

Lecture 25: Multiple Integrals.

MA2032 Vector Calculus

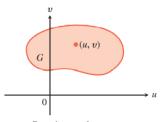
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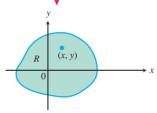
Substitutions in Multiple Integrals

- Today we introduce the ideas involved in **coordinate transformations** to evaluate multiple integrals by **substitution**.
- The method replaces complicated integrals by ones that are easier to evaluate.
- Substitutions accomplish this by simplifying the integrand, the limits of integration, or both.
- The polar coordinate substitution is a special case of a more general substitution method for double integrals.
- Suppose that a region G in the $u\nu$ -plane is **transformed** into the region R in the xy-plane by equations of the form $x = g(u, \nu), y = h(u, \nu)$



Cartesian uv-plane





- We assume the transformation is **one-to-one** on the interior of *G*.
- We call R the **image** of G under the transformation, and G the **preimage** of R.
- Any function f(x, y) defined on R can be thought of as a function $f(g(u, \nu), h(u, \nu))$ defined on G as well.
- How is the integral of f(x,y) over R related to the integral of f(g(u,y),h(u,y)) over G?
- To gain some **insight into the question**, we look at the **single variable case**: substitution method for single integrals.

$$\int_{g(a)}^{g(b)} f(x) \, dx = \int_{a}^{b} f(g(u)) \, g'(u) \, du. \qquad x = g(u), \, dx = g'(u) \, du$$

• To propose an analogue for substitution in a double integral $\iint_R f(x,y) dx \ dy$, we need a **derivative factor** like g'(u) as a **multiplier** that transforms the area element $du \ d\nu$ in the region G to its corresponding area element $dx \ dy$ in the region R.

• We denote this factor by J:

DEFINITION The **Jacobian determinant** or **Jacobian** of the coordinate transformation x = g(u, v), y = h(u, v) is

$$J(u,v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \frac{\partial x}{\partial u} \frac{\partial y}{\partial v} - \frac{\partial y}{\partial u} \frac{\partial x}{\partial v}.$$
 (1)

• The Jacobian measures how much the transformation is expanding or contracting the area around the point (u, ν) .

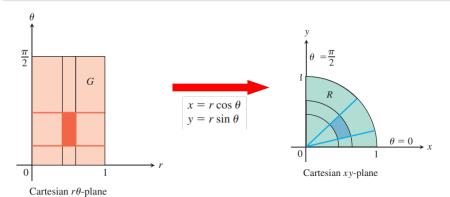
THEOREM 3-Substitution for Double Integrals

Suppose that f(x, y) is continuous over the region R. Let G be the preimage of R under the transformation x = g(u, v), y = h(u, v), which is assumed to be one-to-one on the interior of G. If the functions g and h have continuous first partial derivatives within the interior of G, then

$$\iint\limits_R f(x, y) \, dx \, dy = \iint\limits_G f(g(u, v), h(u, v)) \left| \frac{\partial(x, y)}{\partial(u, v)} \right| du \, dv. \tag{2}$$

Example 1

Find the Jacobian for the polar coordinate transformation $x = r \cos \theta$, $y = r \sin \theta$, and write the Cartesian integral $\iint_R f(x,y) dx dy$ as a polar integral.



Solution Figure 15.58 shows how the equations $x = r \cos \theta$, $y = r \sin \theta$ transform the rectangle $G: 0 \le r \le 1$, $0 \le \theta \le \pi/2$, into the quarter circle R bounded by $x^2 + y^2 = 1$ in the first quadrant of the xy-plane.

For polar coordinates, we have r and θ in place of u and v. With $x = r \cos \theta$ and $y = r \sin \theta$, the Jacobian is

$$J(r,\theta) = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta \\ \sin \theta & r \cos \theta \end{vmatrix} = r(\cos^2 \theta + \sin^2 \theta) = r.$$

Since we assume $r \ge 0$ when integrating in polar coordinates, $|J(r, \theta)| = |r| = r$, so that Equation (2) gives

$$\iint\limits_R f(x, y) \, dx \, dy = \iint\limits_G f(r \cos \theta, r \sin \theta) \, r \, dr \, d\theta. \tag{3}$$

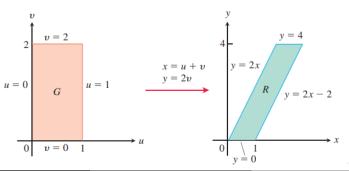
This is the same formula we derived independently using a geometric argument for polar area in Section 15.4.

Example 2

Evaluate

$$\int_0^4 \int_{x=y/2}^{x=(y/2)+1} \frac{2x-y}{2} dx \, dy$$

by applying the transformation $u=\frac{2x-y}{2},\ \nu=\frac{y}{2}$ and integrating over an appropriate region in the $u\nu$ -plane.



Solution We sketch the region R of integration in the xy-plane and identify its boundaries (Figure 15.59).

To apply Equation (2), we need to find the corresponding uv-region G and the Jacobian of the transformation. To find them, we first solve Equations (4) for x and y in terms of u and v. From those equations it is easy to find algebraically that

$$x = u + v, \qquad y = 2v. \tag{5}$$

We then find the boundaries of G by substituting these expressions into the equations for the boundaries of R (Figure 15.59)

xy-equations for the boundary of R	Corresponding uv -equations for the boundary of G	Simplified <i>uv</i> -equations
x = y/2	u + v = 2v/2 = v	u = 0
x = (y/2) + 1	u + v = (2v/2) + 1 = v + 1	u = 1
y = 0	2v = 0	v = 0
y = 4	2v = 4	v = 2

From Equations (5) the Jacobian of the transformation is

$$J(u,v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{\partial}{\partial u}(u+v) & \frac{\partial}{\partial v}(u+v) \\ \frac{\partial}{\partial u}(2v) & \frac{\partial}{\partial v}(2v) \end{vmatrix} = \begin{vmatrix} 1 & 1 \\ 0 & 2 \end{vmatrix} = 2.$$

We now have everything we need to apply Equation (2):

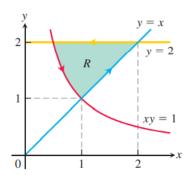
$$\int_{0}^{4} \int_{x=y/2}^{x=(y/2)+1} \frac{2x-y}{2} dx \, dy = \int_{v=0}^{v=2} \int_{u=0}^{u=1} u \, |J(u,v)| \, du \, dv$$
$$= \int_{0}^{2} \int_{0}^{1} (u)(2) \, du \, dv = \int_{0}^{2} \left[u^{2} \right]_{0}^{1} dv = \int_{0}^{2} dv = 2. \quad \blacksquare$$

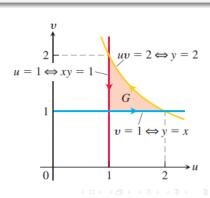
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Example 3

Evaluate the integral

$$\int_1^2 \int_{x=1/y}^{x=y} \sqrt{\frac{y}{x}} e^{\sqrt{xy}} dx \ dy.$$





Example 3. Whiteboard

Solution The square root terms in the integrand suggest that we might simplify the integration by substituting $u = \sqrt{xy}$ and $v = \sqrt{y/x}$. Squaring these equations gives $u^2 = xy$ and $v^2 = y/x$, which imply that $u^2v^2 = y^2$ and $u^2/v^2 = x^2$. So we obtain the transformation (in the same ordering of the variables as discussed before)

$$x = \frac{u}{v}$$
 and $y = uv$,

with u > 0 and v > 0. Let's first see what happens to the integrand itself under this transformation. The Jacobian of the transformation is not constant:

$$J(u, v) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} \end{vmatrix} = \begin{vmatrix} \frac{1}{v} & \frac{-u}{v^2} \\ v & u \end{vmatrix} = \frac{2u}{v}.$$

If G is the region of integration in the uv-plane, then by Equation (2) the transformed double integral under the substitution is

$$\iint\limits_R \, \sqrt{\frac{y}{x}} \, e^{\sqrt{xy}} \, dx \, dy = \iint\limits_G \, v e^u \, \frac{2u}{v} \, du \, dv = \iint\limits_G \, 2u e^u \, du \, dv.$$

The transformed integrand function is easier to integrate than the original one, so we proceed to determine the limits of integration for the transformed integral.

The region of integration R of the original integral in the xy-plane is shown in Figure 15.61. From the substitution equations $u = \sqrt{xy}$ and $v = \sqrt{y/x}$, we see that the image of the left-hand boundary xy = 1 for R is the vertical line segment $u = 1, 2 \ge v \ge 1$, in G (see Figure 15.62). Likewise, the right-hand boundary y = x of R maps to the horizontal line segment $v = 1, 1 \le u \le 2$, in G. Finally, the horizontal top boundary v = 0 of v = 0.

maps to uv = 2, $1 \le v \le 2$, in G. As we move counterclockwise around the boundary of the region R, we also move counterclockwise around the boundary of G, as shown in Figure 15.62. Knowing the region of integration G in the uv-plane, we can now write equivalent iterated integrals:

$$\int_{1}^{2} \int_{1/y}^{y} \sqrt{\frac{y}{x}} e^{\sqrt{xy}} dx dy = \int_{1}^{2} \int_{1}^{2/u} 2ue^{u} dv du.$$
 Note the order of integration.

We now evaluate the transformed integral on the right-hand side,

$$\int_{1}^{2} \int_{1}^{2/u} 2ue^{u} \, dv \, du = 2 \int_{1}^{2} \left[vue^{u} \right]_{v=1}^{v=2/u} du$$

$$= 2 \int_{1}^{2} (2e^{u} - ue^{u}) \, du$$

$$= 2 \int_{1}^{2} (2 - u)e^{u} \, du$$

$$= 2 \left[(2 - u)e^{u} + e^{u} \right]_{u=1}^{u=2}$$
Integrate by parts.
$$= 2(e^{2} - (e + e)) = 2e(e - 2).$$

Substitutions in Triple Integrals

- The **cylindrical and spherical coordinate substitutions** are special cases of a substitution method that pictures changes of variables in **triple integrals** as transformations of three-dimensional regions.
- The method is like the method for double integrals except that now **we work in three dimensions** instead of two.
- Suppose that a region G in $u\nu w$ -space is transformed one-to-one into the region D in xyz-space by differentiable equations of the form

$$x = g(u, v, w),$$
 $y = h(u, v, w),$ $z = k(u, v, w),$

• Then any function F(x, y, z) defined on D can be thought of as a function

$$F(g(u, v, w), h(u, v, w), k(u, v, w)) = H(u, v, w)$$

defined on G.

Substitutions in Triple Integrals

• If g, h, and k have **continuous first partial derivatives**, then the integral of F(x,y,z) over D is related to the integral of H(u,y,w) over G by the equation

$$\iiint\limits_D F(x,y,z)\,dx\,dy\,dz=\iiint\limits_G H(u,v,w)\,\big|J(u,v,w)\big|\,du\,dv\,dw.$$

• The factor $J(u, \nu, w)$, whose absolute value appears in this equation, is

$$J(u, v, w) = \begin{vmatrix} \frac{\partial x}{\partial u} & \frac{\partial x}{\partial v} & \frac{\partial x}{\partial w} \\ \frac{\partial y}{\partial u} & \frac{\partial y}{\partial v} & \frac{\partial y}{\partial w} \\ \frac{\partial z}{\partial u} & \frac{\partial z}{\partial v} & \frac{\partial z}{\partial w} \end{vmatrix} = \frac{\partial(x, y, z)}{\partial(u, v, w)}.$$

the Jacobian determinant

• This determinant measures how much the **volume** near a point in G is being **expanded or contracted** by the transformation from (u, ν, w) to (x, y, z) coordinates.

Substitutions in Triple Integrals. Cylindrical coordinates

For cylindrical coordinates, r, θ , and z take the place of u, v, and w. The transformation from Cartesian $r\theta z$ -space to Cartesian xyz-space is given by the equations

$$x = r \cos \theta$$
, $y = r \sin \theta$, $z = z$

(Figure 15.64). The Jacobian of the transformation is

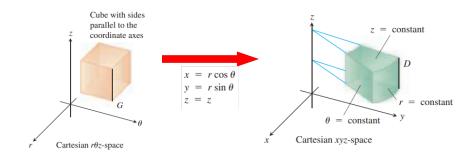
$$J(r, \theta, z) = \begin{vmatrix} \frac{\partial x}{\partial r} & \frac{\partial x}{\partial \theta} & \frac{\partial x}{\partial z} \\ \frac{\partial y}{\partial r} & \frac{\partial y}{\partial \theta} & \frac{\partial y}{\partial z} \\ \frac{\partial z}{\partial r} & \frac{\partial z}{\partial \theta} & \frac{\partial z}{\partial z} \end{vmatrix} = \begin{vmatrix} \cos \theta & -r \sin \theta & 0 \\ \sin \theta & r \cos \theta & 0 \\ 0 & 0 & 1 \end{vmatrix}$$
$$= r \cos^{2} \theta + r \sin^{2} \theta = r.$$

The corresponding version of Equation (7) is

$$\iiint\limits_D F(x,y,z) \, dx \, dy \, dz = \iiint\limits_G H(r,\theta,z) \big| r \big| \, dr \, d\theta \, dz.$$

We can drop the absolute value signs because $r \ge 0$.

Substitutions in Triple Integrals. Cylindrical coordinates



Substitutions in Triple Integrals. Spherical coordinates

For spherical coordinates, ρ , ϕ , and θ take the place of u, v, and w. The transformation from Cartesian $\rho\phi\theta$ -space to Cartesian xyz-space is given by

$$x = \rho \sin \phi \cos \theta$$
, $y = \rho \sin \phi \sin \theta$, $z = \rho \cos \phi$

(Figure 15.65). The Jacobian of the transformation (see Exercise 23) is

$$J(\rho, \phi, \theta) = \begin{vmatrix} \frac{\partial x}{\partial \rho} & \frac{\partial x}{\partial \phi} & \frac{\partial x}{\partial \theta} \\ \frac{\partial y}{\partial \rho} & \frac{\partial y}{\partial \phi} & \frac{\partial y}{\partial \theta} \\ \frac{\partial z}{\partial \rho} & \frac{\partial z}{\partial \phi} & \frac{\partial z}{\partial \theta} \end{vmatrix} = \rho^2 \sin \phi.$$

The corresponding version of Equation (7) is

$$\iiint\limits_{D} F(x,y,z)\,dx\,dy\,dz = \iiint\limits_{G} H(\rho,\phi,\theta)\,\left|\rho^{2}\sin\phi\,\right|\,d\rho\,d\phi\,d\theta.$$

Substitutions in Triple Integrals. Spherical coordinates

