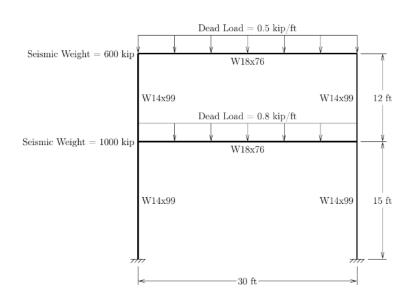
Analisis dinamico no lineal - Portico de acero GMS



```
In [1]: import openseespy.opensees as ops
import scipy.linalg as slin
import numpy as np
import matplotlib.pyplot as plt
import math
```

1.- Unidades basicas

```
In [2]: inch = 1.0
    kip = 1.0
    sec = 1.0
    ksi = kip/inch**2
    ft = 12*inch
    g = 32.2*ft/sec**2
```

2.- Propiedades Geometricas

```
In [3]: L = 30*ft
H1 = 15*ft
H2 = 12*ft
```

3.- Cargas sismcas

```
In [4]: DL1 = 0.8*kip/ft
DL2 = 0.5*kip/ft

W1 = 1000*kip
m1 = W1/g + DL1*L/g

W2 = 600*kip
m2 = W2/g + DL2*L/g

print(m1,m2)
```

2.6501035196687366 1.591614906832298

4.- Propiedades del material

```
In [5]: E = 29000*ksi
Fyb = 50*ksi
Fyc = 36*ksi
bs = 0.005
```

5.- Propiedades de las secciones

5.1.- Columna W14x99

```
In [6]: dc = 14.16*inch
    twc = 0.485*inch
    bfc = 14.565*inch
    tfc = 0.780*inch

Ac = 29.1*inch**2
    Ic = 1110*inch**4
    Sc = 157*inch**3
    Zc = 173*inch**3

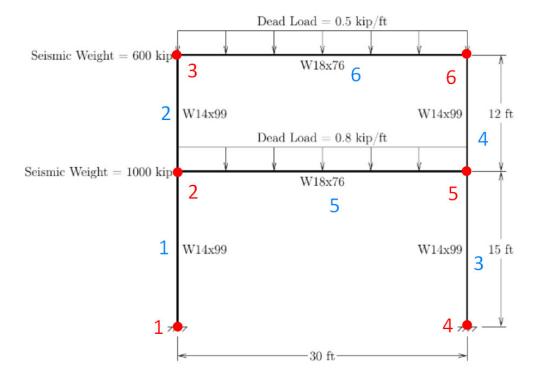
My = Fyc*Sc
Mp = Fyc*Zc
print(My,Mp)
```

5.2- Viga W18x76

5652.0 6228.0

```
In [7]: db = 18.21*inch
    twb = 0.425*inch
    bfb = 11.035*inch
    tfb = 0.680*inch

Ab = 22.3*inch**2
    Ib = 1330*inch**4
    Sb = 146*inch**3
    Zb = 163*inch**3
```



6.- Analisis por gravedad (Cargas Estaticas)

```
ops.wipe()
In [8]:
        ops.model('basic','-ndm',2,'-ndf',3)
        ops.node(1,0.0,0.0); ops.fix(1,1,1,1)
        ops.node(2,0.0,H1)
        ops.node(3,0.0,H1+H2)
        ops.node(4,L,0.0); ops.fix(4,1,1,1)
        ops.node(5,L,H1)
        ops.node(6,L,H1+H2)
        ops.mass(2,0.5*m1,0.5*m1,0.0)
        ops.mass(3,0.5*m2,0.5*m2,0.0)
        ops.mass(5,0.5*m1,0.5*m1,0.0)
        ops.mass(6,0.5*m2,0.5*m2,0.0)
        ops.geomTransf('Linear',10)
        ops.geomTransf('Linear',20)
        ops.uniaxialMaterial('Steel01',1,Fyc,E,bs)
        Nfw = 10
        Nff = 2
        ops.section('WFSection2d',1,1,dc,twc,bfc,tfc,Nfw,Nff)
        Np = 5
        ops.beamIntegration('Lobatto',5,1,Np)
        ops.element('forceBeamColumn',1,1,2,10,5)
        ops.element('forceBeamColumn',2,2,3,10,5)
        ops.element('forceBeamColumn',3,4,5,10,5)
        ops.element('forceBeamColumn',4,5,6,10,5)
        ops.uniaxialMaterial('Steel01',2,Fyb,E,bs)
        Nfw = 10
        Nff = 2
        ops.section('WFSection2d',2,2,db,twb,bfb,tfb,Nfw,Nff)
        Np = 5
        ops.beamIntegration('Lobatto',6,2,Np)
        ops.element('forceBeamColumn',5,2,5,20,6)
        ops.element('forceBeamColumn',6,3,6,20,6)
        ops.rigidLink('beam',2,5)
        ops.rigidLink('beam',3,6)
        ops.timeSeries('Constant',1)
        ops.pattern('Plain',1,1)
        ops.eleLoad('-ele',5,'-type','-beamUniform',-DL1)
        ops.eleLoad('-ele',6,'-type','-beamUniform',-DL2)
        #ops.constraints('Plain')
        ops.constraints('Transformation')
        ops.numberer('Plain')
        ops.system('FullGeneral')
        ops.test('NormDispIncr',1.0e-8,10)
        ops.algorithm('Newton')
        ops.integrator('LoadControl',0.0)
        ops.analysis('Static')
        ops.analyze(1)
        ops.reactions()
        print(ops.nodeReaction(1,2),ops.nodeReaction(4,2))
```

```
#ops.LoadConst('-time',0.0)
```

19.4999999999999 19.500000000000007

7.- Analisis de valores propios

```
In [9]: omegaSquared = ops.eigen(2)
        omega1 = omegaSquared[0]**0.5
        omega2 = omegaSquared[1]**0.5
        # Peridos de vibracion
        T1 = 2*np.pi/omega1
        T2 = 2*np.pi/omega2
        print(T1,T2)
        # Amortiguamiento para modos 1 y 2
        zeta1 = 0.03 # Amort modo 1
        zeta2 = 0.02 # Amort modo 2
        # Calculo de los coeficientes de Rayleigh
        B = np.zeros(shape=(2,2))
        B[0,0] = 1/omega1; B[0,1] = omega1
        B[1,0] = 1/omega2; B[1,1] = omega2
        b = np.zeros(2)
        b[0] = 2*zeta1
        b[1] = 2*zeta2
        a = np.linalg.solve(B,b)
```

1.18106264545646 0.38000552560385165

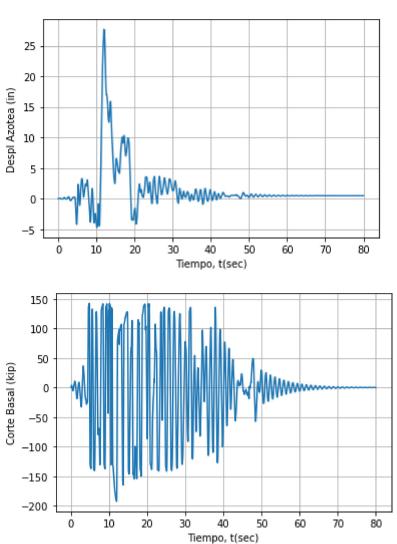
8.- Analisis de respuestas en el tiempo (tiempo-historia) no lineal

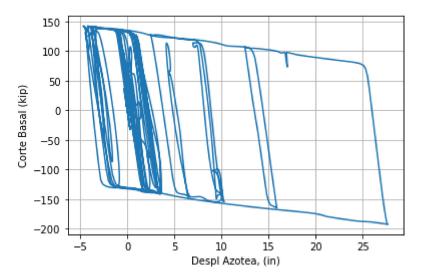
```
In [10]: #
                             KT KI Kn
         ops.rayleigh(a[0],0.0,0.0,a[1])
         # Definir el registro
         # dt = 0.02 es la digitalizacion del registro
         ops.timeSeries('Path',5,'-dt',0.02,'-filePath','tabasFN.txt','-factor',1.0*g
         ops.pattern('UniformExcitation',10,1,'-accel',5)
         ops.integrator('Newmark',0.50,0.25)
         ops.analysis('Transient') # Auntomatica utiliza Newmark Accel Cons gamma=1/2
         tPlot = []
         uPlot = []
         VbPlot = []
         Pl31Plot = []
         Pl33Plot = []
         # Retorna el tiempo
         t = ops.getTime()
         # Delta de t de analisis y duracion
         dt =0.01*sec
         Tfinal = 80.0*sec
         while t < Tfinal:
             ok = ops.analyze(1,dt)
             if ok < 0:
                 break
             ops.reactions()
             t = ops.getTime() # Tiempo actual
             u = ops.nodeDisp(3,1) # Desplazamiento de techo
             Vb = ops.nodeReaction(1,1) + ops.nodeReaction(4,1) # Cortante basal
             MI1 = ops.eleForce(1,3)
             MI3 = ops.eleForce(3,3)
             # Guardar los vectores para ploteo
             tPlot = np.append(tPlot,t)
             uPlot = np.append(uPlot,u)
             VbPlot = np.append(VbPlot,Vb)
             Pl31Plot = np.append(Pl31Plot,MI1)
             Pl33Plot = np.append(Pl33Plot,MI3)
         plt.figure()
         plt.plot(tPlot,uPlot)
         plt.xlabel('Tiempo, t(sec)')
         plt.ylabel('Despl Azotea (in)')
         plt.grid()
         plt.figure()
         plt.plot(tPlot,VbPlot)
         plt.xlabel('Tiempo, t(sec)')
         plt.ylabel('Corte Basal (kip)')
         plt.grid()
         plt.figure()
         plt.plot(uPlot,VbPlot)
         plt.xlabel('Despl Azotea, (in)')
         plt.ylabel('Corte Basal (kip)')
         plt.grid()
```

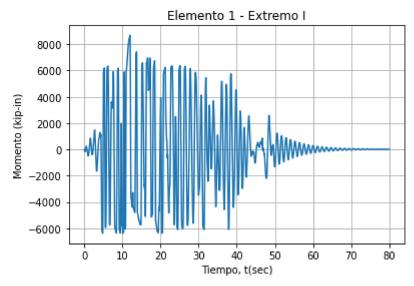
```
plt.figure()
plt.plot(tPlot,Pl31Plot)
plt.title('Elemento 1 - Extremo I')
plt.xlabel('Tiempo, t(sec)')
plt.ylabel('Momento (kip-in)')
plt.grid()

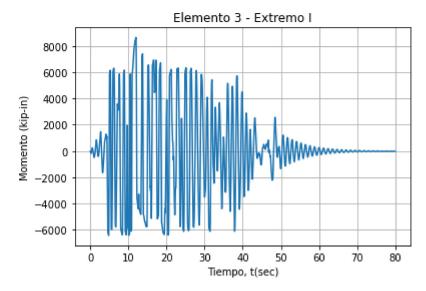
plt.figure()
plt.plot(tPlot,Pl33Plot)
plt.title('Elemento 3 - Extremo I')
plt.xlabel('Tiempo, t(sec)')
plt.ylabel('Momento (kip-in)')
plt.grid()
```

WARNING can't set transient integrator in static analysis WARNING analysis Transient - no Integrator specified, TransientIntegrator default will be used









10.- Analisis de valores propios - Manual

```
In [11]: k1 = 2*(12*E*Ic/H1**3)
    k2 = 2*(12*E*Ic/H2**3)

K = [[k1+k2,-k2],[-k2,k2]]
    M = np.diag([m1,m2])

omegaSquared = slin.eig(K,M)[0]
    modeShape = slin.eig(K,M)[1]

omega1 = math.sqrt(omegaSquared[0])
    omega2 = math.sqrt(omegaSquared[1])

T1 = 2*np.pi/omega1
    T2 = 2*np.pi/omega2

print(T1,T2)

x1 = modeShape[1]
    x2 = modeShape[0]

print(x1,x2)
```

```
1.16902711008068 0.37463284456240714 [0.77239856 0.80754113] [ 0.63513815 -0.58981126]
```

```
C:\Users\skalw\AppData\Local\Temp/ipykernel_26756/1671664552.py:10: Comple
xWarning: Casting complex values to real discards the imaginary part
  omega1 = math.sqrt(omegaSquared[0])
C:\Users\skalw\AppData\Local\Temp/ipykernel_26756/1671664552.py:11: Comple
xWarning: Casting complex values to real discards the imaginary part
  omega2 = math.sqrt(omegaSquared[1])
```