

For each  $p \in \Omega$  there exists an open neighbourhood  $U_p$  and some  $\epsilon > 0$  such that the map

$$\begin{aligned}\varphi : (-\epsilon, \epsilon) \times U &\longrightarrow \Omega, \\ (t, p) &\longrightarrow \varphi(t, p) = \varphi_t(p) = \gamma_p(t).\end{aligned}$$

For all  $s, t \in \mathbb{R}$  we have  $\varphi_s \circ \varphi_t = \varphi_{s+t}$  wherever this expression is meaningful. It is worth noting that domain of  $\varphi_s \circ \varphi_t$  is defined by  $D_{sot} = \{p \mid p \in \mathcal{D}_t, \varphi_t(p) \in \mathcal{D}_s\}$ . In addition we have, in general  $D_{sot} \subset \mathcal{D}_{s+t}$ . The equality holds whenever  $st > 0$ .

We have the following theorem for completeness of vector fields

**Theorem 2.8.4 (Chilingworth, 1976).** *The differential equation  $\dot{x} = f(x)$ , for  $x \in M$  with a compact set  $M$  and  $f \in C^1$  has integral curves defined for all  $t$ .*

### 2.8.4 Linear systems

We first consider the linear dynamical systems  $\dot{x} = Ax$  for  $x \in \mathbb{R}^n$ . It is straightforward to see that the solution of such system is of the form  $x(t) = x_0 e^{At}$ . One can realise the power  $e^{At}$  as a convergent series

$$e^{At} = \sum_{k=0}^{\infty} \frac{1}{k!} A^k = I_n + A + \frac{1}{2} A^2 + \frac{1}{3!} A^3 + \dots$$

Nevertheless, we can take another more constructive steps using linear algebra.

**Theorem 2.8.5.** *Suppose that  $A$  is a square matrix of dimension  $n$  with the characteristic polynomial  $f$  and the minimal polynomial  $g$*

$$f(x) = (x - c_1)^{d_1} \dots (x - c_k)^{d_k}, \quad g(x) = (x - c_1)^{r_1} \dots (x - c_k)^{r_k}.$$

*Let  $W_i = \ker(A - c_i I)^{r_i}$  for each  $i$ . Then we obviously have  $\dim W_i = d_i$  and  $n = \sum_{i=1}^k d_i$  and are nonzero vectors  $\beta_{i1}, \dots, \beta_{ir_i}$  such that*

$$\begin{aligned}(A - c_i I)\beta_{i1} &= 0, \\ (A - c_i I)\beta_{i2} &= \beta_{i1}, \\ &\vdots \\ (A - c_i I)\beta_{ir_i} &= \beta_{ir_{i-1}},\end{aligned} \tag{2.8.8}$$

*so that all sets  $B_i = \{\beta_{i1}, \dots, \beta_{ir_i}\}$  and their union  $\cup_{i=1}^k B_i$  are linearly independent.*

*Proof.* Consider the chain  $\{\ker(A - c_i I)^t\}_{t=1}^{r_i}$ . This chain is strictly increasing because one can easily show  $\ker(A - c_i I)^t = \ker(A - c_i I)^{t+1}$  iff for all  $t' > t$  the equality  $\ker(A - c_i I)^{t'} = \ker(A - c_i I)^t$ . Let  $W'_i = \ker(A - c_i I)^{r'_i}$  for  $r'_i < r_i$ , then  $W'_i$  is invariant under  $A$  and  $A'_i = A|_{W'_i}$  is nilpotent. Therefore the minimal polynomial

of  $A'_i$  is  $(A - c_i I)^{r''_i}$  for some  $r''_i \leq r'_i$  and this contradicts  $W'_i = W_i$ . We take the nonzero vector  $\beta_{ir_i} \in \ker(A - c_i I)^{r_i}$  and let

$$\begin{aligned}\beta_{ir_{i-1}} &= (A - c_i I)\beta_{ir_i}, \\ \beta_{ir_{i-2}} &= (A - c_i I)^2\beta_{ir_i}, \\ &\vdots \\ \beta_{i1} &= (A - c_i I)^{r_i-1}\beta_{ir_i},\end{aligned}$$

It is clear that  $(A - c_i I)\beta_{i1} = 0$ .

In general, we know that each  $c_i$  is an eigenvalue for  $A^*$ . In addition the characteristic and minimal polynomial of  $A^*$  are exactly  $f$  and  $g$  respectively. Here we state the following result, although we will not use it.

**Corollary 2.8.5.** *suppose  $\alpha$  is a nonzero vector orthogonal to all vectors in  $\ker(A - c_i I)^{r_i-1}$  unless  $W_i \setminus \ker(A - c_i I)^{r_i-1}$ . Assume that for all  $j \neq i$  the vector  $\alpha$  is orthogonal to  $W_j$ . Then  $\alpha$  is an eigenvector of  $A^*$  corresponding to  $c_i$ .*

*Proof.* The proof is straightforward and is left as an exercises.

**Corollary 2.8.6.** *According to the Theorem 2.8.5, the solution of  $\dot{x} = Ax$  is explicitly closely given by*

$$x(t) = \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \sum_{i=1}^m \beta_{ij} \frac{t^{m-i}}{(m-i)!} e^{c_j t}.$$

Here  $a_{jm}$  are some constants.

*Proof.* We have

$$\dot{x} = \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \left[ \sum_{i=1}^{m-1} \beta_{ji} \frac{t^{m-i-1}}{(m-i-1)!} e^{c_j t} + c_j \sum_{i=1}^m \beta_{ji} \frac{t^{m-i}}{(m-i)!} e^{c_j t} \right].$$

An also

$$\begin{aligned}Ax(t) &= \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \left[ A\beta_{j1} \frac{t^{m-1}}{(m-1)!} e^{c_j t} + \sum_{i=2}^m A\beta_{ji} \frac{t^{m-i}}{(m-i)!} e^{c_j t} \right] \\ &= \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \left[ c_1 \beta_{j1} \frac{t^{m-1}}{(m-1)!} e^{c_1 t} + \sum_{i=2}^m (\beta_{ji-1} + c_j \beta_{ji}) \frac{t^{m-i}}{(m-i)!} e^{c_j t} \right] \\ &\vdots \\ &= \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \left[ \sum_{i=2}^m \beta_{ji-1} \frac{t^{m-i}}{(m-i)!} e^{c_j t} + c_j \sum_{i=1}^m (\beta_{ji} \frac{t^{m-i}}{(m-i)!} e^{c_j t}) \right] \\ &= \sum_{j=1}^k \sum_{m=1}^{r_j} a_{jm} \left[ \sum_{s=1}^{m-1} s \beta_{js} \frac{t^{m-s-1}}{(m-s-1)!} e^{c_j t} + c_j \sum_{s=1}^m \beta_{js} \frac{t^{m-s}}{(m-s)!} e^{c_j t} \right].\end{aligned}$$