view_frames Result

Recorded at time: 1762637749.7384717

robot1/odom

Broadcaster: default_authority
Average rate: 29.677
Buffer length: 3.1
Most recent transform: 27.2
Oldest transform: 24.1

robot1/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/base_link

Broadcaster: default_authority
Average rate: 19.698
Buffer length: 3.706
Most recent transform: 27.247
Oldest transform: 23.541

Broadcaster: default_authority
Average rate: 19.698
Buffer length: 3.706
Most recent transform: 27.247
Oldest transform: 23.541

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/wheel_left_link

robot1/wheel_right_link

robot1/imu_link

robot1/base_scan

robot3/odom

Broadcaster: default_authority
Average rate: 29.459
Buffer length: 3.7
Most recent transform: 27.2
Oldest transform: 23.5

robot3/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/base_link

Broadcaster: default_authority
Average rate: 19.791
Buffer length: 3.638
Most recent transform: 27.181
Oldest transform: 23.543

Broadcaster: default_authority
Average rate: 19.791
Buffer length: 3.638
Most recent transform: 27.181
Oldest transform: 23.543

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/wheel_left_link

robot3/wheel_right_link

robot3/imu_link

robot3/base_scan