view_frames Result

Recorded at time: 1762640564.306035

robot1/odom

Broadcaster: default_authority
Average rate: 29.412
Buffer length: 3.4
Most recent transform: 16.0
Oldest transform: 12.6

robot1/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/base_link

Broadcaster: default_authority
Average rate: 20.153
Buffer length: 1.836
Most recent transform: 15.987
Oldest transform: 14.151

Broadcaster: default_authority
Average rate: 20.153
Buffer length: 1.836
Most recent transform: 15.987
Oldest transform: 14.151

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/wheel_left_link

robot1/wheel_right_link

robot1/imu_link

robot1/base_scan

robot3/odom

Broadcaster: default_authority
Average rate: 29.31
Buffer length: 2.9
Most recent transform: 16.0
Oldest transform: 13.1

robot3/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/base_link

Broadcaster: default_authority
Average rate: 19.808
Buffer length: 3.332
Most recent transform: 15.981
Oldest transform: 12.649

Broadcaster: default_authority
Average rate: 19.808
Buffer length: 3.332
Most recent transform: 15.981
Oldest transform: 12.649

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/wheel_left_link

robot3/wheel_right_link

robot3/imu_link

robot3/base_scan