

# T. RILEY DAWSON

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 rileydawson.com

 github.com/gnarlywhale

## EDUCATION

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### University of Alberta

MBA\MEng (Computer Engineering; Expected) 2019 - 2023  
MEng focus on Reinforcement Learning

### 上智大学 - Sophia University

Summer Session in Asian Studies Summer 2014

### University of Alberta

BSc Eng - Software Option 2008 - 2014

## PROFESSIONAL EXPERIENCE

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### Gaze and Movement Analysis Inc.

Co-founder, CTO July 2021 - Present  
GaMA is a spin-off venture based on research out of the BLINC Lab. We provide task-agnostic human performance analytics based on motion, gaze, and various other data streams.

### The Bionic Limbs for Improved Natural Control Lab, University of Alberta

Software Engineer In Training Oct. 2016 - Present  
Supervisors: Dr. Craig S. Chapman, Dr. Jacqueline Hebert, Dr. Patrick Pilarski  
Primary focus is on developing **Gaze and Movement Assessment (GaMA)**, a robust software platform for universal multi-modal motion data analysis.

### Diesel Tech Industries

Software Engineer In Training June 2015 - October 2016  
Fully designed and implemented a web-based application for tracking employee hours.

### Common Grounds Arts Society

Android\iOS Developer April 2014 - July 2014  
Sole developer of the official "Found Festival" app

## CONFERENCE PRESENTATIONS & WORKSHOPS

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6. Stone S., Boser Q., **Dawson T.R.**, Vette V., Hebert J., Pilarski P., Chapman C. (2022). Generating accurate 3D gaze vectors using synchronized eye tracking and motion capture. Springer. Behavioural Research Methods. <https://doi.org/10.3758/s13428-022-01958-6>
5. Stone S., Boser Q., **Dawson T.R.**, Vette V., Hebert J., Pilarski P., Chapman C. (2021). Sub-centimeter 3D gaze vector on real-world tasks: an investigation of eye and motion capture calibration routines. Association for Computing Machinery (ACM) Symposium on Eye Tracking Research & Applications (ETRA). Stuttgart, Germany.
4. Cuthbertson L., Kearney A., **Dawson T.R.**, Zawaduk A., Cuthbertson E., Gordon-Tighe A., Mathewson K. (2019) Women, politics and Twitter: Using machine learning to change the discourse. Neural Information Processing Systems Foundation (NeurIPS) Conference. Vancouver BC.
3. Boser Q., **Dawson T.R.**, Lavoie E., Valevicius A., Pilarski P., Vette A., Chapman C., Hebert J. (2019). Characterizing the Eye Gaze Behaviour of Body-powered Prosthesis Users. ISPO Canada RehabWeek (Abstract and Oral Presentation).

2. Boser Q., **Dawson T.R.** (*Presenting Author*), Valevicius A., Vette A., Pilarski P., Hebert J., Chapman C. (2018). A flexible software platform for integrating eye tracking and motion capture data for measuring human movement behaviour in a reconstructed 3D environment. Presented at the Canadian Action and Perception Network (CAPnet) Canadian Physiological Society (CPS) Satellite Symposium at the Canadian Association for Neuroscience (CAN) Conference. Vancouver BC.
1. Stone S.A., **Dawson T.R.**, Boser Q., Hebert J.S., Chapman C.S. (2018). Using Lab Streaming Layer to collect synchronized multimodal datasets. Presented at the Canadian Action and Perception Network (CAPnet) Canadian Physiological Society (CPS) Satellite Symposium at the Canadian Association for Neuroscience (CAN) Conference. Vancouver BC.

## PERSONAL PROJECTS

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### Venture Capital Investment Competition

Sobey School of Business

March 4 2022

Competed with the University of Alberta's MBA team, achieving 2nd place overall

### AXIS Reloaded

University Of Alberta Faculty of Engineering

September 2019 - October 2019

Design and development of control software for a robotic display platform

### aNAOmate

Edmonton Catholic School Board

July 2019 - August 2019

Directed design and implementation of a simplified control interface of Nao robotic platform for elementary education applications

### VR MariNAOette

ISARC Constructing Futures Hackathon

May 2019

Integration of a cloud-based image classifier with the Nao robotic platform

### HumanMachine

Edmonton Fringe Festival

April 2014 - July 2014

Created MariNAOette robotic control interface and piloted robotic performance for the HumanMachine Artificial Intelligence Improv show

## AWARDS

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Dyan and Karyn Triffo Awards for Innovation (\$4000)

May 2022

ISARC Constructing Futures Hackathon - **1st Place** (\$1000)

May 2019

Jason Lang Academic Scholarship (\$1000)

August 2010, 2013

Stowkowy Scholarship in Engineering (\$1500)

August 2010

University of Alberta Academic Excellence Scholarship (\$1250)

August 2008

## GRANTS RECEIVED

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Mitacs, "Accelerate Entrepreneur," \$120,000

July 2022-2023

Campus Alberta Neuroscience, "CAN Entrepreneurship Seed Grant," \$29,596

July 2019

## VOLUNTEER & SERVICE

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Edmonton Advisor Council on Startups (EACOS) Member

March 2021 - Present

University of Alberta Faculty of Engineering Student Leadership Group

October 2019 - Present

UAlberta Move-In Day Volunteer

September 2019

WISEST Workshop Leader

February & November 2019

South Sudanese Youth of Canada Conference- Photographer

July 2018

## TECHNICAL STRENGTHS & EXPERIENCE

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**Languages**

English (Fluent), French (Intermediate), Japanese (Beginner)

**Computer Languages & Software**

MATLAB, Python, R, JavaScript, C#, Java, L<sup>A</sup>T<sub>E</sub>X

**Experimental Techniques**

Motion capture, Eye tracking, Data Analysis