

1. Description

1.1. Project

Project Name	drum
Board Name	custom
Generated with:	STM32CubeMX 6.0.1
Date	09/09/2020

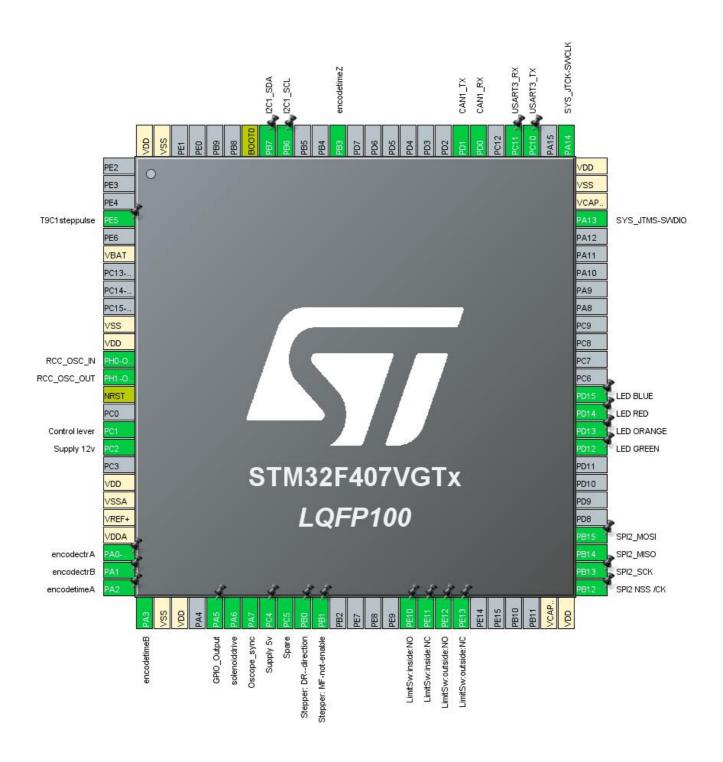
1.2. MCU

MCU Series	STM32F4
MCU Line	STM32F407/417
MCU name	STM32F407VGTx
MCU Package	LQFP100
MCU Pin number	100

1.3. Core(s) information

Core(s)	Arm Cortex-M4	

2. Pinout Configuration



3. Pins Configuration

Pin Number	Pin Name	Pin Type	Alternate	Label
LQFP100	(function after		Function(s)	
	reset)			
4	PE5	I/O	TIM9_CH1	T9C1steppulse
6	VBAT	Power		
10	VSS	Power		
11	VDD	Power		
12	PH0-OSC_IN	I/O	RCC_OSC_IN	
13	PH1-OSC_OUT	I/O	RCC_OSC_OUT	
14	NRST	Reset		
16	PC1	I/O	ADC1_IN11	Control lever
17	PC2	I/O	ADC1_IN12	Supply 12v
19	VDD	Power		
20	VSSA	Power		
21	VREF+	Power		
22	VDDA	Power		
23	PA0-WKUP	I/O	TIM5_CH1	encodectrA
24	PA1	I/O	TIM5_CH2	encodectrB
25	PA2	I/O	TIM2_CH3	encodetimeA
26	PA3	I/O	TIM2_CH4	encodetimeB
27	VSS	Power		
28	VDD	Power		
30	PA5 *	I/O	GPIO_Output	
31	PA6	I/O	TIM13_CH1	solenoiddrive
32	PA7	I/O	TIM14_CH1	Oscope_sync
33	PC4	I/O	ADC1_IN14	Supply 5v
34	PC5	I/O	ADC1_IN15	Spare
35	PB0 *	I/O	GPIO_Output	Stepper: DRdirection
36	PB1 *	I/O	GPIO_Output	Stepper: MF-not-enable
41	PE10	I/O	GPIO_EXTI10	LimitSw:inside:NO
42	PE11	I/O	GPIO_EXTI11	LimitSw:inside:NC
43	PE12	I/O	GPIO_EXTI12	LimitSw:outside:NO
44	PE13	I/O	GPIO_EXTI13	LimitSw:outside:NC
49	VCAP_1	Power		
50	VDD	Power		
51	PB12 *	I/O	GPIO_Output	SPI2 NSS /CK
52	PB13	I/O	SPI2_SCK	
53	PB14	I/O	SPI2_MISO	
54	PB15	I/O	SPI2_MOSI	

Pin Number LQFP100	Pin Name (function after reset)	Pin Type	Alternate Function(s)	Label
59	PD12 *	I/O	GPIO_Output	LED GREEN
60	PD13 *	I/O	GPIO_Output	LED ORANGE
61	PD14 *	I/O	GPIO_Output	LED RED
62	PD15 *	I/O	GPIO_Output	LED BLUE
72	PA13	I/O	SYS_JTMS-SWDIO	
73	VCAP_2	Power		
74	VSS	Power		
75	VDD	Power		
76	PA14	I/O	SYS_JTCK-SWCLK	
78	PC10	I/O	USART3_TX	
79	PC11	I/O	USART3_RX	
81	PD0	I/O	CAN1_RX	
82	PD1	I/O	CAN1_TX	
89	PB3	I/O	TIM2_CH2	encodetimeZ
92	PB6	I/O	I2C1_SCL	
93	PB7	I/O	I2C1_SDA	
94	BOOT0	Boot		
99	VSS	Power		
100	VDD	Power		

^{*} The pin is affected with an I/O function

4. Clock Tree Configuration



5. Software Project

5.1. Project Settings

Name	Value
Project Name	drum
Project Folder	/home/deh/GliderWinchItems/drum
Toolchain / IDE	Makefile
Firmware Package Name and Version	STM32Cube FW_F4 V1.25.0
Application Structure	Basic
Generate Under Root	No
Do not generate the main()	No
Minimum Heap Size	0x200
Minimum Stack Size	0x400

5.2. Code Generation Settings

Name	Value
STM32Cube MCU packages and embedded software	Copy all used libraries into the project folder
Generate peripheral initialization as a pair of '.c/.h' files	No
Backup previously generated files when re-generating	No
Keep User Code when re-generating	Yes
Delete previously generated files when not re-generated	Yes
Set all free pins as analog (to optimize the power	No
consumption)	
Enable Full Assert	No

5.3. Advanced Settings - Generated Function Calls

Rank	Function Name	IP Instance Name
1	MX_GPIO_Init	GPIO
2	MX_DMA_Init	DMA
3	SystemClock_Config	RCC
4	MX_CAN1_Init	CAN1
5	MX_ADC1_Init	ADC1
6	MX_SPI2_Init	SPI2
7	MX_USART3_UART_Init	USART3
8	MX_I2C1_Init	I2C1
9	MX_TIM2_Init	TIM2
10	MX_TIM5_Init	TIM5
11	MX_TIM9_Init	TIM9

Rank	Function Name	IP Instance Name
12	MX_TIM4_Init	TIM4
13	MX_TIM13_Init	TIM13
14	MX_TIM14_Init	TIM14

6. Power Consumption Calculator report

6.1. Microcontroller Selection

Series	STM32F4
Line	STM32F407/417
MCU	STM32F407VGTx
Datasheet	DS8626_Rev8

6.2. Parameter Selection

Temperature	25
Vdd	3.3

6.3. Battery Selection

Battery	Li-SOCL2(A3400)
Capacity	3400.0 mAh
Self Discharge	0.08 %/month
Nominal Voltage	3.6 V
Max Cont Current	100.0 mA
Max Pulse Current	200.0 mA
Cells in series	1
Cells in parallel	1

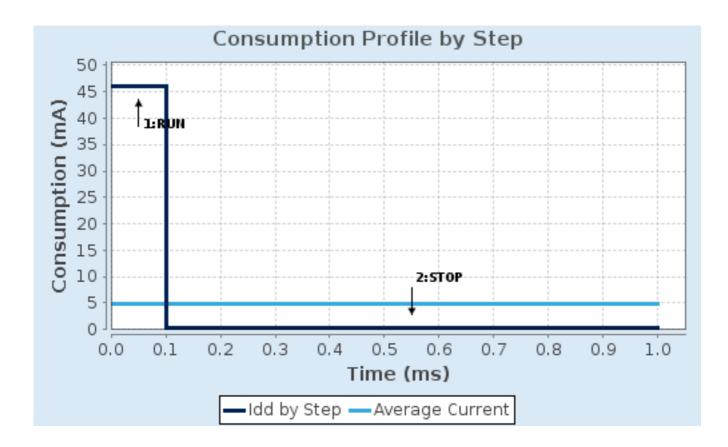
6.4. Sequence

Step	Step1	Step2
Mode	RUN	STOP
Vdd	3.3	3.3
Voltage Source	Battery	Battery
Range	Scale1-High	No Scale
Fetch Type	FLASH	n/a
CPU Frequency	168 MHz	0 Hz
Clock Configuration	HSE PLL	Regulator LP Flash-PwrDwn
Clock Source Frequency	4 MHz	0 Hz
Peripherals		
Additional Cons.	0 mA	0 mA
Average Current	46 mA	280 μΑ
Duration	0.1 ms	0.9 ms
DMIPS	210.0	0.0
Ta Max	98.47	104.96
Category	In DS Table	In DS Table

6.5. Results

Sequence Time	1 ms	Average Current	4.85 mA
Battery Life	29 days, 4 hours	Average DMIPS	210.0 DMIPS

6.6. Chart



7. IPs and Middleware Configuration

7.1. ADC1 mode: IN11 mode: IN12 mode: IN14 mode: IN15

mode: Temperature Sensor Channel

mode: Vrefint Channel7.1.1. Parameter Settings:

ADCs_Common_Settings:

Mode Independent mode

ADC_Settings:

Clock Prescaler PCLK2 divided by 4

Resolution 12 bits (15 ADC Clock cycles)

Data Alignment

Scan Conversion Mode

Continuous Conversion Mode

Discontinuous Conversion Mode

Disabled

DMA Continuous Requests

Right alignment

Enabled

Enabled

Enabled *

Disabled

End Of Conversion Selection EOC flag at the end of single channel conversion

ADC_Regular_ConversionMode:

Number Of Conversion 6 *

External Trigger Conversion Source Regular Conversion launched by software

External Trigger Conversion Edge None
Rank 1

Channel Channel 11
Sampling Time 84 Cycles *

Rank 2 *

Channel 12 *
Sampling Time 84 Cycles *

<u>Rank</u> 3 *

Channel 14 *
Sampling Time 84 Cycles *

<u>Rank</u> 4 *

Channel 15 *
Sampling Time 84 Cycles *

<u>Rank</u> 5 *

Channel Temperature Sensor *

Sampling Time 480 Cycles *

<u>Rank</u> 6 *

Channel Vrefint *

Sampling Time 480 Cycles *

ADC_Injected_ConversionMode:

Number Of Conversions 0

WatchDog:

Enable Analog WatchDog Mode false

7.2. CAN1

mode: Mode

7.2.1. Parameter Settings:

Bit Timings Parameters:

Prescaler (for Time Quantum) 12 *

Time Quantum 285.7142857142857 *

Time Quanta in Bit Segment 1 5 Times *
Time Quanta in Bit Segment 2 1 Time

ReSynchronization Jump Width 1 Time

Basic Parameters:

Time Triggered Communication Mode

Automatic Bus-Off Management

Disable

Automatic Wake-Up Mode

Disable

Automatic Retransmission

Disable

Receive Fifo Locked Mode

Transmit Fifo Priority

Disable

Advanced Parameters:

Operating Mode Normal

7.3. **GPIO**

7.4. I2C1

12C: 12C

7.4.1. Parameter Settings:

Master Features:

I2C Speed Mode Standard Mode

I2C Clock Speed (Hz) 100000

Slave Features:

Clock No Stretch Mode Disabled
Primary Address Length selection 7-bit
Dual Address Acknowledged Disabled
Primary slave address 0
General Call address detection Disabled

7.5. RCC

High Speed Clock (HSE): Crystal/Ceramic Resonator

7.5.1. Parameter Settings:

System Parameters:

VDD voltage (V) 3.3
Instruction Cache Enabled
Prefetch Buffer Enabled
Data Cache Enabled

Flash Latency(WS) 5 WS (6 CPU cycle)

RCC Parameters:

HSI Calibration Value 16
HSE Startup Timout Value (ms) 100
LSE Startup Timout Value (ms) 5000

Power Parameters:

Power Regulator Voltage Scale Power Regulator Voltage Scale 1

7.6. SPI2

Mode: Full-Duplex Master

7.6.1. Parameter Settings:

Basic Parameters:

Frame Format Motorola

Data Size 8 Bits

First Bit MSB First

Clock Parameters:

Prescaler (for Baud Rate) 256 *

Baud Rate 164.062 KBits/s *

Clock Polarity (CPOL) Low
Clock Phase (CPHA) 1 Edge

Advanced Parameters:

CRC Calculation Disabled
NSS Signal Type Software

7.7. SYS

Debug: Serial Wire

Timebase Source: TIM12

7.8. TIM2

Channel1: Output Compare No Output Channel2: Input Capture direct mode Channel3: Input Capture direct mode Channel4: Input Capture direct mode

7.8.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0

Counter Mode Up

Counter Period (AutoReload Register - 32 bits value) 4294967295
Internal Clock Division (CKD) No Division
auto-reload preload Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection Reset (UG bit from TIMx_EGR)

Output Compare No Output Channel 1:

Mode Frozen (used for Timing base)

Pulse (32 bits value) 0

Output compare preload Disable CH Polarity High

Input Capture Channel 2:

Polarity Selection Falling Edge *

IC Selection Direct
Prescaler Division Ratio No division

Input Filter (4 bits value) 0

Input Capture Channel 3:

Polarity Selection Falling Edge *

IC Selection Direct
Prescaler Division Ratio No division

Input Filter (4 bits value) 0

Input Capture Channel 4:

Polarity Selection Falling Edge *

IC Selection Direct
Prescaler Division Ratio No division

Input Filter (4 bits value) 0

7.9. TIM4

Clock Source: Internal Clock

Channel1: Output Compare No Output Channel2: Output Compare No Output

7.9.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value)

Counter Mode

Counter Period (AutoReload Register - 16 bits value)

Internal Clock Division (CKD)

Auto-reload preload

Disable

Trigger Output (TRGO) Parameters:

Master/Slave Mode (MSM bit) Disable (Trigger input effect not delayed)

Trigger Event Selection Reset (UG bit from TIMx_EGR)

Output Compare No Output Channel 1:

Mode Frozen (used for Timing base)

Pulse (16 bits value) 0

Output compare preload Disable
CH Polarity High

Output Compare No Output Channel 2:

Mode Frozen (used for Timing base)

Pulse (16 bits value) 0

Output compare preload Disable

CH Polarity High

7.10. TIM5

Combined Channels: Encoder Mode

7.10.1. Parameter Settings:

Counter Settings:	
Prescaler (PSC - 16 bits value)	0
Counter Mode	Up
Counter Period (AutoReload Register - 32 bits value)	4294967295
Internal Clock Division (CKD)	No Division
auto-reload preload	Disable
Trigger Output (TRGO) Parameters:	
Master/Slave Mode (MSM bit)	Disable (Trigger input effect not delayed)
Trigger Event Selection	Reset (UG bit from TIMx_EGR)
Encoder:	
Encoder Mode	Encoder Mode TI1 and TI2 *
Parameters for Channel 1	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0
Parameters for Channel 2	
Polarity	Rising Edge
IC Selection	Direct
Prescaler Division Ratio	No division
Input Filter	0

7.11. TIM9

mode: Clock Source

Channel1: PWM Generation CH1

mode: One Pulse Mode7.11.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 1680 *

Internal Clock Division (CKD)

No Division

auto-reload preload

Disable

PWM Generation Channel 1:

Mode PWM mode 1

Pulse (16 bits value) 504 *

Output compare preload Enable
Fast Mode Disable
CH Polarity High

7.12. TIM13

mode: Activated

Channel1: PWM Generation CH1

7.12.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0
Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 21000 *

Internal Clock Division (CKD) No Division auto-reload preload Disable

PWM Generation Channel 1:

Mode PWM mode 1

Pulse (16 bits value) 0
Output compare preload Enable
Fast Mode Disable
CH Polarity High

7.13. TIM14

mode: Activated

Channel1: PWM Generation CH1

mode: One Pulse Mode7.13.1. Parameter Settings:

Counter Settings:

Prescaler (PSC - 16 bits value) 0

Counter Mode Up

Counter Period (AutoReload Register - 16 bits value) 840 *

Internal Clock Division (CKD)

No Division

auto-reload preload

Disable

PWM Generation Channel 1:

Mode PWM mode 1

Pulse (16 bits value)

Output compare preload

Fast Mode

CH Polarity

A20 *

Enable

Disable

High

7.14. USART3

Mode: Asynchronous

7.14.1. Parameter Settings:

Basic Parameters:

Baud Rate 115200

Word Length 8 Bits (including Parity)

Parity None Stop Bits 1

Advanced Parameters:

Data Direction Receive and Transmit

Over Sampling 16 Samples

7.15. FREERTOS

Interface: CMSIS_V1

7.15.1. Config parameters:

API:

FreeRTOS API CMSIS v1

Versions:

FreeRTOS version 10.2.1 CMSIS-RTOS version 1.02

MPU/FPU:

ENABLE_MPU Disabled ENABLE_FPU Disabled

Kernel settings:

USE_PREEMPTION Enabled

CPU_CLOCK_HZ SystemCoreClock

TICK_RATE_HZ 512 *

MAX_PRIORITIES 7

MINIMAL_STACK_SIZE 96 *

MAX_TASK_NAME_LEN 16

USE_16_BIT_TICKS Disabled

IDLE_SHOULD_YIELD Enabled

USE_MUTEXES Enabled

USE_RECURSIVE_MUTEXES Disabled
USE_COUNTING_SEMAPHORES Disabled

QUEUE_REGISTRY_SIZE 12 *

USE_APPLICATION_TASK_TAG Disabled
ENABLE_BACKWARD_COMPATIBILITY Enabled
USE_PORT_OPTIMISED_TASK_SELECTION Enabled
USE_TICKLESS_IDLE Disabled
USE_TASK_NOTIFICATIONS Enabled
RECORD_STACK_HIGH_ADDRESS Disabled

Memory management settings:

Memory Allocation Dynamic / Static

TOTAL_HEAP_SIZE 32768 *

Memory Management scheme heap_4

Hook function related definitions:

USE_IDLE_HOOK Disabled
USE_TICK_HOOK Disabled
USE_MALLOC_FAILED_HOOK Disabled
USE_DAEMON_TASK_STARTUP_HOOK Disabled
CHECK_FOR_STACK_OVERFLOW Option2 *

Run time and task stats gathering related definitions:

GENERATE_RUN_TIME_STATS Disabled
USE_TRACE_FACILITY Disabled
USE_STATS_FORMATTING_FUNCTIONS Disabled

Co-routine related definitions:

USE_CO_ROUTINES Disabled MAX_CO_ROUTINE_PRIORITIES 2

Software timer definitions:

USE_TIMERS Enabled *

TIMER_TASK_PRIORITY 2
TIMER_QUEUE_LENGTH 10
TIMER_TASK_STACK_DEPTH 192

Interrupt nesting behaviour configuration:

LIBRARY_LOWEST_INTERRUPT_PRIORITY 15
LIBRARY_MAX_SYSCALL_INTERRUPT_PRIORITY 5

Added with 10.2.1 support:

MESSAGE_BUFFER_LENGTH_TYPE size_t USE_POSIX_ERRNO Disabled

7.15.2. Include parameters:

Include definitions:

vTaskPrioritySet Enabled uxTaskPriorityGet Enabled vTaskDelete Disabled * Disabled vTaskCleanUpResources Enabled vTaskSuspend vTaskDelayUntil Enabled * vTaskDelay Enabled xTaskGetSchedulerState Enabled Enabled xTaskResumeFromISR xQueueGetMutexHolder Disabled xSemaphoreGetMutexHolder Disabled Disabled pcTaskGetTaskName uxTaskGetStackHighWaterMark Enabled *

xTaskGetCurrentTaskHandle Enabled * Disabled eTaskGetState $x \\ Event Group Set Bit From ISR$ Disabled Disabled xTimerPendFunctionCall xTaskAbortDelay Disabled Disabled xTaskGetHandle Disabled uxTaskGetStackHighWaterMark2

7.15.3. Advanced settings:

Newlib settings (see parameter description first):

USE_NEWLIB_REENTRANT

Project settings (see parameter description first):

Use FW pack heap file Enabled

^{*} User modified value

8. System Configuration

8.1. GPIO configuration

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
ADC1	PC1	ADC1_IN11	Analog mode	No pull-up and no pull-down	n/a	Control lever
	PC2	ADC1_IN12	Analog mode	No pull-up and no pull-down	n/a	Supply 12v
	PC4	ADC1_IN14	Analog mode	No pull-up and no pull-down	n/a	Supply 5v
	PC5	ADC1_IN15	Analog mode	No pull-up and no pull-down	n/a	Spare
CAN1	PD0	CAN1_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PD1	CAN1_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
I2C1	PB6	I2C1_SCL	Alternate Function Open Drain	Pull-up	Very High	
	PB7	I2C1_SDA	Alternate Function Open Drain	Pull-up	Very High	
RCC	PH0- OSC_IN	RCC_OSC_IN	n/a	n/a	n/a	
	PH1- OSC_OUT	RCC_OSC_OUT	n/a	n/a	n/a	
SPI2	PB13	SPI2_SCK	Alternate Function Push Pull	No pull-up and no pull-down	Very High *	
	PB14	SPI2_MISO	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PB15	SPI2_MOSI	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
SYS	PA13	SYS_JTMS- SWDIO	n/a	n/a	n/a	
	PA14	SYS_JTCK- SWCLK	n/a	n/a	n/a	
TIM2	PA2	TIM2_CH3	Alternate Function Open Drain *	Pull-up *	Low	encodetimeA
	PA3	TIM2_CH4	Alternate Function Open Drain *	Pull-up *	Low	encodetimeB
	PB3	TIM2_CH2	Alternate Function Open Drain *	Pull-up *	Low	encodetimeZ
TIM5	PA0-WKUP	TIM5_CH1	Alternate Function Push Pull	Pull-up *	Low	encodectrA
	PA1	TIM5_CH2	Alternate Function Push Pull	Pull-up *	Low	encodectrB
TIM9	PE5	TIM9_CH1	Alternate Function Push Pull	•		T9C1steppulse

IP	Pin	Signal	GPIO mode	GPIO pull/up pull down	Max Speed	User Label
				Pull-up *	Very High	
TIM13	PA6	TIM13_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Very High	solenoiddrive
TIM14	PA7	TIM14_CH1	Alternate Function Push Pull	No pull-up and no pull-down	Very High	Oscope_sync
USART3	PC10	USART3_TX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
	PC11	USART3_RX	Alternate Function Push Pull	No pull-up and no pull-down	Very High	
GPIO	PA5	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	
	PB0	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Medium *	Stepper: DRdirection
	PB1	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	Stepper: MF-not-enable
	PE10	GPIO_EXTI10	External Interrupt Mode with Rising edge trigger detection	Pull-up *	n/a	LimitSw:inside:NO
	PE11	GPIO_EXTI11	External Interrupt Mode with Rising edge trigger detection	Pull-up *	n/a	LimitSw:inside:NC
	PE12	GPIO_EXTI12	External Interrupt Mode with Rising edge trigger detection	Pull-up *	n/a	LimitSw:outside:NO
	PE13	GPIO_EXTI13	External Interrupt Mode with Rising edge trigger detection	Pull-up *	n/a	LimitSw:outside:NC
	PB12	GPIO_Output	Output Push Pull	Pull-up *	Medium *	SPI2 NSS /CK
	PD12	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LED GREEN
	PD13	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LED ORANGE
	PD14	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LED RED
	PD15	GPIO_Output	Output Push Pull	No pull-up and no pull-down	Low	LED BLUE

8.2. DMA configuration

DMA request	Stream	Direction	Priority
ADC1	DMA2_Stream0	Peripheral To Memory	Low
USART3_RX	DMA1_Stream1	Peripheral To Memory	Low
USART3_TX	DMA1_Stream3	Memory To Peripheral	Low
I2C1_TX	DMA1_Stream7	Memory To Peripheral	Low
I2C1_RX	DMA1_Stream0	Peripheral To Memory	Low

ADC1: DMA2_Stream0 DMA request Settings:

Mode: Circular *
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Half Word
Memory Data Width: Half Word

USART3_RX: DMA1_Stream1 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Byte
Memory Data Width: Byte

USART3_TX: DMA1_Stream3 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *
Peripheral Data Width: Byte
Memory Data Width: Byte

I2C1_TX: DMA1_Stream7 DMA request Settings:

Mode: Normal

Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *

Peripheral Data Width: Byte
Memory Data Width: Byte

I2C1_RX: DMA1_Stream0 DMA request Settings:

Mode: Normal
Use fifo: Disable
Peripheral Increment: Disable
Memory Increment: Enable *

Peripheral Data Width: Byte
Memory Data Width: Byte

8.3. NVIC configuration

8.3.1. NVIC

Interrupt Table	Enable	Preenmption Priority	SubPriority	
Non maskable interrupt	true	0	0	
Hard fault interrupt	true	0	0	
Memory management fault	true	0	0	
Pre-fetch fault, memory access fault	true	0	0	
Undefined instruction or illegal state	true	0	0	
System service call via SWI instruction	true	0	0	
Debug monitor	true	0	0	
Pendable request for system service	true	15	0	
System tick timer	true	15	0	
DMA1 stream0 global interrupt	true	8	0	
DMA1 stream1 global interrupt	true	10	0	
DMA1 stream3 global interrupt	true	10	0	
ADC1, ADC2 and ADC3 global interrupts	true	6	0	
CAN1 TX interrupts	true	7	0	
CAN1 RX0 interrupts	true	7	0	
CAN1 RX1 interrupt	true	7	0	
TIM1 break interrupt and TIM9 global interrupt	true	6	0	
TIM2 global interrupt	true	2	0	
TIM4 global interrupt	true	2	0	
I2C1 event interrupt	true	10	0	
SPI2 global interrupt	true 13		0	
USART3 global interrupt	true	8	0	
EXTI line[15:10] interrupts	true	11	0	
TIM8 break interrupt and TIM12 global interrupt	true	0	0	
DMA1 stream7 global interrupt	true	12	0	
DMA2 stream0 global interrupt	true	6	0	
PVD interrupt through EXTI line 16		unused		
Flash global interrupt		unused		
RCC global interrupt		unused		
CAN1 SCE interrupt	unused			
I2C1 error interrupt	unused			
TIM8 update interrupt and TIM13 global interrupt	unused			
TIM8 trigger and commutation interrupts and TIM14 global interrupt	unused			
TIM5 global interrupt	unused			
FPU global interrupt	unused			

8.3.2. NVIC Code generation

Enabled interrupt Table	Select for init sequence ordering	Generate IRQ handler	Call HAL handler
Non maskable interrupt	true	true	false
Hard fault interrupt	true	true	false
Memory management fault	true	true	false
Pre-fetch fault, memory access fault	true	true	false
Undefined instruction or illegal state	true	true	false
System service call via SWI instruction	true	false	false
Debug monitor	true	true	false
Pendable request for system service	true	false	false
System tick timer	true	false	false
DMA1 stream0 global interrupt	true	true	true
DMA1 stream1 global interrupt	true	true	true
DMA1 stream3 global interrupt	true	true	true
ADC1, ADC2 and ADC3 global interrupts	true	true	true
CAN1 TX interrupts	true	true	true
CAN1 RX0 interrupts	true	true	true
CAN1 RX1 interrupt	true	true	true
TIM1 break interrupt and TIM9 global interrupt	true	true	true
TIM2 global interrupt	true	true	true
TIM4 global interrupt	true	true	true
I2C1 event interrupt	true	true	true
SPI2 global interrupt	true	true	true
USART3 global interrupt	true	true	true
EXTI line[15:10] interrupts	true	true	true
TIM8 break interrupt and TIM12 global interrupt	true	true	true
DMA1 stream7 global interrupt	true	true	true
DMA2 stream0 global interrupt	true	true	true

^{*} User modified value

9. System Views

9.1. Category view

9.1.1. Current



10. Software Pack Report

10.1. Software Pack selected

Vendor	Name	Version	Component
STMicroelectronic	FreeRTOS	0.0.1	Class : CMSIS
s			Group : RTOS
			SubGroup :
			FreeRTOS
			Version : 10.2.0
			Class : RTOS
			Group : Core
			Version : 10.2.0

11. Docs & Resources

Type Link

Datasheet http://www.st.com/resource/en/datasheet/DM00037051.pdf

Reference http://www.st.com/resource/en/reference_manual/DM00031020.pdf

manual

Programming http://www.st.com/resource/en/programming_manual/DM00046982.pdf

manual

Errata sheet http://www.st.com/resource/en/errata_sheet/DM00037591.pdf

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