic Wake-Up Mode

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Disable

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

3.2. CAN2

mode: Activated

3.2.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 12 *

Time Quantum 285.7142857142857 *

Time Quanta in Bit Segment 1 5 Times *

Time Quanta in Bit Segment 2 1 Time

Time for one Bit 2000 *

Baud Rate 500000 *

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode

Automatic Bus-Off Management

Disable

Automatic Wake-Up Mode

Disable

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Disable

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

3.3. CRC

mode: Activated

3.4. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

3.4.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Enabled
Data Cache Enabled

Flash Latency(WS) 5 WS (6 CPU cycle)

RCC Parameters:

HSI Calibration Value 16
HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

Power Parameters:

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

3.5. SYS

Debug: Serial Wire

Timebase Source: SysTick

3.6. USART3

Mode: Asynchronous

3.6.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

3.7. **WWDG**

mode: Activated

3.7.1. Parameter Settings:

Watchdog Clocking:

WWDG counter clock prescaler 1
WWDG window value 64
WWDG free-running downcounter value 64

Watchdog Interrupt:

Early wakeup interrupt Disable

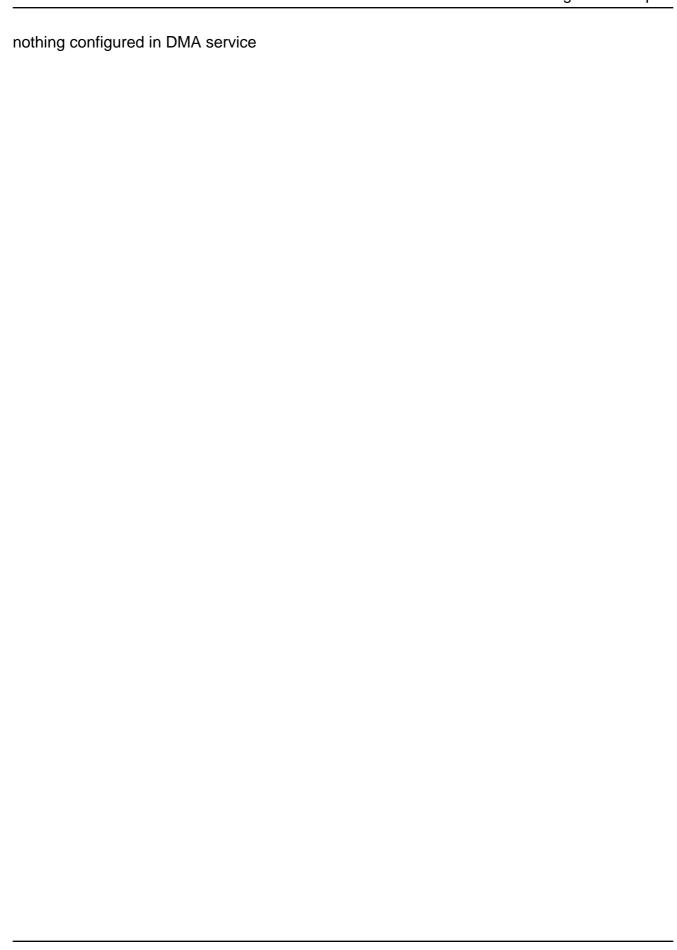
^{*} User modified value

4. System Configuration

4.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label	
CAN1	PD0	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High		
	PD1	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High		
CAN2	PB5	CAN2_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High		
	PB6	CAN2_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	ligh	
RCC	PH0- OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	PH0-OSC_IN	
	PH1- OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	PH1-OSC_OUT	
SYS	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	SWDIO	
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	SWCLK	
USART3	PC10	USART3_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	• •	
	PC11	USART3_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	gh	
GPIO	PE3	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	CS_I2C/SPI [LIS302DL_CS_I2C/SPI]	
	PC0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	OTG_FS_PowerSwitchOn	
	PA0-WKUP	GPIO_EXTI0	External Interrupt Mode with Rising edge trigger detection	No pull-up and no pull-down	n/a	B1 [Blue PushButton]	
	PB2	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	BOOT1	
	PD12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD4 [Green Led]	
	PD13	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD3 [Orange Led]	
	PD14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD5 [Red Led]	
	PD15	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LD6 [Blue Led]	
	PD4	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	Audio_RST [CS43L22_RESET]	
	PD5	GPIO_Input	Input mode	No pull-up and no pull-down	n/a	OTG_FS_OverCurrent	

4.2. DMA configuration



4.3. NVIC configuration

4.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Pre-fetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	0	0	
System tick timer	true	0	0	
CAN1 TX interrupts	true	5	0	
CAN1 RX0 interrupts	true	5	0	
CAN1 RX1 interrupt	true	5	0	
USART3 global interrupt	true	5	0	
CAN2 TX interrupts	true	0	0	
CAN2 RX0 interrupts	true	0	0	
CAN2 RX1 interrupt	true	0	0	
Window watchdog interrupt	unused			
PVD interrupt through EXTI line 16	unused			
Flash global interrupt	unused			
RCC global interrupt	unused			
EXTI line0 interrupt	unused			
CAN1 SCE interrupt	unused			
CAN2 SCE interrupt	unused			
FPU global interrupt		unused		

4.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	false	true	false
Hard fault interrupt	false	true	false
Memory management fault	false	true	false
Pre-fetch fault, memory access fault	false	true	false
Undefined instruction or illegal state	false	true	false
System service call via SWI instruction	false	true	false
Debug monitor	false	true	false
Pendable request for system service	false	true	false
System tick timer	false	true	true

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler	
CAN1 TX interrupts	false	true	true	
CAN1 RX0 interrupts	false	true	true	
CAN1 RX1 interrupt	false	true	true	
USART3 global interrupt	false	true	true	
CAN2 TX interrupts	false	true	true	
CAN2 RX0 interrupts	false	true	true	
CAN2 RX1 interrupt	false	true	true	

^{*} User modified value

5. System Views

5.1. Category view

5.1.1. Current

			Middleware			
System Core	Analog	Timers	Connectivity	Multimedia	Security	Computing
	·				,	
DMA			CAN1 ♥			CRC ⊘
GPIO ⊘			CAN2 🔮			
NVIC ♥			USART3 ⊘			
RCC ♥						
SYS ♥						
WWDG ♥						

6. Docs & Resources

Type Link

BSDL files https://www.st.com/resource/en/bsdl_model/stm32f405-415_407-

417_bsdl.zip

IBIS models https://www.st.com/resource/en/ibis_model/stm32f405-415_407-

417_ibis.zip

System View https://www.st.com/resource/en/svd/stm32f4-svd.zip

Description

Presentations https://www.st.com/resource/en/product_presentation/stm32-

stm8_embedded_software_solutions.pdf

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tools_portfolio.pdf

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Brochures https://www.st.com/resource/en/brochure/products-and-solutions-for-plcs-

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guide-for-stm8-stm32-and-legacy-mcus-stmicroelectronics.pdf

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- Application Notes https://www.st.com/resource/en/application_note/an3070-managing-the-driver-enable-signal-for-rs485-and-iolink-communications-with-the-stm32s-usart-stmicroelectronics.pdf
- Application Notes https://www.st.com/resource/en/application_note/an3126-audio-and-waveform-generation-using-the-dac-in-stm32-products-stmicroelectronics.pdf
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