

Lecture 26: Integrals and Vector Fields.

MA2032 Vector Calculus

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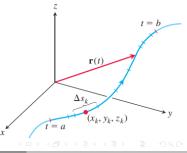
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November 18, 2022

Integrals and Vector Fields. Overview

- We extend the theory of integration to general curves and surfaces in space.
- The resulting **line and surface integrals** give powerful mathematical tools for science and engineering.
- Line integrals are used to find the work done by a force in moving an object along a path, and to find the mass of a curved wire with variable density.
- Surface integrals are used to find the rate of flow of a fluid across a surface and to describe the interactions of electric and magnetic forces.
- We present the **fundamental theorems of vector integral calculus**, and discuss their mathematical consequences and physical applications.
- The theorems of vector calculus are then shown to be **generalized** versions of the Fundamental Theorem of Calculus.

- We need a **more general notion of integral** than was defined in Integral Calculus.
- We need to integrate over a curve C rather than over an interval [a, b].
- These more general integrals are called line integrals.
- Suppose that f(x, y, z) is a **real-valued function** we wish to integrate over the curve $C \in D_f$ **parametrized by** r(t) = g(t)i + h(t)j + k(t)k, a < t < b.
- The values of f along C are given by the composite function f(g(t), h(t), k(t)).
- We are going to integrate this composition with respect to arc length s(t) from t = a to t = b.
- We first **partition** C into a finite number n of **subarcs** with length Δs_k .



• In each subarc we choose a point (x_k, y_k, z_k) and form the **sum**

$$S_n = \sum_{k=1}^n \underbrace{f(x_k, y_k, z_k)}_{\text{value of } f \text{ at a point on the subarc}} \underbrace{\Delta s_k,}_{\text{length of a small subarc of the curve}}$$

- which is similar to a **Riemann sum**.
- If f is **continuous** and the functions g, h, and k have **continuous first** derivatives, then these sums approach a limit as n increases and the lengths Δs_k approach zero.
- This leads to the following **definition**

DEFINITION If f is defined on a curve C given parametrically by $\mathbf{r}(t) = g(t)\mathbf{i} + h(t)\mathbf{j} + k(t)\mathbf{k}$, $a \le t \le b$, then the **line integral of f over C** is

$$\int_C f(x, y, z) ds = \lim_{n \to \infty} \sum_{k=1}^n f(x_k, y_k, z_k) \Delta s_k,$$
 (1)

provided this limit exists.

- If the **curve** C **is smooth** for $a \le t \le b$ (so v = dr/dt is continuous and never 0) and the function f is **continuous on** C, then the limit in Equation (1) can be shown to **exist**.
- We can then apply the Fundamental Theorem of Calculus to differentiate the arc length equation,

$$s(t) = \int_a^t |\mathbf{v}(\tau)| d\tau,$$

• to express ds in Equation (1) as ds = |v(t)|dt and evaluate the integral of f over C as

$$\int_C f(x, y, z) ds = \int_a^b f(g(t), h(t), k(t)) |\mathbf{v}(t)| dt.$$

- The formula evaluates the line integral correctly **no matter what smooth parametrization for** *C* is used.
- Note that the parameter **t defines a direction** along the path.

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How to Evaluate a Line Integral

How to Evaluate a Line Integral

To integrate a continuous function f(x, y, z) over a curve C:

1. Find a smooth parametrization of *C*,

$$\mathbf{r}(t) = g(t)\mathbf{i} + h(t)\mathbf{j} + k(t)\mathbf{k}, \qquad a \le t \le b.$$

2. Evaluate the integral as

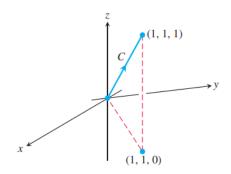
$$\int_C f(x, y, z) ds = \int_a^b f(g(t), h(t), k(t)) |\mathbf{v}(t)| dt.$$

- If f has the constant value 1, then the integral of f over C gives the length of C from t = a to t = b.
- We also write $f(\mathbf{r}(t))$ for the evaluation f(g(t), h(t), k(t)) along the curve \mathbf{r} .

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Example 1

Integrate $f(x, y, z) = x - 3y^2 + z$ over the line segment C joining the origin to the point (1, 1, 1).



Solution Since any choice of parametrization will give the same answer, we choose the simplest parametrization we can think of:

$$\mathbf{r}(t) = t\mathbf{i} + t\mathbf{j} + t\mathbf{k}, \qquad 0 \le t \le 1.$$

The components have continuous first derivatives and $|\mathbf{v}(t)| = |\mathbf{i} + \mathbf{j} + \mathbf{k}| = \sqrt{1^2 + 1^2 + 1^2} = \sqrt{3}$ is never 0, so the parametrization is smooth. The integral of f over C is

$$\int_C f(x, y, z) \, ds = \int_0^1 f(t, t, t) \sqrt{3} \, dt \qquad \text{Eq. (2), } ds = |\mathbf{v}(t)| \, dt = \sqrt{3} \, dt$$

$$= \int_0^1 (t - 3t^2 + t) \sqrt{3} \, dt$$

$$= \sqrt{3} \int_0^1 (2t - 3t^2) \, dt = \sqrt{3} \left[t^2 - t^3 \right]_0^1 = 0.$$

Additivity

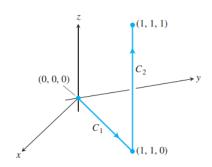
• Line integrals have the **useful property** that if a piecewise smooth curve C is **made by joining a finite number of smooth curves** $C_1, C_2, ..., C_n$ end to end, then the integral of a function over C is the sum of the integrals over the curves that make it up:

$$\int_C f \, ds = \int_{C_1} f \, ds + \int_{C_2} f \, ds + \cdots + \int_{C_n} f \, ds.$$

• The value of the line integral along a path joining two points can change if you change the path between them.

Example 2

Figure shows another path from the origin to (1,1,1), formed from two line segments C_1 and C_2 . Integrate $f(x,y,z) = x - 3y^2 + z$ over $C_1 \cup C_2$.



Solution We choose the simplest parametrizations for C_1 and C_2 we can find, calculating the lengths of the velocity vectors as we go along:

C₁:
$$\mathbf{r}(t) = t\mathbf{i} + t\mathbf{j}$$
, $0 \le t \le 1$; $|\mathbf{v}| = \sqrt{1^2 + 1^2} = \sqrt{2}$
C₂: $\mathbf{r}(t) = \mathbf{i} + \mathbf{j} + t\mathbf{k}$, $0 \le t \le 1$; $|\mathbf{v}| = \sqrt{0^2 + 0^2 + 1^2} = 1$.

With these parametrizations we find that

$$\int_{C_1 \cup C_2} f(x, y, z) \, ds = \int_{C_1} f(x, y, z) \, ds + \int_{C_2} f(x, y, z) \, ds$$

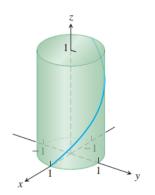
$$= \int_0^1 f(t, t, 0) \sqrt{2} \, dt + \int_0^1 f(1, 1, t) (1) \, dt$$

$$= \int_0^1 (t - 3t^2 + 0) \sqrt{2} \, dt + \int_0^1 (1 - 3 + t) (1) \, dt$$

$$= \sqrt{2} \left[\frac{t^2}{2} - t^3 \right]_0^1 + \left[\frac{t^2}{2} - 2t \right]_0^1 = -\frac{\sqrt{2}}{2} - \frac{3}{2}.$$

Example 3

Find the line integral of $f(x, y, z) = 2xy + \sqrt{z}$ over the helix $\mathbf{r}(t) = \cos t \mathbf{i} + \sin t \mathbf{j} + t \mathbf{k}$, $0 \le t \le \pi$.



Solution For the helix (Figure 16.4) we find $\mathbf{v}(t) = \mathbf{r}'(t) = -\sin t\mathbf{i} + \cos t\mathbf{j} + \mathbf{k}$ and $|\mathbf{v}(t)| = \sqrt{(-\sin t)^2 + (\cos t)^2 + 1} = \sqrt{2}$. Evaluating the function f at the point $\mathbf{r}(t)$, we obtain

$$f(\mathbf{r}(t)) = f(\cos t, \sin t, t) = 2\cos t \sin t + \sqrt{t} = \sin 2t + \sqrt{t}.$$

The line integral is given by

$$\int_C f(x, y, z) ds = \int_0^{\pi} \left(\sin 2t + \sqrt{t}\right) \sqrt{2} dt$$
$$= \sqrt{2} \left[-\frac{1}{2} \cos 2t + \frac{2}{3} t^{3/2} \right]_0^{\pi}$$
$$= \frac{2\sqrt{2}}{3} \pi^{3/2} \approx 5.25.$$

• We treat **coil springs** (Left Figure) and **wires** (Right Figure) as **masses distributed along smooth curves in space**.





- The distribution is described by a continuous density function $\delta(x,y,z)$ representing mass per unit length.
- When a curve C is parametrized by $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j} + z(t)\mathbf{k}$, $a \le t \le b$ then x, y, and z are functions of the parameter t, the **density** is the function $\delta(x(t),y(t),z(t))$, and the **arc length differential** is given by

$$ds = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} dt.$$

- ullet The spring's or wire's mass, center of mass, and moments are then calculated using the formulas in Table on next slide, with the integrations in terms of the parameter t over the interval [a,b].
- For example, the formula for mass becomes

$$M = \int_a^b \delta(x(t),y(t),z(t)) \; \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} \; dt.$$

TABLE 16.1 Mass and moment formulas for coil springs, wires, and thin rods lying along a smooth curve C in space

$$M = \int_C \delta ds$$

Mass:
$$M = \int_{-\pi}^{\pi} \delta ds$$
 $\delta = \delta(x, y, z)$ is the density at (x, y, z)

First moments about the coordinate planes:

$$M_{yz} = \int_C x \, \delta \, ds, \qquad M_{xz} = \int_C y \, \delta \, ds, \qquad M_{xy} = \int_C z \, \delta \, ds$$

Coordinates of the center of mass:

$$\overline{x} = M_{yz}/M, \qquad \overline{y} = M_{xz}/M, \qquad \overline{z} = M_{xy}/M$$

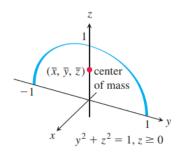
Moments of inertia about axes and other lines:

$$I_x = \int_C (y^2 + z^2) \, \delta \, ds, \qquad I_y = \int_C (x^2 + z^2) \, \delta \, ds, \qquad I_z = \int_C (x^2 + y^2) \, \delta \, ds,$$

$$I_L = \int_C r^2 \delta \, ds \qquad r(x, y, z) = \text{distance from the point } (x, y, z) \text{ to line } L$$

Example 4

A slender metal arch, denser at the bottom than top, lies along the semicircle $y^2+z^2=1,\ z\geq 0$, in the yz-plane. Find the center of the arch's mass if the density at the point (x,y,z) on the arch is $\delta(x,y,z)=2-z$.



Solution We know that $\bar{x} = 0$ and $\bar{y} = 0$ because the arch lies in the yz-plane with its mass distributed symmetrically about the z-axis. To find \bar{z} , we parametrize the circle as

$$\mathbf{r}(t) = (\cos t)\mathbf{j} + (\sin t)\mathbf{k}, \qquad 0 \le t \le \pi.$$

For this parametrization,

$$|\mathbf{v}(t)| = \sqrt{\left(\frac{dx}{dt}\right)^2 + \left(\frac{dy}{dt}\right)^2 + \left(\frac{dz}{dt}\right)^2} = \sqrt{(0)^2 + (-\sin t)^2 + (\cos t)^2} = 1,$$

so $ds = |\mathbf{v}| dt = dt$.

The formulas in Table 16.1 then give

$$M = \int_{C} \delta \, ds = \int_{C} (2 - z) \, ds = \int_{0}^{\pi} (2 - \sin t) \, dt = 2\pi - 2$$

$$M_{xy} = \int_{C} z \delta \, ds = \int_{C} z (2 - z) \, ds = \int_{0}^{\pi} (\sin t)(2 - \sin t) \, dt$$

$$= \int_{0}^{\pi} (2 \sin t - \sin^{2} t) \, dt = \frac{8 - \pi}{2} \qquad \text{Routine integration}$$

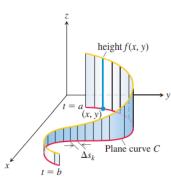
$$\bar{z} = \frac{M_{xy}}{M} = \frac{8 - \pi}{2} \cdot \frac{1}{2\pi - 2} = \frac{8 - \pi}{4\pi - 4} \approx 0.57.$$

With \bar{z} to the nearest hundredth, the center of mass is (0, 0, 0.57).



Line Integrals in the Plane

- Line integrals **for curves in the plane** have a natural geometric interpretation.
- If *C* is a smooth curve in the *xy*-plane parametrized by
- $\mathbf{r}(t) = x(t)\mathbf{i} + y(t)\mathbf{j}, a \le t \le b$, we generate a **cylindrical surface** by moving a straight line along C orthogonal to the plane, holding the line parallel to the z-axis.
- The cylinder cuts through the surface z = (x, y), forming a "curved wall".



• At any point (x, y) along the curve, the height of the wall is f(x, y).

$$\int_C f \, ds = \lim_{n \to \infty} \sum_{k=1}^n f(x_k, y_k) \, \Delta s_k,$$

• The line integral $\int_C f \ ds$ is the area of the wall shown in the figure.