view_frames Result

Recorded at time: 1762701759.8832371

robot1/odom

Broadcaster: default_authority
Average rate: 29.754
Buffer length: 2.924
Most recent transform: 36.913
Oldest transform: 33.989

robot1/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/base_link

Broadcaster: default_authority
Average rate: 20.053
Buffer length: 2.244
Most recent transform: 36.879
Oldest transform: 34.635

Broadcaster: default_authority
Average rate: 20.053
Buffer length: 2.244
Most recent transform: 36.879
Oldest transform: 34.635

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot1/wheel_left_link

robot1/wheel_right_link

robot1/imu_link

robot1/base_scan

robot3/odom

Broadcaster: default_authority
Average rate: 29.879
Buffer length: 2.142
Most recent transform: 36.922
Oldest transform: 34.78

robot3/base_footprint

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/base_link

Broadcaster: default_authority
Average rate: 19.844
Buffer length: 2.822
Most recent transform: 36.888
Oldest transform: 34.066

Broadcaster: default_authority
Average rate: 19.844
Buffer length: 2.822
Most recent transform: 36.888
Oldest transform: 34.066

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

Broadcaster: default_authority
Average rate: 10000.0
Buffer length: 0.0
Most recent transform: 0.0
Oldest transform: 0.0

robot3/wheel_left_link

robot3/wheel_right_link

robot3/imu_link

robot3/base_scan