Anchor
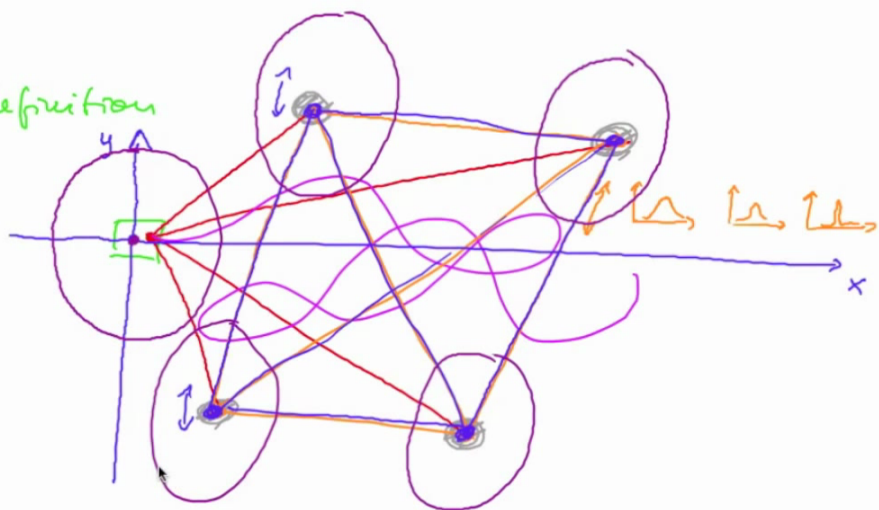Datum definition

Online SLAM : $p(x_t, m \mid z_{1:t}, u_{1:t})$
Full SLAM : $p(x_{1:t}, m \mid z_{1:t}, u_{1:t})$