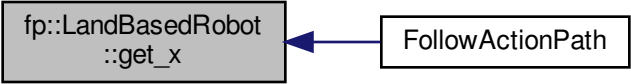


fp::LandBasedRobot
::get_x



```
graph LR; A[FollowActionPath] --> B[fp::LandBasedRobot::get_x]
```

The diagram consists of two rectangular boxes. The box on the left is light gray with a black border and contains the text 'fp::LandBasedRobot' on the top line and '::get_x' on the bottom line. The box on the right is white with a black border and contains the text 'FollowActionPath'. A dark blue arrow points from the right side of the white box to the right side of the gray box.

FollowActionPath