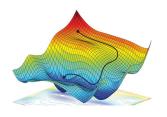
Introduction to Machine Learning

Pseudo-residuals and Gradient Descent



Learning goals

- Learn what pseudo-residuals are
- Understand the relationship between pseudo-residuals and gradient descent

PSEUDO-RESIDUALS

 We further define pseudo-residuals as the negative first derivatives of loss functions w.r.t. f(x)

$$\tilde{r} := -\frac{\partial L(y, f(\mathbf{x}))}{\partial f(\mathbf{x})}.$$

• We will gain more intuition about the principle of pseudo-residuals in a later chapter.

GD IN ML AND PSEUDO-RESIDUALS

By using the chain rule we see that

The Chair rule we see that
$$\nabla_{\boldsymbol{\theta}} \mathcal{R}_{\mathsf{emp}}(\boldsymbol{\theta}) = \sum_{i=1}^{n} \underbrace{\frac{\partial L\left(\boldsymbol{y}^{(i)}, \boldsymbol{f}\right)}{\partial \boldsymbol{f}}}_{=-\tilde{r}^{(i)}} \cdot \nabla_{\boldsymbol{\theta}} \boldsymbol{f}\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)$$
$$= -\sum_{i=1}^{n} \tilde{r}^{(i)} \cdot \nabla_{\boldsymbol{\theta}} \boldsymbol{f}\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)$$

For risk minimization, the update rule for the parameter θ is

$$\boldsymbol{\theta}^{[t+1]} \leftarrow \boldsymbol{\theta}^{[t]} - \alpha^{[t]} \sum_{i=1}^{n} \nabla_{\boldsymbol{\theta}} L\left(y^{(i)}, f\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)\right)\Big|_{\boldsymbol{\theta} = \boldsymbol{\theta}^{[t]}}$$

$$\boldsymbol{\theta}^{[t+1]} \leftarrow \boldsymbol{\theta}^{[t]} + \alpha^{[t]} \sum_{i=1}^{n} \tilde{r}^{(i)} \cdot \nabla_{\boldsymbol{\theta}} f\left(\mathbf{x}^{(i)} \mid \boldsymbol{\theta}\right)\Big|_{\boldsymbol{\theta} = \boldsymbol{\theta}^{[t]}}$$

 $\alpha^{[t]} \in [0, 1]$ is called "learning rate" in this context.