

Lecture 31: Integrals and Vector Fields.

MA2032 Vector Calculus

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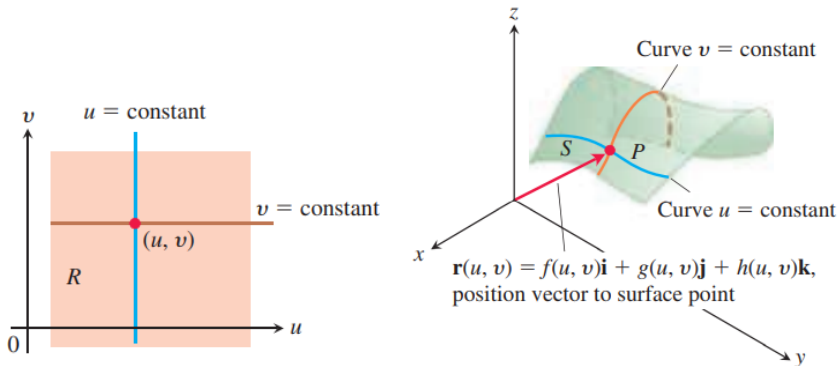
Surfaces and Area

We have **defined curves** in the plane (space) in **three different ways**:

1. **Explicit** form: $y = f(x)$ ($z = f(x, y)$).
 2. **Implicit** form: $F(x, y) = 0$ ($F(x, y, z) = 0$).
 3. **Parametric vector** form: $\mathbf{r}(t) = f(t) \mathbf{i} + g(t) \mathbf{j}$
($\mathbf{r}(t) = f(t) \mathbf{i} + g(t) \mathbf{j} + h(t) \mathbf{k}$), $a \leq t \leq b$.
- There is also a **parametric form for surfaces** that gives the position of a point on the surface as a **vector function of two variables**.
 - We apply the form to obtain the **area of a surface** as a double integral.

Parametrizations of Surfaces

- Suppose $\mathbf{r}(u, v) = f(u, v) \mathbf{i} + g(u, v) \mathbf{j} + h(u, v) \mathbf{k}$ (Eq. 1) is a **continuous vector function** that is defined on a region R in the uv -plane and **one-to-one** on the interior of R .



- The range of \mathbf{r} is the **surface** S defined or traced by \mathbf{r} .

Parametrizations of Surfaces

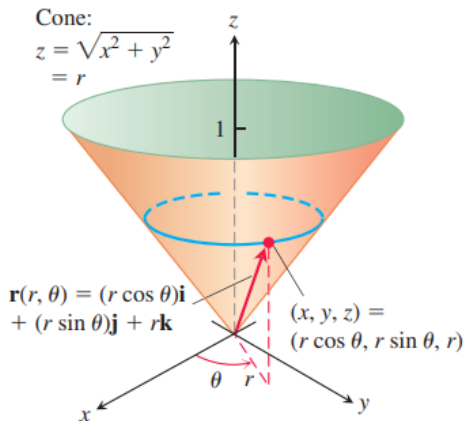
- (Eq. 1) together with the domain R constitutes a **parametrization of the surface**.
- The variables u and v are the **parameters**, and R is the **parameter domain**.
- R is rectangle defined by $a \leq u \leq b$, $c \leq v \leq d$.
- The requirement that \mathbf{r} be **one-to-one** on the interior of R ensures that S **does not cross itself**.
- (Eq. 1) is the vector equivalent of **three parametric equations**:

$$x = f(u, v), \quad y = g(u, v), \quad z = h(u, v).$$

Parametrizations of Surfaces

EXAMPLE 1 Find a parametrization of the cone

$$z = \sqrt{x^2 + y^2}, \quad 0 \leq z \leq 1.$$



Solution Example 1

Solution Here, cylindrical coordinates provide a parametrization. A typical point (x, y, z) on the cone (Figure 16.40) has $x = r \cos \theta$, $y = r \sin \theta$, and $z = \sqrt{x^2 + y^2} = r$, with $0 \leq r \leq 1$ and $0 \leq \theta \leq 2\pi$. Taking $u = r$ and $v = \theta$ in Equation (1) gives the parametrization

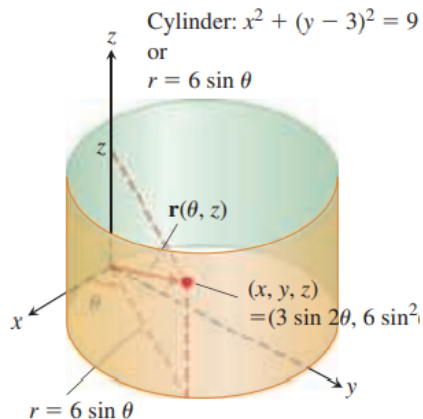
$$\mathbf{r}(r, \theta) = (r \cos \theta)\mathbf{i} + (r \sin \theta)\mathbf{j} + r\mathbf{k}, \quad 0 \leq r \leq 1, \quad 0 \leq \theta \leq 2\pi.$$

The parametrization is one-to-one on the interior of the domain R , though not on the boundary tip of its cone where $r = 0$. ■

Parametrizations of Surfaces

EXAMPLE 3 Find a parametrization of the cylinder

$$x^2 + (y - 3)^2 = 9, \quad 0 \leq z \leq 5.$$



Solution Example 3

Solution In cylindrical coordinates, a point (x, y, z) has $x = r \cos \theta$, $y = r \sin \theta$, and $z = z$. For points on the cylinder $x^2 + (y - 3)^2 = 9$ (Figure 16.42), the equation is the same as the polar equation for the cylinder's base in the xy -plane:

$$x^2 + (y^2 - 6y + 9) = 9$$

$$r^2 - 6r \sin \theta = 0 \quad x^2 + y^2 = r^2, y = r \sin \theta$$

or

$$r = 6 \sin \theta, \quad 0 \leq \theta \leq \pi.$$

A typical point on the cylinder therefore has

$$x = r \cos \theta = 6 \sin \theta \cos \theta = 3 \sin 2\theta$$

$$y = r \sin \theta = 6 \sin^2 \theta$$

$$z = z.$$

Taking $u = \theta$ and $v = z$ in Equation (1) gives the one-to-one parametrization

$$\mathbf{r}(\theta, z) = (3 \sin 2\theta)\mathbf{i} + (6 \sin^2 \theta)\mathbf{j} + z\mathbf{k}, \quad 0 \leq \theta \leq \pi, \quad 0 \leq z \leq 5. \quad \blacksquare$$

Surface Area

- Our goal is to find a double integral for calculating the **area of a curved surface** S based on the parametrization

$$\mathbf{r}(u, v) = f(u, v) \mathbf{i} + g(u, v) \mathbf{j} + h(u, v) \mathbf{k}, \quad a \leq u \leq b, \quad c \leq v \leq d$$

- We need S **to be smooth** for the construction we are about to carry out.
- The definition of smoothness involves the **partial derivatives** of \mathbf{r} with respect to u and v :

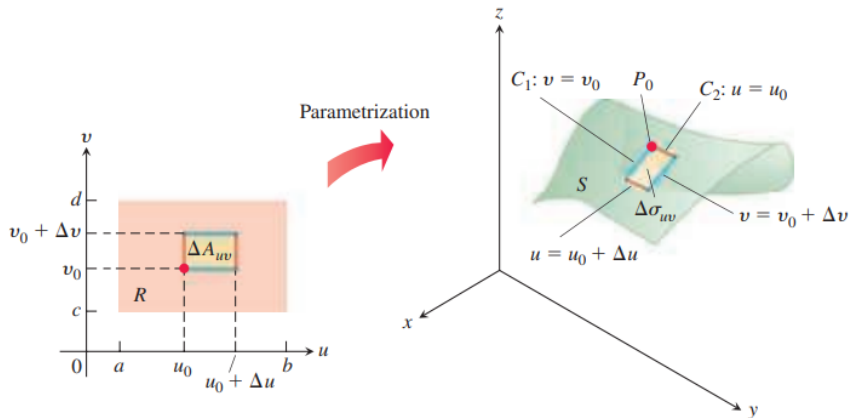
$$\mathbf{r}_u = \frac{\partial \mathbf{r}}{\partial u} = \frac{\partial f}{\partial u} \mathbf{i} + \frac{\partial g}{\partial u} \mathbf{j} + \frac{\partial h}{\partial u} \mathbf{k}$$

$$\mathbf{r}_v = \frac{\partial \mathbf{r}}{\partial v} = \frac{\partial f}{\partial v} \mathbf{i} + \frac{\partial g}{\partial v} \mathbf{j} + \frac{\partial h}{\partial v} \mathbf{k}.$$

DEFINITION A parametrized surface $\mathbf{r}(u, v) = f(u, v)\mathbf{i} + g(u, v)\mathbf{j} + h(u, v)\mathbf{k}$ is **smooth** if \mathbf{r}_u and \mathbf{r}_v are continuous and $\mathbf{r}_u \times \mathbf{r}_v$ is never zero on the interior of the parameter domain.

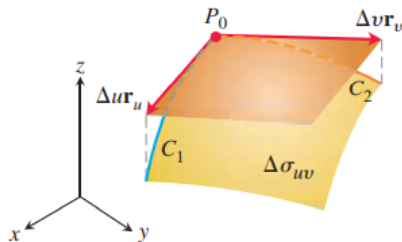
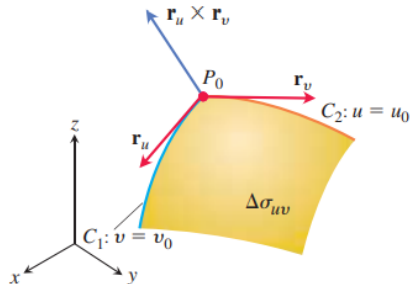
Surface Area

- The **condition** that $\mathbf{r}_u \times \mathbf{r}_v$ is **never the zero vector** in the definition of smoothness means that the two vectors \mathbf{r}_u and \mathbf{r}_v are nonzero and never lie along the same line, so they **always determine a plane tangent to the surface**.



Surface Area

- Consider a small **rectangle** ΔA_{uv} in R
- Each side of ΔA_{uv} maps to a curve on the surface S , and together these four curves bound a "**curved patch element**" $\Delta\sigma_{uv}$.
- The **partial derivative vector** $\mathbf{r}_u(u_0, v_0)$ is **tangent** to C_1 at P_0 . Likewise, $\mathbf{r}_v(u_0, v_0)$ is tangent to C_2 at P_0 .
- The **cross product** $\mathbf{r}_u \times \mathbf{r}_v$ is **normal** to the surface at P_0 .



Surface Area

- We next **approximate** the surface patch element $\Delta\sigma_{uv}$ **by the parallelogram** on the tangent plane whose area is

$$|\Delta u \mathbf{r}_u \times \Delta v \mathbf{r}_v| = |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v.$$

- A **partition** of the surface S into surface patch elements **approximates** the area of S by the sum

$$\sum_n |\mathbf{r}_u \times \mathbf{r}_v| \Delta u \Delta v.$$

Surface Area

- This sum **in limit** sense ($\Delta u \rightarrow 0$, $\Delta v \rightarrow 0$, $n \rightarrow \infty$) approaches the double integral

DEFINITION The **area** of the smooth surface

$$\mathbf{r}(u, v) = f(u, v)\mathbf{i} + g(u, v)\mathbf{j} + h(u, v)\mathbf{k}, \quad a \leq u \leq b, \quad c \leq v \leq d$$

is

$$A = \iint_R |\mathbf{r}_u \times \mathbf{r}_v| dA = \int_c^d \int_a^b |\mathbf{r}_u \times \mathbf{r}_v| du dv. \quad (4)$$

Surface Area

EXAMPLE 4 Find the surface area of the cone in Example 1

Solution In Example 1, we found the parametrization

$$\mathbf{r}(r, \theta) = (r \cos \theta)\mathbf{i} + (r \sin \theta)\mathbf{j} + r\mathbf{k}, \quad 0 \leq r \leq 1, \quad 0 \leq \theta \leq 2\pi.$$

To apply Equation (4), we first find $\mathbf{r}_r \times \mathbf{r}_\theta$:

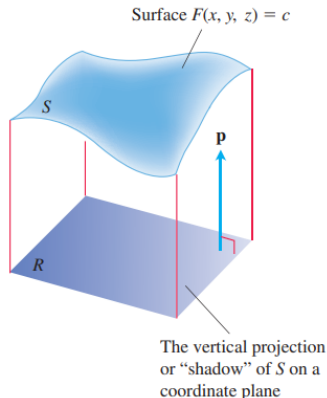
$$\begin{aligned}\mathbf{r}_r \times \mathbf{r}_\theta &= \begin{vmatrix} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ \cos \theta & \sin \theta & 1 \\ -r \sin \theta & r \cos \theta & 0 \end{vmatrix} \\ &= -(r \cos \theta)\mathbf{i} - (r \sin \theta)\mathbf{j} + \underbrace{(r \cos^2 \theta + r \sin^2 \theta)}_r \mathbf{k}.\end{aligned}$$

Thus, $|\mathbf{r}_r \times \mathbf{r}_\theta| = \sqrt{r^2 \cos^2 \theta + r^2 \sin^2 \theta + r^2} = \sqrt{2r^2} = \sqrt{2}r$. The area of the cone is

$$\begin{aligned}A &= \int_0^{2\pi} \int_0^1 |\mathbf{r}_r \times \mathbf{r}_\theta| \, dr \, d\theta \quad \text{Eq. (4) with } u = r, v = \theta \\ &= \int_0^{2\pi} \int_0^1 \sqrt{2}r \, dr \, d\theta = \int_0^{2\pi} \frac{\sqrt{2}}{2} d\theta = \frac{\sqrt{2}}{2} (2\pi) = \pi\sqrt{2} \text{ square units.} \quad \blacksquare\end{aligned}$$

Implicit Surfaces

- Surfaces are often presented as **level sets of a function**, described by an equation such as $F(x, y, z) = c$, for some constant c .
- It may be **difficult to find explicit formulas** for the functions f , g , and h that describe the surface in the form $\mathbf{r}(u, v) = f(u, v) \mathbf{i} + g(u, v) \mathbf{j} + h(u, v) \mathbf{k}$.
- We choose \mathbf{p} to be a **unit vector** (it can be \mathbf{k}) **normal** to the plane region R ($\in xy$ -plane).
- By assumption, we then have
$$\nabla F \cdot \mathbf{p} = \nabla F \cdot \mathbf{k} = F_z \neq 0 \text{ on } S.$$
- The Implicit Function Theorem implies that S is then the **graph of a differentiable function** $z = h(x, y)$.
- Defining $u = x$ and $v = y$, then $z = h(u, v)$ and $\mathbf{r}(u, v) = u \mathbf{i} + v \mathbf{j} + h(u, v) \mathbf{k}$ gives a **parametrization of the surface S** .



Implicit Surfaces

- We use previous results to **find the area** of S :

Calculating the partial derivatives of \mathbf{r} , we find

$$\mathbf{r}_u = \mathbf{i} + \frac{\partial h}{\partial u} \mathbf{k} \quad \text{and} \quad \mathbf{r}_v = \mathbf{j} + \frac{\partial h}{\partial v} \mathbf{k}.$$

Applying the Chain Rule for implicit differentiation (see Equation (2) in Section 14.4) to $F(x, y, z) = c$, where $x = u$, $y = v$, and $z = h(u, v)$, we obtain the partial derivatives

$$\frac{\partial h}{\partial u} = -\frac{F_x}{F_z} \quad \text{and} \quad \frac{\partial h}{\partial v} = -\frac{F_y}{F_z}, \quad F_z \neq 0$$

Substitution of these derivatives into the derivatives of \mathbf{r} gives

$$\mathbf{r}_u = \mathbf{i} - \frac{F_x}{F_z} \mathbf{k} \quad \text{and} \quad \mathbf{r}_v = \mathbf{j} - \frac{F_y}{F_z} \mathbf{k}.$$

From a routine calculation of the cross product we find

Implicit Surfaces

$$\begin{aligned}
 \mathbf{r}_u \times \mathbf{r}_v &= \frac{F_x}{F_z} \mathbf{i} + \frac{F_y}{F_z} \mathbf{j} + \mathbf{k} & \begin{array}{c} \left| \begin{array}{ccc} \mathbf{i} & \mathbf{j} & \mathbf{k} \\ 1 & 0 & -F_x/F_z \\ 0 & 1 & -F_y/F_z \end{array} \right| & \begin{array}{l} \text{cross product of} \\ \mathbf{r}_u \\ \mathbf{r}_v \end{array} \\
 &= \frac{1}{F_z} (F_x \mathbf{i} + F_y \mathbf{j} + F_z \mathbf{k}) \\
 &= \frac{\nabla F}{F_z} = \frac{\nabla F}{\nabla F \cdot \mathbf{k}} \\
 &= \frac{\nabla F}{\nabla F \cdot \mathbf{p}}. & \mathbf{p} = \mathbf{k}
 \end{aligned}$$

Therefore, the surface area differential is given by

$$d\sigma = |\mathbf{r}_u \times \mathbf{r}_v| du dv = \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dx dy. \quad u = x \text{ and } v = y$$

We obtain similar calculations if instead the vector $\mathbf{p} = \mathbf{j}$ is normal to the xz -plane when $F_y \neq 0$ on S , or if $\mathbf{p} = \mathbf{i}$ is normal to the yz -plane when $F_x \neq 0$ on S . Combining these results with Equation (4) then gives the following general formula.

Implicit Surfaces

Formula for the Surface Area of an Implicit Surface

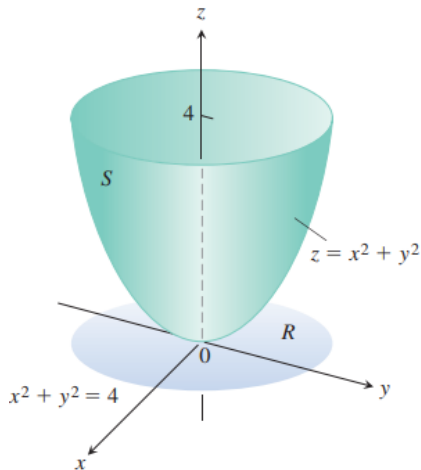
The area of the surface $F(x, y, z) = c$ over a closed and bounded plane region R is

$$\text{Surface area} = \iint_R \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dA, \quad (7)$$

where $\mathbf{p} = \mathbf{i}, \mathbf{j}$, or \mathbf{k} is normal to R and $\nabla F \cdot \mathbf{p} \neq 0$.

Implicit Surfaces

EXAMPLE 7 Find the area of the surface cut from the bottom of the paraboloid $x^2 + y^2 - z = 0$ by the plane $z = 4$.



Solution Example 7

Solution We sketch the surface S and the region R below it in the xy -plane (Figure 16.48). The surface S is part of the level surface $F(x, y, z) = x^2 + y^2 - z = 0$, and R is the disk $x^2 + y^2 \leq 4$ in the xy -plane. To get a unit vector normal to the plane of R , we can take $\mathbf{p} = \mathbf{k}$.

At any point (x, y, z) on the surface, we have

$$F(x, y, z) = x^2 + y^2 - z$$

$$\nabla F = 2x\mathbf{i} + 2y\mathbf{j} - \mathbf{k}$$

$$\begin{aligned} |\nabla F| &= \sqrt{(2x)^2 + (2y)^2 + (-1)^2} \\ &= \sqrt{4x^2 + 4y^2 + 1} \end{aligned}$$

$$|\nabla F \cdot \mathbf{p}| = |\nabla F \cdot \mathbf{k}| = |-1| = 1.$$

In the region R , $dA = dx \, dy$. Therefore,

Solution Example 7

$$\text{Surface area} = \iint_R \frac{|\nabla F|}{|\nabla F \cdot \mathbf{p}|} dA \quad \text{Eq. (7)}$$

$$= \iint_{x^2+y^2 \leq 4} \sqrt{4x^2 + 4y^2 + 1} \, dx \, dy$$

$$= \int_0^{2\pi} \int_0^2 \sqrt{4r^2 + 1} \, r \, dr \, d\theta$$

Polar coordinates

$$= \int_0^{2\pi} \left[\frac{1}{12} (4r^2 + 1)^{3/2} \right]_0^2 d\theta$$

$$= \int_0^{2\pi} \frac{1}{12} (17^{3/2} - 1) \, d\theta = \frac{\pi}{6} (17\sqrt{17} - 1).$$

