

COMSM1302

Overview of Computer Architecture

Lecture 15

Performance Considerations in Assembly Programming



In the previous lecture



- Load and store instructions
 - Single register data transfer (LDR / STR).
 - Block data transfer (LDM/STM).
- Pre- and post- addressing modes
- Direct and sequential access of array elements
- Copy data blocks with Block data transfer instructions
- Stack



In this lecture



Example of
using stack



Program
performance
measures



Performance
considerations in ARM
assembly
programming

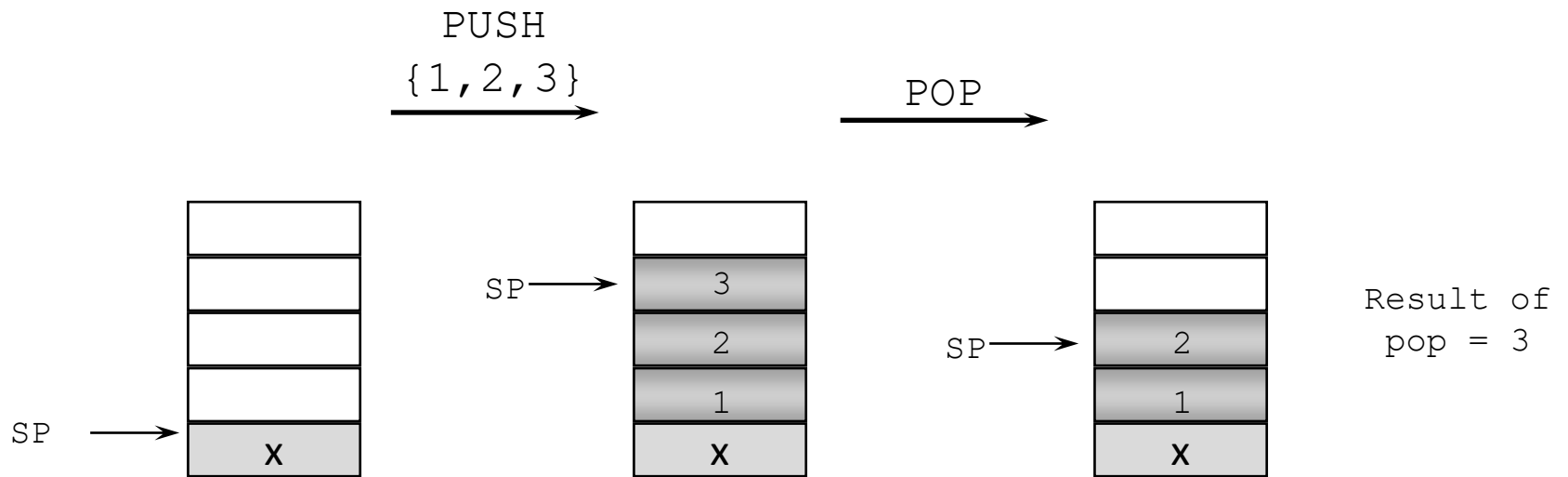
- At the end of this lecture:
 - Understand how the stack help us in tracking function calls.
 - Learn about programs performance measures.
 - Learn how to write efficient assembly programs.



Assembly programming performance



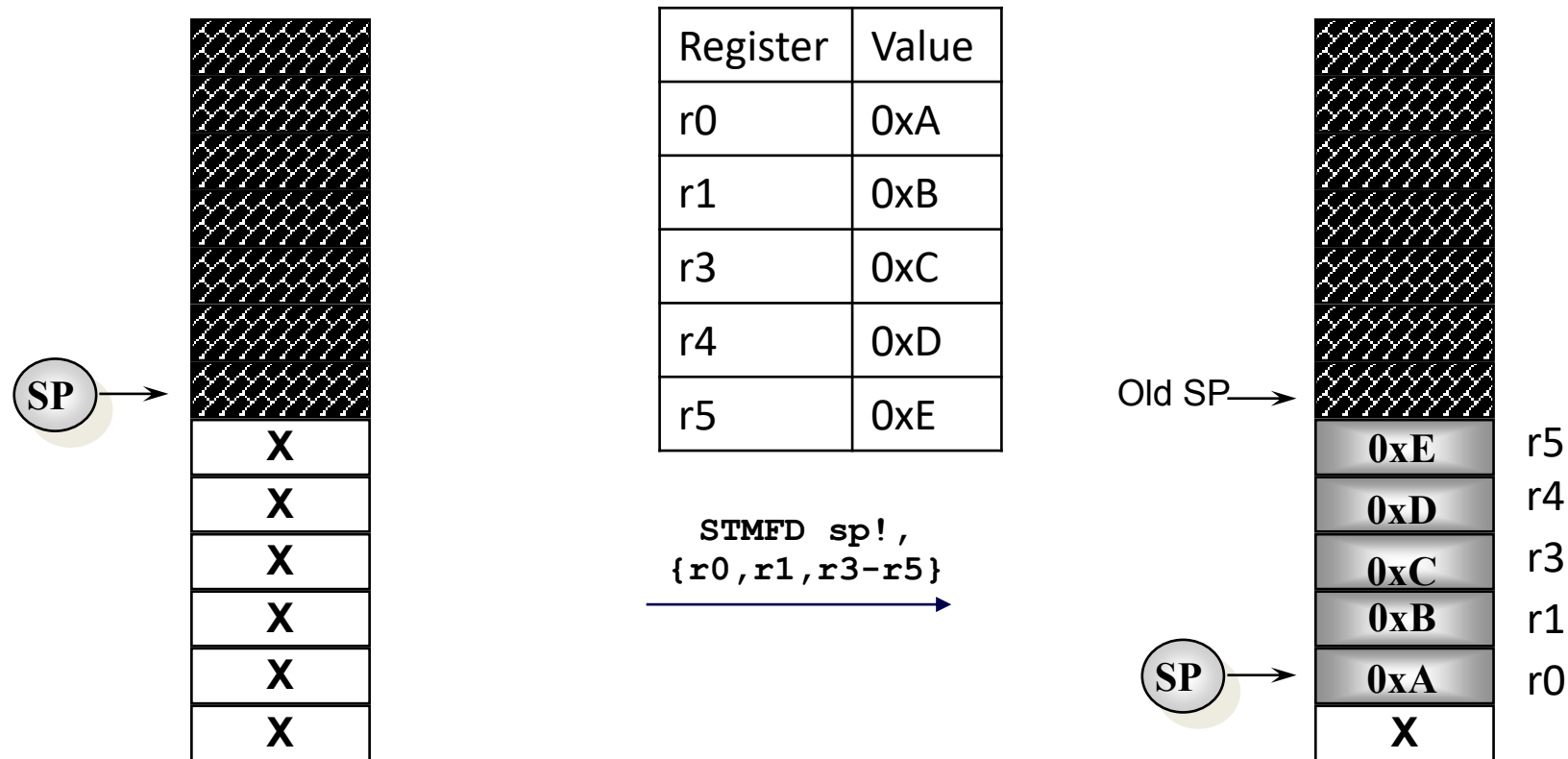
Stack



Stacks in ARM

- The stack type to be used is given by the postfix to the instruction:
 - STMFD / LDMFD : Full Descending stack
 - STMFA / LDMFA : Full Ascending stack.
 - STMED / LDMED : Empty Descending stack
 - STMEA / LDMEA : Empty Ascending stack

🔥 Full Descending stack – 1/3



🔥 Full Descending stack – 2/3

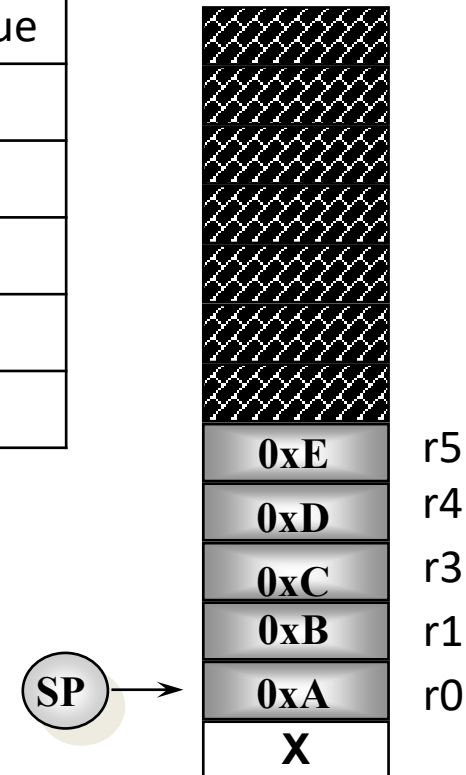


Register	Value
r0	0xA
r1	0xB
r3	0xC
r4	0xD
r5	0xE

Some assembly
code



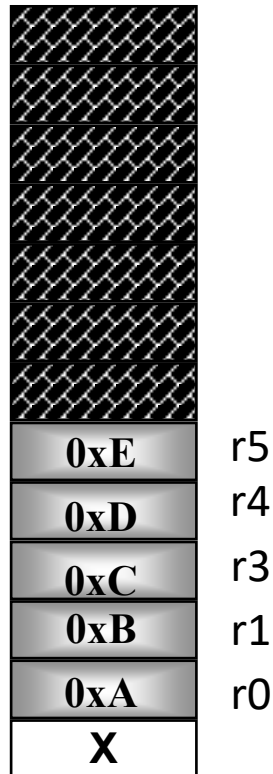
Register	Value
r0	0x1
r1	0x2
r3	0x3
r4	0x4
r5	0x5



🔥 Full Descending stack – 3/3

Register	Value
r0	0x1
r1	0x2
r3	0x3
r4	0x4
r5	0x5

SP →

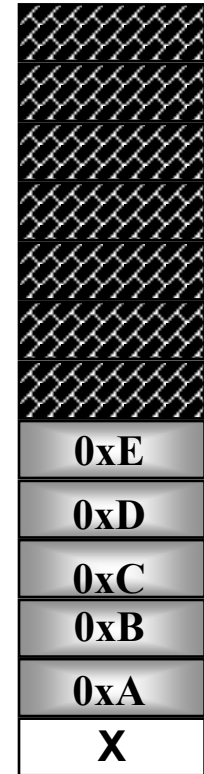


LDMFD sp!,
{r0,r1,r3-r5}



Register	Value
r0	0xA
r1	0xB
r3	0xC
r4	0xD
r5	0xE

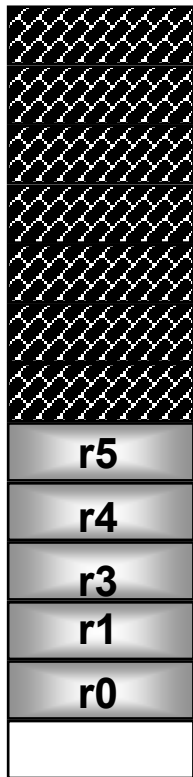
SP →



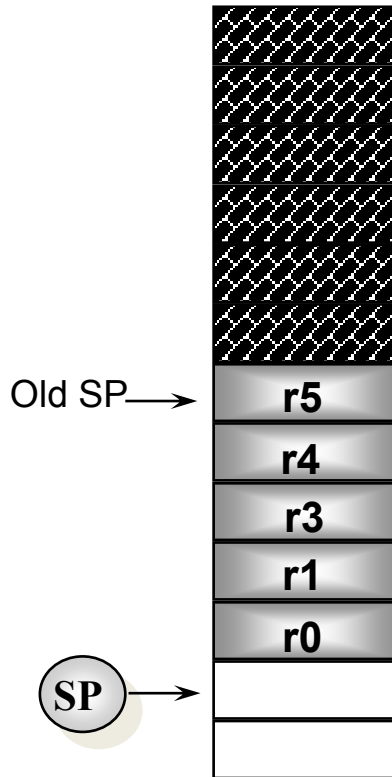
ARM Stack Implementations



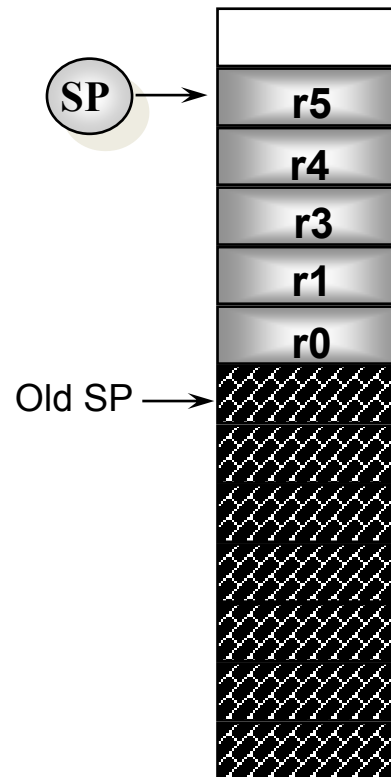
STMFD sp!,
{r0,r1,r3-r5}



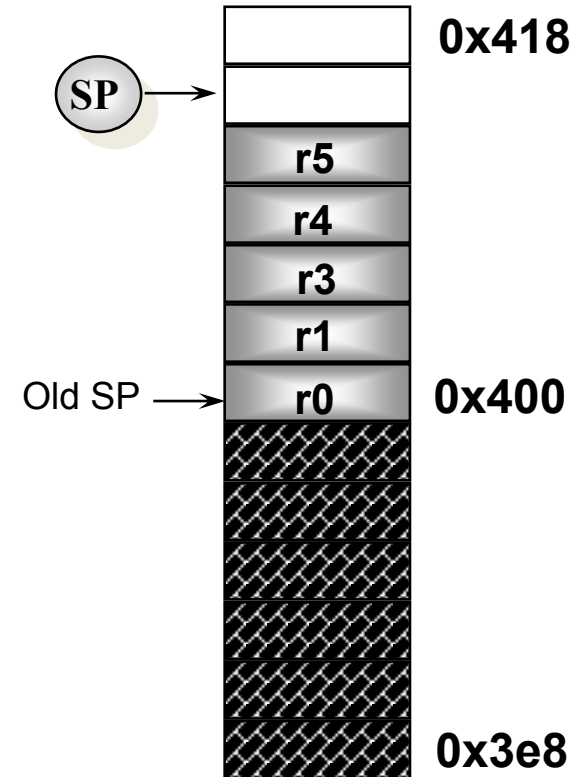
STMED sp!,
{r0,r1,r3-r5}



STMFA sp!,
{r0,r1,r3-r5}



STMEA sp!,
{r0,r1,r3-r5}



Example : factorial

- Factorial of a non-negative integer, is multiplication of all integers smaller than or equal to n . For example factorial of 4 is $4*3*2*1$ which is 24.

- $$n! = n*(n-1)*(n-2)*(n-3)*...*1$$

- $$4! = 4*(4-1)*(4-2)*(4-3) = 24$$

$$4 \times 3 \times 2 \times 1 = 24$$

~~$(4-4)=0$~~

🔥 Factorial – recursive solution

- $n! = n * (n-1) * (n-2) * (n-3) * \dots * 1$
 - $(n-1)! = (n-1) * ((n-1)-1) * ((n-1)-2) * \dots * 1$
 - $(n-1)! = (n-1) * (n-2) * (n-3) * \dots * 1$
- $n! = n * (n-1)!$
- $n! = 1$ if $n = 0$ or $n = 1$

🔥 Factorial – recursive solution – C code

```
// function to find factorial of given number  
unsigned int factorial(unsigned int n)
```

```
{
```

```
    if (n == 0)
```

```
        return 1;
```

```
    return n * factorial(n - 1);
```

```
}
```

$n=0 \Rightarrow n! = 1$

$n=1 \Rightarrow 1 \times f(1-1) = 1 \times f(0) = 1$
 $n! = 1$

🔥 Factorial – recursive solution – assembly code – 1/6

```
Ldr r0, =#3 0x0  
→ bl _factorial 0x1 ⇒ lr = 0x2  
b _end ← 0x2  
_factorial:  
    cmp r0, #0  
    moveq r0, #1    if (n == 0) V0 = 1  
    moveq pc, lr    0x2    return 1;
```

-end: B _end

🔥 Factorial – recursive solution – assembly code – 2/6

```
Ldr r0, =#3
bl _factorial
b _end
```

$n \cdot f(n-1)$

n
 $n-1$
 $n-2$

_factorial:

```
cmp r0, #0
moveq r0, #1
moveq pc, lr
```

if (n == 0)
return 1;

(n)

✗

$r_1 = 3$

$r_0 = 2$

↗

$n-1$

```
← mov r1, r0 ←
sub r0, r0, #1
stmfd sp!, {r1, lr}
bl _factorial
```

Save n and calculate n-1 then call factorial for n-1

$r_0 = n-2$
 $n-3$

🔥 Factorial – recursive solution – assembly code – 3/6

```
Ldr r0, =#3  
bl _factorial  
b _end
```

Handwritten: $lr = 0x2$
 $\leftarrow 0x2$

```
_factorial:  
    cmp r0, #0  
    moveq r0, #1  
    moveq pc, lr  
    mov r1, r0  
    sub r0, r0, #1  
    stmfd sp!, {r1, lr}  
    bl _factorial  
     $\leftarrow 0xA$ 
```

Handwritten: $3 \rightarrow 0x2$

0x2
3

Handwritten: $\leftarrow SP$

🔥 Factorial – recursive solution – assembly code – 4/6

```
Ldr r0, =#3
bl _factorial
b _end                <- 0x2
```

```
_factorial: 2
    cmp r0, #0
    moveq r0, #1
    moveq pc, lr
    mov r1, r0
    sub r0, r0, #1
    stmfd sp!, {r1, lr}
    bl _factorial
    1 <- 0xA
```

Handwritten annotations:
- $V_1 = 2$ (points to the first argument on the stack)
- $V_0 = 1$ (points to the second argument on the stack)
- $LR = 0xA$ (points to the return address on the stack)

0x2
3
0xA
2

← SP

← SP

🔥 Factorial – recursive solution – assembly code – 5/6

```
Ldr r0, =#3
bl _factorial
b _end                <- 0x2
```

```
_factorial:
    cmp r0, #0
    moveq r0, #1
    moveq pc, lr
    mov r1, r0
    sub r0, r0, #1
    stmfd sp!, {r1, lr}
    bl _factorial
    <- 0xA
```

Handwritten notes:

- $r_1 = 1$ (with an arrow pointing to the `mov r1, r0` instruction)
- $r_0 = 0$ (with an arrow pointing to the `sub r0, r0, #1` instruction)
- $lr = 0xA$ (with an arrow pointing to the `stmfd sp!, {r1, lr}` instruction)

0x2
3
0xA
2
0xA
1

← SP

← SP

🔥 Factorial – recursive solution – assembly code – 6/6

```
Ldr r0, =#3
bl _factorial
b _end
```

3! = 6

<- 0x2

_factorial:

```
cmp r0, #0
```

```
moveq r0, #1
```

```
moveq pc, lr
```

```
mov r1, r0
```

```
sub r0, r0, #1
```

```
stmfd sp!, {r1, lr}
```

```
bl _factorial
```

```
lmdfd sp!, {r1, lr}
```

```
mul r0, r1, r0
```

```
mov pc, lr
```

$r_0 = 0$

$r_0 = 1$

$lr = 0xA$

$n = 3$

$lr = 0x2$

$r_0 = 2$

$2 \times 3 = 6$

$r_0 = 6$

0x2
3
0xA
2
0xA
1

← SP

← SP

← SP



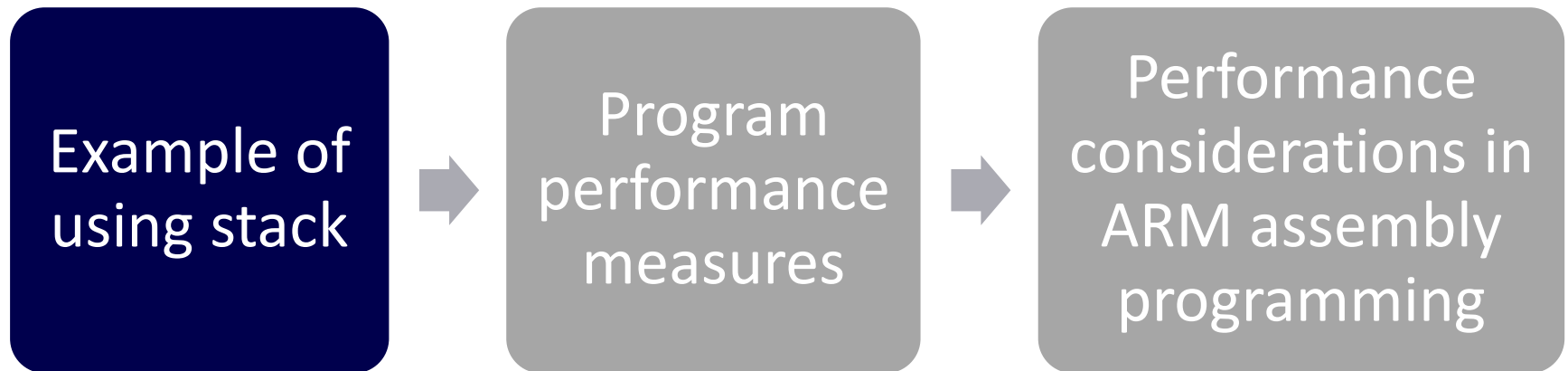
Assembly programming performance



Program performance measures

- Program Execution Time
 - Worst-case execution time (WCET):
 - Best-case execution time (BCET)
 - Average-case execution time (ACET)
- Program Size: number of instructions in ARM
- Program Energy Consumption

Assembly programming performance



ARM assembly programming performance issues



- LDM /STM
- Conditional execution
- Using the barrel shifter
- Optimising register usage
- Loop unrolling
- Initiate a register with zero
- Addressing modes
- Multiplication / Division

LDM / STM

- Use LDM and STM instead of a sequence of LDR or STR instructions wherever possible.
 - The code is smaller.
 - An instruction fetch cycle can be saved for each eliminated LDR or STR.
 - Can turn non-sequential memory cycles into faster memory sequential cycles.

🔥 LDM / STDM - example

9 inst

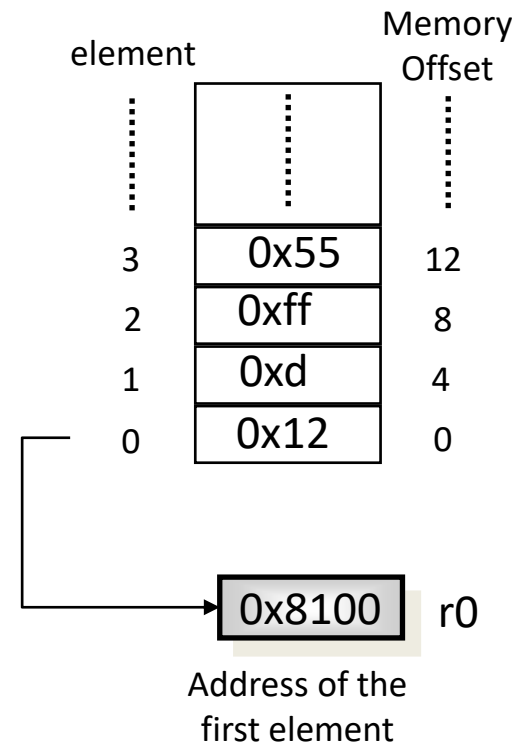
```
MOV r1, #4
MOV r3, #0
LDR r0, =_data
_loop:
LDR r2, [r0], #4
ADD r3, r3, r2
SUBS r1, r1, #1
BNE _loop
STR r3, [r0]
_end: B _end
```

Handwritten annotations: A red bracket groups the first three instructions with a '3' next to it. A red bracket groups the next four instructions with '4x4 = 16' next to it. A red bracket groups the last two instructions with a '2' next to it.

8 inst.

```
MOV r3, #0
LDR r0, =_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```

Handwritten annotations: A red '8 if' is written below the last instruction.



$$if = 3 + 16 + 2 = 21$$

$$r_3 = r_3 + r_4 + r_5 + r_6$$



Conditional execution

- Using conditionally executed instructions can avoid branches around short pieces of code.
 - This reduces the size of code

```
TST r0, #1
BLEQ _even:
_end: B _end

_even:
LSL r0, r0, #1
MOV r1, r0
MOV pc, lr
```

0000
0011
0102
0113
1004
1015
1106
1117
1008

```
TST r0, #1
LSLEQ r0, r0, #1
MOVEQ r1, r0
_end: B _end
```

101
001

001

100
001

000

🔥 Using the barrel shifter

- Combining shift operations with other operations can significantly increase the code density and thus performance.

```
TST r0, #1
LSLEQ r0, r0, #1
MOVEQ r1, r0
_end: B _end
```

→

```
TST r0, #1
MOVEQ r1, r0, LSL, #1
_end: B _end
```

$r_1 = r_0 \times 2$

Conditional execution and barrel shifter example

```
TST r0,#1
BLEQ _even:
_end: B _end
```

```
_even:
LSL r0,r0,#1
MOV r1,r0
MOV pc, lr
```

```
TST r0,#1
LSLEQ r0,r0,#1
MOVEQ r1,r0
_end: B _end
```

```
TST r0,#1
MOVEQ r1,r0,LSL #1
_end: B _end
```

Optimising register usage

- Register spillage happens when we have more variables than the number of available registers.
 - a value has to be reloaded.
 - an intermediate value saved and then reloaded.

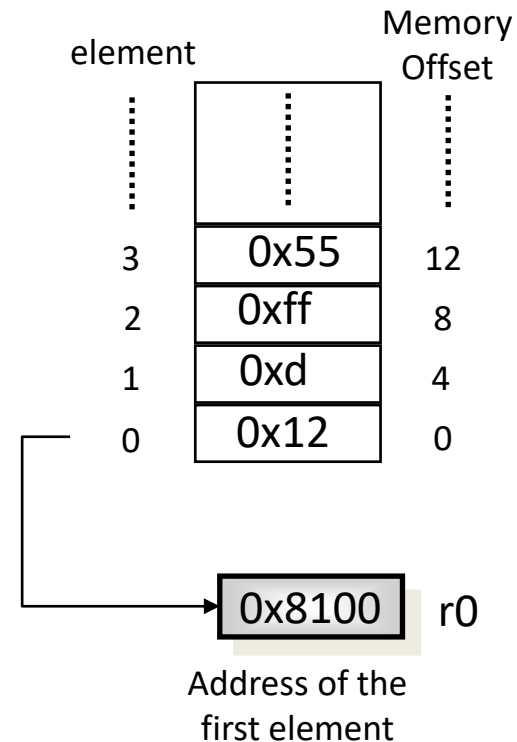
Loop unrolling

- Loop unrolling involves using more than one copy of the inner loop of an algorithm
 - The branch back to the beginning of the loop is executed less frequently.
 - it may be possible to combine some of one iteration with some of the next iteration, and thereby significantly reduce the cost of each iteration.

🔥 Loop unrolling - example

```
MOV r1, #4
MOV r3, #0
LDR r0, =_data
_loop:
LDR r2, [r0], #4
ADD r3, r3, r2
SUBS r1, r1, #1
BNE _loop
STR r3, [r0]
_end: B _end
```

```
MOV r3, #0
LDR r0, =_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```

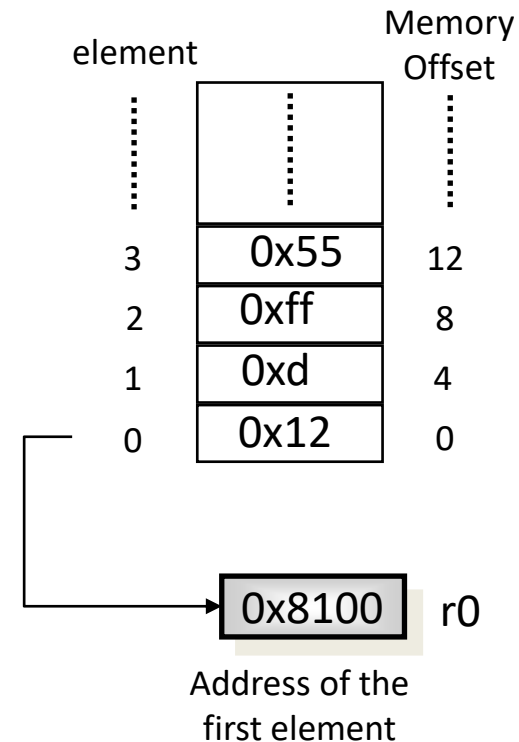


🔥 Initiate a register with zero

- What registers to reset and how?

```
MOV r3, #0
LDR r0,=_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```

```
EOR r3, r3, r3
LDR r0,=_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```

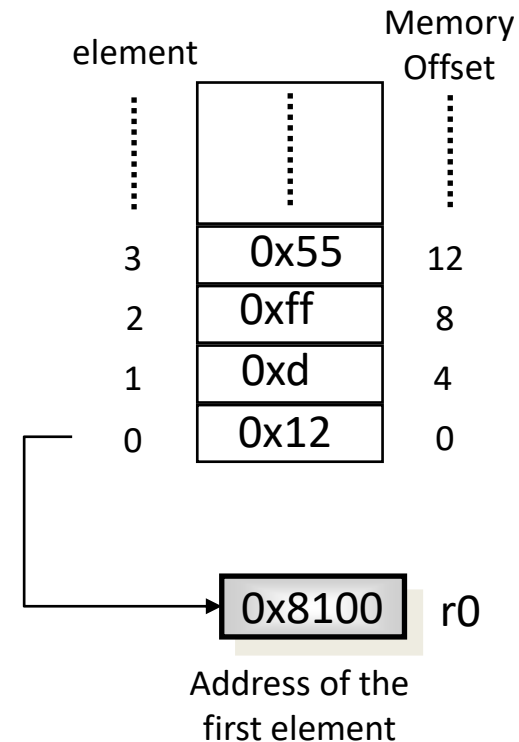


🔥 Initiate a register with zero

- What registers to reset and how?

```
MOV r3, #0
LDR r0,=_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```

```
EOR r3, r3, r3
LDR r0,=_data
LDMIA r0!, {r3-r6}
ADD r3, r3, r4
ADD r3, r3, r5
ADD r3, r3, r6
STR r3, [r0]
_end: B _end
```



Other performance issues

- **Addressing modes**

- Using LDR or STR pre- or post-indexed with a non-zero offset increments the base register and performs the data transfer

- **Multiplication / Division**

- Be aware of the time taken by the ARM multiply and division instructions

Summary

- Stack operation
- Recursive solution to compute the factorial of a given number.
- Programs performance measures
- How to write efficient assembly programs.