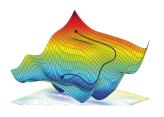
Introduction to Machine Learning

0-1-Loss



Learning goals

- Derive the risk minimizer of the 0-1-loss
- Derive the optimal constant model for the 0-1-loss

0-1-LOSS

- Let us first consider a classifier $h(\mathbf{x}): \mathcal{X} \to \mathcal{Y}$ with $\mathcal{Y} = \{1, ..., g\}$ that outputs discrete classes directly.
- The most natural choice for L(y, h(x)) is of course the 0-1-loss that counts the number of misclassifications

$$L(y, h(\mathbf{x})) = \mathbb{1}_{\{y \neq h(\mathbf{x})\}} = \begin{cases} 1 & \text{if } y \neq h(\mathbf{x}) \\ 0 & \text{if } y = h(\mathbf{x}) \end{cases}.$$

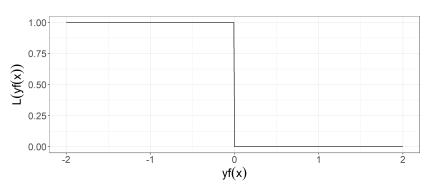
• For the binary case (g = 2) we can express the 0-1-loss for a scoring classifier $f(\mathbf{x})$ based on the margin $r := yf(\mathbf{x})$

$$L(r) = \mathbb{1}_{\{r < 0\}} = \mathbb{1}_{\{y \neq h(\mathbf{x}) < 0\}} = \mathbb{1}_{\{y \neq h(\mathbf{x})\}}.$$

0-1-LOSS

$$L(r) = \mathbb{1}_{\{r < 0\}} = \mathbb{1}_{\{yf(\mathbf{x}) < 0\}} = \mathbb{1}_{\{y \neq h(\mathbf{x})\}}$$

- Intuitive, often what we are interested in.
- Analytic properties: Not continuous, even for linear f the optimization problem is NP-hard and close to intractable.



By the law of total expection we can in general rewrite the risk as

$$\mathcal{R}(f) = \mathbb{E}_{xy} \left[L(y, f(\mathbf{x})) \right] = \mathbb{E}_{x} \left[\mathbb{E}_{y|x} [L(y, f(\mathbf{x}))] \right]$$
$$= \mathbb{E}_{x} \left[\sum_{k \in \mathcal{Y}} L(k, f(\mathbf{x})) \mathbb{P}(y = k \mid \mathbf{x} = \mathbf{x}) \right],$$

with $\mathbb{P}(y = k | \mathbf{x} = \mathbf{x})$ being the posterior probability for class k.

The risk minimizer for a general loss function $L(y, f(\mathbf{x}))$ is

$$\hat{f}(\mathbf{x}) = \underset{f:\mathcal{X} \to \mathbb{R}^g}{\arg \min} \mathbb{E}_{\mathbf{x}} \left[\sum_{k \in \mathcal{V}} L(k, f(\mathbf{x})) \mathbb{P}(y = k | \mathbf{x} = \mathbf{x}) \right].$$

We compute the point-wise optimizer of the above term for the 0-1-loss (defined on a discrete classifier $h(\mathbf{x})$):

$$h^*(\mathbf{x}) = \underset{l \in \mathcal{Y}}{\arg \min} \sum_{k \in \mathcal{Y}} L(k, l) \cdot \mathbb{P}(y = k \mid \mathbf{x} = \mathbf{x})$$

$$= \underset{l \in \mathcal{Y}}{\arg \min} \sum_{k \neq l} \mathbb{P}(y = k \mid \mathbf{x} = \mathbf{x})$$

$$= \underset{l \in \mathcal{Y}}{\arg \min} 1 - \mathbb{P}(y = l \mid \mathbf{x} = \mathbf{x})$$

$$= \underset{l \in \mathcal{Y}}{\arg \max} \mathbb{P}(y = l \mid \mathbf{x} = \mathbf{x}),$$

which corresponds to predicting the most probable class.

Note that some literature refers to $h^*(\mathbf{x})$ as the **Bayes optimal** classifier (without specifying the loss function).

The Bayes risk for the 0-1-loss (also: Bayes error rate) is

$$\mathcal{R}^* = \mathbb{E}_x \left[\min_{l \in \mathcal{Y}} \left(1 - \mathbb{P}(y = l \mid \mathbf{x} = \mathbf{x}) \right) \right]$$
$$= 1 - \mathbb{E}_x \left[\max_{l \in \mathcal{Y}} \mathbb{P}(y = l \mid \mathbf{x} = \mathbf{x}) \right].$$

In the binary case (g=2), we define $\eta(\mathbf{x}) := \mathbb{P}(y=1 \mid \mathbf{x})$ and write risk minimizer and Bayes risk as follows:

$$\begin{array}{lcl} h^*(\mathbf{x}) & = & \begin{cases} 1 & \eta(\mathbf{x}) \geq \frac{1}{2} \\ 0 & \eta(\mathbf{x}) < \frac{1}{2} \end{cases} \\ \mathcal{R}^* & = & \mathbb{E}_x \left[\min(\eta(\mathbf{x}), 1 - \eta(\mathbf{x})) \right] = \mathbb{E}_x \left[\max(\eta(\mathbf{x}), 1 - \eta(\mathbf{x})) \right]. \end{array}$$

Example: Assume that
$$\mathbb{P}(y=1) = \frac{1}{2}$$
 and $\mathbb{P}(\mathbf{x} \mid y) = \begin{cases} \phi_{\mu_1,\sigma^2}(\mathbf{x}) \\ \phi_{\mu_2,\sigma^2}(\mathbf{x}) \end{cases}$.

The decision boundary of the Bayes optimal classifier is shown in orange and the Bayes error rate is highlighted as red area.

