

**Particle**

**Swarm**

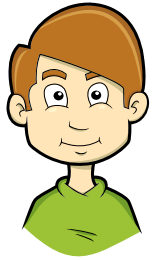
**Optimization**

# Inspiration



# PSO search strategy

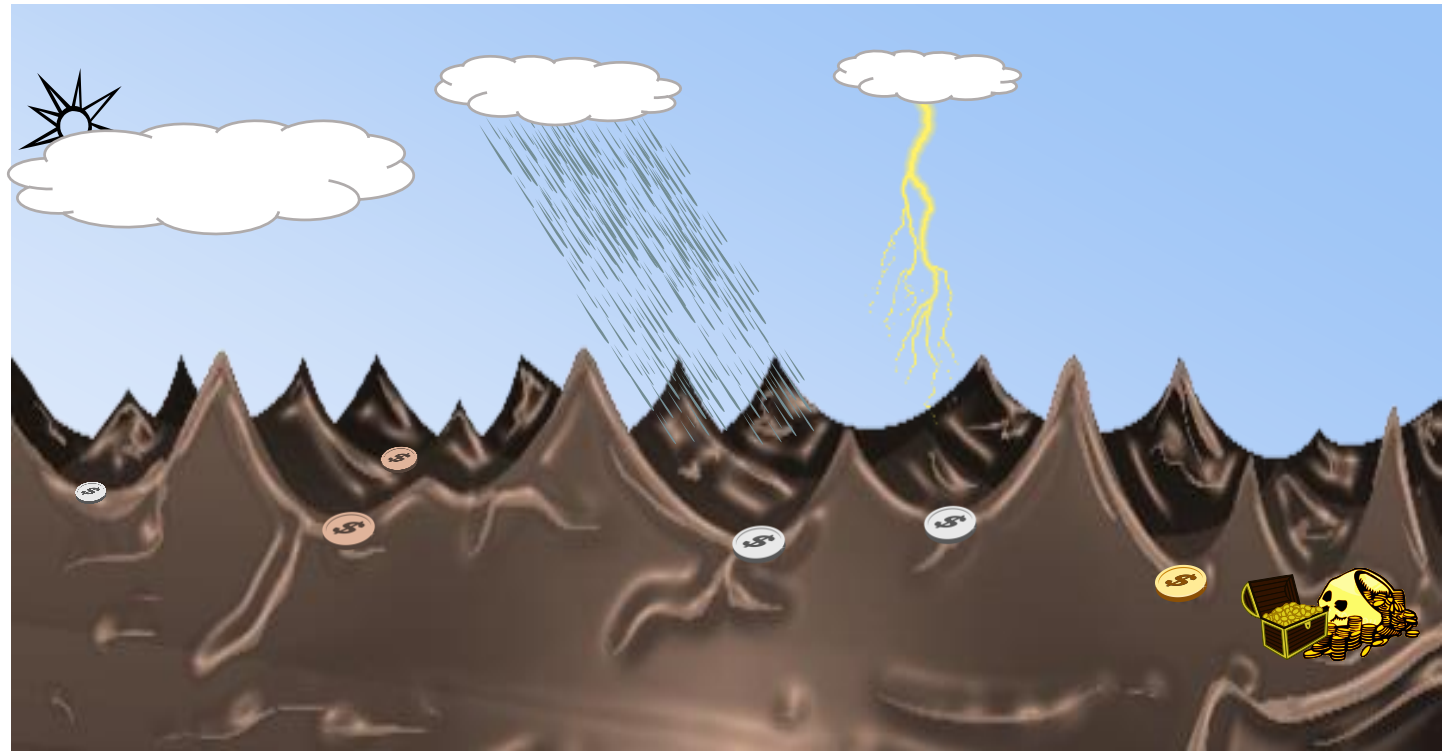
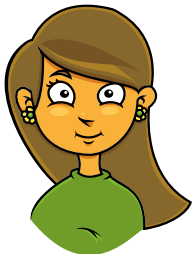
Bob



Anthony

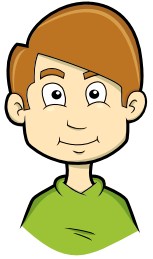


Jennifer



# PSO search strategy

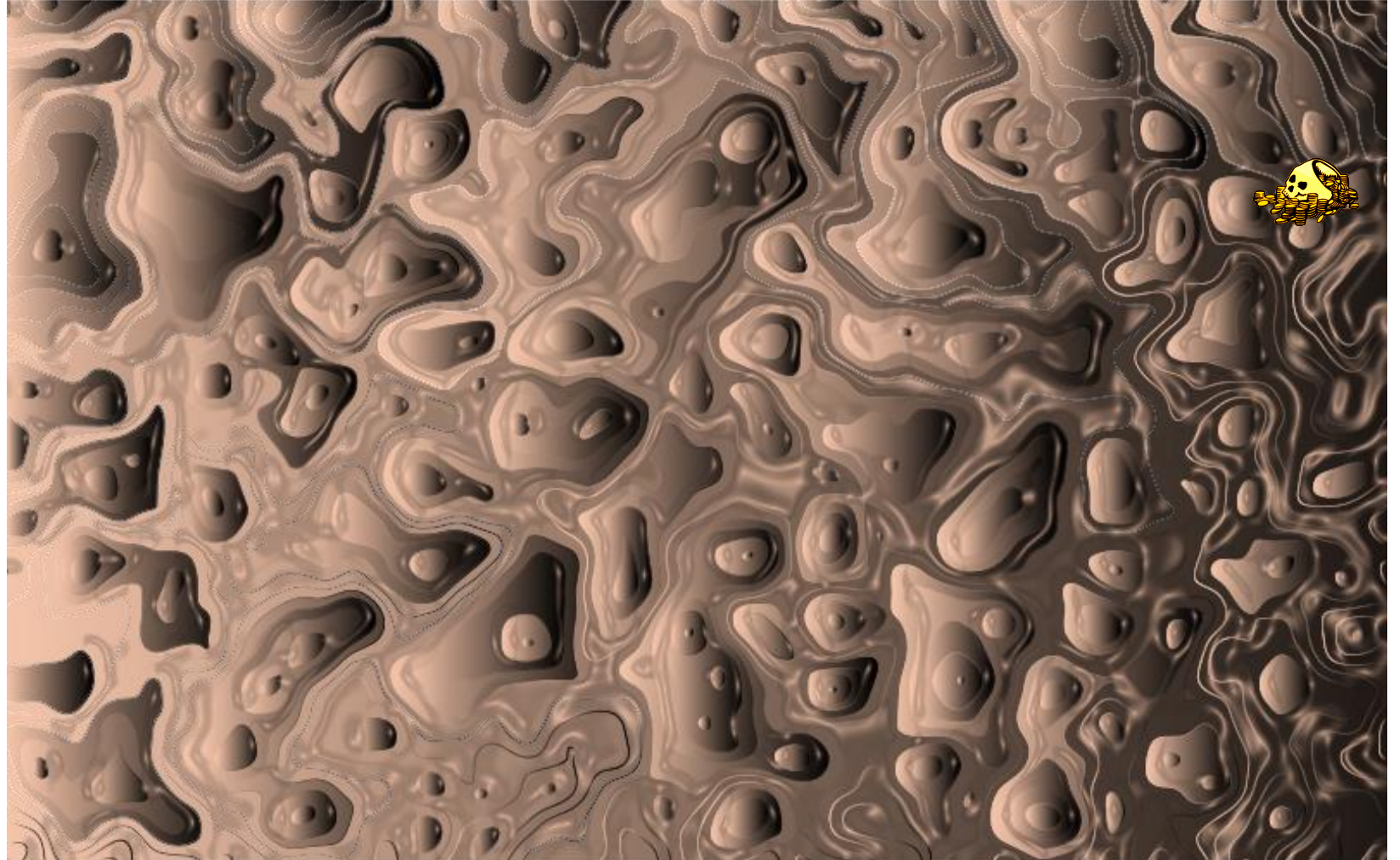
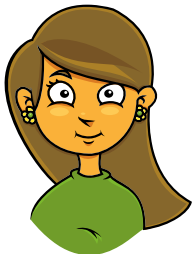
Bob



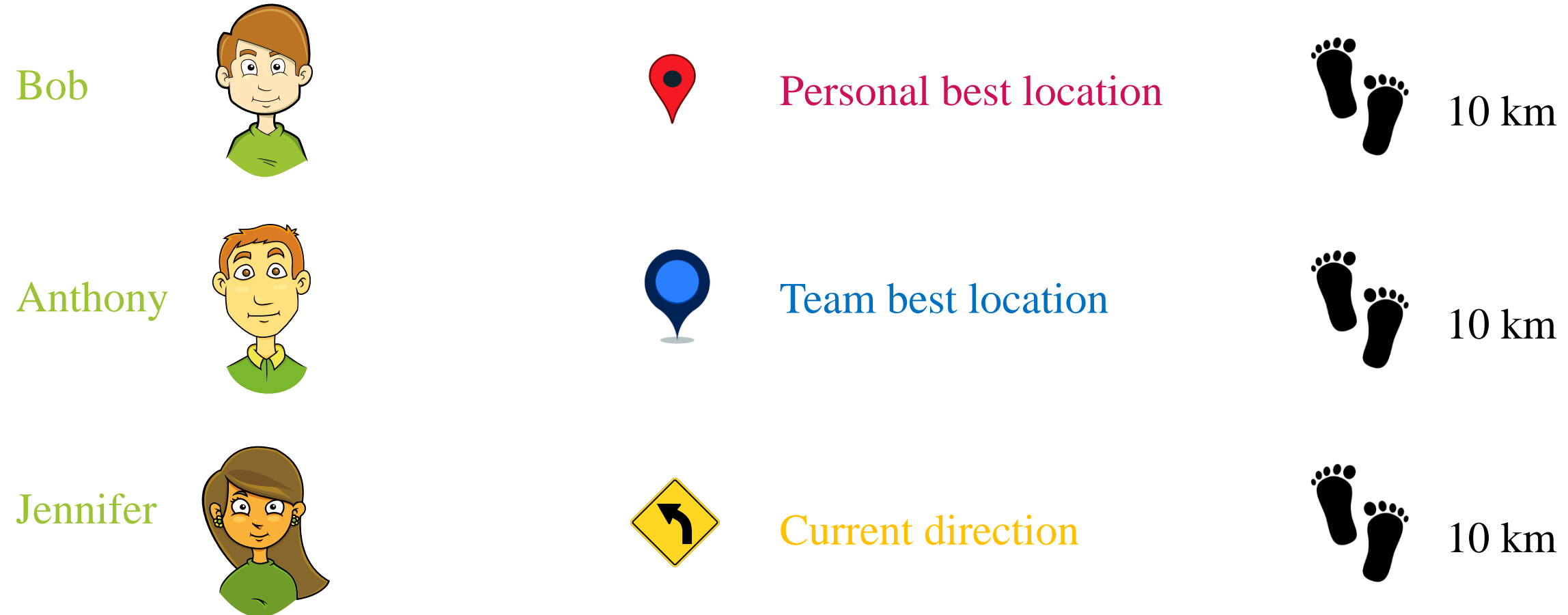
Anthony



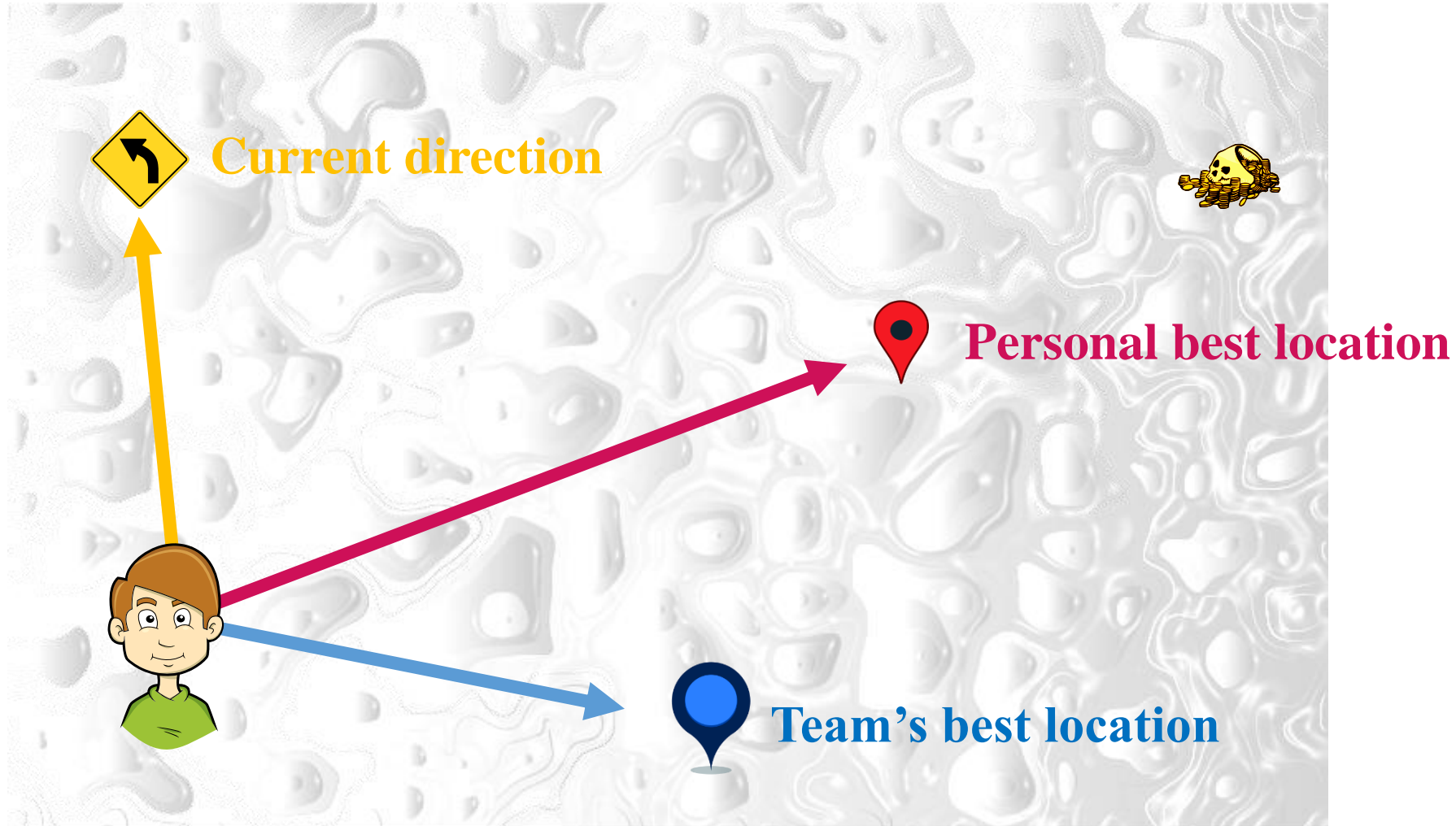
Jennifer



# PSO search strategy

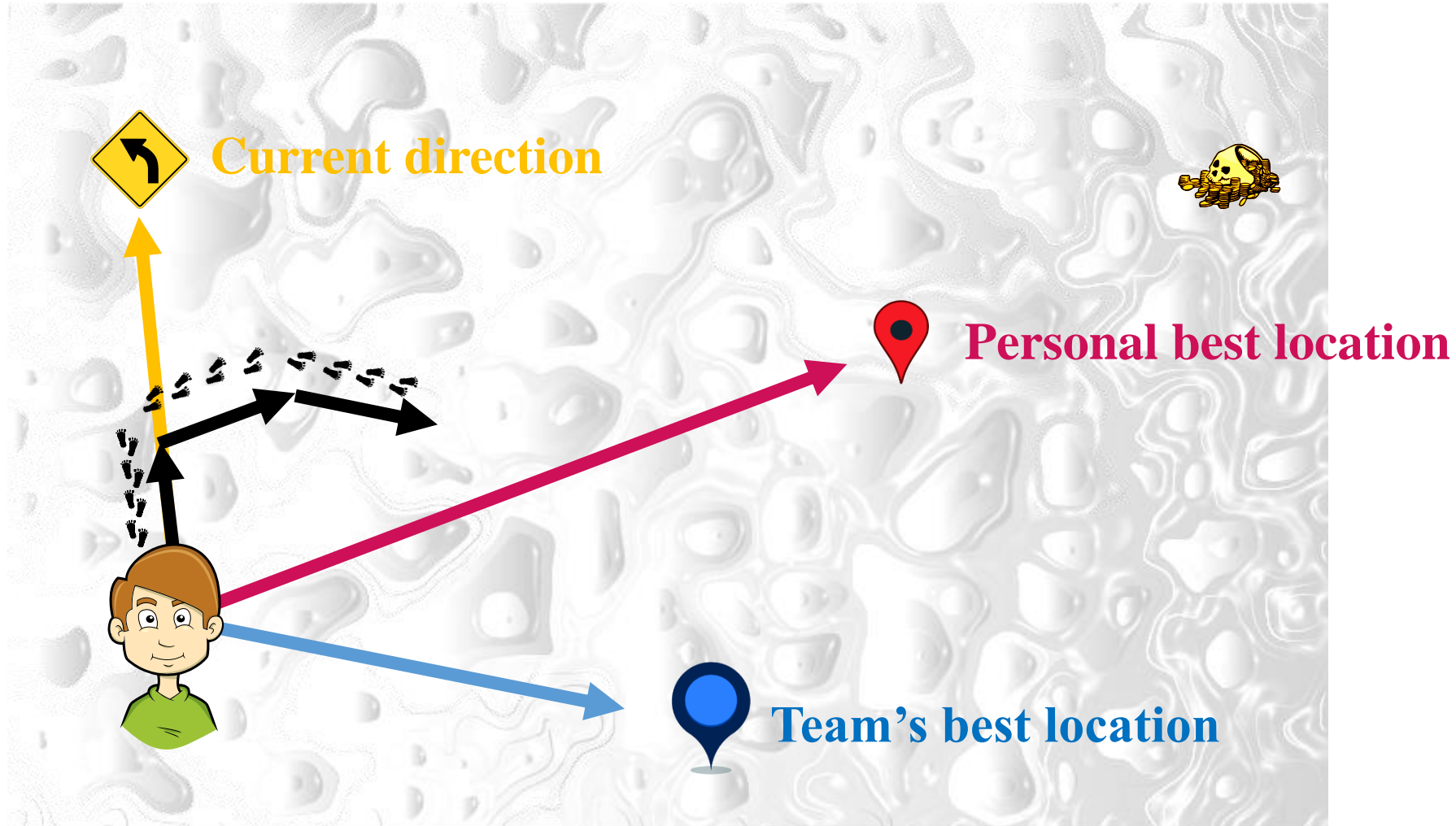


# PSO search strategy

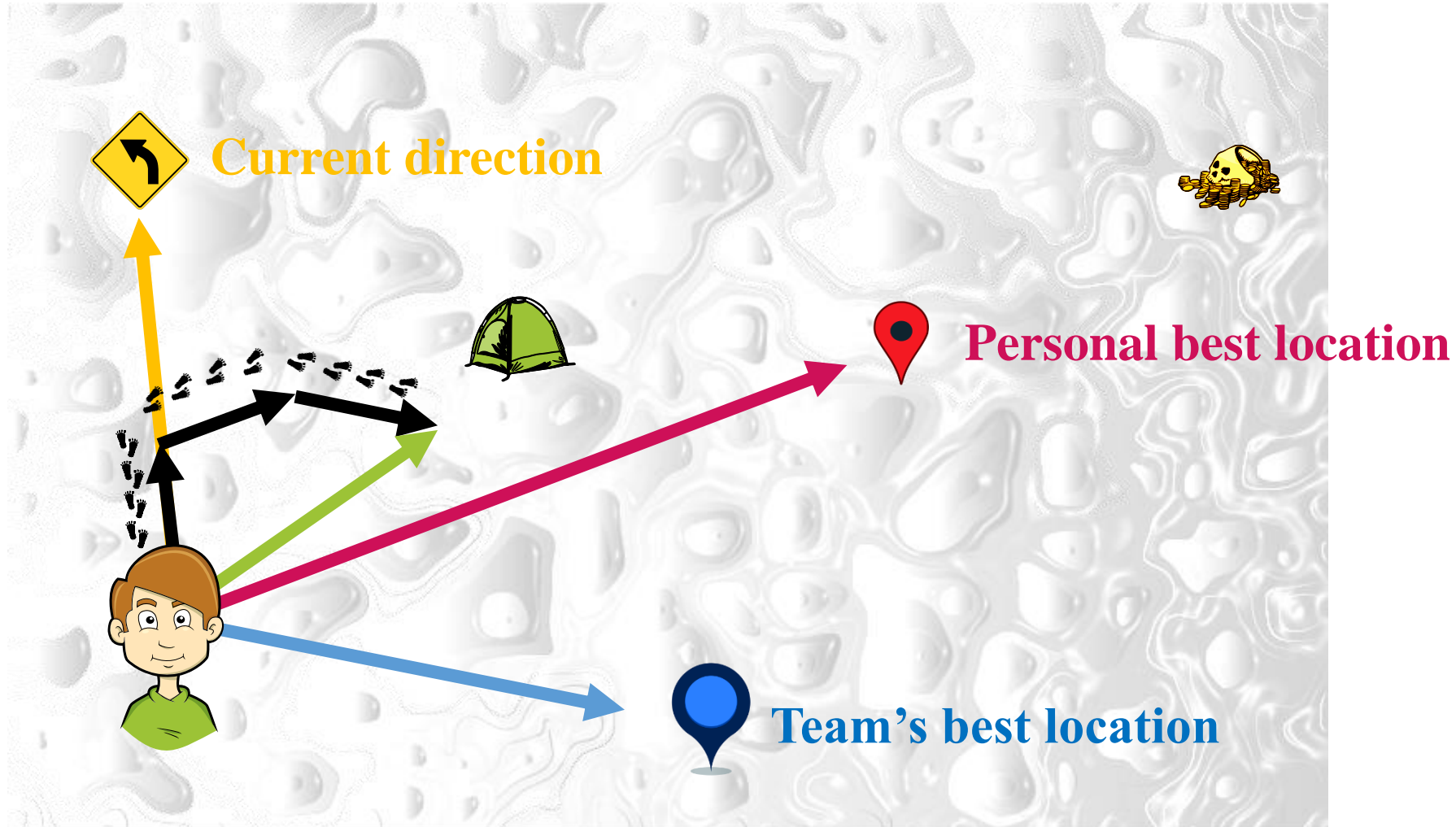




# PSO search strategy

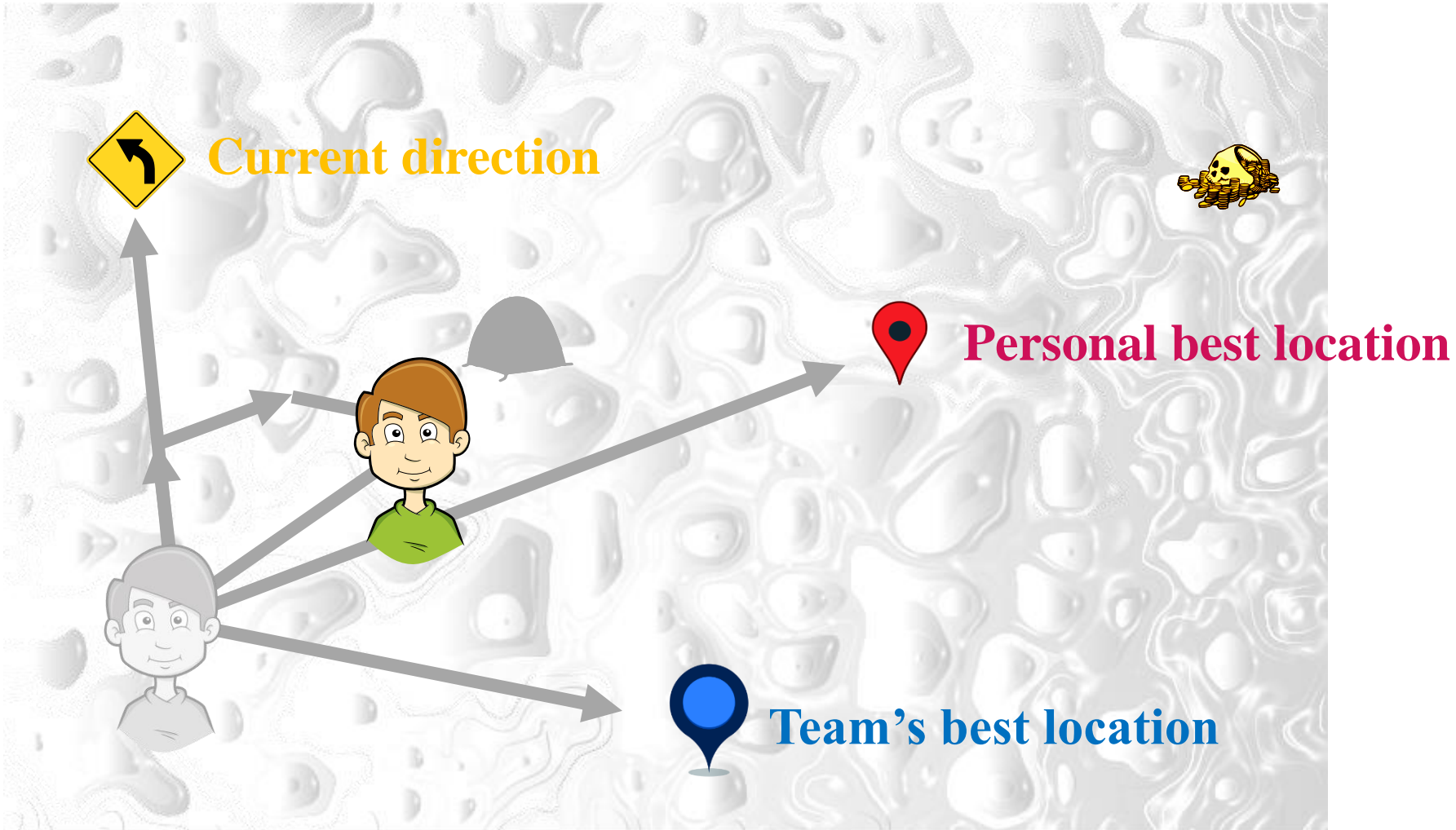


# PSO search strategy

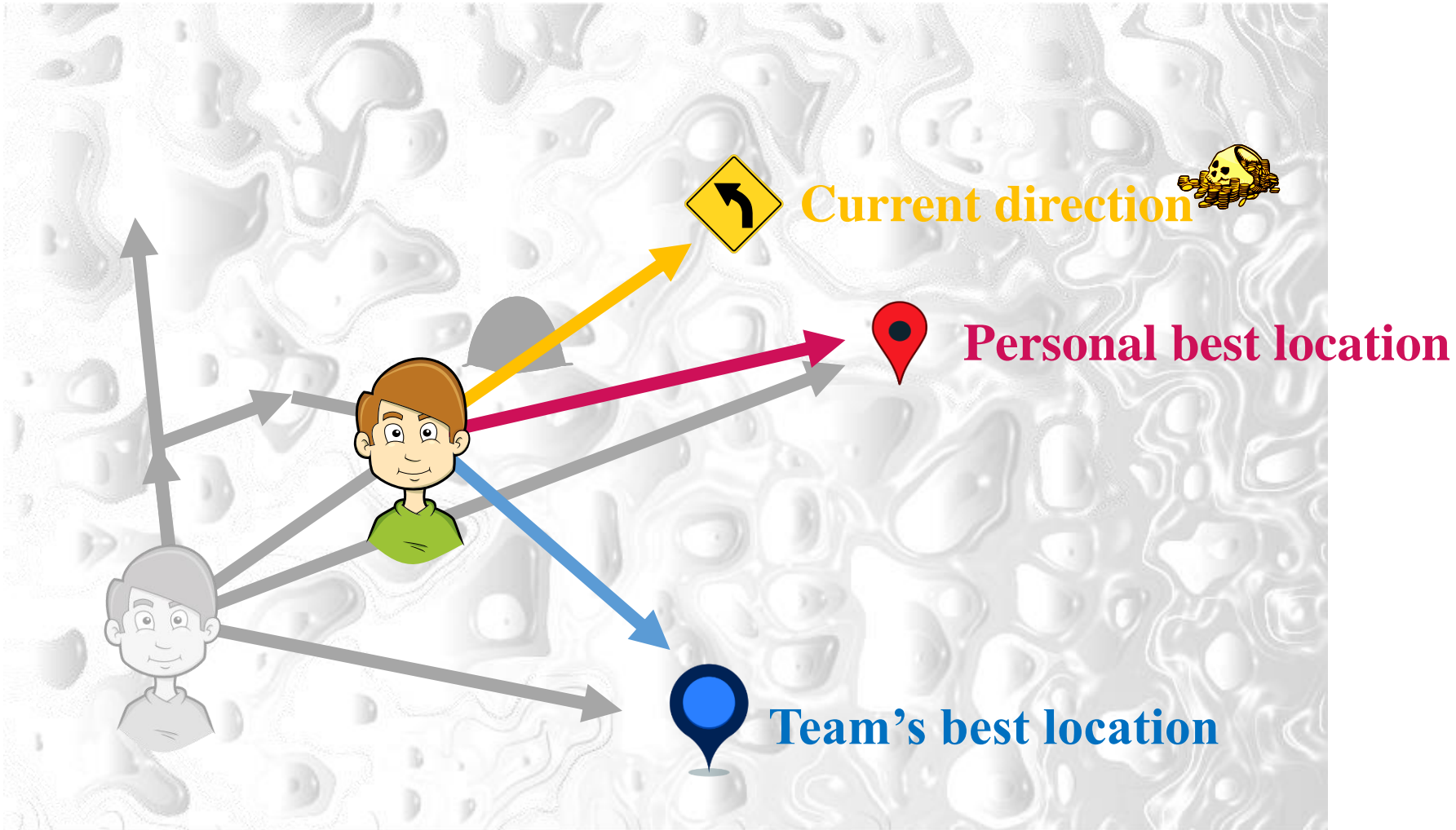




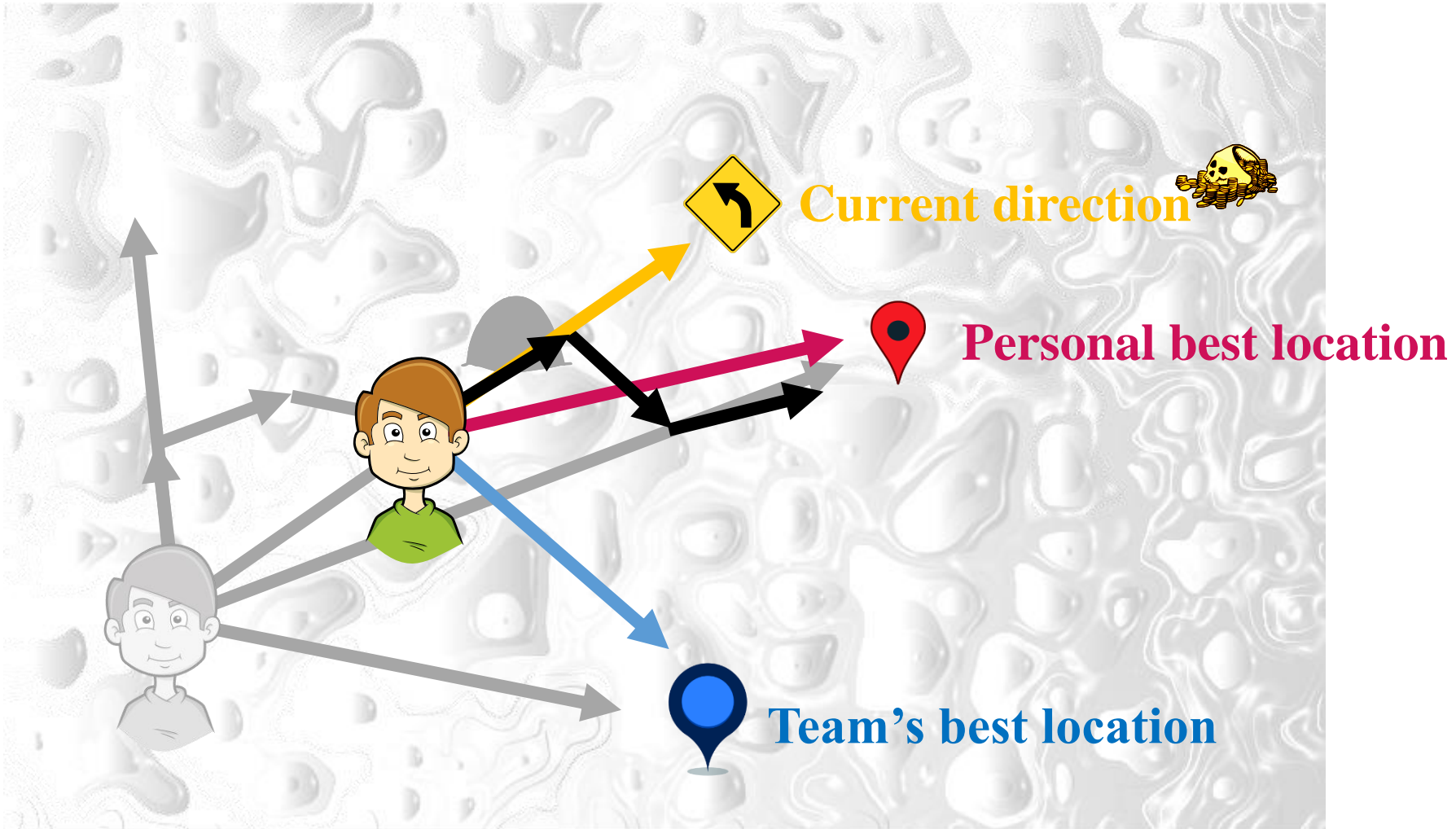
# PSO search strategy



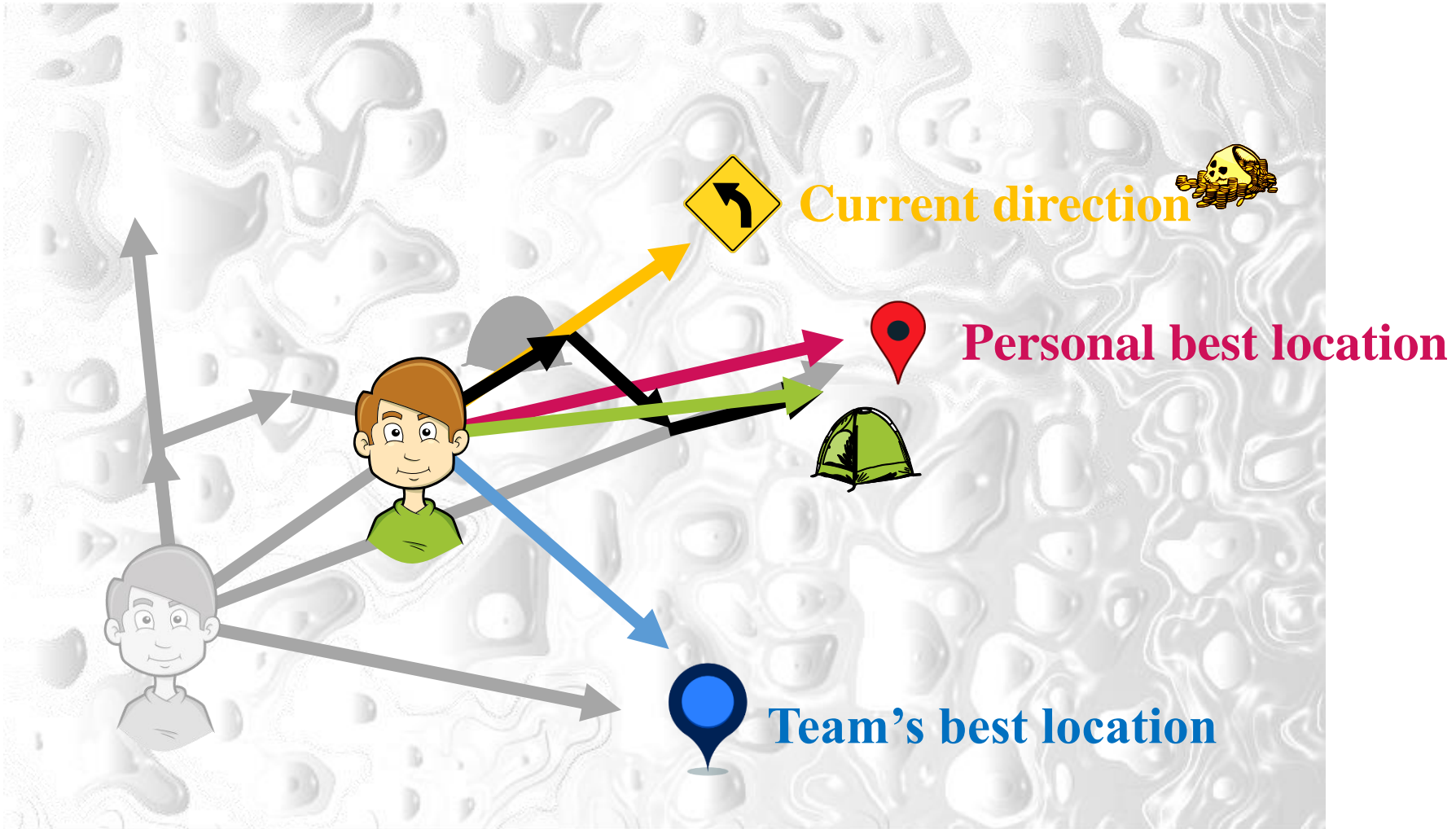
# PSO search strategy



# PSO search strategy

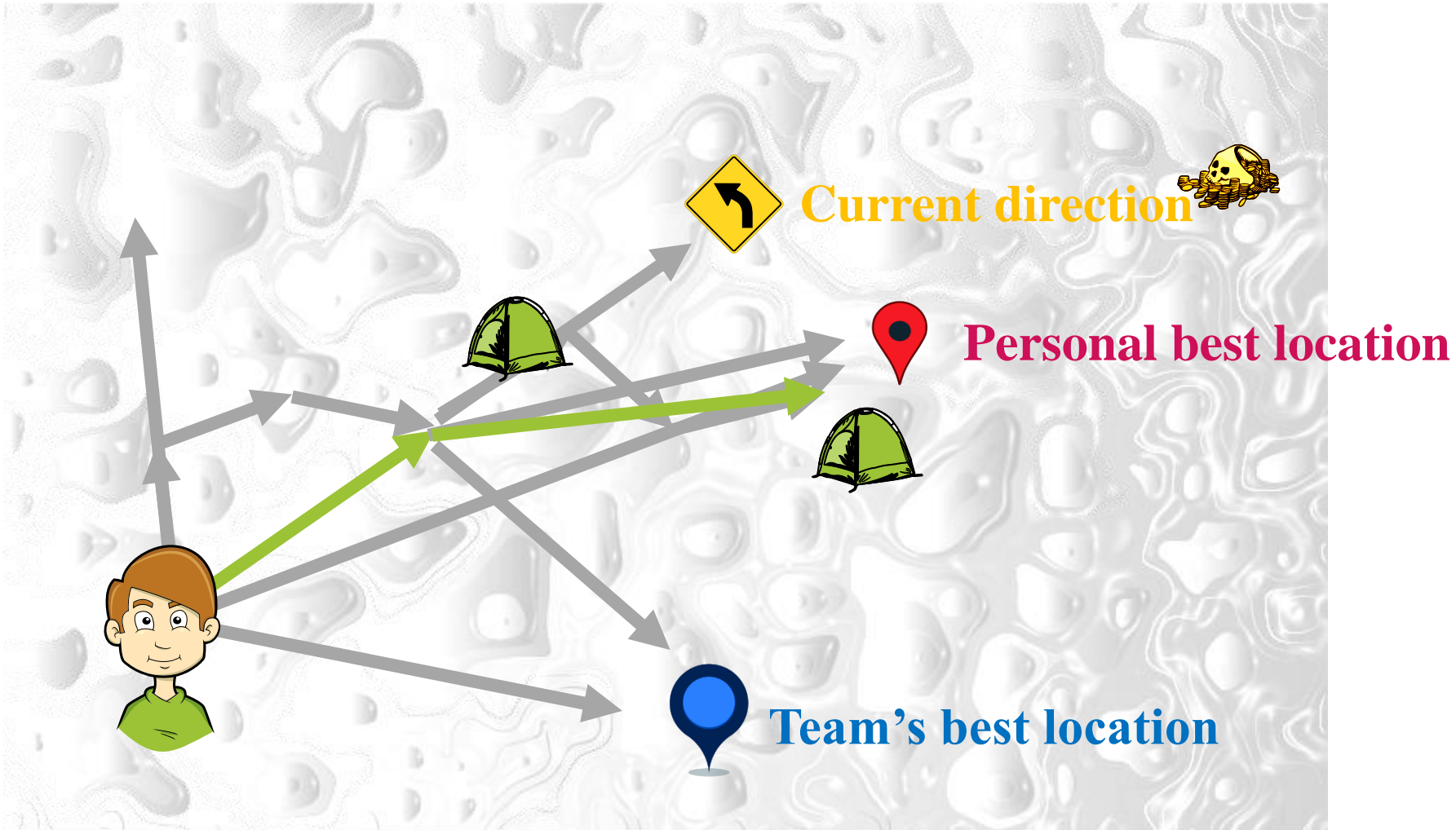


# PSO search strategy





# PSO search strategy





# PSO search strategy



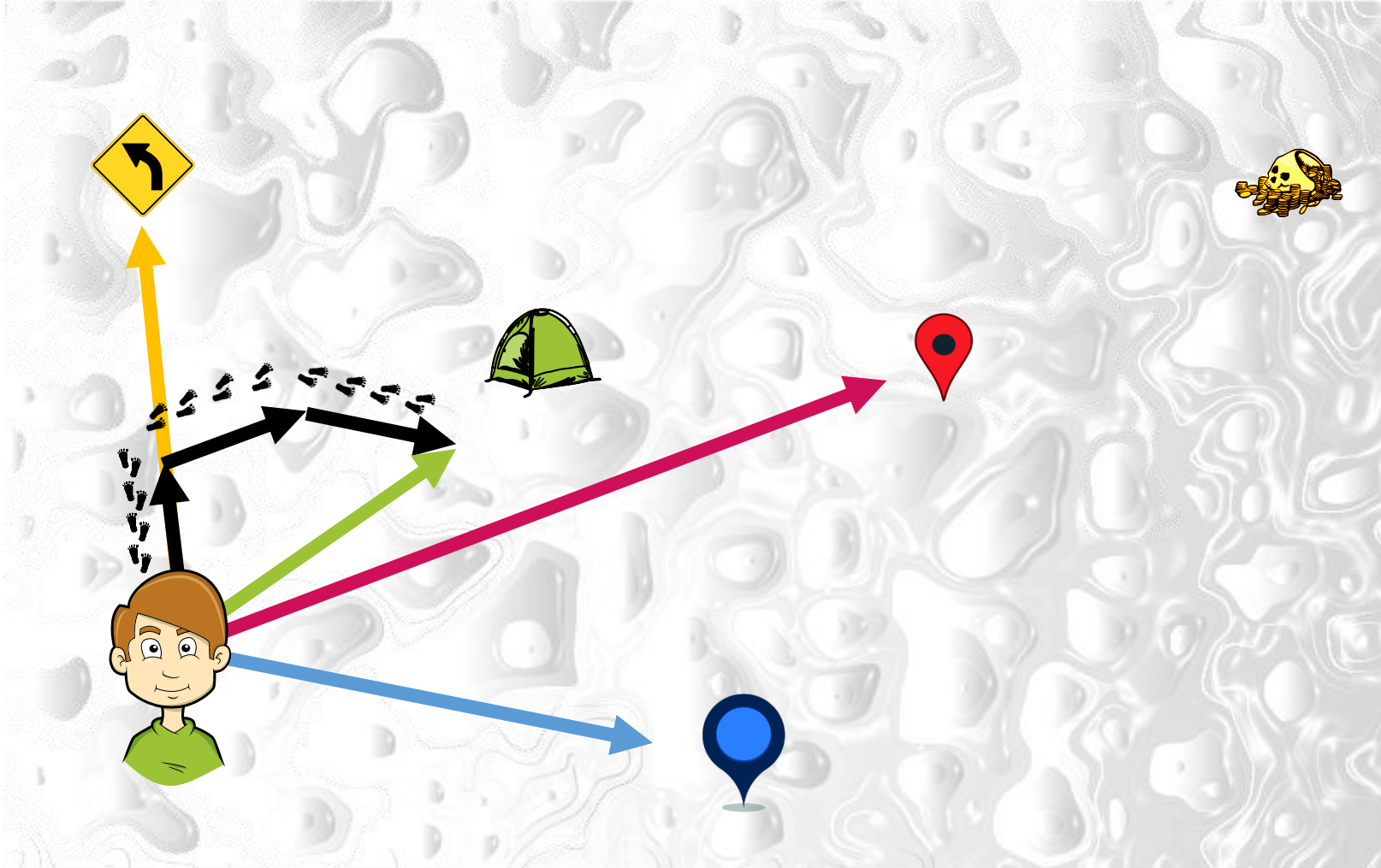
# PSO search strategy



# PSO search strategy

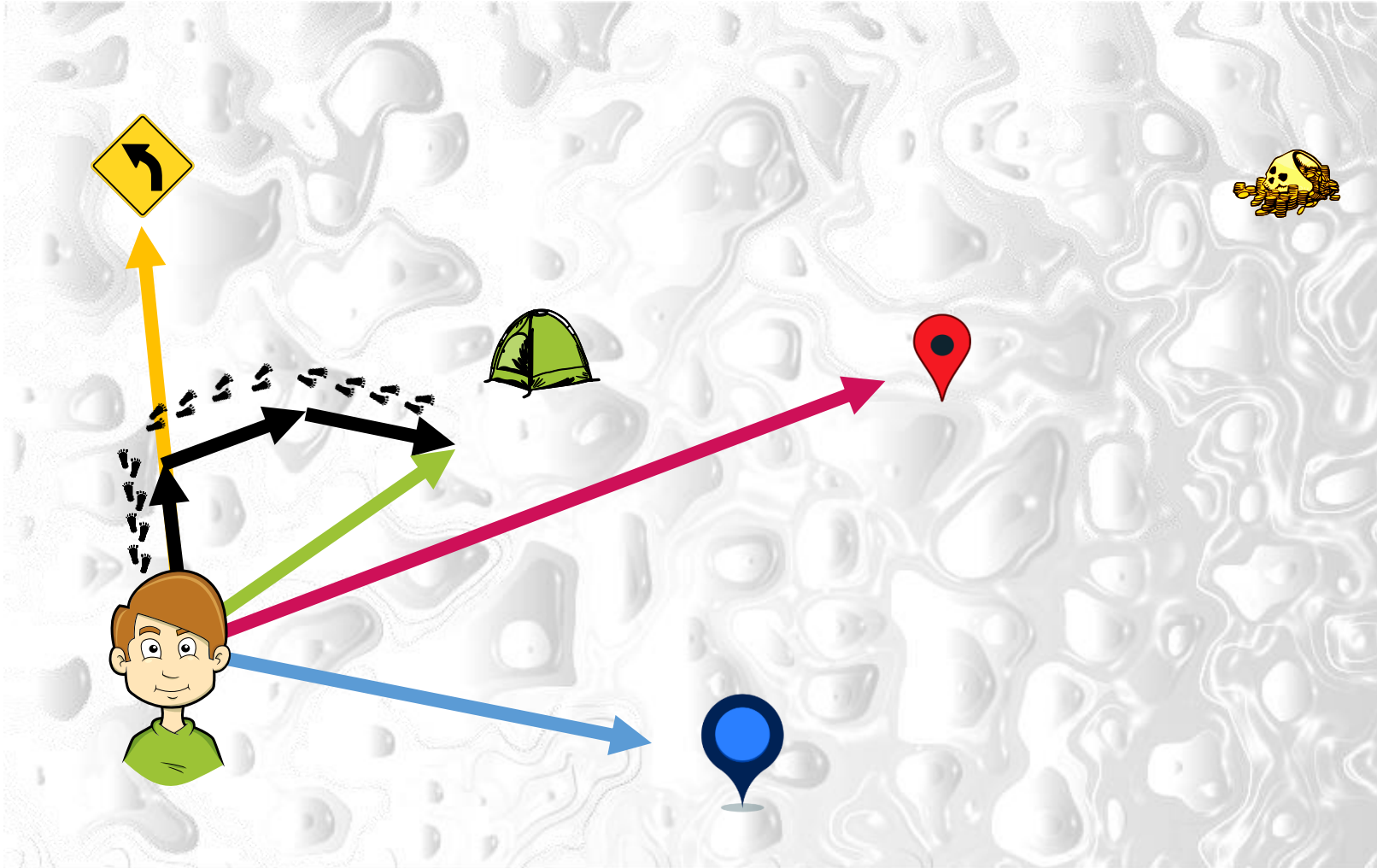


# PSO search strategy





# PSO search strategy



$$2 \times r \times 10 \text{ km}$$

$r$  in  $[0,1]$



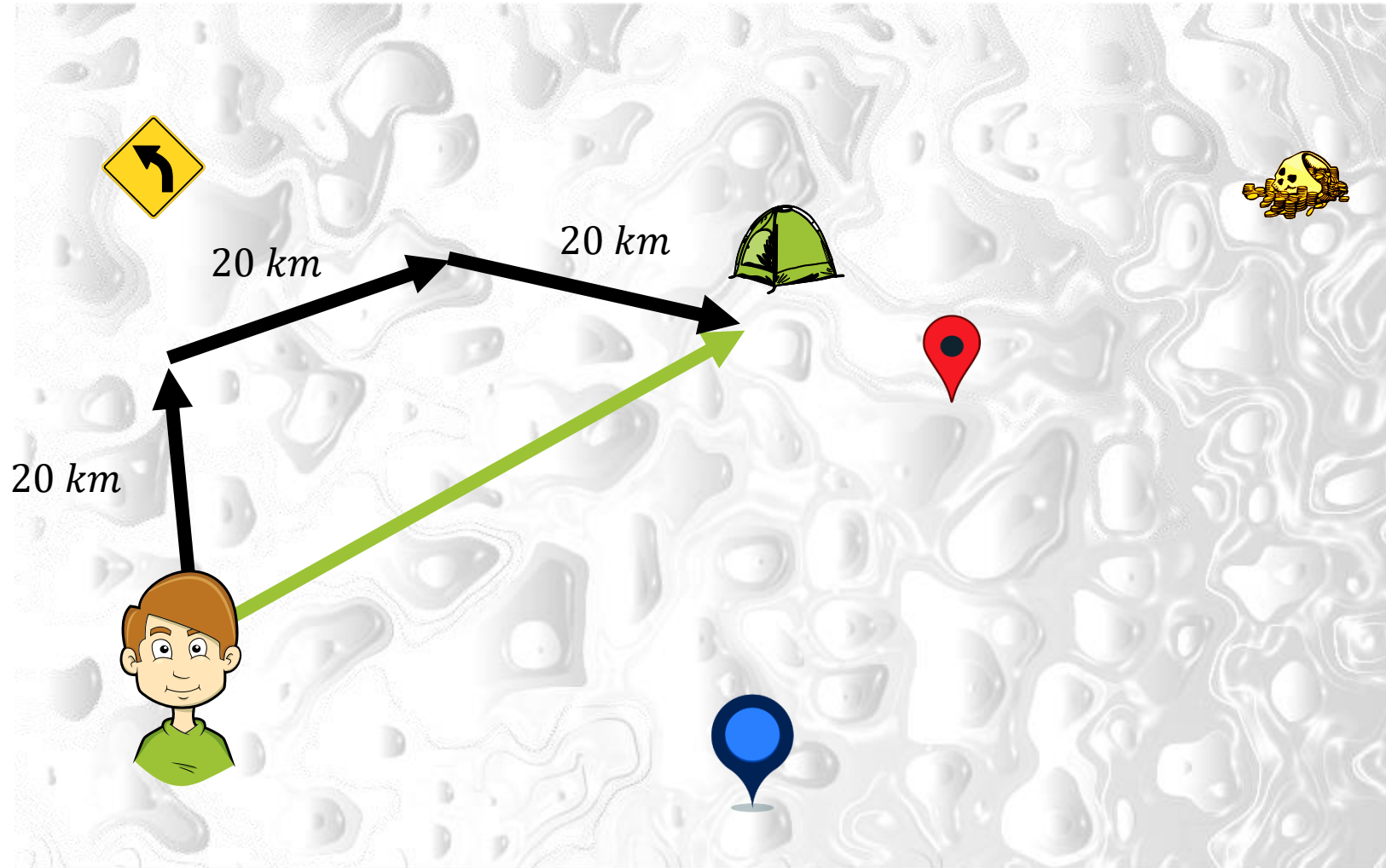
# PSO search strategy



$$2 \times r \times 10 \text{ km}$$

$r$  in  $[0,1]$

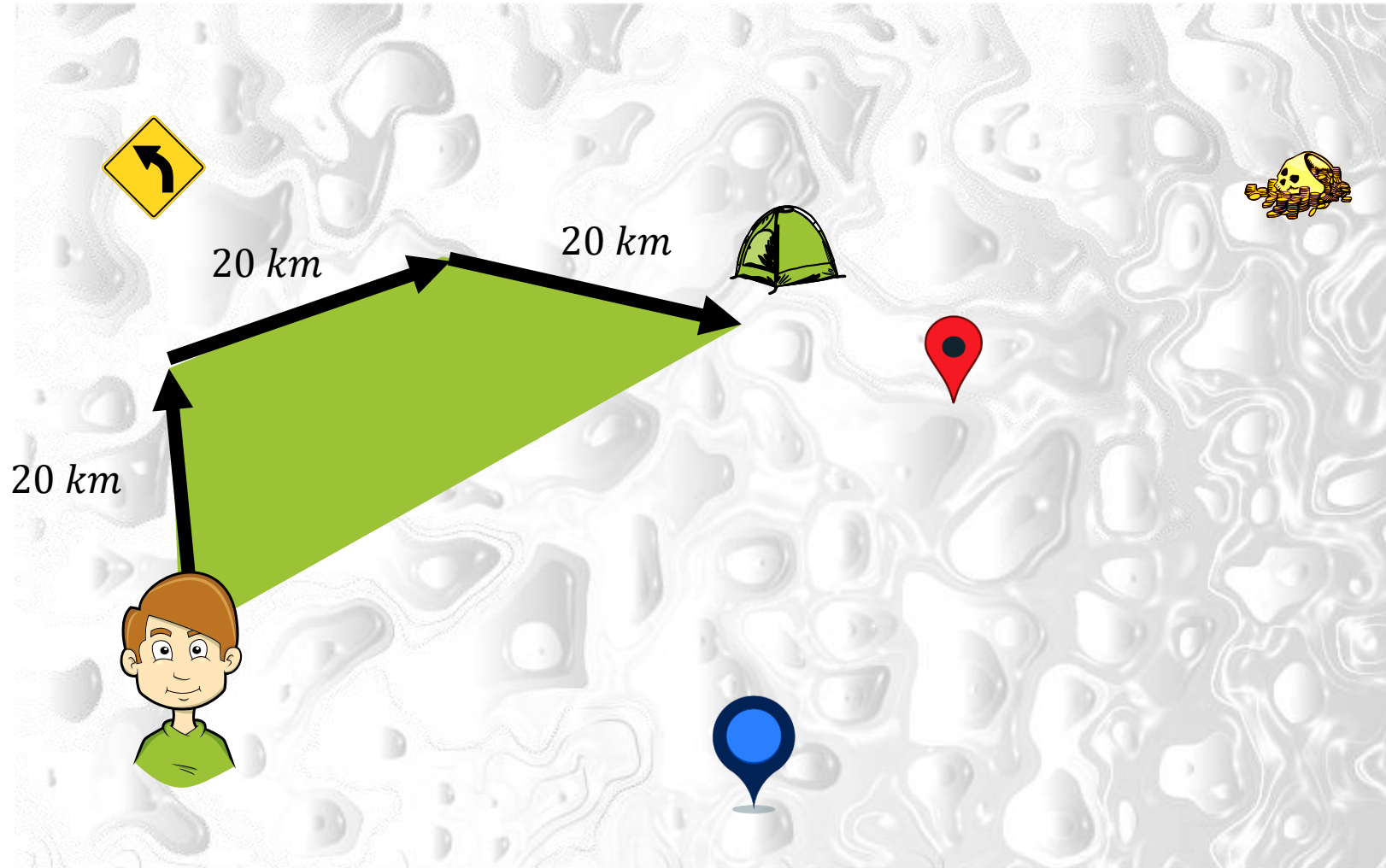
# PSO search strategy



$$2 \times r \times 10 \text{ km}$$

$r$  in  $[0,1]$

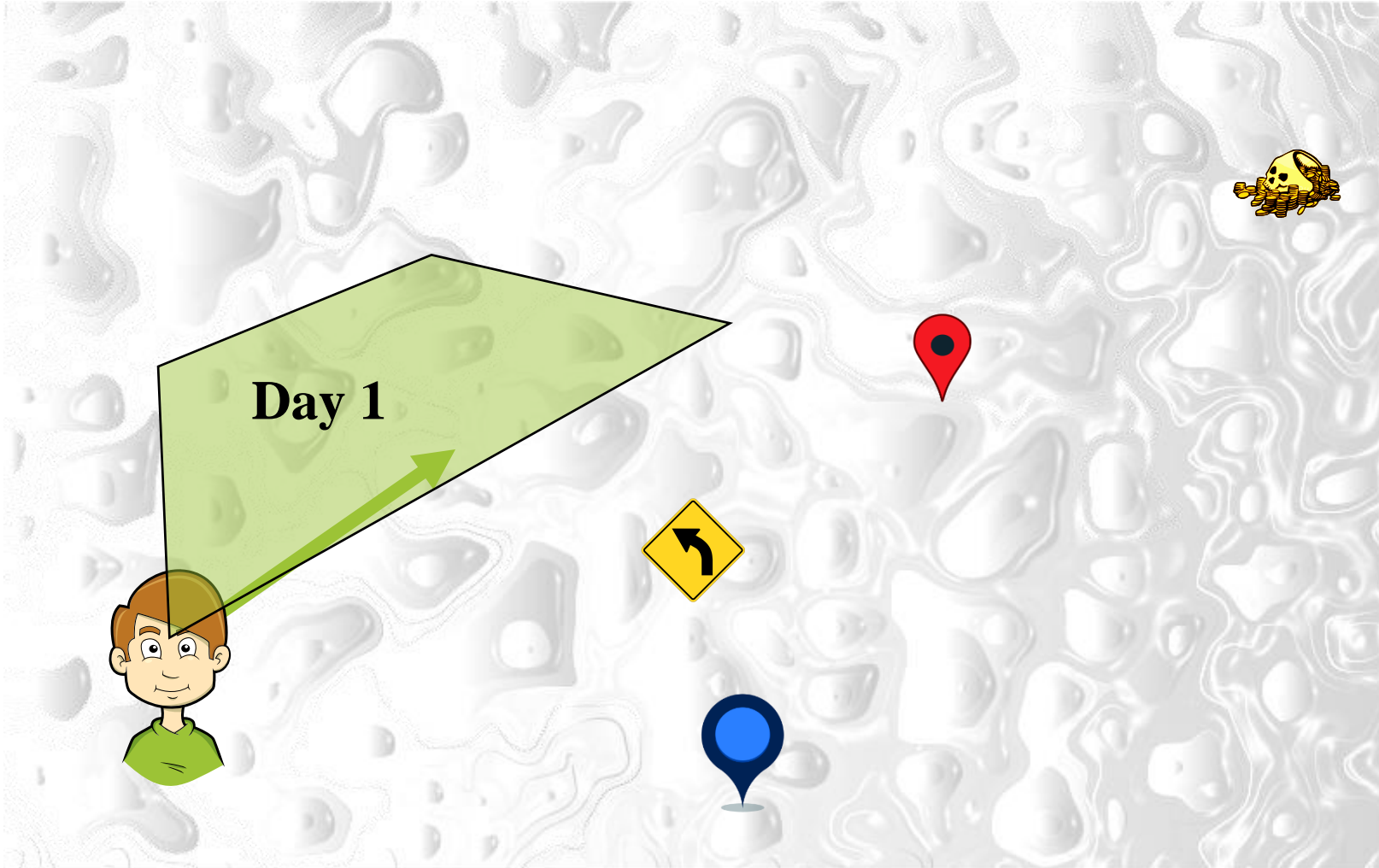
# PSO search strategy



$$2 \times r \times 10 \text{ km}$$

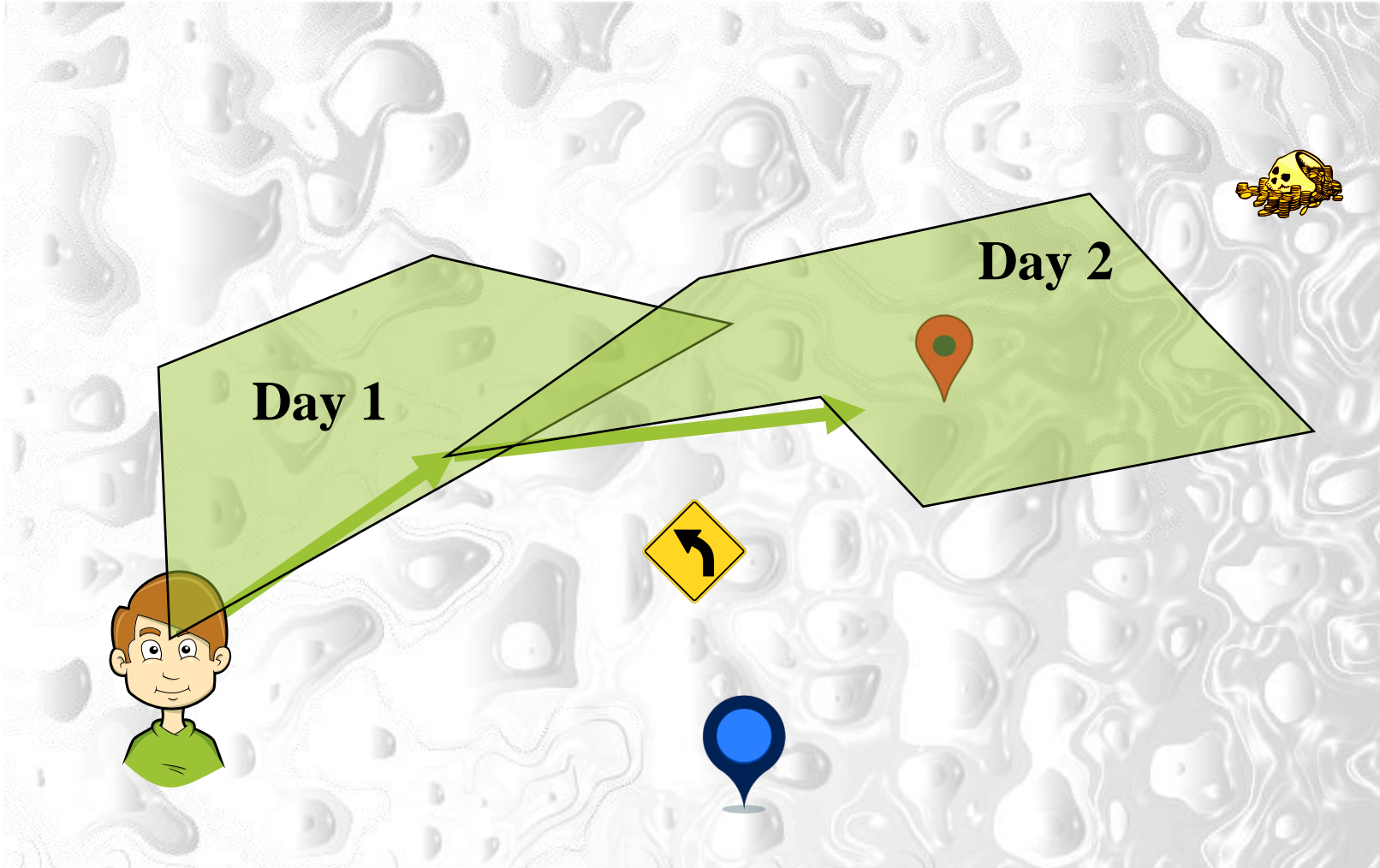
$r$  in  $[0,1]$

# PSO search strategy



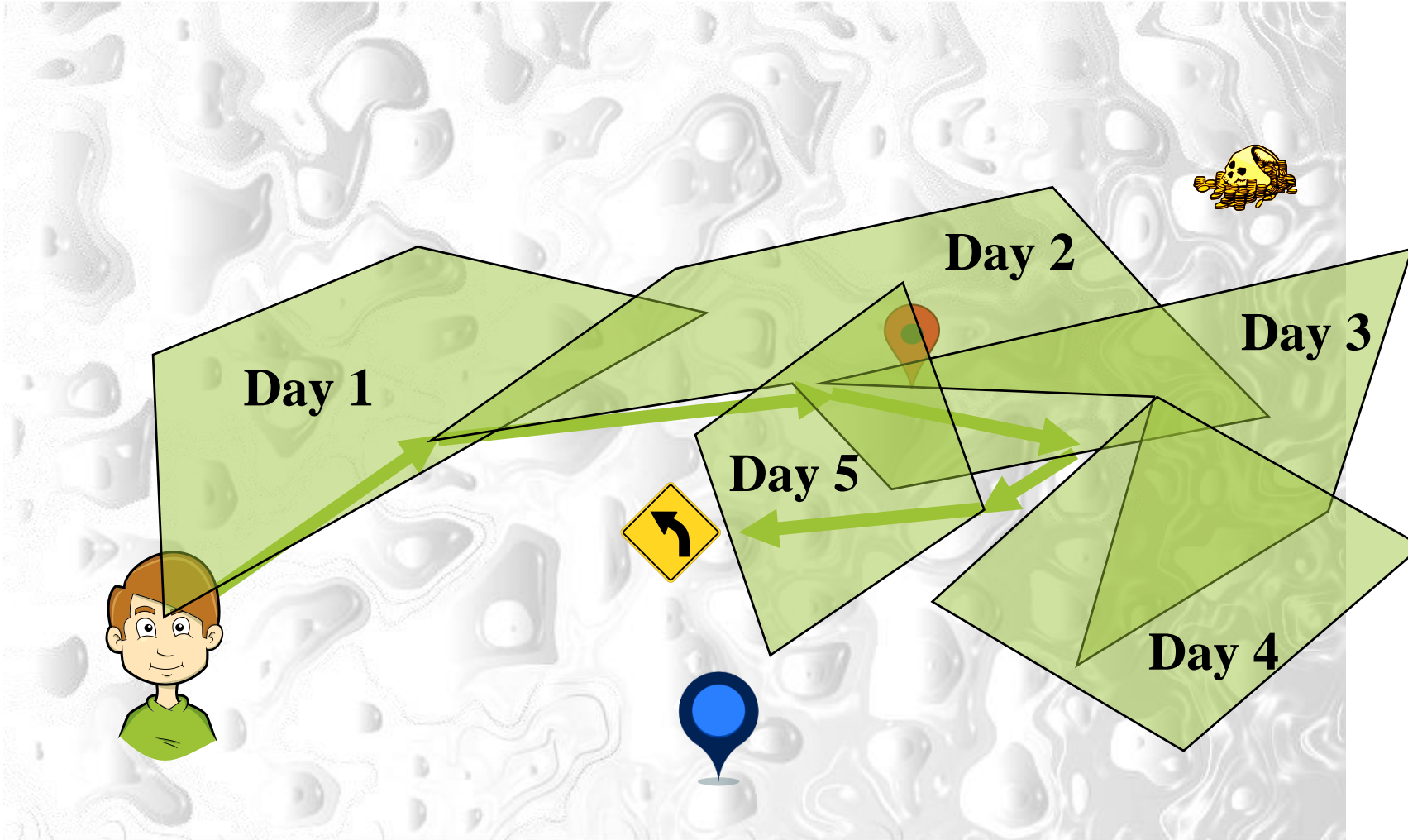


# PSO search strategy

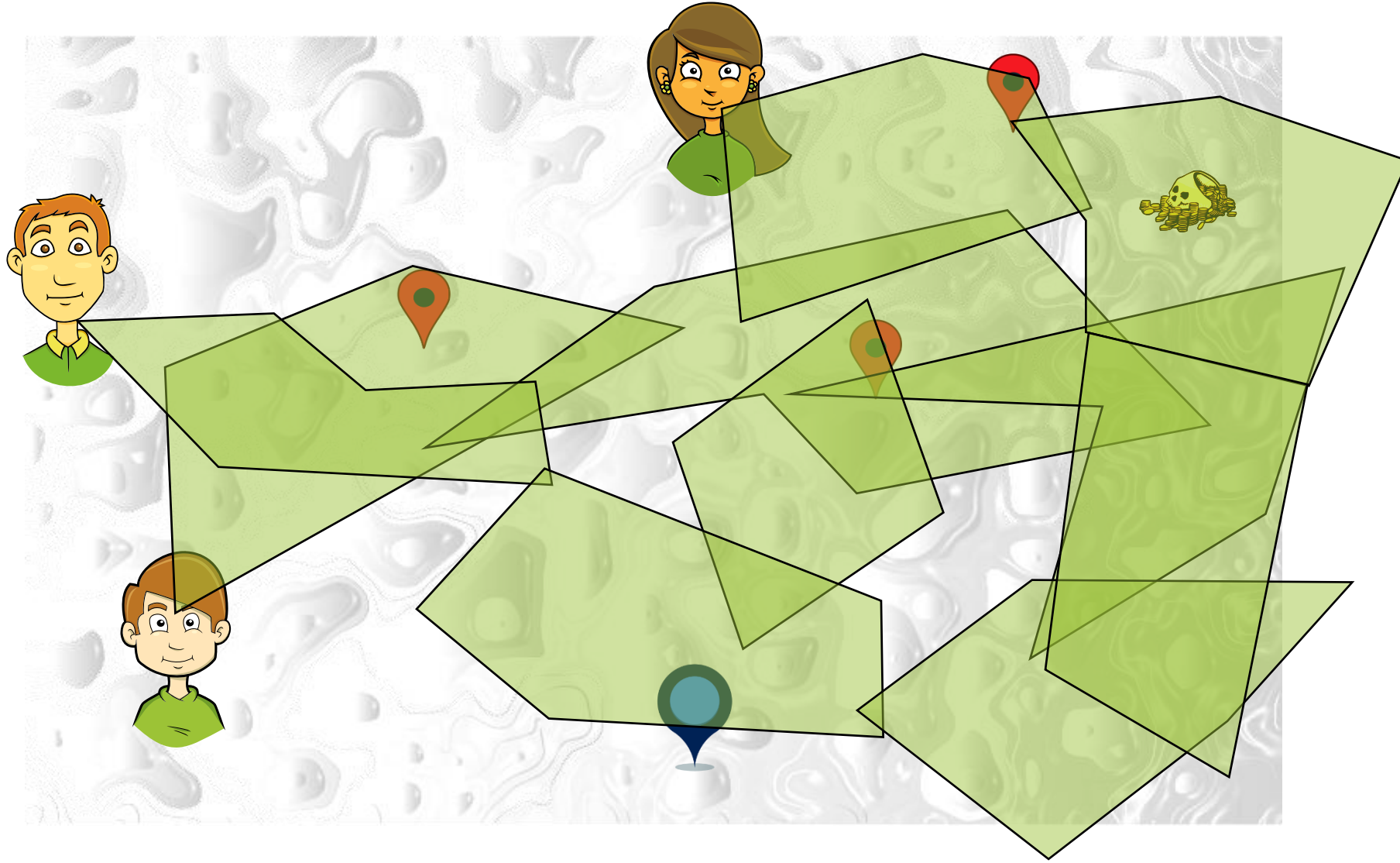




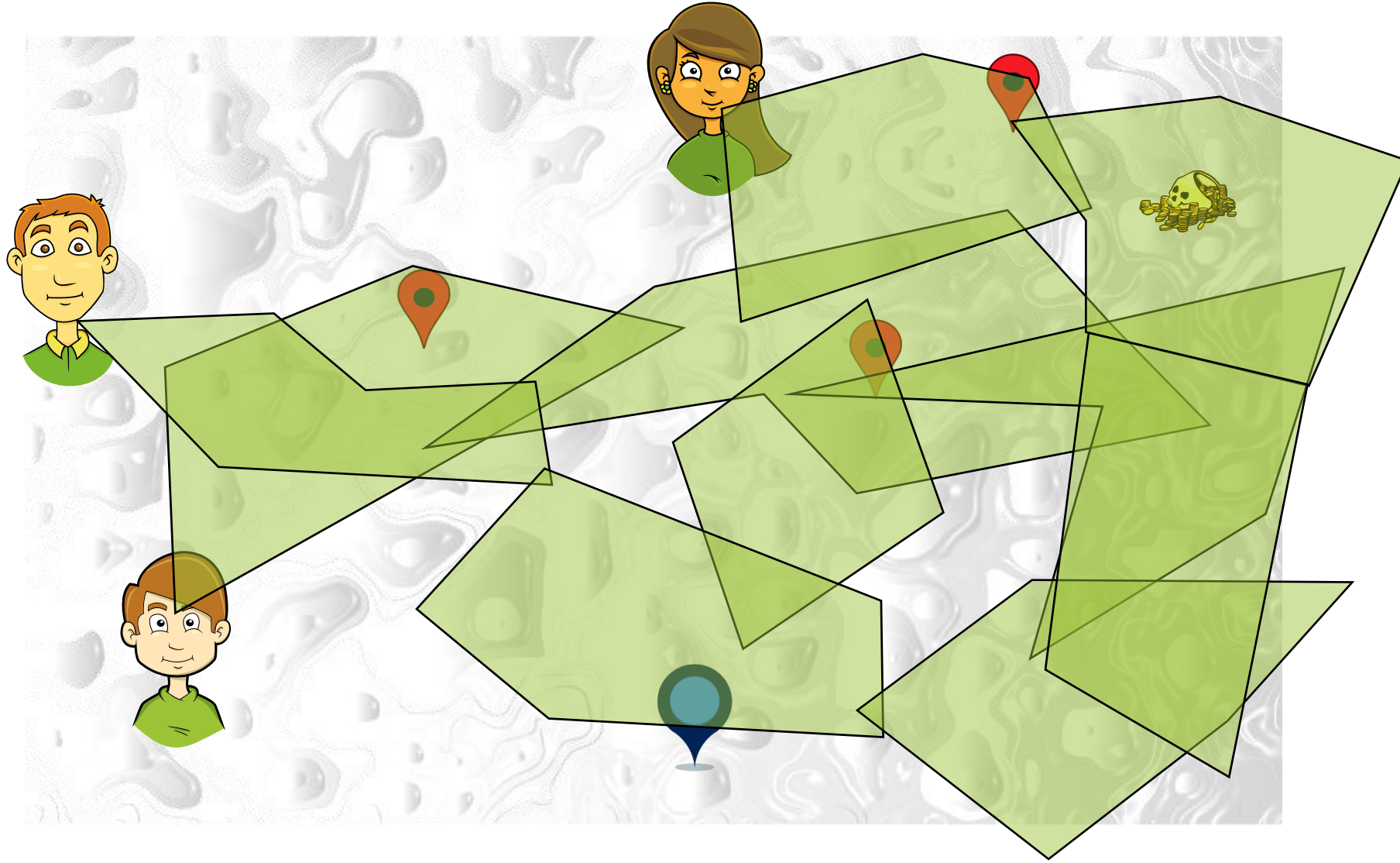
# PSO search strategy



# PSO search strategy

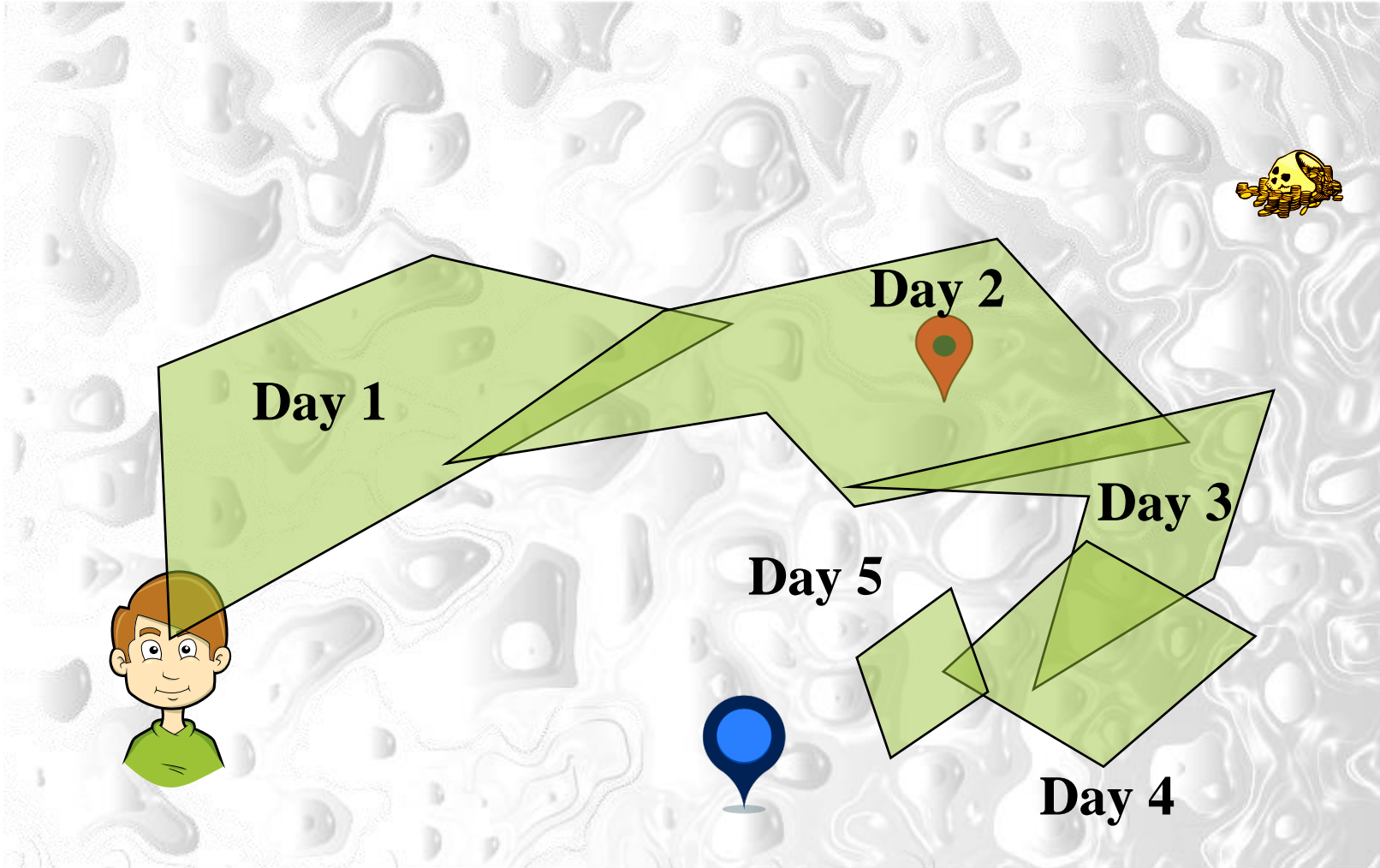


# PSO search strategy

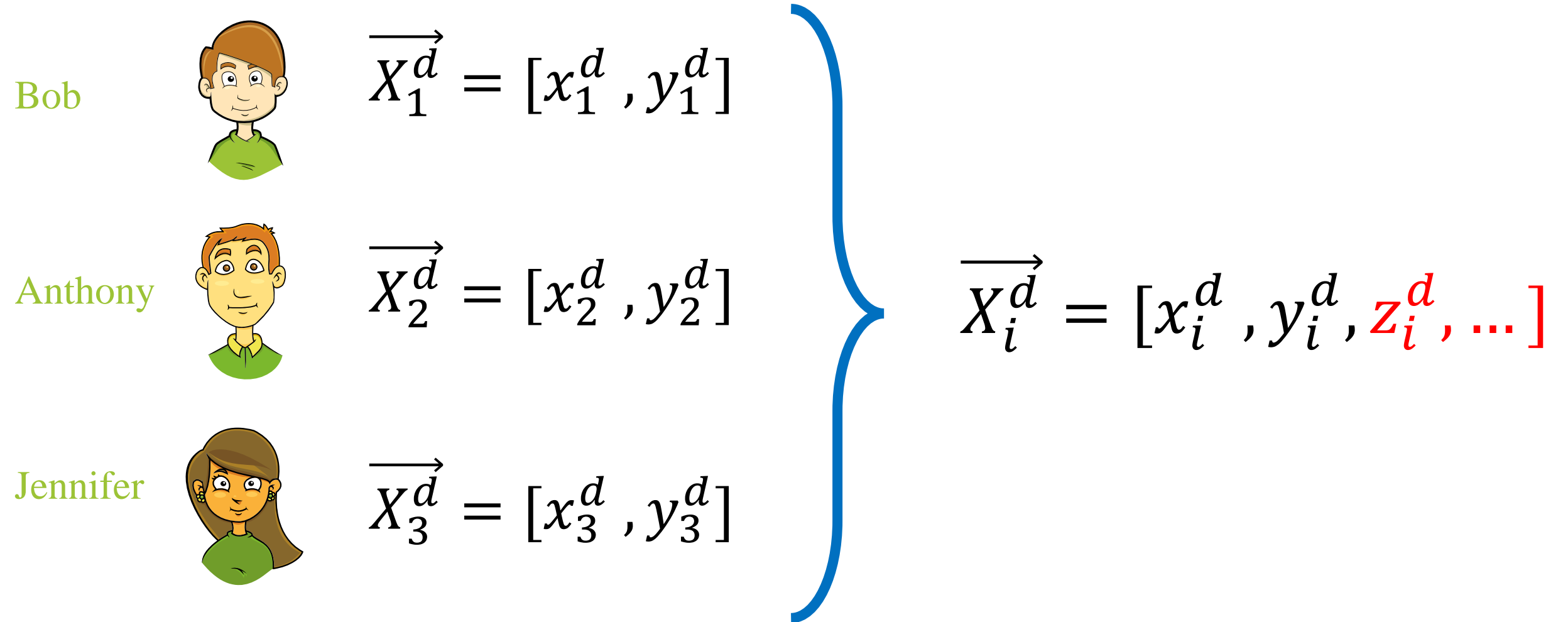




# PSO search strategy



# PSO search strategy





# PSO search strategy

$$\overrightarrow{V_i^{d+1}} = 2r_1 \overrightarrow{V_i^d} + 2r_2 \left( \overrightarrow{P_i^d} - \overrightarrow{X_i^d} \right) + 2r_3 \left( \overrightarrow{G^d} - \overrightarrow{X_i^d} \right)$$

Next  
velocity  
(tomorrow)



Current  
velocity  
(today)



Personal  
best  
solution

Distance to the  
personal best

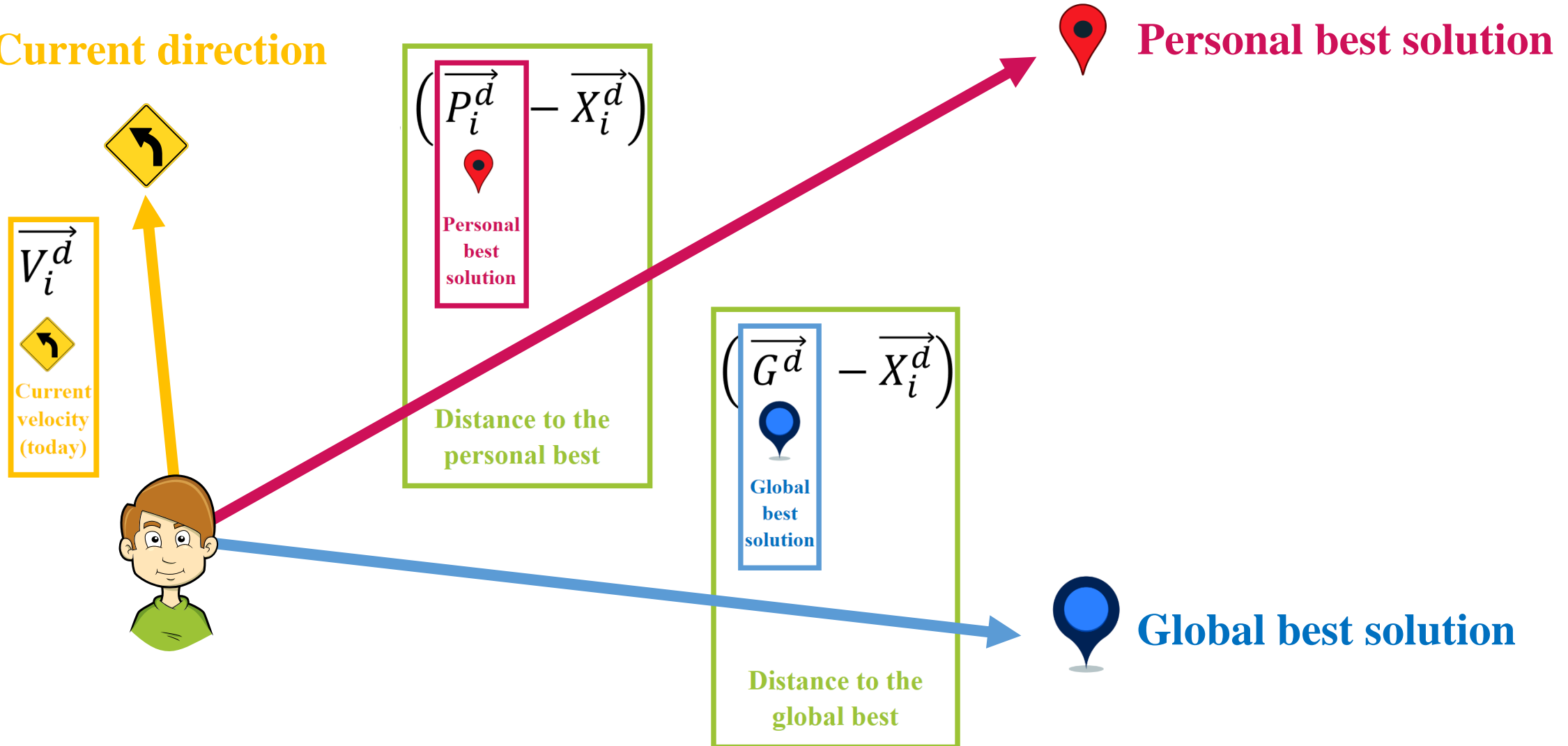


Global  
best  
solution

Distance to the  
global best

# PSO search strategy

Current direction



# PSO search strategy

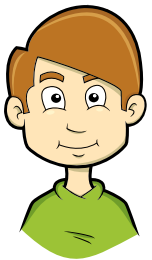
$$\overrightarrow{X_i^{d+1}} = \overrightarrow{X_i^d} + \overrightarrow{V_i^{d+1}}$$



Position in  
day  $d+1$

Position in  
day  $d$

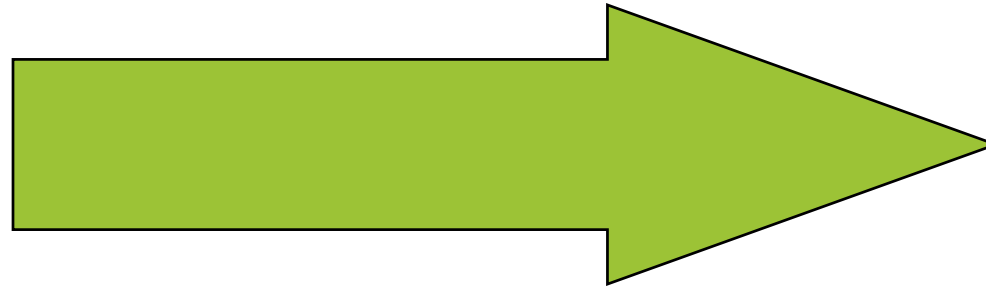
Velocity in  
day  $d+1$



$\overrightarrow{X_i^d}$



$\overrightarrow{V_i^{d+1}}$



$\overrightarrow{X_i^{d+1}}$



# Mathematical model of PSO

$$\overrightarrow{X_i^{t+1}} = \overrightarrow{X_i^t} + \overrightarrow{V_i^{t+1}}$$

$$\overrightarrow{V_i^{t+1}} = w \overrightarrow{V_i^t} + c_1 r_1 \left( \overrightarrow{P_i^t} - \overrightarrow{X_i^t} \right) + c_2 r_2 \left( \overrightarrow{G^t} - \overrightarrow{X_i^t} \right)$$



Inertia



Cognitive component



Social component



# Mathematical model of PSO

$$\overrightarrow{X_i^{t+1}} = \overrightarrow{X_i^t} + \overrightarrow{V_i^{t+1}}$$

$$\overrightarrow{V_i^{t+1}} = w \overrightarrow{V_i^t} + c_1 r_1 \left( \overrightarrow{P_i^t} - \overrightarrow{X_i^t} \right) + c_2 r_2 \left( \overrightarrow{G^t} - \overrightarrow{X_i^t} \right)$$



Inertia



Cognitive component



Social component

# Exploration and exploitation in PSO

$$\overrightarrow{X_i^{t+1}} = \overrightarrow{X_i^t} + \overrightarrow{V_i^{t+1}}$$

$$\overrightarrow{V_i^{t+1}} = w \overrightarrow{V_i^t} + c_1 r_1 \left( \overrightarrow{P_i^t} - \overrightarrow{X_i^t} \right) + c_2 r_2 \left( \overrightarrow{G^t} - \overrightarrow{X_i^t} \right)$$



Inertia



Cognitive component



Social component

# Pseudo code of PSO

**Initialize** the controlling parameters ( $N$ ,  $c1$ ,  $c2$ ,  $Wmin$ ,  $Wmax$ ,  $Vmax$ , and  $MaxIter$ )

**Initialize** the population of  $N$  particles

```
do
  for each particle
    calculate the objective of the particle
    Update PBEST if required
    Update GBEST if required
  end for

  Update the inertia weight
  for each particle
    Update the velocity (V)
    Update the position (X)
  end for
while the end condition is not satisfied
```

**Return** GBEST as the best estimation of the global optimum

# Test function

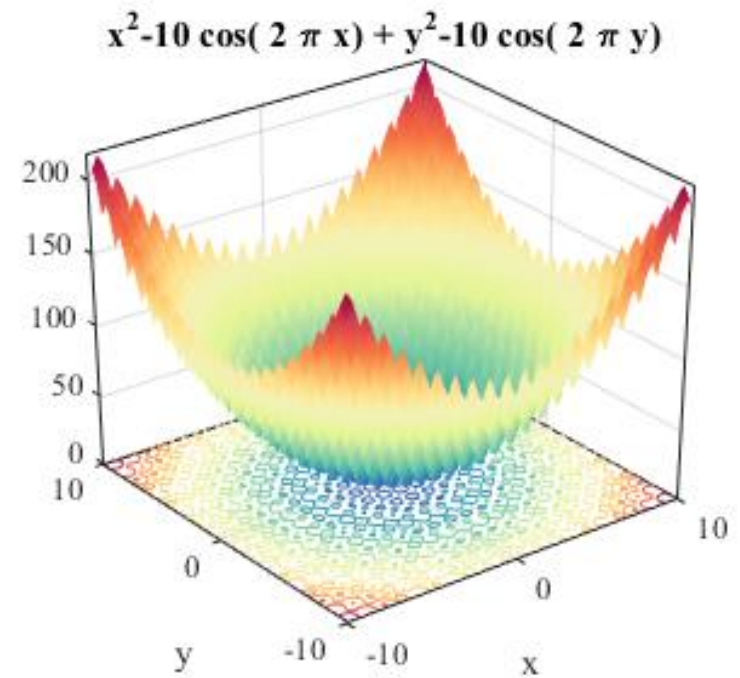
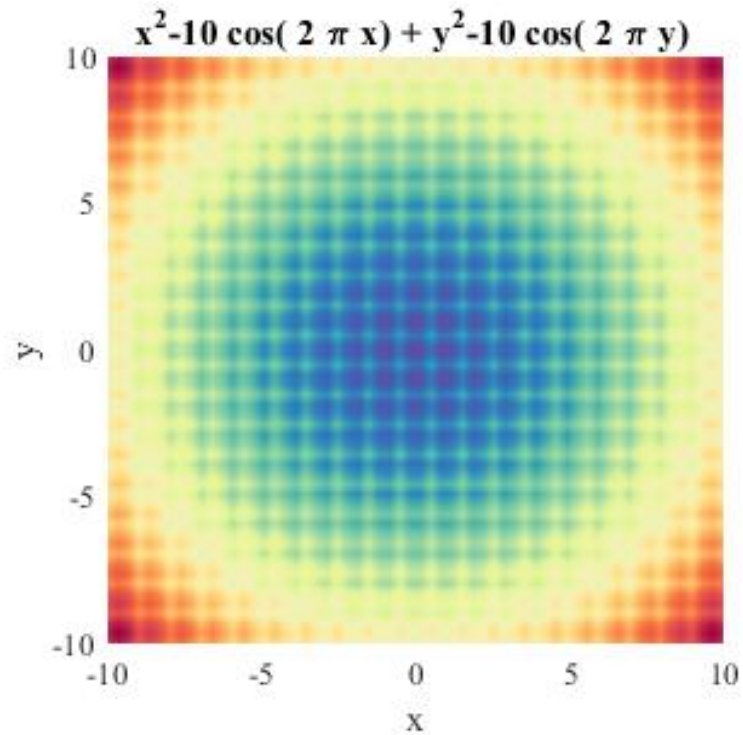
$w$



$c_1$



$c_2$





# Simulation of PSO

# Effect of parameters

$w$



# Effect of parameters

$c_1$  

$c_2$  