## Solution 1:

a) As we would expect, the two formulations are equivalent (up to reparameterization). In order to see this, consider the softmax function components:

$$\pi_1(\mathbf{x} \mid \boldsymbol{\theta}) = \frac{\exp(\boldsymbol{\theta}_1^{\top} \mathbf{x})}{\exp(\boldsymbol{\theta}_1^{\top} \mathbf{x}) + \exp(\boldsymbol{\theta}_2^{\top} \mathbf{x})}$$
$$\pi_2(\mathbf{x} \mid \boldsymbol{\theta}) = \frac{\exp(\boldsymbol{\theta}_2^{\top} \mathbf{x})}{\exp(\boldsymbol{\theta}_1^{\top} \mathbf{x}) + \exp(\boldsymbol{\theta}_2^{\top} \mathbf{x})},$$

where  $\pi_1(\mathbf{x} \mid \boldsymbol{\theta}) + \pi_2(\mathbf{x} \mid \boldsymbol{\theta}) = 1$ .

$$\Rightarrow \pi_1(\mathbf{x} \mid \boldsymbol{\theta}) = \frac{1}{\frac{\exp(\boldsymbol{\theta}_1^{\top} \mathbf{x}) + \exp(\boldsymbol{\theta}_2^{\top} \mathbf{x})}{\exp(\boldsymbol{\theta}_1^{\top} \mathbf{x})}}}$$
$$= \frac{1}{1 + \exp(\boldsymbol{\theta}_2^{\top} \mathbf{x} - \boldsymbol{\theta}_1^{\top} \mathbf{x})}$$
$$= \frac{1}{1 + \exp(-\boldsymbol{\theta}_1^{\top} \mathbf{x})}$$
$$= \pi(\mathbf{x} \mid \boldsymbol{\theta}).$$

i.e., the binary-case logistic function, if we set  $\theta := \theta_1 - \theta_2$ .

b) The joint likelihood is easy to compute with the *iid* assumption we are willing to make. It is simply given by the product over all individual likelihoods:

$$\mathcal{L}(\boldsymbol{\theta}) = \prod_{i=1}^{n} \prod_{j=1}^{g} \pi_{j} \left( \mathbf{x}^{(i)} \mid \boldsymbol{\theta} \right)^{\mathbb{I}(y^{(i)}=j)}.$$

- c) Right now,  $\mathcal{L}(\theta)$  does not look anything like an empirical risk function. However, we will arrive there by some simple transformations you might recall from the first exercise sheet:
  - First we convert our maximum likelihood problem into an empirical risk minimization problem:

$$\arg\max\nolimits_{\boldsymbol{\theta}\in\Theta}\mathcal{L}(\boldsymbol{\theta})=\arg\min\nolimits_{\boldsymbol{\theta}\in\Theta}-\mathcal{L}(\boldsymbol{\theta}).$$

• Then we get rid of the (outer) product over all observations, which we would like to turn into a sum. This is achieved by taking the log, a strictly monotonic transformation that has no effect on the optimizer (recall that  $\log(a \cdot b) = \log a + \log b$ ):

$$\arg\min_{\boldsymbol{\theta}\in\Theta}\prod_{i=1}^{n}-\mathcal{L}_{i}(\boldsymbol{\theta})=\arg\min_{\boldsymbol{\theta}\in\Theta}\sum_{i=1}^{n}-\ell_{i}(\boldsymbol{\theta}).$$

The inner product over all classes also becomes a sum in this new formulation (before, we wanted all probability functions but the one corresponding to the true class to become 1 factors, now we want them to become 0 summands):

$$\arg\min_{\boldsymbol{\theta}\in\Theta} \sum_{i=1}^{n} -\ell_{i}(\boldsymbol{\theta}) = \arg\min_{\boldsymbol{\theta}\in\Theta} \sum_{i=1}^{n} -\left(\sum_{j=1}^{g} \mathbb{I}(y=j) \log \pi_{j}\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)\right)$$

• And we have already found an expression that is conformal with the empirical risk minimization principle:

$$\hat{\boldsymbol{\theta}}_{\text{MLE}} = \hat{\boldsymbol{\theta}}_{\text{ERM}} = \arg\min_{\boldsymbol{\theta} \in \Theta} \sum_{i=1}^{n} \underbrace{-\left(\sum_{j=1}^{g} \mathbb{I}(y=j) \log \pi_{j} \left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)\right)}_{L\left(y^{(i)}, f\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)\right)}$$

As the above transformations are universally applicable, we can always use the negative log-likelihood (NLL) as a loss function in empirical risk minimization (not every loss function, however, has a corresponding likelihood formulation).

d) The k-th discriminant function has the following form:

$$\pi_k(\mathbf{x} \mid \boldsymbol{\theta}) = \frac{\exp(\boldsymbol{\theta}_k^{\top} \mathbf{x})}{\sum_{j=1}^g \exp(\boldsymbol{\theta}_j^{\top} \mathbf{x})} \in [0, 1],$$

and  $\sum_{k=1}^{g} \pi_k(\mathbf{x} \mid \boldsymbol{\theta}) = 1$ . This sum-one constraint means that one set of parameters is actually redundant: if we know the first g-1 discriminant functions, the g-th one is fully specified. Therefore, we set  $\hat{\boldsymbol{\theta}}_g = \mathbf{0}$  and compute  $\mathbb{P}(\hat{y} = g \mid \mathbf{x}, \boldsymbol{\theta}) = 1 - \sum_{k=1}^{g-1} \hat{\pi}_k(\mathbf{x} \mid \boldsymbol{\theta})$ .

The highest of the thus estimated posterior class probabilities then determines the actual class label prediction:

$$\hat{y} = \arg\max_{k \in \{1, \dots, q\}} \hat{\pi}_k(\mathbf{x} \mid \boldsymbol{\theta}).$$

e) In order to state the hypothesis space for the multiclass case we can define a length-g vector of class-individual probability functions that results from applying the softmax function S:

$$[\pi_k(\mathbf{x}\mid\boldsymbol{\theta})]_{k=1,2,\ldots,g} = \begin{pmatrix} \pi_1(\mathbf{x}\mid\boldsymbol{\theta}) & \pi_2(\mathbf{x}\mid\boldsymbol{\theta}) & \ldots & \pi_g(\mathbf{x}\mid\boldsymbol{\theta}) \end{pmatrix}^\top =: \mathcal{S}(\mathbf{x}\mid\boldsymbol{\theta}) \in [0,1]^g.$$

Our parameters are now matrix-valued, where every class-individual parameter vector is of length p, such that

$$oldsymbol{ heta} = egin{pmatrix} oldsymbol{ heta}_1 & oldsymbol{ heta}_2 & \dots & oldsymbol{ heta}_g \end{pmatrix} = egin{pmatrix} eta_{1,1} \ dots \ eta_{1,p} \end{pmatrix} & egin{pmatrix} eta_{2,1} \ dots \ eta_{2,p} \end{pmatrix} & \dots & egin{pmatrix} eta_{g,p} \ dots \ eta_{g,p} \end{pmatrix} \end{pmatrix} & \in \Theta = \mathbb{R}^{p imes g}$$

Then we have for our hypothesis space:

$$\mathcal{H} = \left\{ \mathcal{S}_{\boldsymbol{\theta}} : \mathcal{X} \to [0, 1]^g \mid \mathcal{S}(\mathbf{x} \mid \boldsymbol{\theta}) = \left[ \frac{\exp(\boldsymbol{\theta}_k^{\top} \mathbf{x})}{\sum\limits_{j=1}^g \exp(\boldsymbol{\theta}_j^{\top} \mathbf{x})} \right]_{k=1, 2, \dots, g}, \; \boldsymbol{\theta} \in \mathbb{R}^{p \times g} \right\}$$

## Solution 2:

a) We evaluate

$$\hat{y} = 1 \Leftrightarrow \hat{\pi}(\mathbf{x}) = \frac{1}{1 + \exp(-\hat{\boldsymbol{\theta}}^{\top}\mathbf{x})} \ge \alpha$$

$$\Leftrightarrow 1 + \exp(-\hat{\boldsymbol{\theta}}^{\top}\mathbf{x}) \le \frac{1}{\alpha}$$

$$\Leftrightarrow \exp(-\hat{\boldsymbol{\theta}}^{\top}\mathbf{x}) \le \frac{1}{\alpha} - 1$$

$$\Leftrightarrow -\hat{\boldsymbol{\theta}}^{\top}\mathbf{x} \le \log\left(\frac{1}{\alpha} - 1\right)$$

$$\Leftrightarrow \hat{\boldsymbol{\theta}}^{\top}\mathbf{x} \ge -\log\left(\frac{1}{\alpha} - 1\right).$$

 $\hat{\boldsymbol{\theta}}^{\top}\mathbf{x} = -\log\left(\frac{1}{\alpha} - 1\right)$  is the equation of a linear hyperplane comprised of all linear combinations  $\hat{\boldsymbol{\theta}}^{\top}\mathbf{x}$  that are equal to  $-\log\left(\frac{1}{\alpha} - 1\right)$ . The inequality therefore describes the decision rule for setting  $\hat{y}$  equal to 1 by taking all points that lie on or above this hyperplane.

## b) We observe

- in plot (1): the logistic function runs parallel to the  $x_2$  axis, so it is the same for every value of  $x_2$ . In other words,  $x_2$  does not contribute anything to the class discrimination and its associated parameter  $\hat{\theta}_2$  is equal to 0.
- in plot (2): both dimensions affect the logistic function to equal degree in this case, meaning  $x_1$  and  $x_2$  are equally important. If  $\hat{\theta}_1$  were larger than  $\hat{\theta}_2$  or vice versa the hypersurface would be more tilted towards the respective axis.
- in plot (3): this is the same situation as in plot (2) but the logistic function is steeper, which is due to  $\hat{\theta}_1, \hat{\theta}_2$  having larger absolute values. We therefore get a sharper separation between classes (fewer predicted probability values close to 0.5, so we are overall more confident in our decision).
- in plot (4): this is the same situation as in plot (1). The different values for  $\alpha$  represent different thresholds: a high value (leftmost line) means we only assign class 1 if the estimated class-1 probability is large. Conversely, a low value (rightmost line) signifies we are ready to predict class 1 at a low threshold in effect, this is the same as the previous scenario, only the class labels are flipped. The mid line corresponds to the common case  $\alpha = 0.5$  where we assign class 1 as soon as the predicted probability is more than 50%.
- c) We make use of our results from a):

$$\hat{y} = 1 \Leftrightarrow \hat{\boldsymbol{\theta}}^{\top} \mathbf{x} \ge -\log\left(\frac{1}{\alpha} - 1\right)$$
$$\Leftrightarrow \hat{\boldsymbol{\theta}}^{\top} \mathbf{x} \ge -\log\left(\frac{1}{0.5} - 1\right)$$
$$\Leftrightarrow \hat{\boldsymbol{\theta}}^{\top} \mathbf{x} \ge -\log 1$$
$$\Leftrightarrow \hat{\boldsymbol{\theta}}^{\top} \mathbf{x} \ge 0.$$

The 0.5 threshold therefore leads to the coordinate hyperplane and divides the input space into the positive "1" halfspace where  $\hat{\boldsymbol{\theta}}^{\top}\mathbf{x} \geq 0$  and the "0" halfspace where  $\hat{\boldsymbol{\theta}}^{\top}\mathbf{x} < 0$ .

d) When the threshold  $\alpha=0.5$  is chosen, the losses of misclassified observations, i.e.,  $L(\hat{y}=0\mid y=1)$  and  $L(\hat{y}=1\mid y=0)$ , are treated equally, which is often the intuitive thing to do. It means a=0.5 is a sensible threshold if we do not wish to avoid one type of misclassification more than the other. If, however, we need to be cautious to only predict class 1 if we are very confident (for example, when the decision triggers a costly therapy), it would make sense to set the threshold considerably higher.