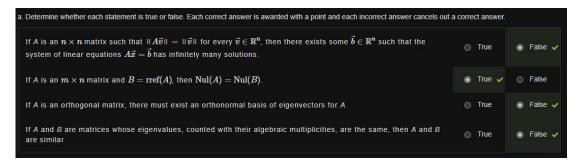
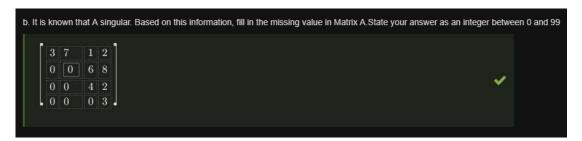
```
In []: import sympy as sp
    from scipy import *
    from sympy import *
    init_printing()
    from IPython.display import display, Latex, HTML, Math
    import numpy as np
    import pandas as pd
    from sympy import Rational as R
```

In []: # a) FTFF



In []: # b) Must be 0



In []: # c) Echelon form so eigenvalues are on diagonal. Determinant is product of diag

In []: # d) Swap a and d and change signs on b and c

```
d. Let A be an invertible 2 \times 2 matrix. Fill in the missing values in the below expressions. State your answers as integers between 0 and 99. A^{-1} = \frac{1}{10} \begin{bmatrix} 6 & -7 \\ -2 & 4 \end{bmatrix}, \quad A = \begin{bmatrix} 4 & 7 \\ 2 & 6 \end{bmatrix}
```

```
In [ ]: # a)
         A = Matrix([[1,1,0],[0,1,1],[0,0,1]])
         B = Matrix([[2,0,0],[1,1,2],[2,0,1]])
         C = Matrix([[1,1,0],[0,1,0],[0,1,2]])
         X = C*(A - B)**-1
         X.det()
Out[ ]: 1
          Find the determinant of matrix X in the following matrix equation XA = XB + C. State your answer as an integer between 0 and 99.
            \det X = 1
In [ ]: # b)
         A = Matrix([[-1,2],[1,1]])
         B = Matrix([[1,2],[0,1]])
         C = Matrix([[2,2],[3,1]])
In [ ]: BAC = B * A * C
         CAB = C * A*B
In [ ]: # Try to Isolate Y
         \# CY = BAC - AX and
         # -BY = CAB - CX
         # Get Y on its own:
         # Y = C^{**}-1^*BAC - C^{**}-1 * AX and
         # - Y = B^{**}-1*CAB - B^{**}-1CX
         # Now, calculate all parts not involving X and Y
In [ ]: # Simplify a bit by making up new matrices that are known
         Q = C^{**}-1 * BAC
         P = B^{**}-1 * CAB
         # Y = Q - C^{**}-1 * AX og -Y = P - B^{**}-1*CX
In [ ]: # Add the two equations in order to elimaínate Y:
         # Y + (-Y) = Q - C^{**} - 1 * AX + (P - B^{**} - 1^{*}CX)
         # The left side becomes 0. Now move all parts containing X to the left:
         \# C^{**}-1 * AX + B^{**}-1*CX = Q + P
         # Take X out of the parenthesis:
         \# (C^{**}-1 * A + B^{**}-1*C)X = Q + P
         # Since the matrices inside the parenthesis do not invlove X,
         # you canb just calculate it, I assign it to R:
```

```
In [ ]: R = C^{**}-1 * A + B^{**}-1 * C
               # and you get
               # Og du får så
               \# RX = Q+P
               \# X = R^{**}-1(Q+P)
In [ ]: X = R^{**}-1^*(Q+P)
Out[]: \begin{bmatrix} -\frac{12}{13} & 0 \\ \frac{99}{26} & 3 \end{bmatrix}
In [ ]: det(X)
Out[]: -\frac{36}{13}
In [ ]: # Use X to find Y in one of the expressions above
               Y = Q-C^{**}-1 *A*X
               # We see it is 0
Out[]: \begin{bmatrix} -\frac{4}{13} & 0\\ \frac{79}{26} & 0 \end{bmatrix}
In [ ]: det(Y)
Out[ ]: 0
                 b. Given the three matrices
                 A = \begin{bmatrix} -1 & 2 \\ 1 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 1 & 2 \\ 0 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 2 & 2 \\ 3 & 1 \end{bmatrix}
                 solve the following system of matrix equations (i.e. find matrices X and Y)
                 \int AX + CY = BAC
                 CX - BY = CAB
                 and state the determinants of X and Y. State your answers as integers between 0 and 99.
```

Out[]: a^3-3a+2

```
= a(a^{2} - 1) - (1)(a - 1) + (1)(1 - a) = a^{3} - 3a + 2
```

```
In [ ]: # b)
solve(A.det(), a)
```

Out[]: [-2, 1]

b. For what values of a is A not invertible? State your answer as integers between 0 and 99.

$$a = \left\{ -2, 1 \right\}$$

```
In []: # c)
A = Matrix([[2,1,1],[1,2,1],[1,1,2]])
B = A.row_join(eye(3))
B[2,:] = B[2,:]-B[1,:] # r3 -r2
B[1,:] = B[1,:]-Rational(1,2) * B[0,:] # r2 - 1/2r1
B[1,:] = Rational(2,3)*B[1,:] # r2 -> 2/3 r2
B[2,:] = B[2,:] + B[1,:] # r3 + r2
B[1,:] = B[1,:] - Rational(1,4) * B[2,:] # r2 - 1/4 r3
B[2,:] = Rational(3,4)*B[2,:] # 3/4 r3
B[0,:] = B[0,:] - B[2,:] # r1 -r3
B[0,:] = B[0,:] - B[1,:] # r1 - r2
B[0,:] = Rational(1,2)*B[0,:] # 1/2 r1
B
```

Out[]:
$$\begin{bmatrix} 1 & 0 & 0 & \frac{3}{4} & -\frac{1}{4} & -\frac{1}{4} \\ 0 & 1 & 0 & -\frac{1}{4} & \frac{3}{4} & -\frac{1}{4} \\ 0 & 0 & 1 & -\frac{1}{4} & -\frac{1}{4} & \frac{3}{4} \end{bmatrix}$$

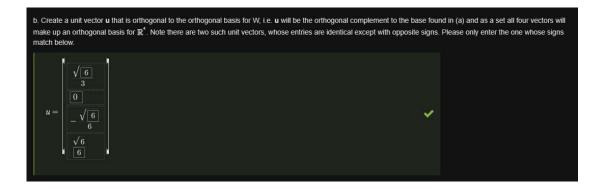
In []: # d)
B[:, 3:]*Matrix([2,4,6])

Out[]: $\begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix}$

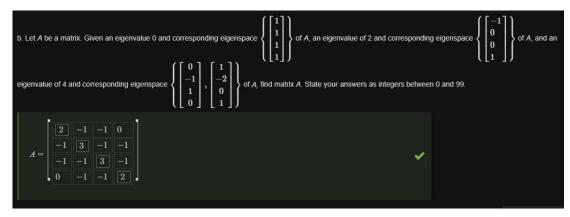
d. Use the result obtained in part (c) to solve the matrix equation below. State your answers as integers between 0 and 99. $\begin{bmatrix} 2 & 1 & 1 \\ 1 & 2 & 1 \\ 1 & 1 & 2 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \\ 3 \end{bmatrix} = \begin{bmatrix} 2 \\ 4 \\ 6 \end{bmatrix}$

Let $W\subset\mathbb{R}^4$ be the subspace of vectors (x_1,x_2,x_3,x_4) that satisfy $2x_1-x_3+x_4=0$ a. Find an orthonormal basis for W. State your answers as integers between 0 and 99.

```
In []: # b)  u4 = u1.row_join(u2).row_join(u3).T.nullspace()[0].normalized()   u4  Out[]:  \begin{bmatrix} \frac{\sqrt{6}}{3} \\ 0 \\ -\frac{\sqrt{6}}{6} \\ \frac{\sqrt{6}}{6} \end{bmatrix}
```



```
In [ ]: # a)
               v1 = Matrix([1,1])
               v2 = Matrix([2,3])
               v = Matrix([3,4])
               P = Matrix.hstack(v1,v2)
               D = diag(2,1)
                (P*D*P**-1)**3 * v
Out[]: \lceil 10 \rceil
                 a. Let A be a 2 \times 2 such that \overrightarrow{v_1} = \begin{bmatrix} 1 \\ 1 \end{bmatrix} is an eigenvector for A with eigenvalue 2 and \overrightarrow{v_2} = \begin{bmatrix} 2 \\ 3 \end{bmatrix} is an eigenvector for A with eigenvalue 1. If \overrightarrow{v} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}, compute A^3\overrightarrow{v}.
In [ ]: # b)
               p1 = Matrix([1,1,1,1])
               p2 = Matrix([-1,0,0,1])
               p3 = Matrix([0,-1,1,0])
               p4 = Matrix([1, -2, 0, 1])
               P = p1.row_join(p2).row_join(p3).row_join(p4)
               D = diag(0,2,4,4)
               P*D*P**-1
      \begin{bmatrix} 2 & -1 & -1 & 0 \\ -1 & 3 & -1 & -1 \\ -1 & -1 & 3 & -1 \\ 0 & -1 & -1 & 2 \end{bmatrix}
```



```
In []: # c)  v1 = \text{Matrix}([\text{Rational}(2,3), \text{ Rational}(-1,3), \text{ Rational}(-2,3)]) 
 v2 = \text{Matrix}([-\text{sqrt}(2)/2, 0, -\text{sqrt}(2)/2]) 
 v1.\text{row\_join}(v2).\text{T.nullspace}()[0].\text{normalized}() 
Out[]:  \begin{bmatrix} -\frac{\sqrt{2}}{6} \\ -\frac{2\sqrt{2}}{3} \\ \frac{\sqrt{2}}{6} \end{bmatrix} 
 c. \text{ Let } \vec{v}_1 \text{ and } \vec{v}_2 \text{ denote the following vectors in } \mathbb{R}^2. 
 \vec{v}_1 = \begin{bmatrix} 2/3 \\ -1/3 \\ -2/3 \end{bmatrix} \quad \vec{v}_2 = \begin{bmatrix} -\sqrt{2}/2 \\ 0 \\ -\sqrt{2}/2 \end{bmatrix} 
Find a vector \vec{v}_3 so that \vec{v}_1, \vec{v}_2, \vec{v}_3 form an orthonormal basis for \mathbb{R}^2. Note there are two such vectors, whose entires are identical except with opposite signs. Please enter both. State your answers as integers between 0 and 99. 
 v_3 = \begin{bmatrix} \frac{\sqrt{2}}{6} \\ -\frac{2}{2}\sqrt{2} \\ \frac{\sqrt{2}}{3} \end{bmatrix}, \text{ or } v_3 = \begin{bmatrix} \frac{\sqrt{2}}{6} \\ \frac{2}{2}\sqrt{2} \\ \frac{\sqrt{2}}{3} \end{bmatrix}
```

```
15,
                                   16,
                                   13,
                                   25,
                                   27,
                                   21,
                                   20,
                                   21,
                                   15
                        ])
                        X1 = Matrix([ones(len(x), 1)]).row_join(Matrix(x**3))
                        X2 = Matrix([ones(len(x), 1)]).row join(Matrix(x)).row join(Matrix(x**3))
                        X3 = Matrix([ones(len(x), 1)]).row_join(Matrix(x))
                        display(Math(r'X_1 = ' + latex(X1) + r')quad X_2 = ' + latex(X2) + r')quad X_3 = ' + latex(X2) + r' quad X_3 = ' + latex(X3) + r' quad X_3 = ' + latex(X3)
                                                            + latex(Matrix(y))))
                                                                                         [1 \ 35 \ 42875]
                                     [1 \ 42875]
                                                                                                                                                                                                    21
                                                                                                                                                                    35
                                      1 21952
                                                                                          1 \quad 28 \quad 21952
                                                                                                                                                                    28
                                                                                                                                                                                                    15
                                      1 \ \ 32768
                                                                                        1 32 32768
                                                                                                                                                                                                    16
                                     1 19683
                                                                                        1 27 19683
                                                                                                                                                                                                    13
                                                                      X_2 = \begin{bmatrix} 1 & 37 & 50653 \\ 1 & 38 & 54872 \end{bmatrix}
                                     1 50653
                                                                                                                                                                                                    25
                                                                                                                                                                                                    27
                                     1 39304
                                                                                          1 34 39304
                                                                                                                                                                                                    21
                                      1 42875
                                                                                           1 35 42875
                                                                                                                                                           1 35
                                                                                                                                                                                                    20
                                      1 \quad 39304
                                                                                           1 34 39304
                                                                                                                                                                    34
                                                                                                                                                                                                    21
                                     1 29791
                                                                                         1 \quad 31 \quad 29791
                                                                                                                                                                                                  15
In [ ]: X1tX1 = X1.T*X1
                        X1ty = X1.T*Matrix(y)
                        Mat, _ = X1tX1.row_join(X1ty).rref()
                        B1 = Mat[:,-1]
                        X2tX2 = X2.T*X2
                        X2ty = X2.T*Matrix(y)
                        Mat, _ = X2tX2.row_join(X2ty).rref()
                        B2 = Mat[:,-1]
                        X3tX3 = X3.T*X3
                        X3ty = X3.T*Matrix(y)
                        Mat, _ = X3tX3.row_join(X3ty).rref()
                        B3 = Mat[:,-1]
In [ ]: display(Math(r'X_1^TX_1 = ' + latex(X1tX1)))
                        display(Math(r'X_1^Ty = ' + latex(X1ty)))
                        display(Math(r'X_2^TX_2 = ' + latex(X2tX2)))
                        display(Math(r'X_2^Ty = ' + latex(X2ty)))
                        display(Math(r'X_3^TX_3 = ' + latex(X3tX3)))
                        display(Math(r'X_3^Ty = ' + latex(X3ty)))
                  X_1^T X_1 = \begin{bmatrix} 10 & 374077 \\ 374077 & 15173359173 \end{bmatrix}
```

 $X_1^T y = egin{bmatrix} 194 \ 7712824 \end{bmatrix}$

```
Reexam_ALI_2020 - Solution
        X_2^T X_2 = egin{bmatrix} 10 & 331 & 374077 \ 331 & 11073 & 12751413 \ 374077 & 12751413 & 15173359173 \end{bmatrix}
        X_2^Ty = \left[egin{array}{c} 194 \ 6562 \ 7712824 \end{array}
ight]
         X_3^T X_3 = \begin{bmatrix} 10 & 331 \\ 331 & 11073 \end{bmatrix}
         X_3^T y = \left[egin{array}{c} 194 \ 6562 \end{array}
ight]
In [ ]: # b)
           display(Latex("$$y_1(t) = {}+{}t^3$$".format(round(B1[0],2), round(B1[1], 4))))
           display(Latex("$$y 2(t) = {}{}t+{}t^3$$".format(round(B2[0],2), round(B2[1], 4),
           display(Latex("$$y_3(t) = {}+{}t$$".format(round(B3[0],2), round(B3[1], 4))))
                                                   y_1(t) = 4.95 + 0.0004t^3
                                             y_2(t) = 41.66 - 1.7164t + 0.0009t^3
                                                  y_3(t) = -20.41 + 1.2027t
In [ ]: # c)
           display(Latex("$\$e_1 = {}\$\$".format(round((Matrix(y)-X1*B1).norm(), 2))))
           display(Latex("\$\$e_2 = \{\}\$\$".format(round((Matrix(y)-X2*B2).norm(), 2))))
           display(Latex("$$e_3 = {}$$".format(round((Matrix(y)-X3*B3).norm(), 2))))
```

$$e_1 = 3.52$$

$$e_2 = 2.97$$

$$e_3 = 4.39$$

$$f_2(40) = 32$$

```
In []: A = Matrix([[2,0,0],[2,1,0],[0,-2,0]])
        AtA = A.T*A
        vecs1 = AtA.eigenvects()
```

```
display(A)
               display(vecs1)
                     1
                            0
             \left[ \left(0, 1, \left\lceil \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} \right), \left(4, 1, \left| \left| \begin{bmatrix} -\frac{1}{2} \\ 1 \\ 0 \end{bmatrix} \right| \right), \left(9, 1, \left[ \begin{bmatrix} 2 \\ 1 \\ 0 \end{bmatrix} \right] \right) \right|
In [ ]: s1 = sqrt(vecs1[2][0])
               s2 = sqrt(vecs1[1][0])
               s3 = sqrt(vecs1[0][0])
               v1 = vecs1[2][2][0].normalized()
               v2 = vecs1[1][2][0].normalized()
               v3 = vecs1[0][2][0].normalized()
               u1 = ((s1**-1)*A*v1)
               u2 = ((s2**-1)*A*v2)
               # We need one more eigenvectors for U
               u3 = Matrix([u1.T, u2.T]).nullspace()[0].normalized()
               U1 = u1.row_join(u2).row_join(u3)
               V = v1.row_join(v2).row_join(v3)
               Vt1 = V.T
               S1 = diag(s1, s2, s3)
               display(Math('U \Sigma V^T = {}{}\.format(latex(U1), latex(S1), latex(Vt1))))
               display(Latex("Test:"))
               display(U1*S1*Vt1)
               display(A)
               display(U1*S1*Vt1==A)
           U\Sigma V^T = \begin{bmatrix} \frac{4\sqrt{5}}{15} & -\frac{\sqrt{5}}{5} & -\frac{2}{3} \\ \frac{\sqrt{5}}{3} & 0 & \frac{2}{3} \\ -\frac{2\sqrt{5}}{3} & -\frac{2\sqrt{5}}{5} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 3 & 0 & 0 \\ 0 & 2 & 0 \\ 0 & 0 & 0 \end{bmatrix} \begin{bmatrix} \frac{2\sqrt{5}}{5} & \frac{\sqrt{5}}{5} & 0 \\ -\frac{\sqrt{5}}{5} & \frac{2\sqrt{5}}{5} & 0 \\ 0 & 0 & 1 \end{bmatrix}
            Test:
                     1
              0
                     0
                     1
             \lfloor 0 \rfloor
            True
In [ ]: # b: U and V wont be the same, but Sigma will.
```

