

COMSM1302

Overview of Computer Architecture

Lecture 12

ARM Instruction Set



Recap

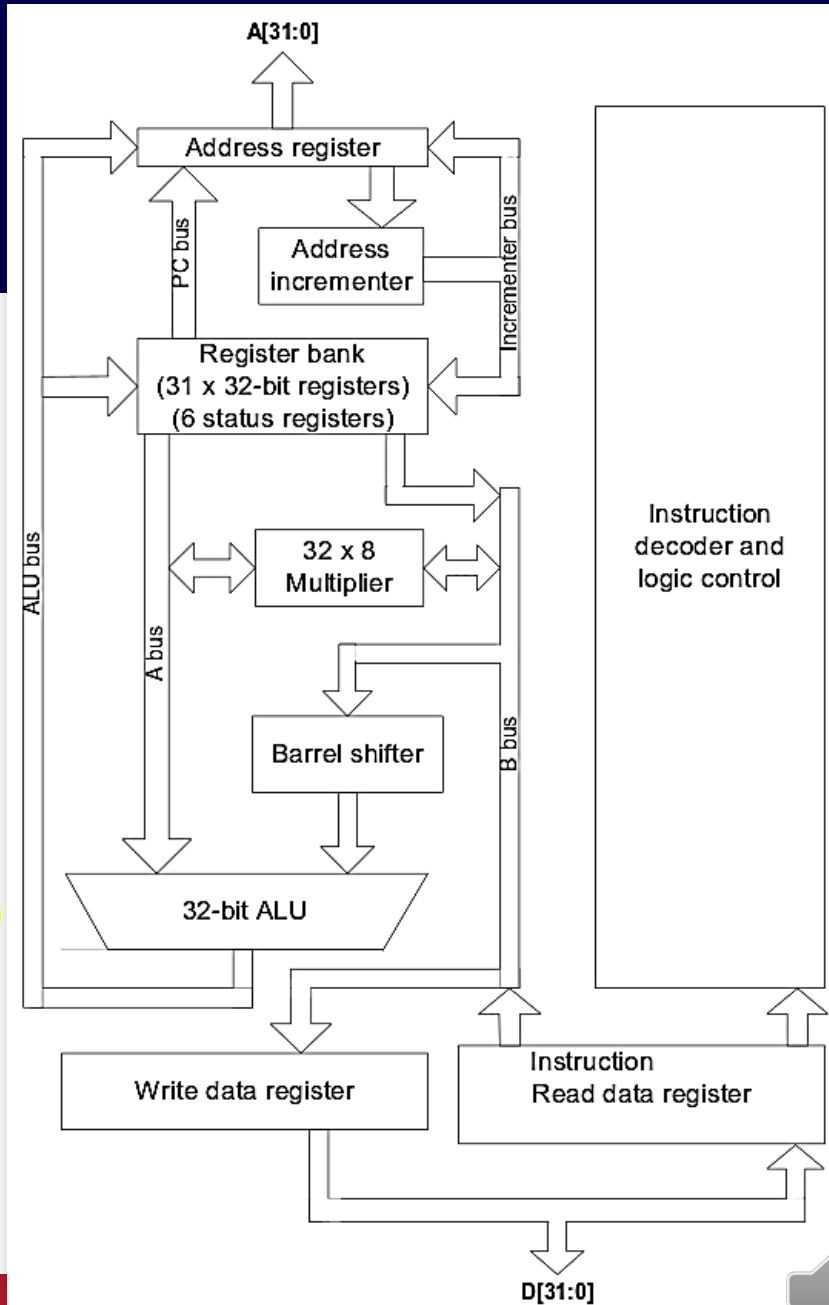
- We have designed a 4-bit CPU.
- In the labs, we have implemented our CPU.
- We have seen how the basic instructions have to be supported by hardware.
- We have programmed our first assembly code.
- We have seen how flexible assembly programming can be.

What are we missing?

- Our instruction set:
 - Is limited to 4-bit data width and just two general purpose registers.
 - Does not support the following:
 - Conditional execution.
 - Moving data between registers.
 - Logical operations and shifts.
 - Multiplication and division.
 - Branching



- The ARM instruction set is a set of 32-bit instructions.
- There are 37 total registers in the processor.
- In user mode we can access:
 - 15 general-purpose 32-bit registers (R0 to R14)
 - Program counter (R15)
 - Current Program Status Register (CPSR)
- We will use ARM7TDMI processor.



🔥 A bit of history – Acorn



Acorn Computer Ltd

Acron RISC Machine (arm)

1985



1987

🔥 A bit of history - Apple



Apple Computer, Inc.



1993

<https://www.wired.com/2013/08/remembering-the-apple-newtons-prophetic-failure-and-lasting-ideals/>

🔥 A bit of history - ARM



Apple Computer, Inc.



Acorn Computer Ltd



VLSI

VLSI Technology, Inc.

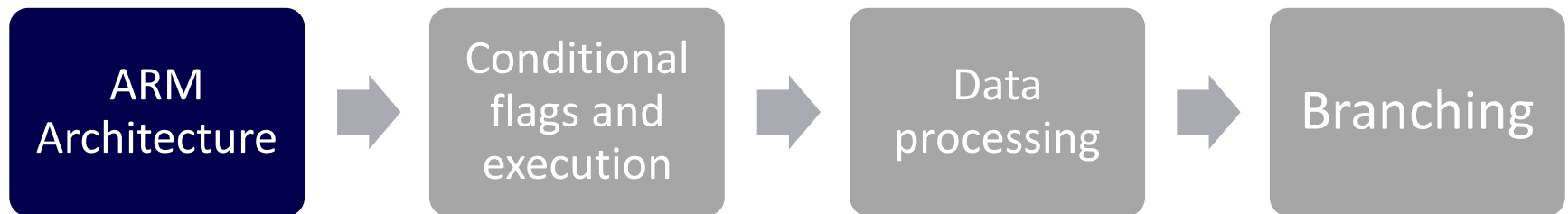
arm

1990

Advanced RISC Machine Ltd (arm)



ARM Instruction Set



What is arm architecture? - 1

- The ARM architecture is based on *Reduced Instruction Set Computer* (RISC) principles.
- All instructions are 32 bits long.
- Most instructions execute in a single cycle.
- Every instruction can be conditionally executed.



🔥 What is arm architecture? - 2

- A load/store architecture
 - Data processing instructions act only on registers
 - Combined ALU and shifter for high speed bit manipulation. ALU output: linked back to the registers
 - Specific memory access instructions with powerful auto-indexing addressing modes. helpful for accessing arrays.
- Instruction set extension via coprocessors



Why ARM ?

- The ARM architecture is based on a simple design.
 1. A high instruction throughput.
 2. An excellent real-time interrupt response.
 3. A small processor die.
 1. Less material so it is cost-effective.
 2. Less transistors so low power.

About the ARM7TDMI Core

- The ARM7TDMI core is based on the **von Neumann architecture** with a 32-bit data bus that carries **both instructions and data**.

Processor Operating States

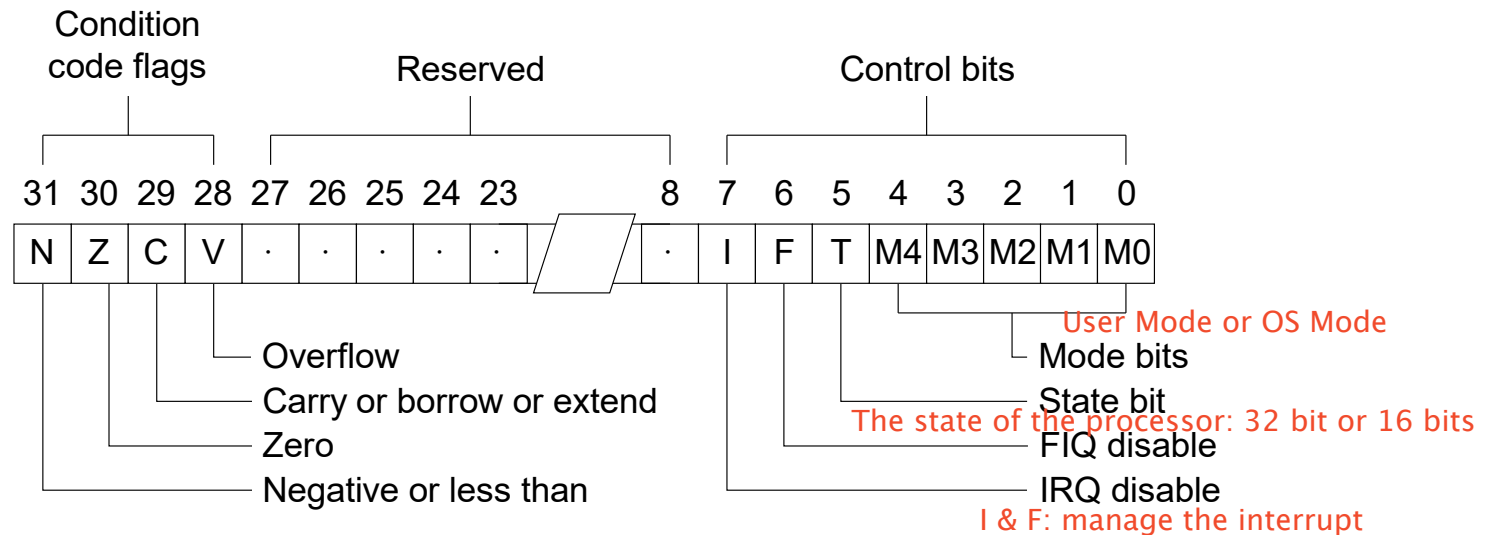
- **ARM 32-bit**, word-aligned ARM instructions are executed in this state.
- **Thumb 16-bit**, halfword-aligned Thumb instructions are executed in this state.
- <https://developer.arm.com/documentation/dai0494/d/CACCIIDAH>

The ARM-state Registers Set

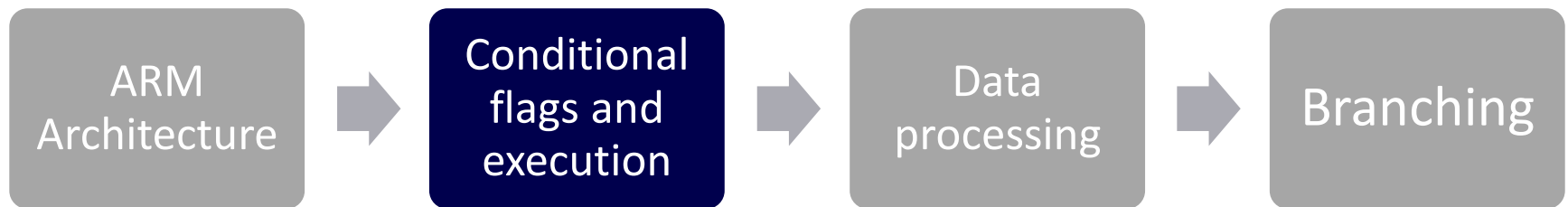
1. Registers r0 to r13 are general-purpose registers used to hold either data or address values.
2. Register r14 is used as the subroutine *link Register* (LR).
3. Register r15 holds the PC.
4. By convention, r13 is used as the *Stack Pointer* (SP).

Program Status Registers

- Current Program Status Registers, CPSR.



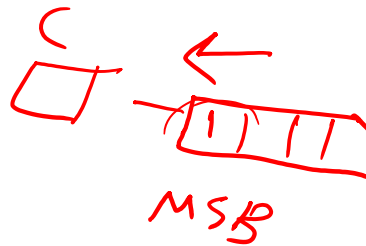
ARM Instruction Set



🔥 Condition Code Flags



Flag	Logical Instruction	Mathematics Instruction
Negative, N = 1	No meaning	Bit 31 of the result has been set Indicates a negative number in signed operations
Zero, Z = 1	Result is all zeroes	Result is zero
Carry, C = 1	After Shift operation '1' was left in carry flag	Explained in the next slides
Overflow, V = 1	No meaning	Explained in the next slides



if MSB is 1 and do the LSL operation, the carry bit will be set

Overflow Flag - Add

- Overflow happens if the result of :
 - adding two positive numbers is a negative number
 - adding two negative numbers is a positive number
- It cannot happen when adding positive and negative numbers.
- It has no meaning if we are interpreting the data as unsigned. The ALU will still update this flag, but we can ignore it.

Overflow Flag - Sub

- Overflow happens if the result of :
 - Subtracting a positive number from a negative number is positive $(-7) - (2) = -9$
 - Subtracting a negative number from a positive number is negative $(+7) - (-2) = 9$
- It cannot happen when subtracting two positive or two negative numbers.

Carry Flag

- Carry happens when:
 - Adding two unsigned numbers and the result cannot fit in 32 bits.
 - Doing a subtraction operation and no borrowing is needed.
- It has no meaning if we are interpreting the data as signed. The ALU will still update this flag, but we can ignore it.

1010
0111

10001

1010
0001

1001

there we have to look at the overflow flag

Conditional Execution

- All instructions can execute conditionally in ARM state.
- For example:
 - `ADD r0, r1, r2 ; r0 = r1 + r2`
- To execute this only if the zero flag is set:
 - `CMP r1, r2 ; Compare r1 and r2`
 - `ADDEQ r0, r1, r2 ; If zero flag set`

🔥 Conditional Execution - Example

- `CMP r1, r2` ; Compare r1 and r2
- `ADDEQ r0, r1, r2` ; If zero flag set
- Try this assembly code with the following values:

1. `r0 = 0, r1 = 10, and r2 = 4` $Z = 0$

2. `r0 = 0, r1 = 7, and r2 = 7` $Z = 1$

- What is the value of r0 in both cases?

1. $r_0 = 0$
2. $r_0 = r_1 + r_2 = 7 + 7 = 14$

Update Condition Flags

- By default, data processing operations do not affect the condition flags (apart from the comparisons where this is the only effect).
- To cause the condition flags to be updated postfix the instruction (and any condition code) with an “S”.
- ADDEQS or ADDS

🔥 Update Condition Flags - Example

- Assume:

– $r1 = \#ffffff$, $r2 = \#1$, $r3 = \#ff$,
and $CPSR = 0$ i.e. the condition EQ is
false. Z = 0

1111
0000
→ ADDS r0, r1, r2 Z = 1
MOVEQ r3, r0 r0 = 0
Z = 1

ADD r0, r1, r2 r0 = 0
MOVNE r3, r0 r3 = 0
Z = 0

Condition Fields - 1



Suffix	Meaning (for cmp or subs)	Condition
EQ	Equal	Z set
NE	Not equal	Z clear
CS or HS	Unsigned higher, or same (or no borrow)	C set
CC or LO	Unsigned lower or borrow	C clear
MI	Negative	N set
PL	Positive or zero	N clear
VS	Signed overflow	V set
VC	No signed overflow	V clear

Condition Fields - 2

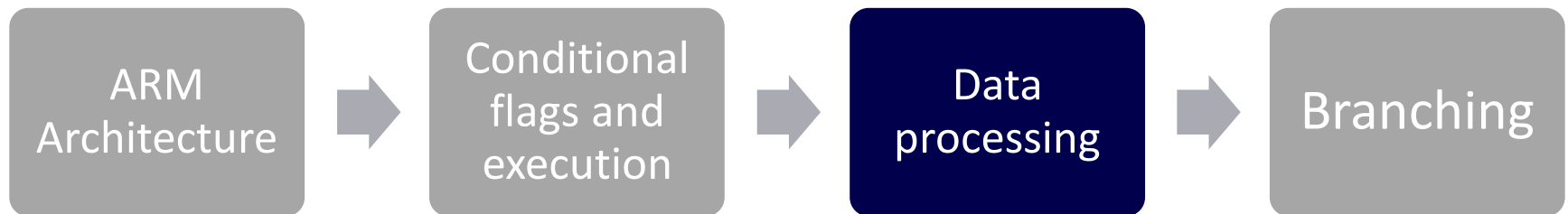


Suffix	Meaning (for cmp or subs)	Condition
HI	Unsigned higher	C set, Z clear
LS	Unsigned lower, or same	C clear, Z set
GE	Signed greater than, or equal	N=V (N and V set or N and V clear)
LT	Signed less than	N<>V (N set and V clear) or (N clear and V set)
GT	Signed greater than	Z clear, N=V (N and V set or N and V clear)
LE	Signed less than, or equal	Z set or N<>V (N set and V clear) or (N clear and V set)
AL	Always	Flag ignored

🔥 Condition fields – examples

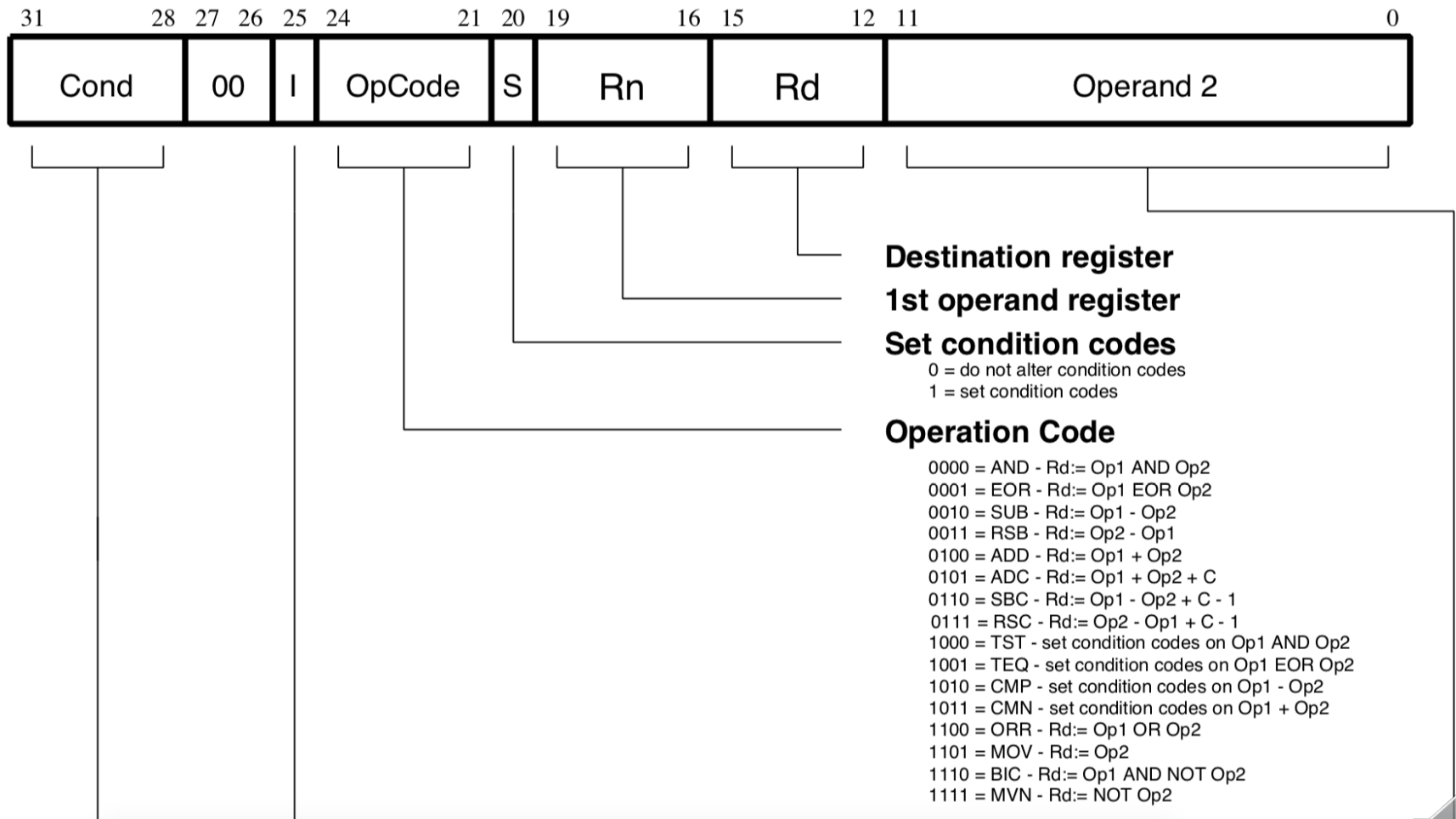
1. `cpsr[31:28] = 0x2`, which of the conditional fields are true?
2. Let `r0 = 0x8000000f`, `r1 = 0x800000ff`.
After executing `adds r2, r0, r1`:
 1. What is the value of `r2` ?
 2. What is the value of `cpsr[31:28]` ?
 3. Which conditional fields are true ?
 4. What is the meaning of the overflow flag in this example?

ARM Instruction Set



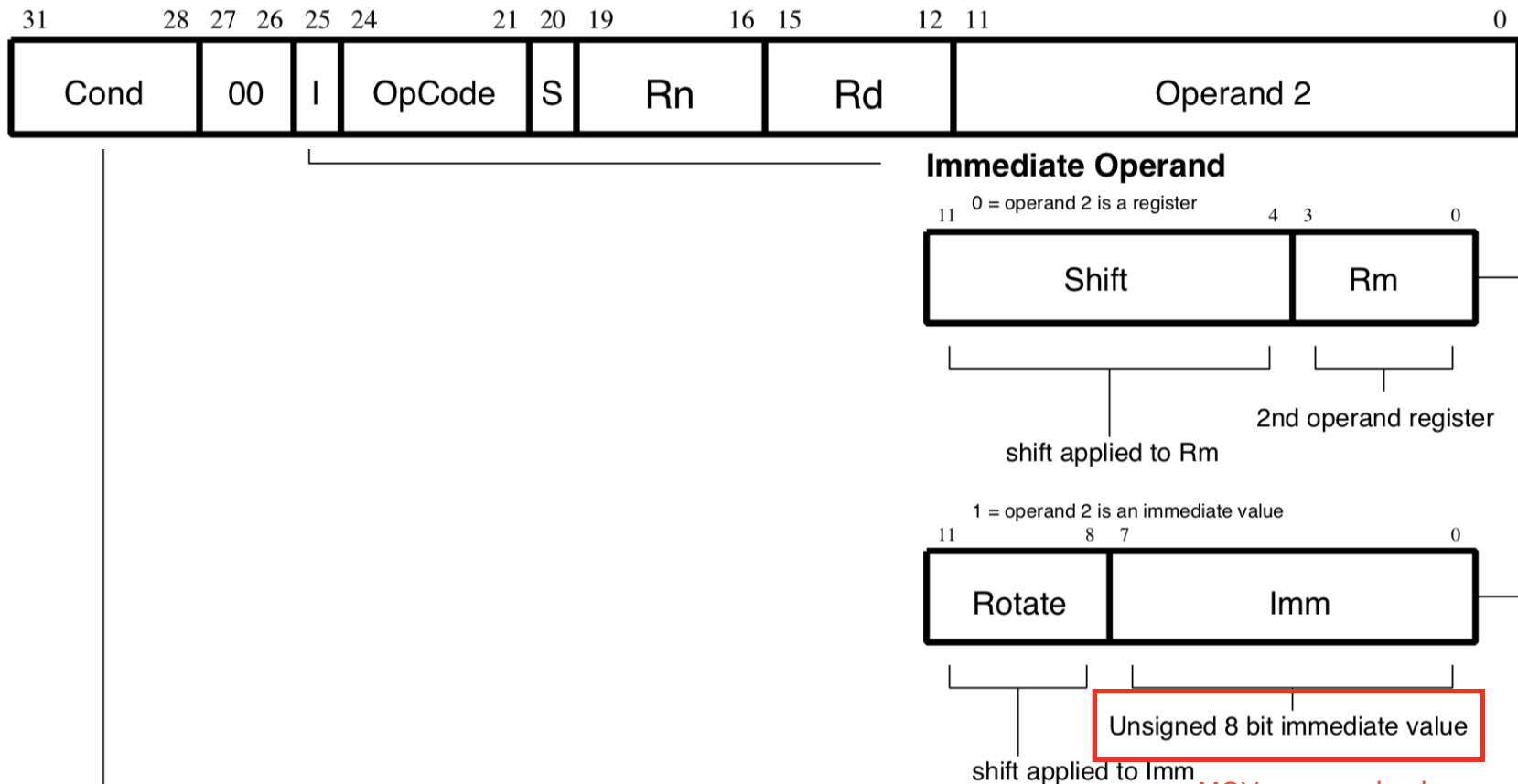
🔥 Data Processing Instructions

Format - 1



🔥 Data Processing Instructions

Format - 2



Condition field

MOV can send value smaller than 8 bit (255) to register.



Data Processing Instructions

- Contains:
 - Arithmetic operations
 - Comparisons (no results - just set condition codes)
 - Logical operations
 - Data movement between registers

Arithmetic Operations - 1

- Operations are:
 - ADD $\text{operand1} + \text{operand2}$
 - ADC $\text{operand1} + \text{operand2} + \text{carry}$
 - SUB $\text{operand1} - \text{operand2}$
 - SBC $\text{operand1} - \text{operand2} + \text{carry} - 1$
 - RSB $\text{operand2} - \text{operand1}$
 - RSC $\text{operand2} - \text{operand1} + \text{carry} - 1$

Arithmetic Operations - 2



- Syntax:
 - $\langle \text{Operation} \rangle \{ \langle \text{cond} \rangle \} \{ S \} \text{ Rd, Rn, Operand2}$
× ×
- Examples
 - ADD r0, r1, r2 ←
 - SUBGT r3, r3, #1
 - RSBLES r4, r5, #5

Comparisons - 1

- The only effect of the comparisons is to
 - **UPDATE THE CONDITION FLAGS.** Thus no need to set S bit.
- Operations are:
 - CMP operand1 - operand2, No result
 - CMN operand1 + operand2, No result
 - TST operand1 AND operand2, No result
 - TEQ operand1 EOR operand2, No result

Comparisons - 2

- Syntax:
 - <Operation>{<cond>} Rn, Operand2
- Examples:
 - CMP r0, r1
 - TSTEQ r2, #5

🔥 Logical Operations - 1

- Operations are:
 - AND operand1 AND operand2
 - EOR operand1 EOR operand2
 - ORR operand1 OR operand2
 - BIC operand1 AND NOT operand2 [ie bit clear]

Handwritten example of BIC operation:

$R_0 = 1110$
 $R_1 = 0110$

Diagram showing the BIC operation: $R_0 \oplus R_1$ (XOR) followed by AND with 1 (bit clear).

Result: $1110 \oplus 0110 = 1000$

BIC R_0, R_0, R_1

Logical Operations - 2

- Syntax:
 - `<Operation>{<cond>}{S} Rd, Rn, Operand2`
- Examples:
 - `AND r0, r1, r2`
 - `BICEQ r2, r3, #7`
 - `EORS r1, r3, r0`

Data Movement

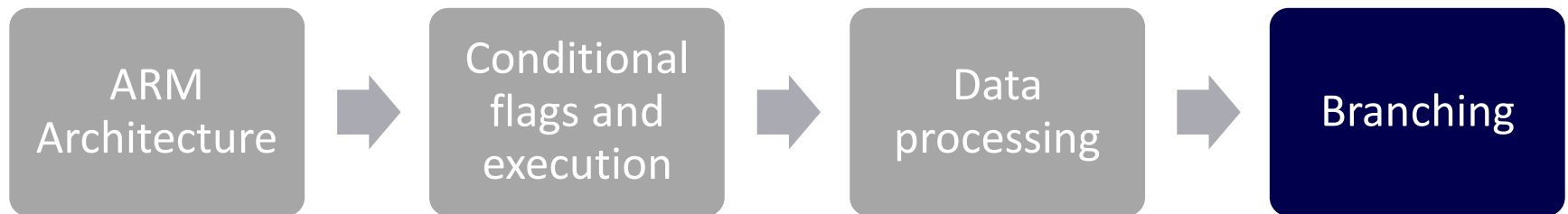
- Operations are:
 - MOV operand2 to the destination register
 - MVN NOT operand2 to the destination register
 - MRS The value of cpsr to the destination register

Data Movement

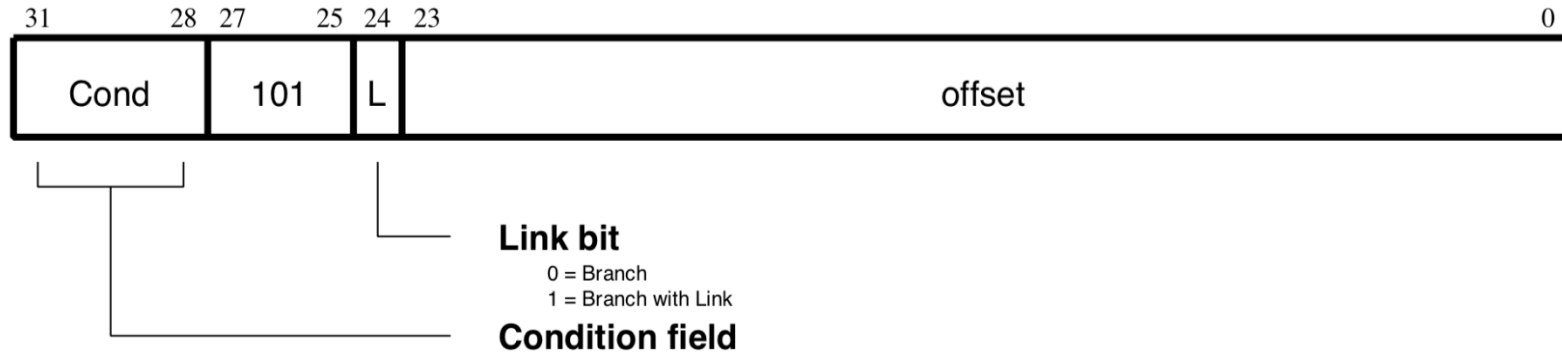
- Syntax:
 - MOV and MNV
 <Operation>{<cond>}{S} Rd, Operand2
 - MRS{cond} Rd, cpsr
- Examples:
 - MOV r0, r1
 - MOVS r2, #10
 - MVNEQ r1, #0
 - MRS r0, cpsr



ARM Instruction Set



Branch Instructions Format



- Contains:
 - Branch
 - Branch with Link

Branch

- Syntax:

- Branch : B { <cond> } label

- Examples:

```
16 MOV r1, #5   $R_1 = 5$ 
8  MOV r0, #0   $R_0 = 0$ 
4  _loop:
   ADD r0, #2   $R_0 = R_0 + 2$ 
   SUBS r1, #1  $R_1 = R_1 - 1$ 
   BNE _loop
   end:
   B _end
```

Some instructions
...

Handwritten annotations: $r_0 = 2$, $r_1 = 4$, $z = 1$, $R_0 = R_0 + 2$, $R_1 = R_1 - 1$. Red circles highlight _loop:, end:, and B _end.

Branch with Link

- Syntax:
 - Branch with Link : `BL {<cond>} label`
- Operation:
 - BL writes the the address of the instruction following the BL into the link register (R14).
- Use:
 - It saves the address of the next instruction before branching to a sub-routine.
 - To return form the sub routine use `MOV pc, lr`

🔥 Branch with Link - Example

MOV r0, #5 $R_0 = 5$

MOV r1, #0 $R_1 = 0$

BL _accumulator

LR = add

$R_2 = R_1$

A - MOV r2, r1

→ B _end

→ _accumulator:

ADD r1, r1, r0

$R_1 = R_1 + R_0$ / $R_1 = 5 + 4 + 3 + 2 + 1$

$R_0 = 4$

→ SUBS r0, r0, #1 $R_0 = 0$

BNE _accumulator

→ MOV PC, LR = A

_end:

→ B _end

References

- ARM7TDMI processor is an implementation of ARMv4T architecture.
- References:
 - ARM Architecture Reference Manual
 - ARM7TDMI Technical Reference Manual

Summary

- Introduction to ARM architecture.
- Conditional flags and conditional execution.
- Data processing instructions .
- Branch instructions.
- Difference between architecture and implementation.