

```
In [ ]: import sympy as sp
        from scipy import *
        from sympy import *
        init_printing()
        from IPython.display import display, Latex, HTML, Math
        import numpy as np
        import pandas as pd
        from sympy import Rational as R
```

Assignment 1

```
In [ ]: # a)
        # i. True
        # ii. False
        # iii. True. In fact these are equivalent conditions.
        # iv. False. This would mean the eigenvectors form a line, but it could be a plane.
        # v. False.  $A^3 = PD^3P^{-1}$ 
        # vi. False. It might be diagonalizable and it might not be.
        # vii. True
        # viii. True
        # ix. False
        # x. False. It would be true with the condition that  $v \neq 0$ .
```

You will need very few and simple calculation in order to solve the problems of this assignment.

a. Mark each statement as either true or false

- i. Two vectors are linearly independent if one is not a scalar multiple of the other.
- ii. Every 2×2 matrix is diagonalizable.
- iii. If A is diagonalizable, then there is a basis of eigenvectors of A
- iv. If λ is an eigenvalue for A , then the eigenvectors with eigenvalue λ are scalar multiples of each other.
- v. If $A = PDP^{-1}$, then $A^3 = P^3D^3P^{-3}$
- vi. If A does not have n distinct eigenvalues, then A is not diagonalizable.
- vii. If $S = \{v_1, \dots, v_n\} \subseteq \mathbb{R}^n$ and $\text{span}(S) = \mathbb{R}^n$ then S is a basis for \mathbb{R}^n
- viii. A is invertible if and only if $\det(A) \neq 0$
- ix. If A is diagonalizable, then A is invertible.
- x. If $A\bar{v} = c\bar{v}$ for some $c \in \mathbb{R}$, then \bar{v} is an eigenvector for A .

a. Mark each statement as true or false.

| | | |
|-------|---|--|
| i. | <input checked="" type="radio"/> True ✓ | <input type="radio"/> False |
| ii. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |
| iii. | <input checked="" type="radio"/> True ✓ | <input type="radio"/> False |
| iv. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |
| v. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |
| vi. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |
| vii. | <input checked="" type="radio"/> True ✓ | <input type="radio"/> False |
| viii. | <input checked="" type="radio"/> True ✓ | <input type="radio"/> False |
| ix. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |
| x. | <input type="radio"/> True | <input checked="" type="radio"/> False ✓ |

```
In [ ]: # b
b = symbols('b')
solve(3*b*4*3 - 72, b)
```

Out[]: [2]

b. It is known that the determinant of A is 72. Based on this information, determine the value of b :

$$\begin{bmatrix} 3 & 7 & 1 & 2 \\ 0 & b & 6 & 8 \\ 0 & 0 & 4 & 2 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

State your answer as a positive integer.

$b =$



```
In [ ]: # c)
# Symmetric matrix so  $\lambda_1 + \lambda_2 + \lambda_3 = \text{sum of diagonal (called trace)} = 6$ 
l1, l2, l3 = symbols('λ1 λ2 λ3')
l2 = l1 + sqrt(l1)
l3 = l1 - sqrt(l1)

x1 = solve(l1 + l2 + l3 - 6, l1)[0]
x2 = l2.subs(l1, x1)
x3 = l3.subs(l1, x1)

x1, x2, x3
```

Out[]: $(2, \sqrt{2} + 2, 2 - \sqrt{2})$

e. Consider the following matrix

$$A = \begin{bmatrix} 2 & a & b \\ a & 2 & c \\ b & c & 2 \end{bmatrix}$$

It is known that $\lambda_2 = \lambda_1 + \sqrt{\lambda_1}$ and $\lambda_3 = \lambda_1 - \sqrt{\lambda_1}$. What are the eigenvalues of A ?

State your answer as positive integers.

$$\lambda_1 = \boxed{2}, \quad \lambda_2 = \boxed{2} + \sqrt{\boxed{2}}, \quad \lambda_3 = \boxed{2} - \sqrt{\boxed{2}}$$

Assignment 2

Let A be the following matrix:

$$\begin{bmatrix} 1 & 3 \\ -2 & -8 \end{bmatrix}$$

- Find numbers p and q , such that $A^2 = pA + qI$, where I is the 2×2 identity matrix.
- Let $B = A - tI$, where t is a scalar. For which values of t is B not invertible?
- What are the values (t) found in part (b) called relative to A ?
- Find all the orthonormal eigenvectors of A .

```
In [ ]: # a)
p, q = symbols('p q')
A = Matrix([[1, 3], [-2, -8]])
A2 = A**2
res = A2 - p*A - q*eye(2)
p = solve(res[0, -1], p)[0]
q = solve(-p - q - 5, q)[0]
display(Math(r'p = ' + latex(p) + r'\text{ and } q = ' + latex(q)))
```

$$p = -7 \text{ and } q = 2$$

```
In [ ]: # b)
t = symbols('t')
```

```
B = A-t*eye(2)
B.echelon_form()
```

Out[]: $\begin{bmatrix} -2 & -t-8 \\ 0 & -t^2-7t+2 \end{bmatrix}$

In []: `solve(B.echelon_form()[-1,-1], t)`

Out[]: $\left[-\frac{7}{2} + \frac{\sqrt{57}}{2}, -\frac{\sqrt{57}}{2} - \frac{7}{2} \right]$

In []: `# c) Eigenvalues`

c. Choose the correct answer below. Only one answer is correct.

A The singular values of A

B The determinants of A

C The explicit values of A

D The discriminants of A

E The eigenvalues of A

F The inverse values of A

G The ranks of A

In []: `# d)`

```
A.eigenvectors()[0][2][0].normalized().evalf(4), A.eigenvectors()[1][2][0].normalized()
```

Out[]: $\left(\begin{bmatrix} -0.972 \\ 0.2349 \end{bmatrix}, \begin{bmatrix} -0.3408 \\ 0.9401 \end{bmatrix} \right)$

d. Choose **one** or **multiple** options below. The values are rounded to four decimal precision.

A

$$\begin{bmatrix} -0.7201 \\ 0.1207 \end{bmatrix}$$

B

$$\begin{bmatrix} -0.647 \\ 0.6603 \end{bmatrix}$$

C

$$\begin{bmatrix} -0.3408 \\ 0.9401 \end{bmatrix}$$

D

$$\begin{bmatrix} -0.972 \\ 0.2349 \end{bmatrix}$$

E

$$\begin{bmatrix} 0.5608 \\ 0.0921 \end{bmatrix}$$

F

$$\begin{bmatrix} -0.8408 \\ 0.0401 \end{bmatrix}$$

Assignment 3

```
In [ ]: h = symbols('h')
solve(Matrix([[-1, 4, 10], [-4, 5, 7], [3, 0, h+3]]).echelon_form()[-1,-1], h)[0]
```

```
Out[ ]: 3
```

Consider the following vectors in \mathbb{R}^3

$$\vec{u} = \begin{bmatrix} -1 \\ -4 \\ 3 \end{bmatrix}, \quad \vec{v} = \begin{bmatrix} 4 \\ 5 \\ 0 \end{bmatrix}, \quad \vec{w} = \begin{bmatrix} 10 \\ 7 \\ h+3 \end{bmatrix}$$

For which values of h do these three vectors form a basis for \mathbb{R}^3 ?

State your answer as a positive integer.

$$h \neq 3$$

Assignment 4

```
In [ ]: # a)

v1 = Matrix([[2],[2],[-2],[-2]])
v2 = Matrix([[1],[-1],[1],[-1]])
```

```

v3 = Matrix([[0],[3],[3],[0]])
x = Matrix([[0],[1],[2],[3]])

V = Matrix.hstack(v1, v2, v3)
G = V.T * V
G

```

Out[]:

$$\begin{bmatrix} 16 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 18 \end{bmatrix}$$

The following three vectors are given in \mathbb{R}^4

$$\bar{v}_1 = \begin{bmatrix} 2 \\ 2 \\ -2 \\ -2 \end{bmatrix}, \quad \bar{v}_2 = \begin{bmatrix} 1 \\ -1 \\ 1 \\ -1 \end{bmatrix}, \quad \bar{v}_3 = \begin{bmatrix} 0 \\ 3 \\ 3 \\ 0 \end{bmatrix}$$

- Construct the Gram matrix, G , for \bar{v}_1, \bar{v}_2 , and \bar{v}_3 and confirm that this set of vectors form an orthogonal set V .
- Calculate the projection, $\text{proj}_V \bar{x}$, of

$$\bar{x} = \begin{bmatrix} 0 \\ 1 \\ 2 \\ 3 \end{bmatrix}$$

onto the subspace spanned by V .

- Use $\bar{v}_1, \bar{v}_2, \bar{v}_3, \bar{x}$ and $\text{proj}_V \bar{x}$ to construct an orthonormal basis B for \mathbb{R}^4

- State your answer as positive integers. Indexing is done according to the vector index.

$$G = \begin{bmatrix} 16 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 18 \end{bmatrix}$$

```

In [ ]: # b)
proj = x.project(v1) + x.project(v2) + x.project(v3)
proj

```

Out[]:

$$\begin{bmatrix} -\frac{3}{2} \\ 1 \\ 2 \\ \frac{3}{2} \end{bmatrix}$$

```

In [ ]: # c)
v4 = x - proj
v1.normalized(), v2.normalized(), v3.normalized(), v4.normalized()

```

Out[]:

$$\left(\begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{\sqrt{2}}{2} \\ \frac{\sqrt{2}}{2} \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{\sqrt{2}}{2} \\ 0 \\ 0 \\ \frac{\sqrt{2}}{2} \end{bmatrix} \right)$$

c. State your answer as positive integers.

$$\left\{ \begin{bmatrix} \frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} \frac{1}{2} \\ -\frac{1}{2} \\ \frac{1}{2} \\ -\frac{1}{2} \end{bmatrix}, \begin{bmatrix} 0 \\ \frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \begin{bmatrix} \frac{1}{\sqrt{2}} \\ 0 \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} \right\}$$

Assignment 5

```
In [ ]: # a)
k = symbols('k')
A = Matrix([[1,3,0],[1,1,1],[4,1,1]])
B = Matrix([[2,5,3],[1,1,2],[4,0,1]])
C = Matrix([[1,1,3],[3,2,1],[0,1,2]])
D = Matrix([[3,1,k],[3*k,k,2*k],[9,3,3*k]])

X2 = (A+B)**-1*C
detX = sqrt(det(X2))
detX
```

Out[]: $\frac{\sqrt{6}}{11}$

Consider the following matrices:

$$A = \begin{bmatrix} 1 & 3 & 0 \\ 1 & 1 & 1 \\ 4 & 1 & 1 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 5 & 3 \\ 1 & 1 & 2 \\ 4 & 0 & 1 \end{bmatrix}, \quad C = \begin{bmatrix} 1 & 1 & 3 \\ 3 & 2 & 1 \\ 0 & 1 & 2 \end{bmatrix}, \quad D = \begin{bmatrix} 3 & 1 & k \\ 3k & k & 2k \\ 9 & 3 & 3k \end{bmatrix}$$

- Find the determinant of matrix X in the following matrix equation $AX^2 + BX^2 = C$.
- Let $Y = D^T D$. What is the sum of the eigenvalues of Y ?
- For which value(s) of k , if any, is $\dim \text{Nul } D = 2$?

a. State your answer as a positive integer.

$$\det X = \frac{\sqrt{6}}{11}$$

```
In [ ]: # b)
Y = D.T * D
Y.trace()
```

Out[]: $24k^2 + 100$

```
In [ ]: # c)
D.echelon_form()
```

```
Out[ ]: 
$$\begin{bmatrix} 3 & 1 & k \\ 0 & 0 & -3k^2 + 6k \\ 0 & 0 & 0 \end{bmatrix}$$

```

```
In [ ]: solve(D.echelon_form()[1,-1], k)
```

```
Out[ ]: [0, 2]
```

c. Choose **one or multiple** options below.

| | |
|---|---|
| A | $k = 10$ |
| B | $k \in \{\emptyset\}$, i.e. no such value exists |
| C | $k \in \mathbb{R}$ |
| D | $k \in \mathbb{R} \setminus \{0\}$ |
| E | $k = -2\sqrt{10}$ |
| F | $k = 2$ |
| G | $k = 0$ |
| H | $k = -4$ |

Assignment 6

```
In [ ]: # a)

x = np.array([0.66, 1.32, 1.98, 2.64, 3.3, 3.96, 4.62, 3.28, 5.94, 6.6])
y = np.array([7.32, 12.22, 16.34, 23.66, 28.06, 33.39, 34.12, 39.21, 44.21, 47.4])

X = Matrix.hstack(Matrix(x**3), Matrix(x**2), Matrix(x), ones(len(x), 1))
X.evalf(5)
```



```
Out[ ]: 
$$\begin{bmatrix} 0.2875 & 0.4356 & 0.66 & 1.0 \\ 2.3 & 1.7424 & 1.32 & 1.0 \\ 7.7624 & 3.9204 & 1.98 & 1.0 \\ 18.4 & 6.9696 & 2.64 & 1.0 \\ 35.937 & 10.89 & 3.3 & 1.0 \\ 62.099 & 15.682 & 3.96 & 1.0 \\ 98.611 & 21.344 & 4.62 & 1.0 \\ 35.288 & 10.758 & 3.28 & 1.0 \\ 209.58 & 35.284 & 5.94 & 1.0 \\ 287.5 & 43.56 & 6.6 & 1.0 \end{bmatrix}$$

```

Consider the following data points

| | | | | | | | | | | |
|-----|------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| t | 0.66 | 1.32 | 1.98 | 2.64 | 3.3 | 3.96 | 4.62 | 3.28 | 5.94 | 6.6 |
| h | 7.32 | 12.22 | 16.34 | 23.66 | 28.06 | 33.39 | 34.12 | 39.21 | 44.21 | 47.48 |

We would like to model the data according to the following polynomial: $pt^3 + qt^2 + rt + s$. This corresponds to solving the system of linear equations given by $Ax = b$.

- Determine matrix A in the above system.
- Find the least squares solution to $A\bar{x} = \bar{b}$, and state the estimates of p, q, r, s . Remember to store the exact values and not the rounded values.
- Using the exact value estimates found above, find the least squares error of the system
- Using the model found in (b) with the exact values for p, q, r, s , determine the value of h when $t = 8$

a. State only the **first** and last **row** of matrix A . State your answer as positive integers.

```

$$\begin{bmatrix} 0 & .29 & 0 & .44 & 0 & .66 & 1 \\ \vdots & & \vdots & & \vdots & & \vdots \\ 287 & .50 & 43 & .56 & 6 & .6 & 1 \end{bmatrix}$$

```

```
In [ ]: # b)
B = Matrix.hstack(X.T * X, X.T * Matrix(y)).rref()[0][:,-1]
B
```

```
Out[ ]: 
$$\begin{bmatrix} 0.0737485703615477 \\ -1.43455749869459 \\ 13.7797191051537 \\ -2.64941752283648 \end{bmatrix}$$

```

```
In [ ]: round((Matrix(y)-X*B).norm(), 2)
```

```
Out[ ]: 11.06
```

```
In [ ]: # d)
def f(t): return B[0]*t**3+B[1]*t**2 + B[2]*t + B[3]
round(f(8), 2)
```

```
Out[ ]: 53.54
```

Assignment 7

```
In [ ]: a = 5
        b = 3
        c = a+b
        d = a

        A = 200
        B = 100

        Y = Matrix([[ -R(c,A), R(b,B)], [R(c,A), -R((b+d),B)]])
        Y.eigenvects()
```

```
Out[ ]:  $\left[ \left( -\frac{1}{10}, 1, \begin{bmatrix} -\frac{1}{2} \\ 1 \end{bmatrix} \right), \left( -\frac{1}{50}, 1, \begin{bmatrix} \frac{3}{2} \\ 1 \end{bmatrix} \right) \right]$ 
```

```
In [ ]: l1 = Y.eigenvects()[0][0]
        l2 = Y.eigenvects()[1][0]
        v1 = Y.eigenvects()[0][2][0]
        v2 = Y.eigenvects()[1][2][0]

        y0 = Matrix([100, 10])

        Matrix.hstack(v1, v2, y0).rref()
```

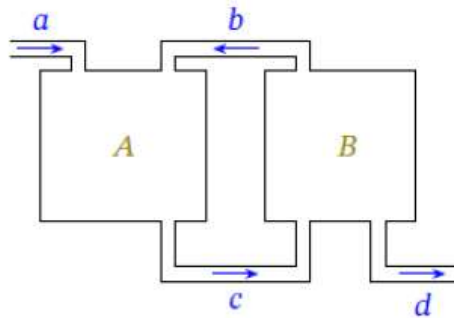
```
Out[ ]:  $\left( \begin{bmatrix} 1 & 0 & -\frac{85}{2} \\ 0 & 1 & \frac{105}{2} \end{bmatrix}, (0, 1) \right)$ 
```

```
In [ ]: c1 = Matrix.hstack(v1, v2, y0).rref()[0][0,-1]
        c2 = Matrix.hstack(v1, v2, y0).rref()[0][1,-1]
```

```
In [ ]: def y(t): return c1*v1*exp(t*l1) + c2*v2*exp(t*l2)
        y(11).evalf(2)
```

```
Out[ ]:  $\begin{bmatrix} 70.0 \\ 28.0 \end{bmatrix}$ 
```

Two containers are connected by pipes, as in the figure below. Container A holds 200 l and container B 100 l. Initially, there is 100 g of salt in container A and 10 g of salt in container B . Through pipe a 5 l/min of pure water is added to A and through pipe b 3 l/min of a salt-water mixture is added to container A .



State the above case in terms of a system of differential equations and find the unique solution. How much salt (in grams) will there be in A and B , respectively, at time $t = 11$? Please round to the nearest integer.

State your answer as positive integers. Remember to round to the nearest integer.

A : g B : g