COMSM1302 Overview of Computer Architecture

Lecture 15

Performance Considerations in Assembly Programming



In the previous lecture

- Load and store instructions
 - Single register data transfer (LDR / STR).
 - Block data transfer (LDM/STM).
- Pre- and post- addressing modes
- Direct and sequential access of array elements
- Copy data blocks with Block data transfer instructions
- Stack



In this lecture

Example of using stack

Program performance measures

Performance considerations in ARM assembly programming

- At the end of this lecture:
 - Understand how the stack help us in tracking function calls.
 - Learn about programs performance measures.
 - Learn how to write efficient assembly programs.



Assembly programming performance

Example of using stack



Program performance measures

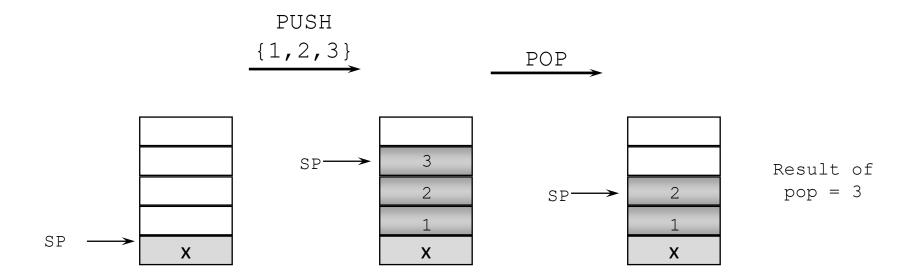


Performance considerations in ARM assembly programming







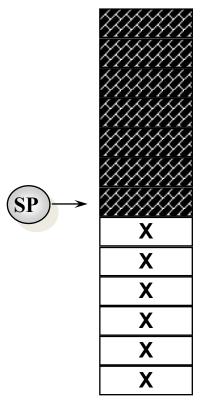


Stacks in ARM

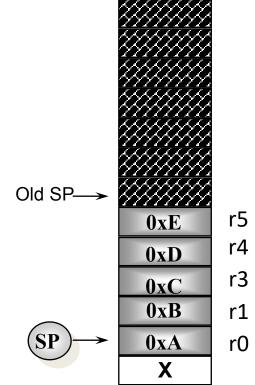
- The stack type to be used is given by the postfix to the instruction:
 - STMFD / LDMFD : Full Descending stack
 - STMFA / LDMFA : Full Ascending stack.
 - STMED / LDMED : Empty Descending stack
 - STMEA / LDMEA : Empty Ascending stack



Full Descending stack − 1/3



Register	Value	
r0	0xA	
r1	0xB	
r3	0xC	
r4	0xD	
r5	0xE	C
STMFD s		

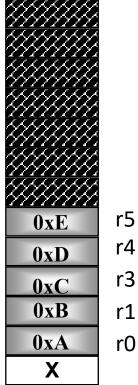


Full Descending stack – 2/3

Register	Value
r0	0xA
r1	0xB
r3	0xC
r4	0xD
r5	0xE

Some assembly code

Register	Value
r0	0x1
r1	0x2
r3	0x3
r4	0x4
r5	0x5



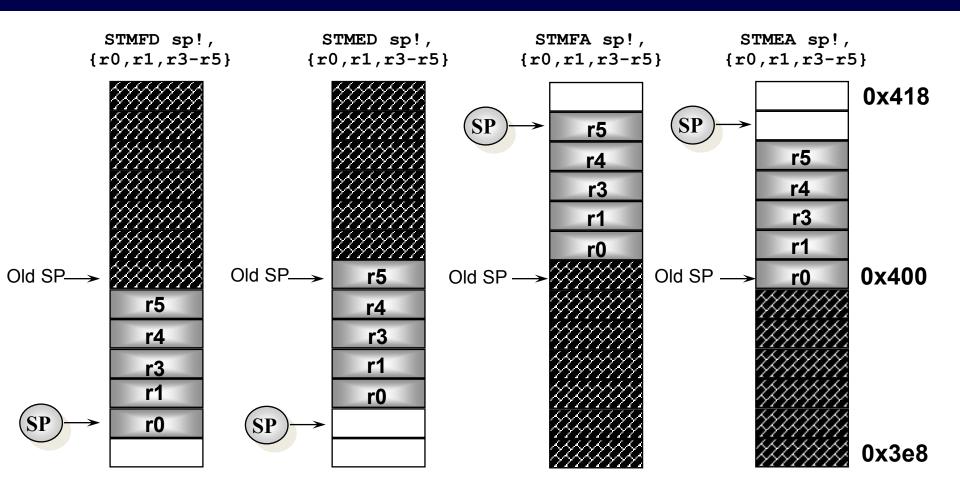




Register r0	Value 0x1						
r1	0x2						
r3	0x3			LDMFD sp!,			
r4	0x4			{r0,r1,r3-r5} →		(CP)	
r5	0x5	0xE	r5			(SP)	0xE
			r4		Register	Value	0xD
		UAC	r3		r0	0xA	0xC
	(CD)		r1		r1	0xB	0xB
	$(SP) \longrightarrow$	0xA X	r0		r3	0xC	0xA X
					r4	0xD	
					r5	OxE	



ARM Stack Implementations



Example : factorial

 Factorial of a non-negative integer, is multiplication of all integers smaller than or equal to n. For example factorial of 4 is 4*3*2*1 which is 24.

•
$$n! = n*(n-1)*(n-2)*(n-3)*...*1$$

•
$$4! = 4*(4-1)*(4-2)*(4-3) = 24$$



Factorial – recursive solution

- n! = n*(n-1)*(n-2)*(n-3)*...*1
- (n-1)! = (n-1)*((n-1)-1)*((n-1)-2)*...*1
- (n-1)! = (n-1)*(n-2)*(n-3)*...*1
- n! = n * (n-1)!
- n! = 1 if n = 0 or n = 1



Factorial – recursive solution – C code

```
// function to find factorial of given number
unsigned int factorial (unsigned int n)
  if (n == 0)
    return 1;
  return n * factorial(n - 1);
```

Factorial – recursive solution – assembly code – 1/6

Factorial – recursive solution – assembly code – 2/6

```
Ldr r0, =#3
bl factorial
b end
 factorial:
       cmp r0, #0
                            if (n == 0)
       moveq r0, #1
                               return 1;
       moveq pc , lr
       mov r1, r0
                         Save n and calculate n-1 then call factorial for n-1
       sub r0, r0, #1
       stmfd sp!, {r1,lr}
       bl factorial
```



Factorial − recursive solution − assembly code − 3/6

```
Ldr r0, =#3
bl factorial
                    <-0x2
b end
 factorial:
      cmp r0, #0
      moveq r0, #1
      moveq pc , lr
      mov r1, r0
      sub r0, r0, #1
      stmfd sp!, {r1,lr}
      bl factorial
                       <- 0xA
```

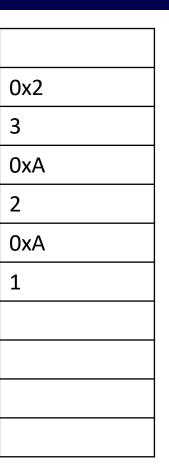
Factorial − recursive solution − assembly code − 4/6

```
Ldr r0, =#3
bl factorial
                    <-0x2
b end
 factorial:
      cmp r0, #0
      moveq r0, #1
      moveq pc , lr
      mov r1, r0
      sub r0, r0, #1
      stmfd sp!, {r1,lr}
      bl factorial
                       <- 0xA
```

0x2	
3	
0xA	
2	

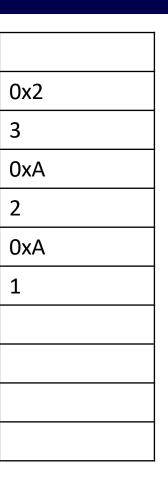
Factorial – recursive solution – assembly code – 5/6

```
Ldr r0, =#3
bl factorial
                    <- 0x2
b end
 factorial:
      cmp r0, #0
      moveq r0, #1
      moveq pc , lr
      mov r1, r0
       sub r0, r0, #1
       stmfd sp!, {r1,lr}
      bl factorial
                       <- OxA
```



Factorial – recursive solution – assembly code – 6/6

```
Ldr r0, =#3
bl factorial
b end
                        <- 0x2
 factorial:
      cmp r0, #0
      moveq r0, #1
      moveq pc , lr
      mov r1, r0
       sub r0, r0, #1
       stmfd sp!, {r1,lr}
      bl factorial
       lmdfd sp!, \{r1, lr\} < -0xA
      mul r0, r1, r0
      mov pc, lr
```



Assembly programming performance

Example of using stack



Program performance measures



Performance considerations in ARM assembly programming



Program performance measures

- Program Execution Time
 - Worst-case execution time (WCET):
 - Best-case execution time (BCET)
 - Average-case execution time (ACET)
- Program Size: number of instructions in ARM
- Program Energy Consumption



Assembly programming performance

Example of using stack



Program performance measures



Performance considerations in ARM assembly programming



ARM assembly programming performance issues

- LDM /STM
- Conditional execution
- Using the barrel shifter
- Optimising register usage
- Loop unrolling
- Initiate a register with zero
- Addressing modes
- Multiplication / Division



LDM / STM

- Use LDM and STM instead of a sequence of LDR or STR instructions wherever possible.
 - The code is smaller.
 - An instruction fetch cycle can be saved for each eliminated LDR or STR.
 - Can turn non-sequential memory cycles into faster memory sequential cycles.



LDM / STDM - example

```
MOV r1,#4
MOV r3,#0
LDR r0_{,} = data
loop:
LDR r2, [r0], #4
ADD r3, r3, r2
SUBS r1, r1, #1
BNQ loop
STR r3, [r0]
end: B end
```

```
MOV r3,#0

LDR r0,=_data

LDMIA r0!, {r3-r6}

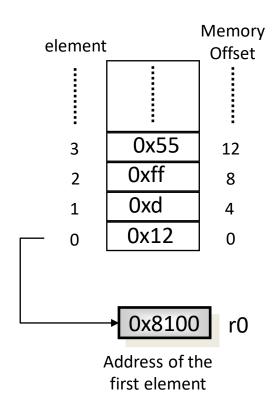
ADD r3, r3, r4

ADD r3, r3, r5

ADD r3, r3, r6

STR r3, [r0]

_end: B _end
```



Conditional execution

- Using conditionally executed instructions can avoid branches around short pieces of code.
 - This reduces the size of code



Using the barrel shifter

 Combining shift operations with other operations can significantly increase the code density and thus performance.

```
TST r0,#1
LSLEQ r0,r0,#1
MOVEQ r1,r0
_end: B _end
```

```
TST r0,#1

MOVEQ r1,r0,LSL #1

_end: B _end
```

Conditional execution and barrel shifter example

```
TST r0,#1

BLEQ _even:
_end: B _end

_even:
LSL r0,r0,#1

MOV r1,r0

MOV pc, lr
```

```
TST r0,#1
LSLEQ r0,r0,#1
MOVEQ r1,r0
_end: B _end
```

```
TST r0,#1
MOVEQ r1,r0,LSL#1
_end: B _end
```

Optimising register usage

- Register spillage happens when we have more variables than the number of available registers.
 - a value has to be reloaded.
 - an intermediate value saved and then reloaded.



Loop unrolling

- Loop unrolling involves using more than one copy of the inner loop of an algorithm
 - The branch back to the beginning of the loop is executed less frequently.
 - it may be possible to combine some of one iteration with some of the next iteration, and thereby significantly reduce the cost of each iteration.

Loop unrolling - example

```
MOV r1,#4
MOV r3,#0
LDR r0_{,} = data
loop:
LDR r2, [r0], #4
ADD r3, r3, r2
SUBS r1, r1, #1
BNQ loop
STR r3, [r0]
end: B end
```

```
MOV r3,#0

LDR r0,=_data

LDMIA r0!, {r3-r6}

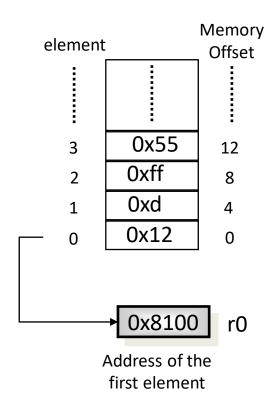
ADD r3, r3, r4

ADD r3, r3, r5

ADD r3, r3, r6

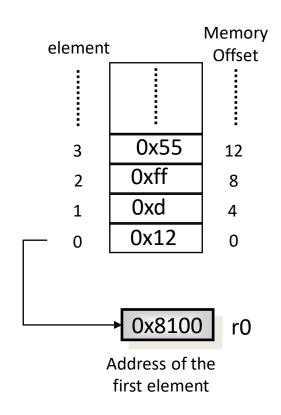
STR r3, [r0]

_end: B _end
```



Initiate a register with zero

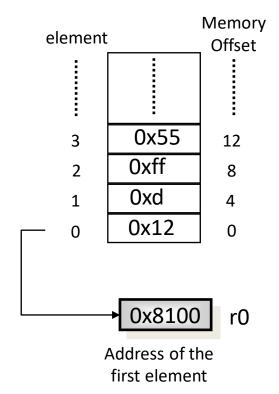
What registers to reset and how?



Initiate a register with zero

What registers to reset and how?

```
instruction size是一樣的
          execution time 是一樣的
MOV r3,#0 power consumption E O R 較高R r3,r3,r3
LDR r0, = data
                        LDR r0_{,} = data
                        LDMIA r0!, {r3-r6}
LDMIA r0!, {r3-r6}
                        ADD r3, r3, r4
ADD r3, r3, r4
ADD r3, r3, r5
                        ADD r3, r3, r5
                        ADD r3, r3, r6
ADD r3, r3, r6
                        STR r3, [r0]
STR r3, [r0]
                        end: B end
end: B end
```



Other performance issues

Addressing modes

 Using LDR or STR pre- or post-indexed with a nonzero offset increments the base register and performs the data transfer

Multiplication / Division

可以用shift做比較好

 Be aware of the time taken by the ARM multiply and division instructions



Summary

- Stack operation
- Recursive solution to compute the factorial of a given number.
- Programs performance measures
- How to write efficient assembly programs.

