## 第一章 质点机械运动的描述

## 一、选择题

- 1. 1. 1. D
- **1. 1. 2.** C
- **1.1.3.** C
- **1. 1. 4.** B
- **1. 1. 5.** B
- 1.1.6.B, C, D, F
- 1.1.7.B, C, D, E, G, I, J
- 1.1.8. A
- **1.1.9.** B
- 1. 1. 10. A
- **1. 1. 11.** C
- **1. 1. 12.** C
- **1. 1. 13.** C
- 1.1.14. A, D, E, E
- 1.1.15. 全错

## 二、填空题

- 1.2.1. 有关, 无关
- 1. 2. 2.  $v_1 = 1.5$  (SI),沿x轴正方向

1. 2. 3. 
$$\vec{v}_1 = \hat{i} + 6\hat{j}$$
,  $\vec{a}_1 = 12\hat{j}$ ,  $\vec{v} = \hat{i} + 26\hat{j}$ ,  $\vec{a} = 24\hat{j}$ 

1.2.4. 加速度大小恒为零;速率恒定不变;圆周运动;匀速圆周运动

1. 2. 5. 
$$\vec{r} = 2t\hat{i} + (19 - t^2)\hat{j}$$
,  $\vec{v} = 2\hat{i} - 2t\hat{j}$ ,  $\vec{a} = -2\hat{j}$ 

1.2.6. 大小, 方向

1. 2. 7. 
$$\theta_1 = \frac{1}{36} \text{ rad}$$
,  $\beta_1 = \frac{1}{6} \text{ rad} \cdot \text{s}^{-2}$ ,  $a_1 = \frac{\sqrt{577}}{48} \text{ m} \cdot \text{s}^{-2}$ 

1. 2. 8. 
$$\omega = 3t^2 + \omega_0$$
,  $\theta = t^3 + \omega_0 t + \theta_0$ ,  $a_t = 6Rt$ ,  $a_n = (3t^2 + \omega_0)^2 R$ 

1. 2. 9. 
$$v = 4t - \frac{1}{3}t^3 - 1$$
,  $x = 2t^2 - \frac{1}{12}t^4 - t + \frac{3}{4}$ 

- 1. 2. 10.  $v = 2(kt^2 + 1)v_0$
- 1.2.11. 绝对的, 绝对的, 绝对的; 绝对
- 1. 2. 12.  $\vec{v}_1 + \vec{v}_2 + \vec{v}_3 = 0$

## 三、计算题

1.3.1. (1) 轨道方程 
$$y^3 = 125x$$
; (2)  $\vec{v}_{t=2s} = 3 \times 2^2 \hat{i} + 5 \hat{j} = 12 \hat{i} + 5 \hat{j}$ ,  $\vec{a}_{t=2s} = 6 \times 2 \hat{i} = 12 \hat{i}$ 

**1.3.2.** (1) 
$$y = 19 - \frac{1}{2}x^2$$

(2) t = 2s 时刻质点的位置矢量

$$\vec{r}_{t=2s} = 2 \times 2\hat{i} + (19 - 2 \times 2^2)\hat{j} = 4\hat{i} + 11\hat{j}$$
,  $\vec{r}_{t=2s} = 4\hat{i} + 11\hat{j}$ 

第 2s 内的平均速度为

$$\frac{\vec{v}_{t=1s \to t=2s}}{\vec{v}_{t=1s \to t=2s}} = \frac{\vec{r}_{t=2s} - \vec{r}_{t=1s}}{\Delta t_{t=1s \to t=2s}} = \frac{(4\hat{i} + 11\hat{j}) - (2\hat{i} + 17\hat{j})}{2 - 1} = 2\hat{i} - 6\hat{j}$$

(3) 
$$\vec{v}_{t=2s} = 2\hat{i} - 4 \times 2\hat{j} = 2\hat{i} - 8\hat{j}$$
,  $\vec{a}_{t=2s} = -4\hat{i}$ 

(4) 
$$t = 3s$$
;  $x_{t=3s} = 2 \times 3 = 6$ ,  $y_{t=3s} = 19 - 2 \times 3^2 = 1$ 

**1.3.3.** (1) t = 4s 时质点的位置矢量、速度、加速度为

$$\vec{r}_{t=4\,\mathrm{s}} = 193\hat{i} - 40\,\hat{j} + 115\hat{k} \ , \quad \vec{v}_{t=4\,\mathrm{s}} = 144\hat{i} - 30\,\hat{j} + 41\hat{k} \ , \quad \vec{a}_{t=4\,\mathrm{s}} = 72\hat{i} - 10\,\hat{j} + 8\hat{k}$$

(2) 前 4s 的位移、平均速度、平均加速度为

$$\Delta \vec{r} = \vec{r}_{t=4s} - \vec{r}_{t=0s} = (193\hat{i} - 40\hat{j} + 115\hat{k}) - (\hat{i} + 15\hat{k}) = 192\hat{i} - 40\hat{j} + 100\hat{k}$$

$$\overline{\vec{v}} = \frac{\Delta \vec{r}}{\Delta t} = \frac{192\hat{i} - 40\hat{j} + 100\hat{k}}{4} = 48\hat{i} - 10\hat{j} + 25\hat{k}$$

$$\overline{\vec{a}} = \frac{\Delta \vec{v}}{\Delta t} = \frac{\vec{v}_{t=4s} - \vec{v}_{t=0s}}{\Delta t} = \frac{144\hat{i} - 30\hat{j} + 41\hat{k} - 10\hat{j} - 9\hat{k}}{4} = 36\hat{i} - 10\hat{j} + 8\hat{k}$$

1.3.4. (1) t = 1s 时粒子的速率为  $v_{t=1s} = \sqrt{388}$ 

(2) 
$$t = 1s$$
 时的切向加速度为  $a_{\tau t = 1s} = \frac{1488}{2\sqrt{388}} = \frac{372}{\sqrt{97}}$ 

(4) 
$$t = 1$$
s 时粒子的总加速度为  $a = \sqrt{a_x^2 + a_y^2} = 12\sqrt{9t^2 + 1}$ 

(3) 
$$t = ls$$
 时粒子的法向加速度为  $a_{n t = ls} = \frac{36}{\sqrt{97}}$ 

1.3.5. (1) 
$$\omega = 4t \text{ rad} \cdot \text{s}^{-1}$$
,  $\beta = 4 \text{ rad} \cdot \text{s}^{-2}$  (2)  $t = 0.5 \text{ s}$ 

**1.3.6.** (1) 
$$v = v_0 \exp(-kt)$$
 (2)  $x_{\text{max}} = \frac{v_0}{k}$ 

1.3.7. (1) 
$$a_{\tau} = g \sin \alpha$$
,  $a_{n} = g \cos \alpha$  (2)  $\rho = \frac{v_{0}^{2}}{g \cos \alpha}$ 

1.3.8. 
$$v^2 = v_0^2 - 2x^3$$

**1.3.9.** (1) 
$$t_1 = \frac{2\sqrt{v_0}}{k}$$
 (2)  $S = \frac{2v_0\sqrt{v_0}}{3k}$ 

1.3.10. (1) 运动方程 
$$\vec{r} = x\hat{i} + y\hat{j} = A\exp(kt)\hat{i} + B\exp(-kt)\hat{j}$$

- (2) 轨迹方程 xy = AB
- (3) 速度  $\vec{v} = Ak \exp(kt)\hat{i} kB \exp(-kt)\hat{j}$
- (4) 加速度  $\vec{a} = k^2 A \exp(kt)\hat{i} + k^2 B \exp(-kt)\hat{j}$

**1.3.11.** (1) 
$$y = \frac{g}{2(u + v_0)^2} x^2$$
 (2)  $y = \frac{g}{2v_0^2} x^2$