STA2005S - Regression Assignment

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Abstract

In this report, we explored the efficiency of 6 programming languages through the approximation of π . We found that efficiency of various programming languages can vary widely, with C and C++ being the most efficient programming languages. We also presented evidence for compiled languages having better performance than interpreted languages. Our results suggest that programmers can benefit from taking the efficiency of various programming languages into account, rather than simply opting for simplicity in the syntax of these languages .

1 Part One: Analysis

1.1 Section 1: Introduction

Air pollution, particularly high levels of particulate matter (PM), is a major environmental and public health issue in South Africa's urban centers. Exposure to elevated PM levels is linked to respiratory diseases and other serious health conditions. Understanding the factors influencing PM concentrations is crucial for developing policies that improve air quality and protect public health. This analysis seeks to identify the key drivers of air pollution in South Africa's cities, focusing on how various urban, environmental, and socioeconomic factors affect particulate matter levels.

Unknown Factors to Investigate:

Traffic Density: How do varying levels of vehicle traffic contribute to PM levels in different areas?

Industrial Activity: What is the impact of industrial activity near monitoring stations on air quality?

Temperature & Humidity: How do changes in weather conditions, like temperature and humidity, influence PM concentrations?

Wind Speed: How does wind speed affect the dispersion or accumulation of particulate matter in urban areas?

Day of the Week & Public Holidays: Do patterns of human activity on weekdays, weekends, and holidays significantly influence pollution levels?

Urban Greenery: How effective are green spaces in reducing air pollution in densely populated areas?

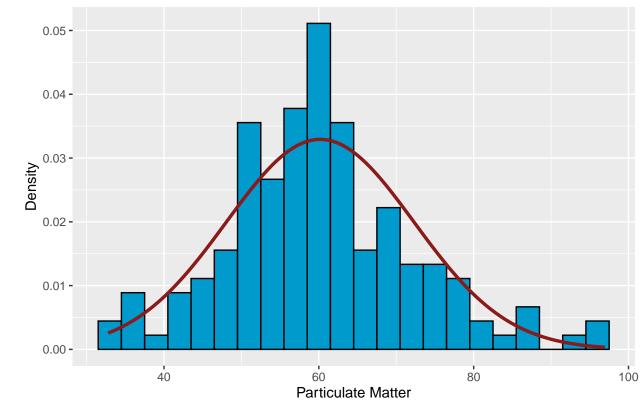
2 Objective

The goal of this analysis is to explore the relationships between PM levels and these explanatory variables. By identifying the most influential factors, we aim to inform urban planning and public health strategies that address air pollution and improve the quality of life in South African cities.

2.1 Section 2: Data Exploration

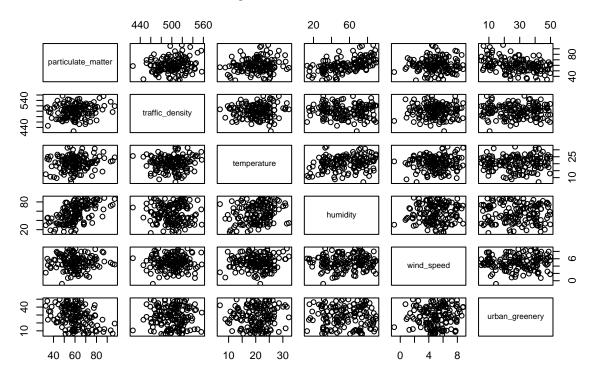
2.1.1 Density plot

Density Plot of Particulate Matter

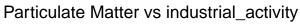


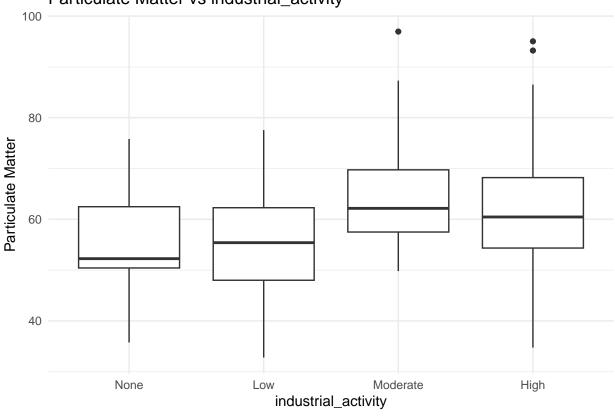
2.1.2 Pairwsie Plots

Pairwise Scatterplots of Continuous Variables

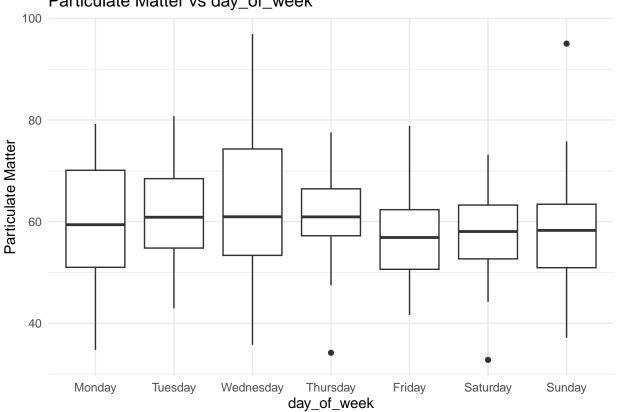


2.1.3 Categorial Variable Plots

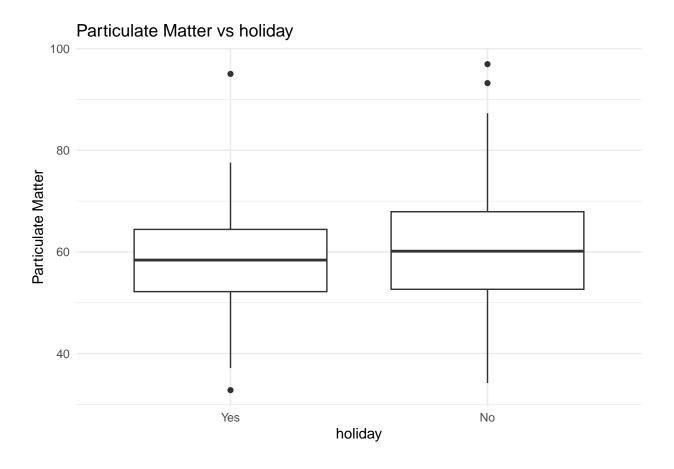




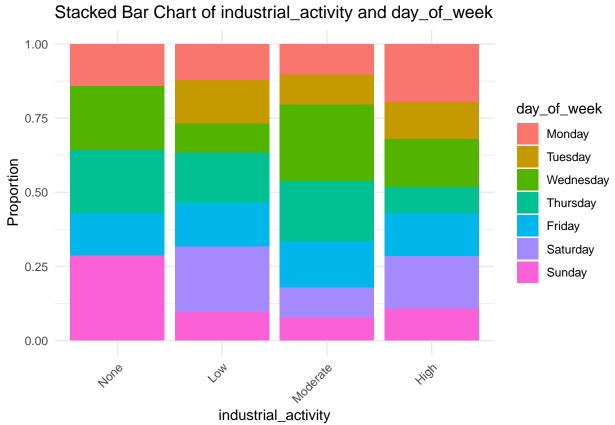
Particulate Matter vs day_of_week

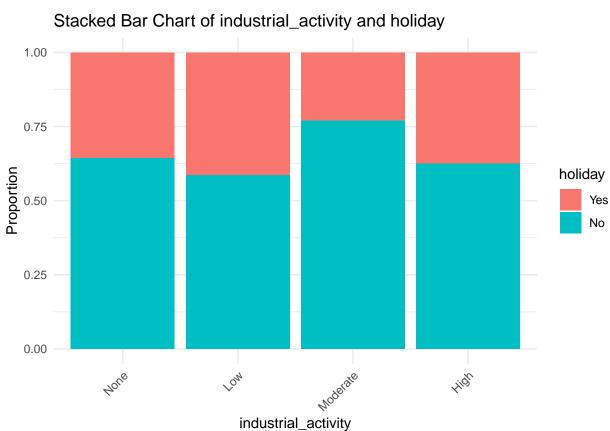


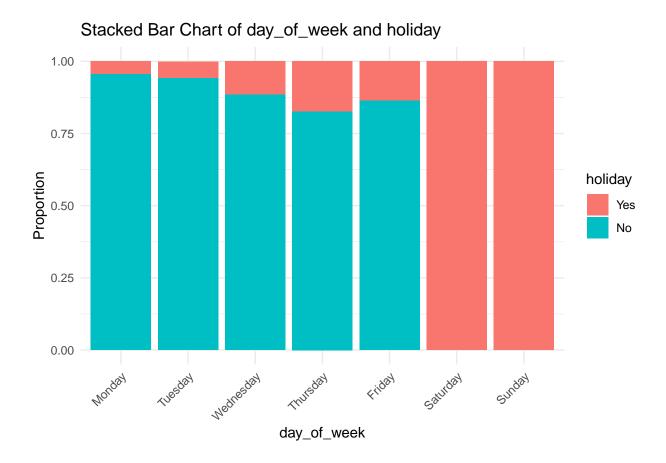
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2.1.4 Visual Representation of Relationship between Categorial Variables







2.1.5 Comments

Distribution characterisitcs:

The distribution of particulate matter levels is generally right-skewed, indicating that a small number of observations have significantly high levels of particulate matter while most observations are clustered at lower levels. The presence of outliers suggests variations in local conditions affecting air quality.

Observed Relationships

- 1. Traffic Density: A positive correlation exists between particulate matter levels and traffic density, suggesting that areas with higher vehicle traffic tend to experience elevated levels of particulate matter.
- 2. Urban Greenery: A negative trend is observed, where higher urban greenery correlates with lower particulate matter, indicating that vegetation may help mitigate air pollution.
- 3. Temperature and Wind Speed: No strong relationship was identified between particulate matter and temperature. However, there is a slight negative correlation with wind speed, indicating that higher wind speeds may help disperse particulate matter.

Potential Collinearity

Some potential collinearity is observed among the explanatory variables, particularly between traffic density and urban greenery. High traffic areas often have less vegetation, leading to a relationship that may confound the analysis. Additionally, temperature and wind speed may also exhibit collinearity, as changes in one could affect the other.

3 Section 3

3.1 Simple linear regression

```
X <- cbind(1,data_tidy_air_quality$traffic_density)
Y <-data_tidy_air_quality$particulate_matter
bhat <- solve(t(X) %*% X) %*% t(X) %*% Y

Cmat <- solve(t(X) %*% X)
k <- ncol(X)
rss <- t(Y - X %*% bhat) %*% (Y - X %*% bhat)
# Calculate s2 = RSS/(n-k)
s2 <- as.numeric((rss)/148)
s2

## [1] 143.5745

c_ii <- diag(Cmat)
std.error <- sqrt(s2 * c_ii)
std.error</pre>
## [1] 20.37801682 0.04065266
```

3.2 Hpothesis Test

```
# Calculate F-statistic and p-value manually
group_means <- tapply(data_tidy_air_quality$particulate_matter,</pre>
                       data_tidy_air_quality$industrial_activity, mean)
overall_mean <- mean(data_tidy_air_quality$particulate_matter)</pre>
# Calculate SST
SST <- sum((data_tidy_air_quality$particulate_matter - overall_mean)^2)
# Calculate SStreatment
n <- table(data_tidy_air_quality$industrial_activity)</pre>
SStreatment <- sum(n * (group_means - overall_mean)^2)</pre>
# Calculate SSerror
group_means_vector <- unlist(tapply(data_tidy_air_quality$particulate_matter, data_tidy_air_quality$ind
[data_tidy_air_quality$industrial_activity])
SSerror <- sum((data_tidy_air_quality$particulate_matter - group_means_vector)^2)
# Calculate degrees of freedom
k <- length(unique(data_tidy_air_quality$industrial_activity))</pre>
N <- nrow(data)</pre>
DFtreatment <- k - 1
```

```
DFerror <- 150 - k

# Calculate Mean Squares
MStreatment <- SStreatment / DFtreatment
MSerror <- SSerror / DFerror

# Calculate F-statistic
F_statistic <- MStreatment/MSerror
F_statistic</pre>
```

[1] 5.395959

```
# Calculate p-value
p_value <- pf(F_statistic, DFtreatment, DFerror, lower.tail = FALSE)
p_value</pre>
```

[1] 0.001502236

4 Question 4

Table 1: Confidence Interval for each Coefficient

	2.5 %	Estimate	97.5 %
Intercept			
(Intercept)	-21.0568	13.7937	48.6442
Traffic Density			
${\it traffic_density}$	0.0155	0.0799	0.1444
Industrial Activity			
$industrial_activityLow$	-3.1721	2.6589	8.4900
$industrial_activity Moderate$	0.6047	6.4545	12.3043
$industrial_activity High$	-0.2503	5.3652	10.9806
Natural Factors			
temperature	-1.1521	-0.2815	0.5891
humidity	-0.1111	0.1926	0.4962
wind _speed	-0.8040	0.0193	0.8426
temperature:humidity	-0.0088	0.0061	0.0209
Day of Week			
$day_of_weekTuesday$	-5.9877	0.0133	6.0142
$day_of_weekWednesday$	-5.3501	0.1565	5.6630
$day_of_weekThursday$	-5.5367	0.1662	5.8690
$day_of_weekFriday$	-8.0602	-2.4221	3.2161
$day_of_weekSaturday$	-12.3605	-4.4832	3.3940
$day_of_weekSunday$	-10.2167	-2.0885	6.0396
Holiday			
holidayNo	-6.7151	-0.9961	4.7228
Urban Greenery			
urban_greenery	-0.4142	-0.2954	-0.1766

4.1 Hypothesis Testing

We'd like to perform hypothesis tests on the following variables: Temperature, Humidity, Industrial Levels, and Day of Week.

We'll start by examining whether Temperature has an effect on the concentration of Particulate Matter. We'll use the following set of hypothesis:

$$\begin{split} H_0: \beta_{temp} &= \beta_{hum:temp} = 0 \\ H_A: \beta_{temp} &\neq 0 \text{ and } \beta_{hum:temp} \neq 0 \end{split}$$

We'll compare the restricted model with the unrestricted model:

Using the anova function in R, we compare the two models with F test. The F test yields a P value 0.6815, suggesting that temperature doesn't have a significant effect on the concentration of particular matter.

We now test for the effect of humidity. Repeating the same procedure, we obtain a P value < 0.00001. Suggesting that it's likely that humidity has an effect on the concentration of particulate matters.

$$H_0: \beta_{hum} = \beta_{hum:temp} = 0$$

 $H_A: \beta_{hum} \neq 0 \text{ and } \beta_{hum:temp} \neq 0$

4.1.1 Categorical Variables

For the day of week, we take Monday as the reference category and test for the following set of hypothesis, using the same procedure.

```
H_0: \beta_{Tuesday} = \beta_{Wednesday} = \beta_{Thursday} = \beta_{Friday} = \beta_{Saturday} = \beta_{Sunday} = 0
H_A: \beta_{Tuesday} \neq 0 \text{ and } \beta_{Wednesday} \neq 0 \text{ and } \beta_{Thursday} \neq 0 \text{ and } \beta_{Friday} \neq 0 \text{ and } \beta_{Saturday} \neq 0 \text{ and } \beta_{Sunday} \neq 0
```

The P value is 0.7735, indicating that there is no evidence that supports rejecting the null hypothesis.

We do the same for industrial activity, taking No Activity as the reference category to test for the set of hypothesis:

```
H_0: \beta_{Low} = \beta_{Moderate} = \beta_{High} = 0

H_A: \beta_{Low} \neq 0 \text{ and } \beta_{Moderate} \neq 0 \text{ and } \beta_{High} \neq 0
```

We obtain a P-value of 0.0707, suggesting that there's no evidence that supports rejecting the null hypothesis at 5% significance level.

4.2 Interretation

From the summary output and the F test for Natural Factors, we get that only Moderate Industrial Activity (p-value: 0.03), Traffic Density (p-value: 0.0155), Urban Greenery (p-value: 0.0001), and Humidity (p-value: 0.0001) have a significant effect (p value less than or equal to 0.05) on the concentration of particulate matters.

The average increase in concentration of particulate matter by Moderate Industrial Activity is estimated to be 6.4545 $\frac{\mu g}{m^3}$ (CI95%: 0.6047, 12.3043), indicating a positive association between the two factors, although the amount of increase is unclear as the confidence interval is quite wide. The average increase in concentration of particulate matter caused by Traffic Density, that is one extra vehicle per hour, is estimated to be 0.0799 $\frac{\mu g}{m^3}$ (CI95%: 0.0155, 0.1444), indicating a positive association. The average decrease in concentration of particulate matter caused by a unit increase in the percentage of area covered by Urban Greenery is estimated to be 0.2954 $\frac{\mu g}{m^3}$ (CI95%:-0.4142, -0.1766), indicating a negative association between the two. The effect of humidity interacts with the effects of temperature. Using the anova model, we can only examine the effects of humidity and humidity:temperature separately.

5 part 2

5.1 Scenario A

5.2 Scenario A:

5.2.1 Methodology

We know that there is no correlation between temperature and the response variable as the variation in it is caused by random noises. So any rejection of the null hypothesis is a type I error.

Simulation under the null hypothesis ($\beta_1 = 0$):

We simulate the data assuming $\beta_0 = 30$, $\beta_1 = 0$, and errors are uniformly distributed. The errors will be sampled from a uniform distribution where $e \sim U(a, b)$ with the constraint that Var(e) = 100

For a uniform distribution $e \sim U(a,b)$ with a variance $\sigma^2 = 100$, $Var(e) = \frac{(b-a)^2}{12}$. Solving for a and b we get a = -17.32 and b = 17.32

To simulate our data, we created a function 'run_simulation' which runs a simulation once. In a simulation, we used runif(length(temperature), min = a, max = b) to generate random errors. Next calculated $Y_i = 30 + e$ as the vector of response variables for the trial. We then used the lm function to fit our regression model. We extracted p values from our model, and ran ifelse statement to check whether our null hypothesis was rejected or not, at 5% significance level. Then we used the replicate() function to run the simulation 1000 times. Finally, we counted the number of null hypothesis rejected and we observed that our type 1 error rate for this scenario is $0.043 \ 0.054$

5.2.2 Results

Type I error is the probability of incorrectly rejecting the null hypothesis when it is true (false positive). Under the null hypothesis, the expected Type I error rate should be equal to the chosen significance level, typically 0.05.

We have found that the Type I error rate is 0.044, which is less than the expected 0.05. This is because a uniform distribution is bounded, meaning that values drawn from it are more tightly spread compared to values drawn from a normal distribution, which can take on more extreme values due to its unbounded nature. This results in the simulated error term, and thus the response variable, having less variation. This leads to β_1 being less likely to deviate from zero, as stated by the null hypothesis.

For interest's sake, if we increase the number of simulations to 10000, the Type I error rate becomes 0.0501, which is much closer to the expected 0.05. However, if we fix the number of simulations to 1000 and reduce each sample size to only 3 observations, the Type I error rate drops to 0.036, which is much smaller than the expected 0.05.

This can be explained by the fact that despite the model violation (using uniformly distributed errors instead of normally distributed ones), the Central Limit Theorem helps mitigate the impact as the sample size increases. With 150 observations per sample and 10000 samples in total, the distribution of the sample means of the estimated coefficients approaches normality, making the Type I error rate approach the expected value. With smaller sample sizes, the uniform errors result in less variation in the estimates, leading to a lower Type I error rate.

5.3 Scenario B:

5.3.1 Methodology

Again we created a single function to run a single simulation. In each simulation, We simulate the error variances using the normal distribution with mean of 100 and variance of 50. Then we simulated error terms using a normal distribution with a mean of 0 and a variance of our error_variance calculated before. This ensures that our errors have a non constant variance. We then repeated the same steps as above to obtain our type 1 error rate. Our observed type 1 error rate is 0.042.

5.3.2 Results

The observed type 1 error rate is 0.046, less than the expected 0.05. This is caused by the heteroscedasticity we intentionally introduced to the model. Constant variance is one of the key assumptions for the Gauss-Markov theorem. By breaking the assumption, the ordinary least square estimate(OLS) for β_1 , $\hat{\beta}_1$ is no longer guaranteed to be the best linear unbiased estimate(BLUE), thereby making the type I error rate inaccurate. The deviation could be more pronounced if the variability of the errors is made larger to make the in a way that increases the Type I error.

5.4 Scenario C:

5.4.1 Methodology and discussion of results for Scenario C:

Using our function again, we replicate 1000 simulations, but this time we test the dependence of errors in our model. To generate Correlated errors in our model we, use the provided function given to us. As above we repeated the same steps in order to obtain the proportion of the number of times our null hypothesis was incorrectly rejected. OUr type 1 error rate was 0.053.

Autocorrelation violates the assumption of independent errors in linear regression. This can lead to incorrect standard errors for the regression coefficients, making hypothesis tests less reliable.

Typically, autocorrelated errors inflate Type I errors if unaccounted for because the model underestimates the true error variability. However, depending on the specific pattern of autocorrelation and sample size, this effect can vary.