

GMP102 Digital Barometric Pressure Sensor

General Introduction

GMP102 is a digital barometric pressure sensor especially designed for applications requiring highly-precision pressure measurement like quadcopter altitude control and portable navigation device. It is both a pressure and temperature sensor housed in a compact $2.1\times2.6\times1.05~\text{mm}^3$ package. The pressure sensor is based on the industry-recognized piezo-resistive technology featuring long-term stability and EMC robustness. A high-performance 24-bit ADC provides pressure resolution up to 0.18Pa, and temperature resolution up to 0.004°C . The pressure sensor has a wide operating range from 300 to 1100hPa that covers all surface elevations on earth.

GMP102 can detect absolute barometric pressure with highly accuracy for applications like quadcopter altitude control. The maximum altitude resolution can be up to less than 0.1m. Several operation options further offer large window for user optimization on the power consumption, resolution and filter performance.

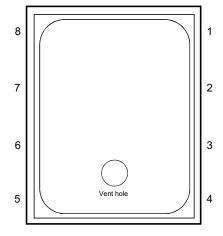
Features

- O Operation range:
 - Pressure: 300~1100hPa (Absolute)
 - Temperature: -40~+85°C
- O Built-in 24-bit ADC:
 - Pressure resolution: up to 0.18Pa
 - Temperature resolution: up to 0.004°C
- O Digital interface:
 - I2C supporting both standard (100kHz), and fast (400kHz) mode

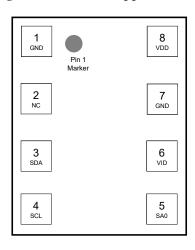
- O Supply voltage:
 - VDD: +1.8V ~ +5.5V
 - VID: $+1.2V \sim +5.5V$
- O Power Consumption:
 - Standby ~ 1uA
- O RoHS-compliance package:
 - 8-pin LGA with metal lid
 - Footprint: $2.1 \times 2.6 \text{ mm}^2$
 - Height: 1.05 mm.

Applications

Ascending/descending speed estimation, altimetry and barometry, indoor navigation for floor/elevator detection, GPS applications, activity tracking for health care applications



Top View



Bottom View



Specifications

Table 1: Pin Descriptions

Pin#	Name	Description
1	GND	Ground pin
2	NC	No connection inside
3	SDA	I2C data pin
4	SCL	I2C clock pin
5	SA0	I2C slave address select pin
6	VID	Digital interface power supply in
7	GND	Ground pin
8	VDD	Core circuit power supply in

Table 2: Specification

Parameter	Symbol	Condition	Min.	Тур.	Max.	Unit
Operation voltage	VDD		1.8	_	5.5	V
IO voltage	VID		1.2	_	VDD	V
Temperature range	Ta		-40	25	+85	°C
Pressure range	P		300	_	1100	hPa
Operation current OSR=256 OSR=1024 (default) OSR=4096 OSR=16384	IDD	VDD = 3.3V 20Hz P+T conversion	_	97 120 190 420	_	uA
Standby current	IDDSD	After POR or soft reset	_	1	_	uA
Relative accuracy pressure	PREL	Relative accuracy during pressure change between 700 to 950 hPa at any constant temperature between 25°C to 40°C		±0.12	_	hPa
Offset temperature coefficient	TCO		_	±1.5	_	Pa/K
Absolute accuracy pressure	PABS		_	1	_	hPa



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Noise in pressure			_	1.9	_	Pa RMS
Absolute accuracy	TADO	@25°C	_	0.5	_	°C
temperature	TABS	-40 to 85°C	_	1	_	°C
Long term stability			_	±1		hPa

Table 3: Absolute Maximum Rating

Parameter	Symbol	Min.	Max.	Unit
Power supply voltage	VDD, VID	-0.3	6.5	V
Signal input voltage	VIS	-0.3	VDD/VID + 0.3	V
Pressure	PMAX	0	20000	hPa
Storage temperature	TST	-40	+125	°C
ESD	HBM	_	±2	kV



Block Diagram and Connection

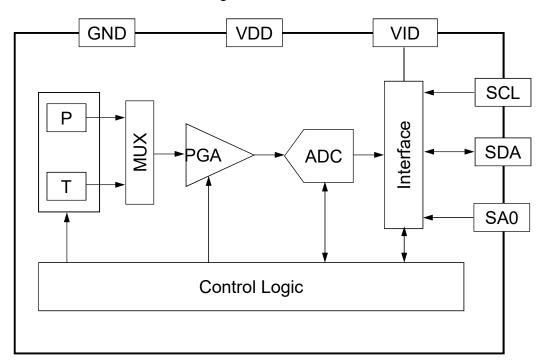


Figure 1: GMP102 Block Diagram

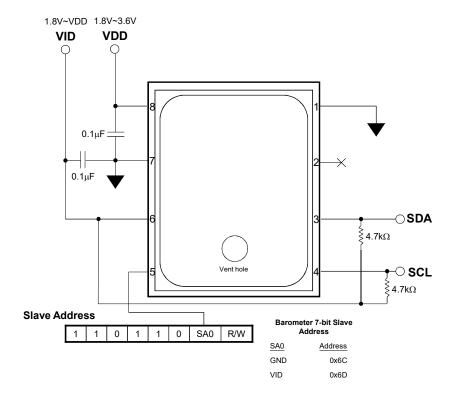


Figure 2: GMP102 I2C Connection Example



Functional Description

Power Management

GMP102 has two separate power supply pins: VDD and VID. VDD is the major power supply pin for all internal analog and digital functional blocks. VID provides a reference voltage level for the digital interface.

When the power is set on, power-on reset (POR) circuit will be active to reset the internal circuits and registers. After the POR sequence, all registers will be initialized to the default values and GMP102 will transit to standby mode.

Reset Functions

GMP102 has two types of reset as summarized below:

- Power-on reset (POR): as described in the previous Power Management section.
- Soft reset: Set RESET register (00h) to 0x24 will trigger the device soft reset by resetting all register to default values.

Initialization

GMP102 will automatically initialize to standby mode upon power-up after POR. The following steps are recommended for initialization:

- 1. Set RESET register (00h) to 0x24 for device soft reset.
- 2. Read 18-byte calibration parameters from AAh to BBh. Keep these parameters for use in the pressure sensor calibration.
- 3. Set four registers AAh ~ ADh to 0x00 to complete the calibration set up.

Power Modes

GMP102 offers three power modes, standby, P-Forced and T-Forced mode, by setting the 30h[3:0] (Measure CTRL[3:0]) bits, see 30h register description for more detail.

The transitions between different modes are illustrated in Figure 3.

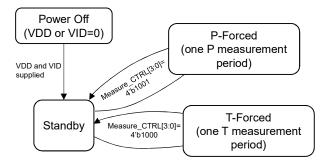


Figure 3: Mode transactions diagram

Standby mode

GMP102 will enter standby mode after complete POR sequence. In this mode, data measurement stops and the power consumption is at the minimum. All registers, including PID



and calibration parameters, are accessible.

• P-Forced mode

In P-Forced mode, GMP102 will take one-time pressure measurement and returns to standby mode automatically. The measurement results can then be obtained from the pressure data registers. Users need to set to P-Forced mode again to have another pressure measurement. The timing diagram of the P-Forced mode is illustrated in the following Figure 4.

Before set to the P-Forced mode, make sure the A5h[1] (Raw) bit value is 1'b1 in order to have the raw pressure ADC output. Below summarized the single shot pressure conversion steps:

- 1. Make sure A5h[1] (Raw) is set. If not, set A5h = 0x02.
- 2. Set to the P-Forced mode by set 30h = 0x09.
- 3. Check 02h[0] (DRDY) bit and wait until its value is set. The data is available in the registers when DRDY = 1'b1.
- 4. Read the raw pressure ADC output from the pressure data registers (06h~08h).

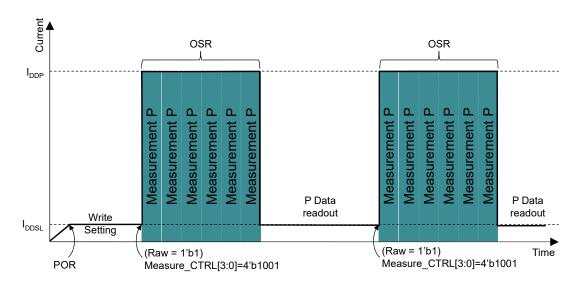


Figure 4: P-Forced mode timing diagram



• T-Forced mode

In T-Forced mode, GMP102 will take one-time temperature measurement and returns to standby mode automatically. The measurement results can then be obtained from the temperature data registers. Users need to set to T-Forced mode again to have another temperature measurement. The timing diagram of the T-Forced mode is illustrated in the following Figure 5.

Before set to the T-Forced mode, make sure the A5h[1] (Raw) bit value is 1'b0 in order to have the calibrated temperature output. Below summarized the single shot temperature conversion steps:

- 1. Make sure A5h[1] (Raw) is not set. If not so, set A5h = 0x00.
- 2. Set to the T-Forced mode by set 30h = 0x08.
- 3. Check 02h[0] (DRDY) bit and wait until its value is set. The data is available in the registers when DRDY = 1'b1.
- 4. Read the calibrated temperature output from the temperature data registers (09h~0Ah).

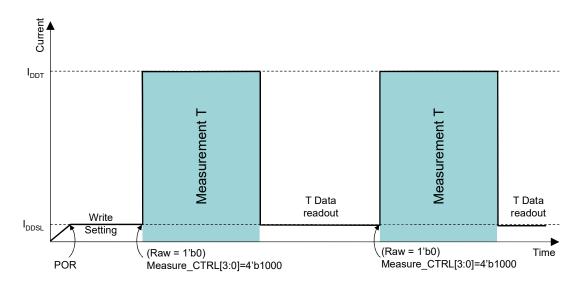


Figure 5: T-Forced mode timing diagram



User Register Map

Table 4: User Register Map Table

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
00h	RESET	Reserved RST 0 0 RST Reserved					RW	0x00			
01h	PID				PID	[7:0]				R	0x02
02h	STATUS		Reserved 0 0 DRDY								NA
06h	PRESSH]	Pressur	e [23:16]			R	NA
07h	PRESSM		Pressure [15:8]								NA
08h	PRESSL			R	NA						
09h	ТЕМРН			Т	emperat	ture[15:	8]			R	NA
0Ah	TEMPL			Γ	lempera	.ture[7:0)]			R	NA
30h	CMD		Rese	erved		Measur	e_CTRI	7[3:0]		RW	0x00
A5h	CONFIG1			Rese	erved			Raw	Reserved	RW	0x00
A6h	CONFIG2		I	Reserve	d		(OSR[2:0]	RW	0x00
AAh	Calib00										
~	~		Calibration data								NA
BBh	Calib17										



Description of Registers

Register 00h: RESET Register

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
00h	RESET	Rese	erved	RST	0	0	RST	Rese	erved	RW	0x00

Set RESET register (00h) to 0x24 to trigger the device soft reset. All register values will be reset to default. The RST bits will automatically return to 1'b0 when the soft reset complete.

Register 01h: PID Register

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
01h	PID		PID[7:0]								0x02

PID is the product identification register and the value is fixed to 0x02. This register is available for reading after the device finished the power-on-reset.

Register 02h: STATUS Register

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
02h	STATUS	Reserved				0	0	0	DRDY	R	NA

The DRDY bit will be set once the data conversion is complete. The output data is ready for reading from pressure or temperature data registers.

Register 06h~08h: Pressure Data Registers

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
06h	PRESSH		Pressure [23:16]								NA
07h	PRESSM		Pressure [15:8]							R	NA
08h	PRESSL		Pressure [7:0]								NA

The pressure data output is encoded to a 24-bit value and stored across three bytes. Data representation is 2's complement, i.e. MSB (bit 23) is the sign bit with 1'b1 representing negative value.

The pressure data output is raw pressure sensor ADC value. User can then calculate the calibrated pressure value with the calibration parameters (AAh~BBh). Reference calibration code is available upon request.

Register 09h~0Ah: Temperature Data Registers

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default



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09h	ТЕМРН	Temperature[15:8]	R	NA	
0Ah	TEMPL	Temperature[7:0]	R	NA	

The temperature data output is encoded to a 16-bit value and stored across two bytes. Data representation is 2's complement, i.e. MSB (bit 15) is the sign bit with 1'b1 representing negative value.

The temperature sensor has sensitivity of 256 LSB/ $^{\circ}$ C. The central value (0x00) stands for 0 $^{\circ}$ C. Thus the Celsius temperature can be converted from the temperature reading by the following formula:

$$T (^{\circ}C) = \frac{Temperature[15:0]}{256}$$

Register 30h: CMD Register

Addr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
30h	CMD		Reserved			Me	easure_	CTRL[3	:0]	RW	NA

Measure_CTRL[3:0] control the signal conversion mode. After each single shot signal conversion, GMP102 will return to standby mode. Available setting is summarized in the following table.

Measure_CTRL[3:0]	Power Mode
4%1000	T-Forced mode
4'b1000	Make a single shot temperature conversion.
42.1001	P-Forced mode
4'b1001	Make a single shot pressure conversion
Others	Reserved

Register A5h: CONFIG1 Register

Add	r. Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
A5]	CONFIG1	Reserved					Raw	0	RW	0x00	

Set Raw = 1'b0 before making a single shot temperature conversion. This will output calibrated temperature value to the temperature data registers $(09h\sim0Ah)$.

Set Raw = 1'b1 before making a single shot pressure conversion. This will output raw pressure ADC value to the pressure data registers (06h~08h). User can then calculate the calibrated pressure value with the calibration parameters (AAh~BBh). Reference calibration code is available upon request.



Register A6h: CONFIG2 Register

Ad	dr.	Name	bit7	bit6	bit5	bit4	bit3	bit2	bit1	bit0	Access	Default
A	sh	CONFIG2	Reserved			(OSR[2:0]	RW	0x00		

OSR[2:0] selects the oversampling ratio for the pressure data conversion as summarized in the following table.

OSR[2:0]	Oversampling Ratio	Typical Resolution (ENOB)
3'b000	1024	18.4
3'b001	2048	18.9
3'b010	4096	19.2
3'b011	8192	19.8
3'b100	256	17.6
3'b101	512	18
3'b110	16384	20.3
3'b111	32768	20.8



Digital Interface

I2C Interface General Description

The I2C interface is compliant with standard and fast I2C standard. The devices support the 7-bit control functions and SDA and SCL facilitate communication between GMP102 and master with clock rate up to 400kHz.

The 7-bit device slave address can be selected by the SA0 pin as summarized in the below table.

SA0	7-bit Slave Address
1'b0	0x6C
1'b1	0x6D

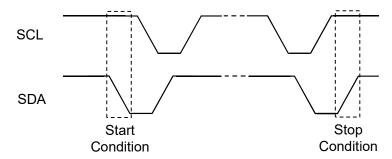
The I2C bus takes master clock through SCL pin and exchanges serial data via SDA. SDA is a bidirectional (input/output) connection. Both are open-drain connection and must be connected externally to VID via a pull-up resistor. The I2C interface supports multiple read and write. When using multiple read/write, the internal I2C address pointer will automatically increase by 1 for the next access.

I2C Access Format: Standard and Fast Mode

One data bit is transferred for each SCL cycle. The SDA must not change level when the SCL is high. The level changes in SDA while SCL is high are reserved control signals. The SDA and SCL remain high when I2C bus is idle.

Data transfer begins by bus master indicating a start condition (ST) of a falling edge on SDA when SCL is high. The master terminates transmission and frees the bus by issuing a STOP condition (SP). Stop condition is a rising edge on SDA while SCL is high. The bus remains active if a repeated START (SR) condition is generated instead of a STOP condition. Figure 6 illustrates the START and STOP condition.

Figure 6: I2C START and STOP condition

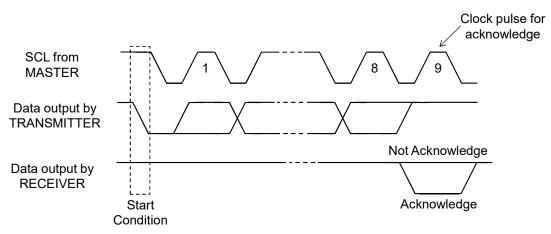


After a start condition (ST), the 7-bit slave address + RW bit must be sent by master. If the slave address does not match with GMP102, there is no acknowledge and the following data transfer will not affect GMP102. If the slave address corresponds to GMP102, it will acknowledge by pulling SDA to low and the SDA line should be let free by bus master to enable the data transfer. The master should let the SDA high (no pull down) and generate a high SCL pulse for



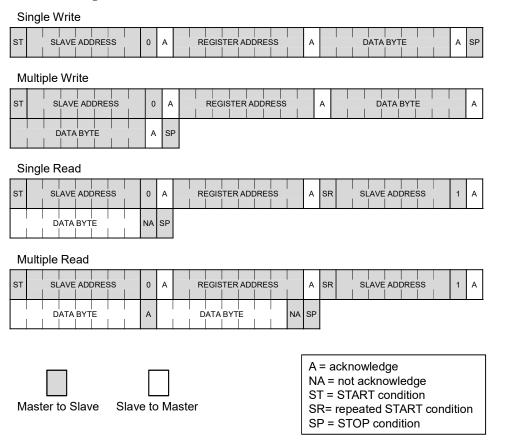
GMP102 acknowledge. Figure 7 illustrates the acknowledge signal sequence.

Figure 7: Acknowledge signal sequence



A write to GMP102 includes transmission of a START condition, the slave address with R/W bit=1'b0, one byte of data to specify the register address to write, subsequent one or more bytes of data, and finally a STOP condition. "Single Write" and "Multiple Write" in Figure 8 illustrates the frame format of single and multiple write to GMP102 respectively.

Figure 8: I2C access format: standard and fast mode



A read from GMP102 starts with transmission of a START condition, the slave address with R/W bit=1'b0, and one byte of data to specify the register address to read. A repeated START condition



and the slave address with R/W bit=1'b1 are transmitted subsequently. The slave address with R/W bit=1'b1 initiates a read operation. GMP102 acknowledge receipt of the read operation command by pulling SDA low during the 9th SCL clock and begin transmitting the contents starting from the specified register address. The master must acknowledge all correctly received bytes except the last byte. The final byte must be followed by a not acknowledge from the master and the STOP condition. "Single Read" and "Multiple Read" in Figure 8 illustrates the frame format for reading single or multiple byte from GMP102.



I2C Specifications

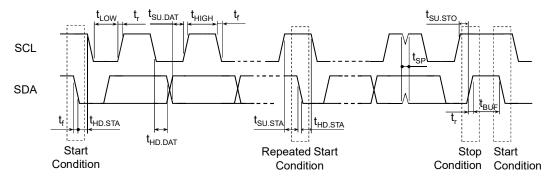
Table 5: I2C Timing Specification: Standard Mode

Parameter	Symbol	Minimum	Typical	Maximum	Unit
SCL clock frequency	$\mathbf{f}_{\mathrm{SCL}}$	_	_	100	kHz
Clock low period	tLow	4.7	_	_	μs
Clock high period	thigh	4	_	_	μs
Start hold time	thd.sta	4	_	_	μs
Start setup time	tsu.sta	4.7	_	_	μs
Data-in hold time	thd.dat	0	_	_	μs
Data-in setup time	tsu.dat	250	_	_	ns
Stop setup time	tsu.sto	4	_	_	μs
Rise time	$ m t_{r}$	_	_	1	μs
Fall time	t_{f}			0.3	μs

Table 6: I2C Timing Specification: Fast Mode

Parameter	Symbol	Minimum	Typical	Maximum	Unit
SCL clock frequency	$\mathbf{f}_{\mathrm{SCL}}$	_		400	kHz
Clock low period	${ m t_{LOW}}$	1.3		_	μs
Clock high period	${ m t_{HIGH}}$	0.6		_	μs
Bus free to new start	${f t}_{ m BUF}$	1.3		_	μs
Start hold time	thd.sta	0.6		_	μs
Start setup time	$\mathbf{t}_{\mathrm{SU.STA}}$	0.6		_	μs
Data-in hold time	${ m t_{HD,DAT}}$	0	_		μs
Data-in setup time	${ m t}_{ m SU.DAT}$	100	_		ns
Stop setup time	$t_{ m SU.STO}$	0.6	_		μs
Rise time	$\mathrm{t_{r}}$	_	_	0.3	μs
Fall time	$\mathrm{t_{f}}$	_	_	0.3	μs
Spike width	$ m t_{SP}$	_		50	μs

Figure 9: I2C Timing Diagram: Standard and Fast Mode





Package

Outline Dimension

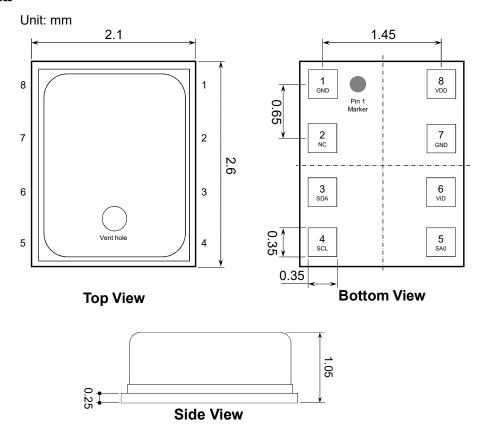


Figure 10: Package Outline Dimension

RoHS Compliance

GMEMS LGA with metal lid packaged sensors are compliant with Restrictions on Hazardous Substances (RoHS), having halide-free molding compound (green) and lead-free terminations. Reflow profiles applicable to those processes can be used successfully for soldering the devices.



Recommended PCB Foot Print Layout

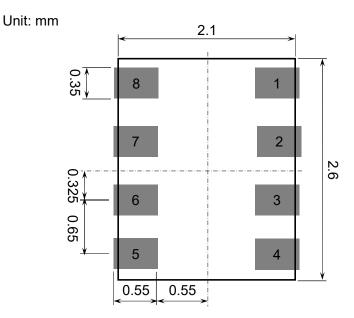


Figure 11: Layout Recommendation for PCB Land Pad

Moisture Sensitivity Level

GMP102 package MSL rating is Level 3.



Document History and Modification

Revision No.	Description	Date
V0.1	Preliminary first release	2016/8/23
V0.2	Update TBD specification items	2016/8/24
V0.3	Update the initialization stepUpdate package outline dimension	2016/10/06