

## Task 1

I have created the following five routines to compute the following linear algebra operations on vectors, they are all documented [here](#) in the [Software Manual](#).

### 1. Vector Addition

```
1 def VecAdd(arr1, arr2):
2     sum = []
3     for i in range(len(arr1)):
4         sum.append(arr1[i] + arr2[i])
5     return sum
```

### 2. Vector Subtraction

```
1 def VecSub(arr1, arr2):
2     diff = []
3     for i in range(len(arr1)):
4         diff.append(arr1[i] - arr2[i])
5     return diff
```

### 3. Scalar Multiplication for Vectors

```
1 def ScaMul(c, arr):
2     ScalarProduct = c * arr
3     return ScalarProduct
```

### 4. Dot Product for Two Vectors of the Same Length

```
1 def DotPro(arr1, arr2):
2     if len(arr1) != len(arr2):
3         print('two vectors are not the same length')
4     sum = 0
5     for i in range(len(arr1)):
6         sum += arr1[i] * arr2[i]
7     return sum
```

### 5. Outer Product for Two Vectors of the Same Length

```
1 import numpy as np
2
3 def OutPro(arr1, arr2):
4     if len(arr1) != len(arr2):
5         print('two vectors are not the same length')
6
7     OutPro = np.outer(arr1, arr2)
8     return OutPro
```

I have also created the following testing code that test each of the routines,

```
1 import numpy as np
2 from VecAdd import VecAdd
3 from VecSub import VecSub
4 from ScaMul import ScaMul
5 from DotPro import DotPro
6 from OutPro import OutPro
7
8 # testing vectors and constant
9 arr1 = np.array([1, 1, 1])
```

```

10 arr2 = np.array([1, 2, 3])
11 C = 2
12
13 print('Vector Addition Result:', VecAdd(arr1, arr2))
14 print('Vector Subtraction Result:', VecSub(arr1, arr2))
15 print('Scalar Multiplication Result:', ScaMul(C, arr1))
16 print('Dot Product Result:', DotPro(arr1, arr2))
17 print('Outer Product Result:\n', OutPro(arr1, arr2))

```

Which has the following output:

```

xianggao@Xiangs-MacBook-Pro Tasksheet_09 % python Task_1.py
('Vector Addition Result:', array([2, 3, 4]))
('Vector Subtraction Result:', array([ 0, -1, -2]))
('Scalar Multiplication Result:', array([2, 2, 2]))
('Dot Product Result:', 6)
('Outer Product Result:\n', array([[1, 2, 3],
                                     [1, 2, 3],
                                     [1, 2, 3]]))

```

Figure 1. The Test Result of Each Routine from Terminal.

```

Vector Addition Result: [2 3 4]
Vector Subtraction Result: [ 0 -1 -2]
Scalar Multiplication Result: [2 2 2]
Dot Product Result: 6
Outer Product Result:
[[1 2 3]
 [1 2 3]
 [1 2 3]]

```

Figure 1.5. The Test Result of Each Routine from IDE.

## Task 2

I have created the following six routines to compute the following linear algebra operations on vectors, they are all documented [here](#) in the [Software Manual](#).

1. The magnitude of a vector - ( $l_1$ ) norm version

```

1 import numpy as np

```

```

2
3 def L1_Norm (arr1):
4     norm = np.linalg.norm(arr1, ord=1)
5     return norm

```

2. The magnitude of a vector - ( $l_2$ ) norm version

```

1 import numpy as np
2
3 def L2_Norm (arr1):
4     norm = np.linalg.norm(arr1, ord=2)
5     return norm

```

3. The magnitude of a vector - ( $l_\infty$ ) norm version

```

1 import numpy as np
2
3 def Linf_Norm (arr1):
4     norm = np.linalg.norm(arr1, ord=np.inf)
5     return norm

```

4. The error between vectors - ( $l_1$ ) norm version.

```

1 import numpy as np
2
3 def L1_Norm_Error (arr1, arr2):
4     norm = np.linalg.norm((arr1 - arr2), ord=1)
5     return norm

```

5. The error between vectors - ( $l_2$ ) norm version.

```

1 import numpy as np
2
3 def L2_Norm_Error (arr1, arr2):
4     norm = np.linalg.norm((arr1 - arr2), ord=2)
5     return norm

```

6. The error between vectors - ( $l_\infty$ ) norm version.

```

1 import numpy as np
2
3 def Linf_Norm_Error (arr1, arr2):
4     norm = np.linalg.norm((arr1 - arr2), ord=np.inf)
5     return norm

```

I have also created the following testing code that test each of the routines,

```

1 import numpy as np
2 from L1_Norm import L1_Norm
3 from L2_Norm import L2_Norm
4 from Linf_Norm import Linf_Norm
5 from L1_Norm_Error import L1_Norm_Error
6 from L2_Norm_Error import L2_Norm_Error
7 from Linf_Norm_Error import Linf_Norm_Error
8
9 # testing vectors
10 arr1 = np.array([1, 2, 3, 4])
11 arr2 = np.array([2, 3, 4, 5])
12
13 print('L1 Norm Result:', L1_Norm(arr1))

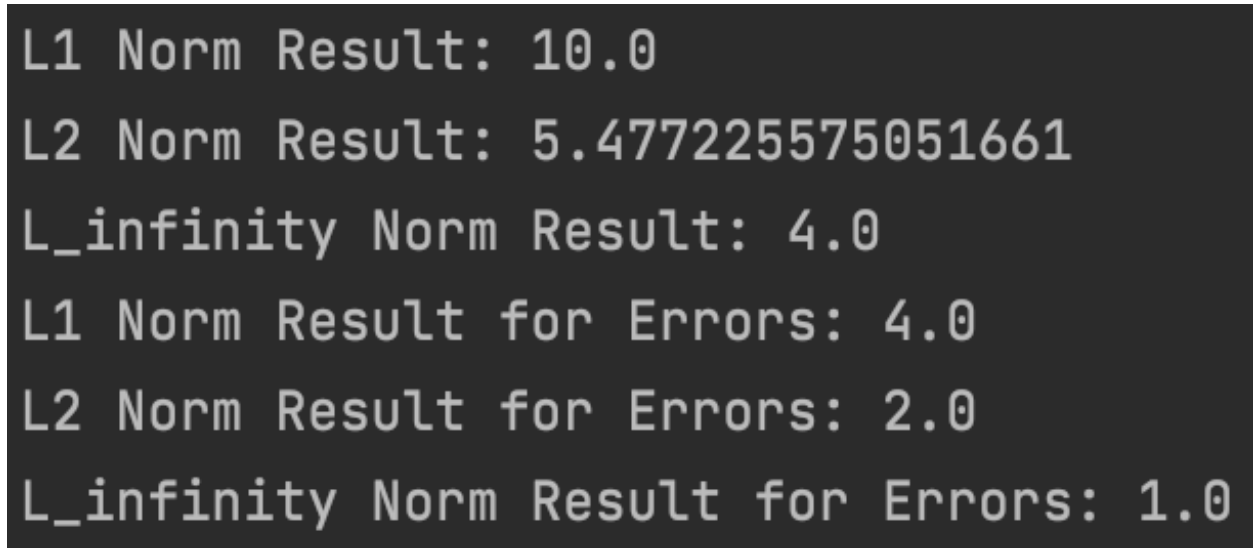
```

```

14 print('L2 Norm Result:', L2_Norm(arr1))
15 print('L_infinity Norm Result:', Linf_Norm(arr1))
16 print('L1 Norm Result for Errors:', L1_Norm_Error(arr1, arr2))
17 print('L2 Norm Result for Errors:', L2_Norm_Error(arr1, arr2))
18 print('L_infinity Norm Result for Errors:', Linf_Norm_Error(arr1, arr2))

```

Which has the following output:



```

L1 Norm Result: 10.0
L2 Norm Result: 5.477225575051661
L_infinity Norm Result: 4.0
L1 Norm Result for Errors: 4.0
L2 Norm Result for Errors: 2.0
L_infinity Norm Result for Errors: 1.0

```

**Figure 2.** The Test Result of Each Routine from IDE.

## Task 3

I have created the following six routines to compute the following linear algebra operations on vectors, they are all documented [here](#) in the [Software Manual](#).

### 1. Matrix Addition

```

1 import numpy as np
2
3 def MatAdd (mat1, mat2):
4     sum = np.add(mat1, mat2)
5     return sum

```

### 2. Matrix Subtraction

```

1 import numpy as np
2
3 def MatSub (mat1, mat2):
4     diff = np.subtract(mat1, mat2)
5     return diff

```

### 3. Scalar Multiplication for a Matrix

```

1 def MatScaMul(c, mat1):
2     ScalarProduct = c * mat1
3     return ScalarProduct

```

### 4. The Transpose of a Matrix.

```

1 import numpy as np
2
3 def MatTran (mat1):
4     transpose = np.transpose(mat1)
5     return transpose

```

5. The Product of a Rectangular Matrix and Vector.

```

1 import numpy as np
2
3 def MatVecPro (mat, vec):
4     product = np.dot(mat, vec)
5     return product

```

6. The Product of Two Rectangular Matrices.

```

1 def MatMatPro (mat1, mat2):
2     res = [[0 for x in range(len(mat1))] for y in range(len(mat2))]
3     for i in range(len(mat1)):
4         for j in range(len(mat2[0])):
5             for k in range(len(mat2)):
6                 # resulted matrix
7                 res[i][j] += mat1[i][k] * mat2[k][j]
8     return res

```

I have also created the following testing code that test each of the routines,

```

1 import numpy as np
2 from matAdd import MatAdd
3 from matSub import MatSub
4 from matScaMul import MatScaMul
5 from matTran import MatTran
6 from matVecPro import MatVecPro
7 from matMatPro import MatMatPro
8
9 # testing matrices, vector, and constant
10 mat1 = np.array([[2, -7, 5], [-6, 2, 0]])
11 mat2 = np.array([[5, 8, -5], [3, 6, 9]])
12 matR = np.array([[5, 1, 3], [1, 1, 1], [1, 2, 1]])
13 arr = np.array([1, 2, 3])
14 C = 2
15
16 print('Matrix Addition Result:\n', MatAdd(mat1, mat2))
17 print('Matrix Subtraction Result:\n', MatSub(mat1, mat2))
18 print('Scalar Multiplication for a Matrix Result:\n', MatScaMul(C, mat1))
19 print('The Transpose of a Matrix Result:\n', MatTran(mat1))
20 print('The Product of a Rectangular Matrix and Vector Result:\n', MatVecPro(matR, arr))
21 print('The Product of Two Rectangular Matrices Result:\n', MatMatPro(matR, matR))

```

Which has the following output:

```

Matrix Addition Result:
[[ 7  1  0]
 [-3  8  9]]

Matrix Subtraction Result:
[[ -3 -15  10]
 [ -9  -4  -9]]

Scalar Multiplication for a Matrix Result:
[[  4 -14  10]
 [-12  4   0]]

The Transpose of a Matrix Result:
[[ 2 -6]
 [-7  2]
 [ 5  0]]

The Product of a Rectangular Matrix and Vector Result:
[16  6  8]

The Product of Two Rectangular Matrices Result:
[[29, 12, 19], [7, 4, 5], [8, 5, 6]]

```

**Figure 3.** The Test Result of Each Routine from IDE.

## Task 4

I have written the following code to implement Jacobi Iteration for solving linear systems of equations, it's documented [here](#) in the [Software Manual](#).

```

1 # Defining equations to be solved
2 # in diagonally dominant form
3 f1 = lambda x, y, z: (17 - y + 2 * z) / 20
4 f2 = lambda x, y, z: (-18 - 3 * x + z) / 20
5 f3 = lambda x, y, z: (25 - 2 * x + 3 * y) / 20
6
7 # Initial setup
8 x0 = 0
9 y0 = 0
10 z0 = 0
11 count = 1
12
13 # Reading tolerable error
14 e = float(input('Enter tolerable error: '))
15
16 # Implementation of Jacobi Iteration

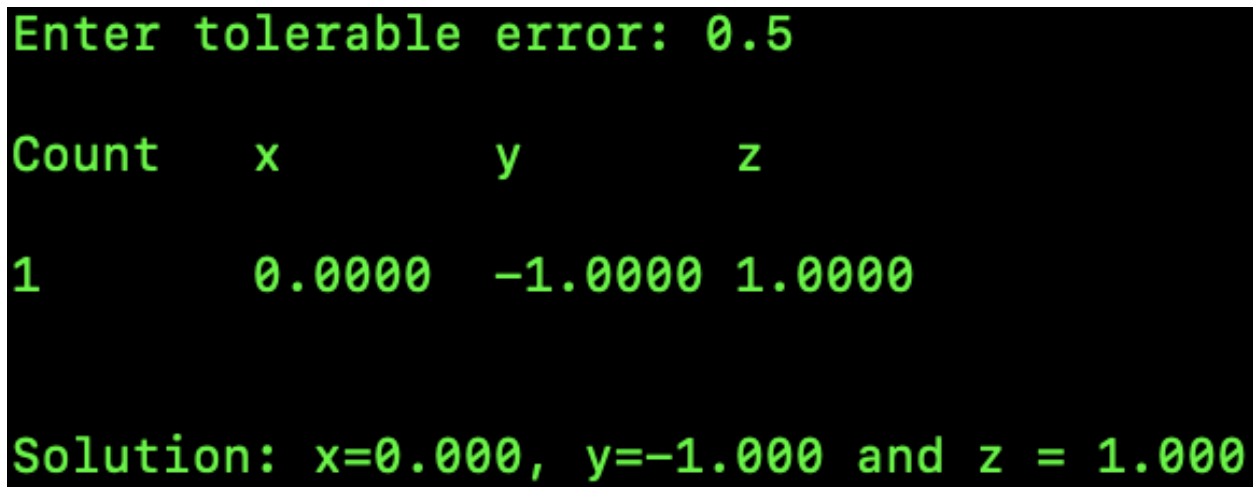
```

```

17 print('\nCount\tx\ty\tz\n')
18
19 condition = True
20
21 while condition:
22     x1 = f1(x0, y0, z0)
23     y1 = f2(x0, y0, z0)
24     z1 = f3(x0, y0, z0)
25     print('%d\t%0.4f\t%0.4f\t%0.4f\n' % (count, x1, y1, z1))
26     e1 = abs(x0 - x1);
27     e2 = abs(y0 - y1);
28     e3 = abs(z0 - z1);
29
30     count += 1
31     x0 = x1
32     y0 = y1
33     z0 = z1
34
35     condition = e1 > e and e2 > e and e3 > e
36
37 print('\nSolution: x=%0.3f, y=%0.3f and z = %0.3f\n' % (x1, y1, z1))

```

Which has the following output:



```

Enter tolerable error: 0.5

Count      x          y          z

1          0.0000    -1.0000    1.0000

Solution: x=0.000, y=-1.000 and z = 1.000

```

Figure 4. The Test Result of the Jacobi Method from Terminal.

## Task 5

I have written the following code to compare the results for the Gaussian elimination to the results from Jacobi Iteration for solving linear systems of equations, it's documented [here](#) in the [Software Manual](#).

```

1 import numpy as np
2
3 ones = [1 for i in range(100)]
4 solution = np.array(1 for i in range(100))
5
6 def jacobi(A, b, tolerance=1e-10, max_iterations=10000):
7     x = np.zeros_like(b, dtype=np.double)
8     T = A - np.diag(np.diagonal(A))
9     for k in range(max_iterations):
10         x_old = x.copy()
11         x[:] = (b - np.dot(T, x)) / np.diagonal(A)
12         error = np.linalg.norm(x - x_old, ord=np.inf) / np.linalg.norm(x, ord=np.inf)
13         if error < tolerance:
14             break
15     return error

```

```

16
17
18 def gauss(A, b, tolerance=1e-10, max_iterations=10000):
19     x = np.zeros_like(b, dtype=np.double)
20     # Iterate
21     for k in range(max_iterations):
22         x_old = x.copy()
23         # Loop over rows
24         for i in range(A.shape[0]):
25             x[i] = (b[i] - np.dot(A[i, :i], x[:i]) - np.dot(A[i, (i + 1):], x_old[(i + 1):])
26             ) / A[i, i]
27         # Stop condition
28         error = np.linalg.norm(x - x_old, ord=np.inf) / np.linalg.norm(x, ord=np.inf)
29         if error < tolerance:
30             break
31     return error
32
33 print('The Error for the Jacobi Iteration is:', jacobi(ones, solution))
34 print('The Error for the Gaussian Method is:', gauss(ones, solution))

```

Which has the following output:

```

The Error for the Jacobi Iteration is: 1.67e-11
The Error for the Gaussian Method is: 0.0

Process finished with exit code 0

```

Figure 5. The Comparison of the Results.

## Task 6

In [this website](#)<sup>1</sup> I found, the Gauss-Seidel method has a faster rate of convergence than the Jacobi Iteration.

The element-wise formula for the Gauss-Seidel method is extremely similar to that of the Jacobi method. However, in [this website](#)<sup>2</sup> I found, unlike the Jacobi method, the computations for each element are generally much harder to implement in parallel, since they can have a very long critical path, and are thus most feasible for sparse matrices. Furthermore, the values at each iteration are dependent on the order of the original equations.

<sup>1</sup><https://www.math-linux.com/mathematics/linear-systems/article/gauss-seidel-method>

<sup>2</sup>[https://johnfoster.pge.utexas.edu/numerical-methods-book/LinearAlgebra\\_IterativeSolvers.html](https://johnfoster.pge.utexas.edu/numerical-methods-book/LinearAlgebra_IterativeSolvers.html)