

**EXP NO: 7****IMPLEMENTATION OF VARIOUS IMAGE SEGMENTATION ALGORITHMS****AIM:**

To implement different image segmentation algorithms (edge-based, region-based, clustering, and advanced methods like watershed and GrabCut).

**REQUIREMENTS:**

Software: Python 3.x

Libraries: OpenCV, NumPy, Matplotlib, scikit-image, scikit-learn

Install:

`pip install opencv-python numpy matplotlib scikit-image scikit-learn`

**ALGORITHMS COVERED:**

1. Edge-based Segmentation (Canny)
2. Region Growing (Seed-based)
3. Watershed Segmentation
4. Mean-Shift Segmentation (using skimage)
5. GrabCut (Graph-cut based)

**EDGE-BASED SEGMENTATION (CANNY)****ALGORITHM STEPS:**

Convert to grayscale and apply Gaussian blur to reduce noise.

1. Use `cv2.Canny` with thresholds (`minVal`, `maxVal`) to detect edges.
2. Optionally apply morphological closing to get continuous contours.
3. Find contours and mask regions if desired.

**REGION GROWING (SEED-BASED)****ALGORITHM STEPS:**

1. Choose one or more seed points inside the object region.
2. Initialize a region containing the seed(s).
3. Iteratively add neighboring pixels whose similarity to region (e.g., intensity difference) is below threshold.
4. Stop when no more pixels can be added.

## WATERSHED SEGMENTATION

### ALGORITHM STEPS:

1. Compute sure background via dilation and sure foreground via distance transform + threshold.
2. Compute unknown region and label markers.
3. Apply cv2.watershed to segment regions; boundaries marked on image.
4. Refine using morphological operations.

## MEAN-SHIFT / FELZENSZWALB / SLIC (SUPERPIXEL-STYLE)

### ALGORITHM STEPS:

1. Convert image to appropriate float range.
2. Use skimage.segment.felzenszwalb or slic or quickshift to obtain segments.
3. Map labels to colors and visualize.

## GRAB CUT (INTERACTIVE GRAPH-CUT)

### ALGORITHM STEPS:

1. Provide an initial bounding rectangle around the object, or use mask with probable foreground/background.
2. Initialize bgdModel and fgdModel and call cv2.grabCut with iterCount.
3. Extract mask where probable/definite foreground labels are kept and visualize result.

### CODE:

```
import cv2, numpy as np, matplotlib.pyplot as plt

# Read image
img = cv2.imread("/content/img.jpg")
gray = cv2.cvtColor(img, cv2.COLOR_BGR2GRAY)

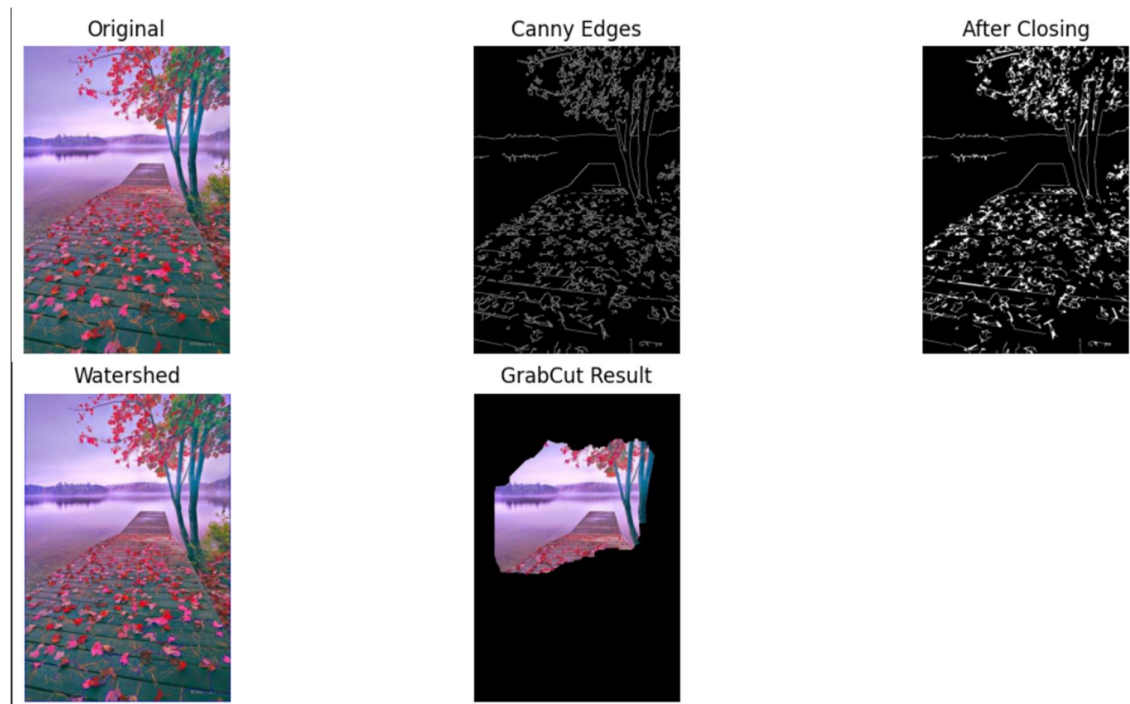
# ---- Canny Edge Detection ----
edges = cv2.Canny(cv2.GaussianBlur(gray,(5,5),0),100,200)
closed = cv2.morphologyEx(edges, cv2.MORPH_CLOSE, np.ones((3,3),np.uint8))

# ---- Watershed Segmentation ----
_,thresh = cv2.threshold(gray,0,255,cv2.THRESH_BINARY_INV+cv2.THRESH_OTSU)
opening = cv2.morphologyEx(thresh,cv2.MORPH_OPEN,np.ones((3,3),np.uint8),iterations=2)
```

```
sure_bg = cv2.dilate(opening, None, iterations=3)
dist = cv2.distanceTransform(opening, cv2.DIST_L2, 5)
_, sure_fg = cv2.threshold(dist, 0.7 * dist.max(), 255, 0)
unknown = cv2.subtract(sure_bg, np.uint8(sure_fg))
_, markers = cv2.connectedComponents(np.uint8(sure_fg))
markers = markers + 1; markers[unknown == 255] = 0
ws_img = img.copy(); markers = cv2.watershed(ws_img, markers)
ws_img[markers == -1] = [255, 0, 0]
ws_disp = ws_img.astype(np.uint8)

# ---- GrabCut Segmentation ----
mask = np.zeros(img.shape[:2], np.uint8)
bgdModel, fgdModel = np.zeros((1, 65), np.float64), np.zeros((1, 65), np.float64)
rect = (50, 50, img.shape[1] - 100, img.shape[0] - 100)
cv2.grabCut(img, mask, rect, bgdModel, fgdModel, 5, cv2.GC_INIT_WITH_RECT)
result = img * np.where((mask == 2) | (mask == 0), 0, 1).astype(np.float)

# ---- Display ----
titles = ["Original", "Canny Edges", "After Closing", "Watershed", "GrabCut Result"]
images = [img[...,:-1], edges, closed, ws_disp[...,:-1], result[...,:-1]]
plt.figure(figsize=(12, 6))
for i in range(5):
    plt.subplot(2, 3, i + 1)
    plt.imshow(images[i], cmap='gray' if i in [1, 2] else None)
    plt.title(titles[i]); plt.axis('off')
plt.tight_layout()
plt.show()
```

**OUTPUT:****RESULT:**

The image was successfully segmented using different algorithms, effectively separating regions of interest from the background. Methods like thresholding, region-based, and edge-based segmentation highlighted distinct objects and boundaries, producing clear segmented outputs for analysis.