CENG 218 Design and Analysis of Algorithms

Izmir Institute of Technology

Lecture 11: Dynamic programming

Slides were mostly prepared using the material provided by Prof. Charles E. Leiserson and Prof. Erik Demaine from MIT

Dynamic programming (DP)

It is a design technique, like divide-and-conquer.

Contrast to divide-and-conquer, DP applies when the subproblems overlap.

When subproblems overlap, divide-and-conquer approach does unnecessary work by repeatedly solving common subproblems.

DP approach, however, solves each subproblem just once and saves the answer in a table.

Example 1: LCS

Longest Common Subsequence (LCS)

• Given two sequences x[1 ...m] and y[1 ...n], find a longest subsequence common to them both.

$$x: A B C B D A B$$
 $y: B D C A B A$

$$y: B D C A B A$$

Brute-force LCS algorithm

Check every subsequence of x[1 ...m] to see if it is also a subsequence of y[1 ...n].

Analysis

- Checking is O(n) time **per subsequence** since we are searching it in y.
- 2^m subsequences of x
 - \blacksquare each bit-vector of length m is a distinct subsequence of x
 - Or, enumerate all elements in *x* and count subsets
- Worst-case running time is $O(n2^m)$ which is exponential time.

Towards a better algorithm

Simplification:

- 1. First, find the *length* of a LCS.
- 2. Extend the algorithm to find the LCS itself.

Notation: Denote the length of sequence s by |s|.

Strategy: Consider *prefixes* of x and y and find the LCS(x, y) in terms of those.

- Define c[i, j] = |LCS(x[1 ... i], y[1 ... j])|.
- Remember, x[1 ...m] and y[1 ...n].
- Then, c[m, n] = |LCS(x, y)|.

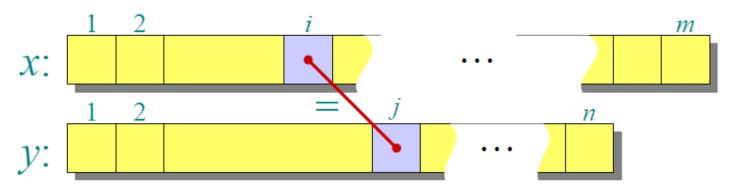
Recursive formulation

$$c[i,j] = \begin{cases} c[i-1,j-1] + 1 & \text{if } x[i] = y[j], \\ \max\{c[i-1,j], c[i,j-1]\} & \text{otherwise.} \end{cases}$$

Recursive formulation

Proof.

Case 1: x[i] = y[j]



Let z[1...k] = LCS(x[1...i], y[1...j]), where c[i, j] = k. Then, z[k] = x[i] (= y[j]).

Or, maybe x[i] is in it and y[j] is not (or vice versa). But, in this case we might as well match x[i] with y[j].

Thus, z[1 ... k-1] is CS of x[1 ... i-1] and y[1 ... j-1].

Proof (continued)

Claim: z[1 ... k-1] = LCS(x[1 ... i-1], y[1 ... j-1]).

Proof by contradiction: Suppose w is a longer CS of x[1 ... i-1] and y[1 ... j-1], that is, |w| > k-1. Then, $w \mid\mid z[k]$ (w concatenated with z[k]) is a common subsequence of x[1 ... i] and y[1 ... j] with $|w| \mid z[k]| > k$. Contradiction!

Thus, c[i-1, j-1]=k-1, implying c[i, j]=c[i-1, j-1]+1.

Proof (continued)

Case 2: x[i] != y[j]

Then, the LCS of x[1..i] and y[1..j] cannot contain both x[i] and y[j]. The answer ignores either x[i] or y[j] or both.

Thus, $c[i, j] = \max\{ c[i-1, j], c[i, j-1] \}.$

Dynamic programming hallmark #1

Optimal substructure An optimal solution to a problem (instance) contains optimal solutions to subproblems.

Hallmark here means a requirement to apply DP.

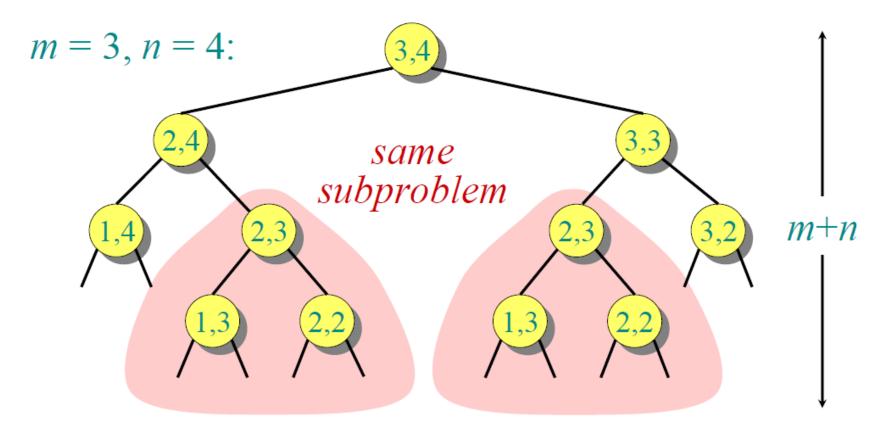
If z = LCS(x, y), then any prefix of z is an LCS of a prefix of x and a prefix of y. optimal substructure is satisfied

Recursive algorithm for LCS

$$\begin{aligned} \operatorname{LCS}(x, y, i, j) \\ & \quad \text{if } x[i] = y[j] \\ & \quad c[i, j] \leftarrow \operatorname{LCS}(x, y, i-1, j-1) + 1 \\ & \quad \text{else } c[i, j] \leftarrow \max\{\operatorname{LCS}(x, y, i-1, j), \\ & \quad \operatorname{LCS}(x, y, i, j-1)\} \end{aligned}$$

Worst-case: $x[i] \neq y[j]$, in which case the algorithm evaluates two subproblems, each with only one parameter decremented.

Recursion tree



Height = $m + n => T(n) = O(2^{m+n})$, and we're solving subproblems already solved!

Dynamic programming hallmark #2

Overlapping subproblems
A recursive solution contains a
"small" number of distinct
subproblems repeated many times.

How many distinct LCS subproblems are there for two strings of lengths *m* and *n*? Only *mn*.

Memoization algorithm

Memoization: After computing a solution to a subproblem, store it in a table. Subsequent calls check the table to avoid redoing work.

Let c[1..m,1..n] a 2D array initialized with NIL

```
LCS (x, y, i, j)

if c[i, j] = NIL

checking the table

if x[i] = y[j]

c[i, j] \leftarrow LCS(x, y, i-1, j-1) + 1

else c[i, j] \leftarrow \max\{LCS(x, y, i-1, j),

LCS(x, y, i, j-1)\}

return c[i, j]
```

Memoization algorithm

Call the following subroutine with LCS(x,y,m,n)

```
LCS (x, y, i, j)

if c[i, j] = NIL

if x[i] = y[j]

c[i, j] \leftarrow LCS(x, y, i-1, j-1) + 1

else c[i, j] \leftarrow max\{LCS(x, y, i-1, j),

LCS(x, y, i, j-1)\}

return c[i, j]
```

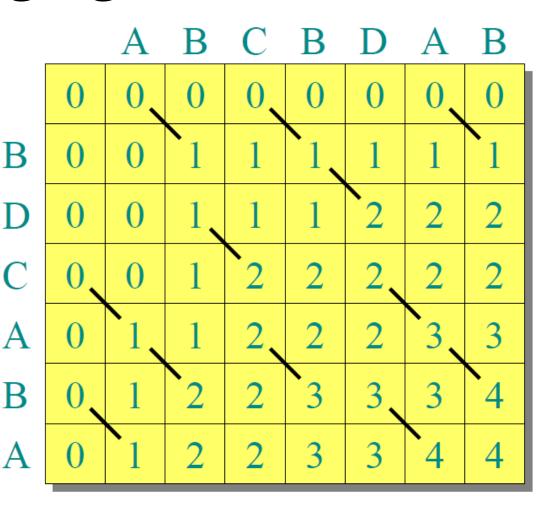
Time = $\Theta(mn)$ assuming constant work per table entry. Storage Space = $\Theta(mn)$.

Bottom-up (non-recursive) dynamic programming algorithm

IDEA:

Compute the table bottom-up. Time = $\Theta(mn)$.

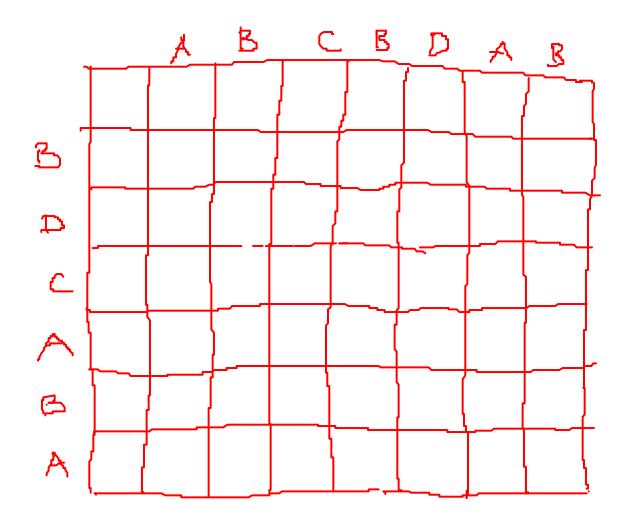
Note: Additional zero vectors at the top and at the left.



Bottom-up algorithm

```
LCS-LENGTH(X, Y)
 1 m = X.length
 2 n = Y.length
 3 let b[1..m, 1..n] and c[0..m, 0..n] be new tables
 4 for i = 1 to m
   c[i,0] = 0
 6 for j = 0 to n
    c[0, j] = 0
    for i = 1 to m
 9
         for j = 1 to n
             if x_i == y_i
10
                 c[i, j] = c[i-1, j-1] + 1
11
                 b[i, j] = "\\\"
12
             elseif c[i - 1, j] \ge c[i, j - 1]
13
                 c[i, j] = c[i - 1, j]
14
                 b[i, j] = "\uparrow"
15
             else c[i, j] = c[i, j - 1]
16
                 b[i, j] = "\leftarrow"
17
18
    return c and b
```

Bottom-up algorithm



Bottom-up algorithm

В

IDEA:

Compute the table bottom-up.

Time = $\Theta(mn)$.

Construct an LCS by tracing backwards.

Space = $\Theta(mn)$.

	A	В	C	В	D	A	В
0	0	0	0	0	0	0	0
0	0	1	1	1	1	1	1
0	0	1	1	1	2	2	2
0	0	1	2	2	2	2	2
0	1	1	2	2	2	3	3
0	1	2	2	3	3	3	4
0	1	2	2	3	3	4	4

Summary for LCS problem

Computation time for sequences x[1 ...m] and y[1 ...n]:

- 1) Brute-force algorithm: $O(n2^m)$
- 2) Recursive algorithm: $O(2^{m+n})$
- 3) Recursive algorithm with memoization: $\Theta(mn)$
- 4) Bottom-up algorithm: $\Theta(mn)$

Dynamic programming

Example 2: Rod-cutting

Given a rod of length n inches and a table of prices p_i for i = 1, 2, ..., n, determine the maximum revenue r_n obtainable by cutting up the rod and selling the pieces.

length i	1	2	3	4	5	6	7	8	9	10
price p_i	1	5	8	9	10	17	17	20	24	30

Consider the case when n = 4. All possible cuts are:



Cutting the rod into two 2-inch pieces produces the maximum revenue: 5+5=10.

Rod-cutting: Optimal substructure

To solve the original problem, we solve smaller problems of the same type. We say, rod-cutting problem exhibits optimal substructure (hallmark #1).

```
r_1 = 1 from solution 1 = 1 (no cuts),
r_2 = 5 from solution 2 = 2 (no cuts),
r_3 = 8 from solution 3 = 3 (no cuts),
r_4 = 10 from solution 4 = 2 + 2,
r_5 = 13 from solution 5 = 2 + 3,
r_6 = 17 from solution 6 = 6 (no cuts),
r_7 = 18 from solution 7 = 1 + 6 or 7 = 2 + 2 + 3,
r_8 = 22 from solution 8 = 2 + 6,
r_9 = 25 from solution 9 = 3 + 6,
r_{10} = 30 from solution 10 = 10 (no cuts).
```

Rod-cutting: Recursive top-down implementation

```
CUT-ROD(p, n)

1 if n == 0

2 return 0

3 q = -\infty

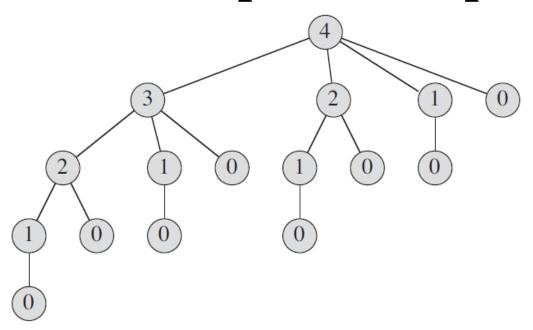
4 for i = 1 to n

5 q = \max(q, p[i] + \text{CUT-ROD}(p, n - i))

6 return q
```

p is the price list, n is the problem size. For n=40, it takes about several minutes. Why?

Rod-cutting: Overlapping subproblems (Recursive top-down implementation)



The recursion tree showing recursive calls from a call of CUT-ROD(p,n) when n=4.

$$T(n)=O(2^n)$$

Rod-cutting: Memoized approach

```
MEMOIZED-CUT-ROD (p, n)
  let r[0...n] be a new array
                                             Initializing table
2 for i = 0 to n
 r[i] = -\infty
  return MEMOIZED-CUT-ROD-AUX(p, n, r)
MEMOIZED-CUT-ROD-AUX(p, n, r)
  if r[n] \geq 0
                     \vdash If the problem is previously solved for n
 return r[n]
3 if n == 0
4 	 q = 0
5 else q = -\infty
  for i = 1 to n
           q = \max(q, p[i] + \text{MEMOIZED-CUT-ROD-AUX}(p, n - i, r))
 r[n] = q
   return q
                      T(n) = \Theta(n^2)
```

Rod-cutting: Bottom-up approach

```
BOTTOM-UP-CUT-ROD(p, n)
  let r[0...n] be a new array
2 r[0] = 0
3 for j = 1 to n
       q = -\infty
       for i = 1 to j
           q = \max(q, p[i] + r[j - i])
       r[j] = q
   return r[n]
```

Again $T(n) = \Theta(n^2)$. This implementation is even simpler.

The End

In summary, DP

- defines the value of an optimal solution based on optimal solutions of subproblems.
- computes the solutions in top-down (recursive calls and memoization) or bottom-up fashion.

Textbook Section 15.1 (rod-cutting), 15.2 (matrix-chain multiplication), 15.3 (DP elements) and 15.4 (LCS).