

A Heap Implementation

Chapter 26

Data Structures and Abstractions with Java, 4e, Global Edition
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Heap and Maxheap

- Heap: complete binary tree whose nodes contain **Comparable** objects
- Maxheap: object in each node is greater than or equal to the objects in the node's descendants

Heap and Maxheap

```
public interface MaxHeapInterface<T extends Comparable<? super T>>
{
    public void add(T newEntry);
    public T removeMax();
    public T getMax();
    public boolean isEmpty();
    public int getSize();
    public void clear();
} // end MaxHeapInterface
```

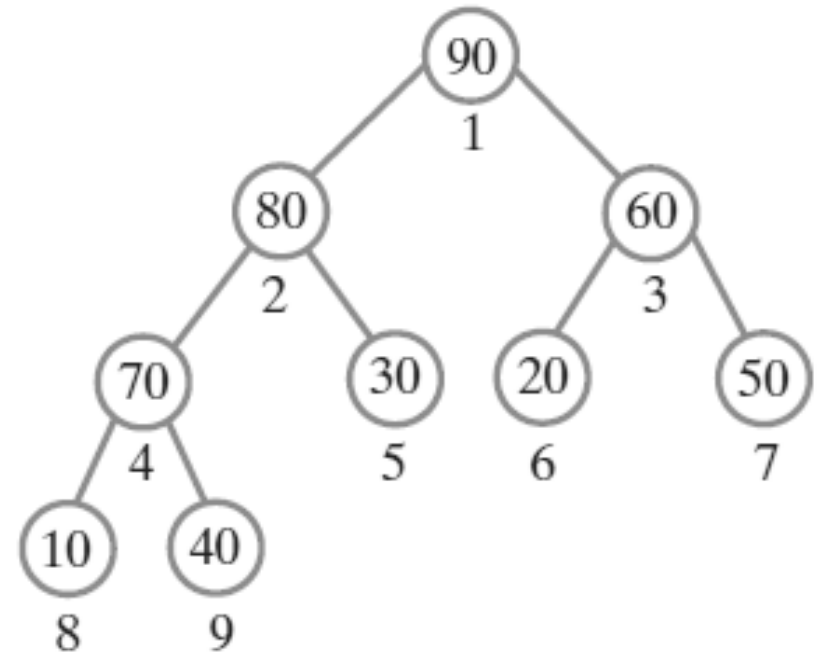
Interface for the maxheap

An Array to Represent a Heap

- Use an array to represent a complete binary tree
- Number nodes in the order in which a level-order traversal would visit them
- Can locate either the children or the parent of any node
 - Perform a simple computation on the node's number

An Array to Represent a Heap

(a)



(b)

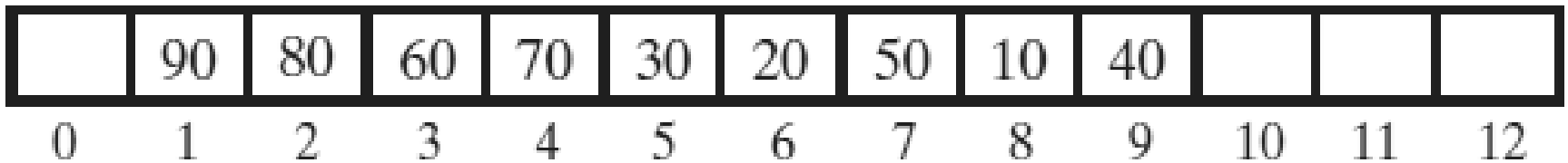


FIGURE 26-1 (a) A complete binary tree with its nodes numbered in level order; (b) its representation as an array

An Array to Represent a Heap

```
1 import java.util.Arrays;
2 public final class MaxHeap<T extends Comparable<? super T>>
3     implements MaxHeapInterface<T>
4 {
5     private T[] heap;          // Array of heap entries
6     private int lastIndex;     // Index of last entry
7     private boolean initialized = false;
8     private static final int DEFAULT_CAPACITY = 25;
9     private static final int MAX_CAPACITY = 10000;
10
11     public MaxHeap()
12     {
13         this(DEFAULT_CAPACITY); // Call next constructor
14     } // end default constructor
15
```

An Array to Represent a Heap

```
public MaxHeap(int initialCapacity)
{
    // Is initialCapacity too small?
    if (initialCapacity < DEFAULT_CAPACITY)
        initialCapacity = DEFAULT_CAPACITY;
    else // Is initialCapacity too big?
        checkCapacity(initialCapacity);

    // The cast is safe because the new array contains all null entries
    @SuppressWarnings("unchecked")
    T[] tempHeap = (T[]) new Comparable[initialCapacity + 1];
    heap = tempHeap;
    lastIndex = 0;
    initialized = true;
} // end constructor

public void add(T newEntry)
{
    < See Segment 26.8. >
} // end add

public T removeMax()
```

An Array to Represent a Heap

```
36
37     public T removeMax()
38     {
39         < See Segment 26.12. >
40     } // end removeMax
41
42     public T getMax()
43     {
44         checkInitialization();
45         T root = null;
46         if (!isEmpty())
47             root = heap[1];
48         return root;
49     } // end getMax
50
```

LISTING 26-1 The class **MaxHeap**, partially completed

An Array to Represent a Heap

```
50
51     public boolean isEmpty()
52     {
53         return lastIndex < 1;
54     } // end isEmpty
55
56     public int getSize()
57     {
58         return lastIndex;
59     } // end getSize
60
```

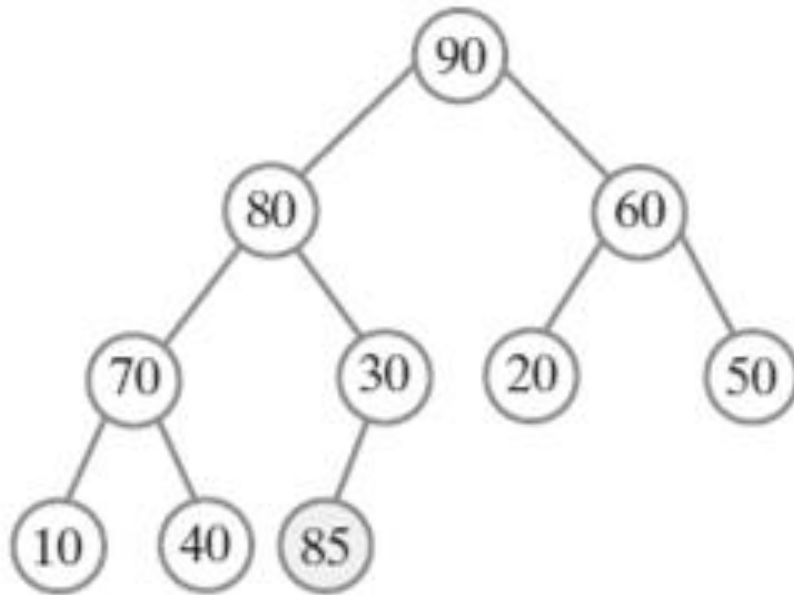
LISTING 26-1 The class **MaxHeap**, partially completed

An Array to Represent a Heap

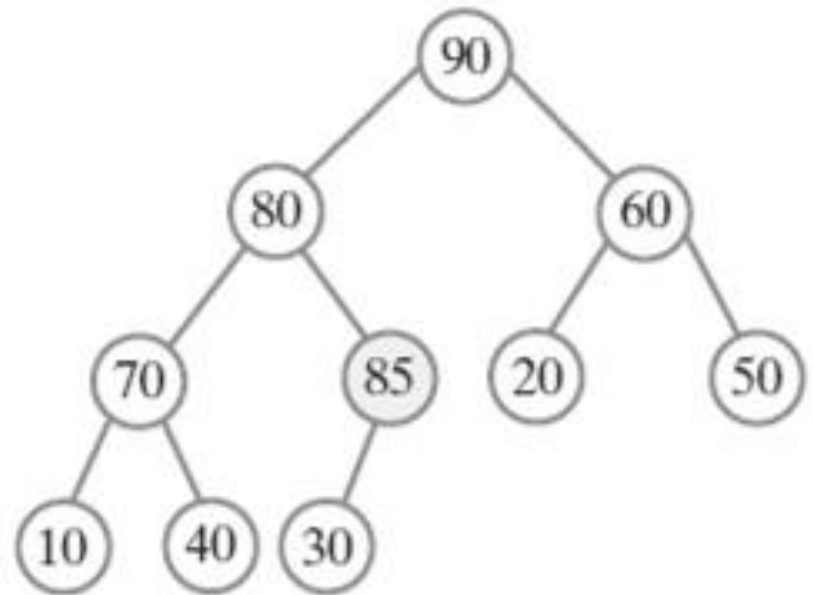
```
60
61     public void clear()
62     {
63         checkInitialization();
64         while (lastIndex > -1)
65         {
66             heap[lastIndex] = null;
67             lastIndex--;
68         } // end while
69         lastIndex = 0;
70     } // end clear
71     < Private methods >
72     . . .
73 } // end MaxHeap
```

LISTING 26-1 The class **MaxHeap**, partially completed

(a)

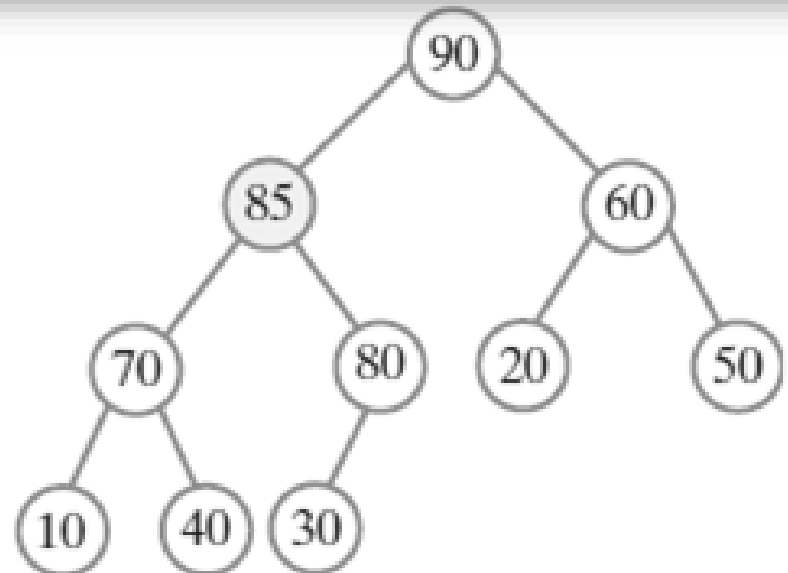


(b)



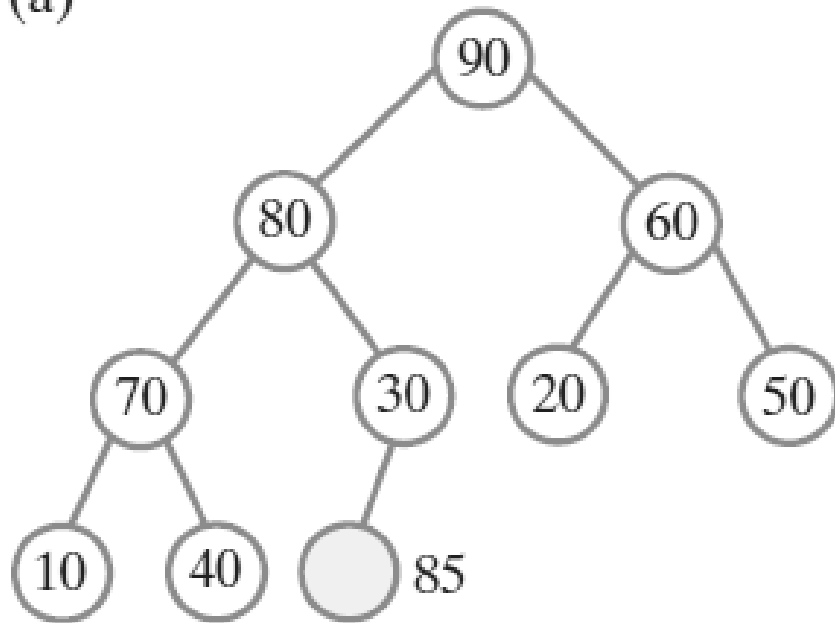
Adding an Entry

FIGURE 26-2 The steps
in adding 85 to
the maxheap in Figure
26-1a



Adding an Entry

(a)



(b)

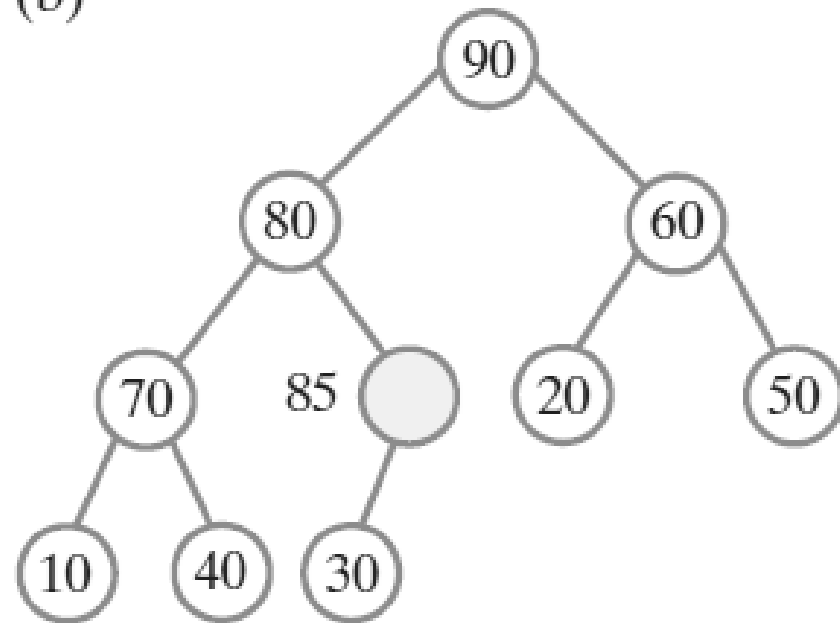


FIGURE 26-3 A revision of the steps shown in Figure 26-2, to avoid swaps

Adding an Entry

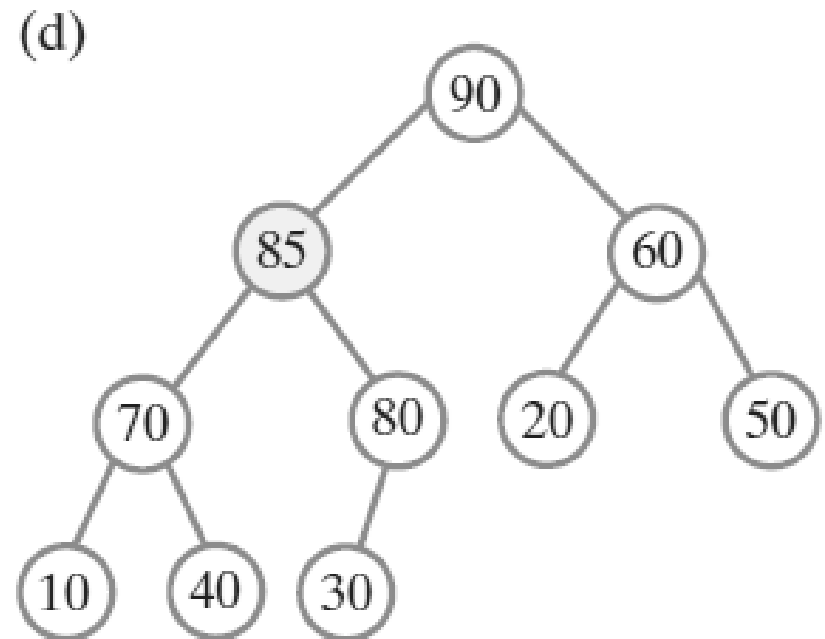
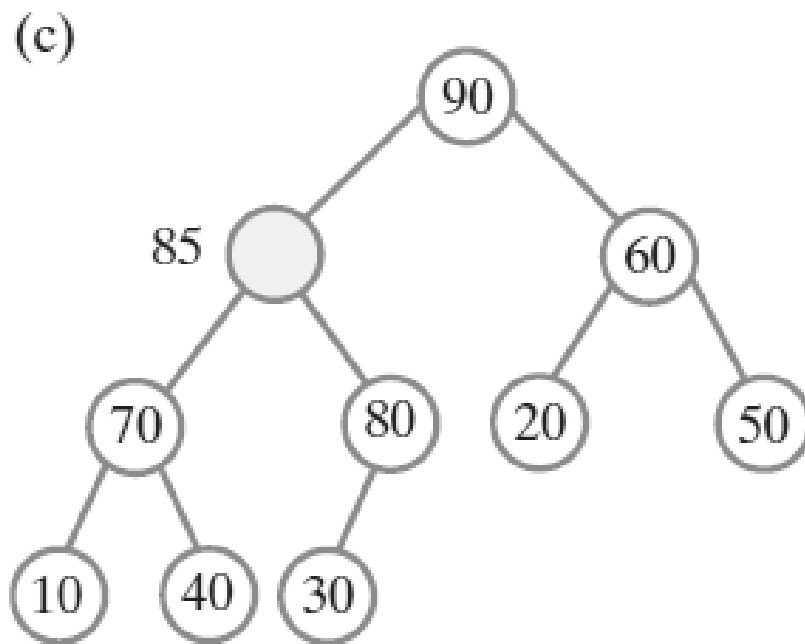
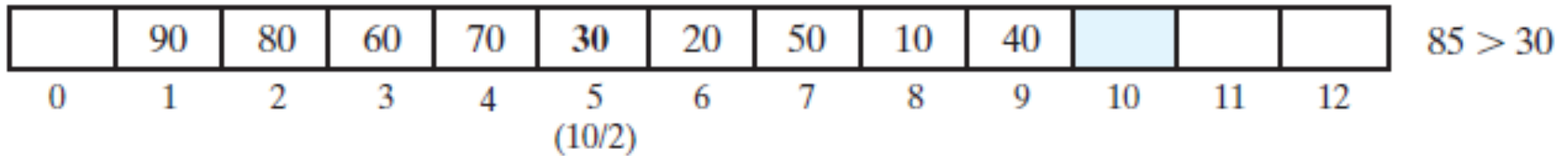


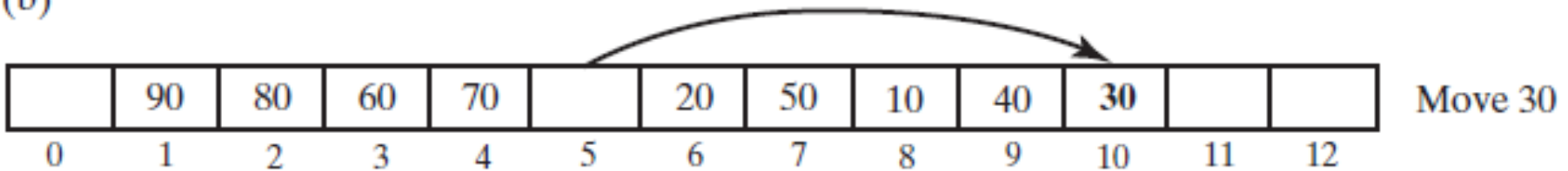
FIGURE 26-3 A revision of the steps shown in Figure 26-2, to avoid swaps

Adding an Entry

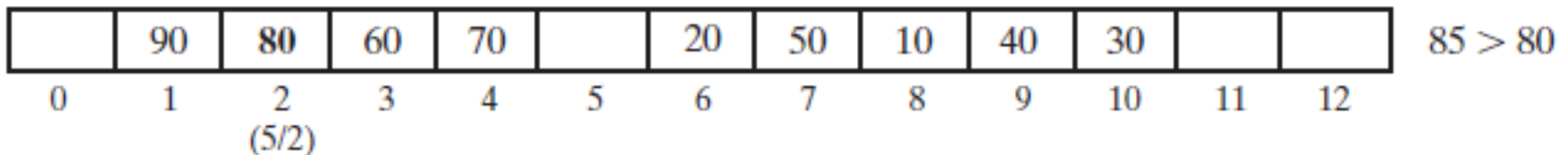
(a)



(b)



(c)



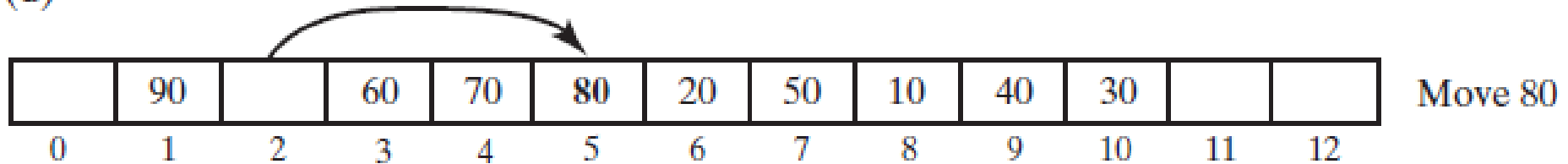
(d)

FIGURE 26-4 An array representation of the steps in Figure 26-3

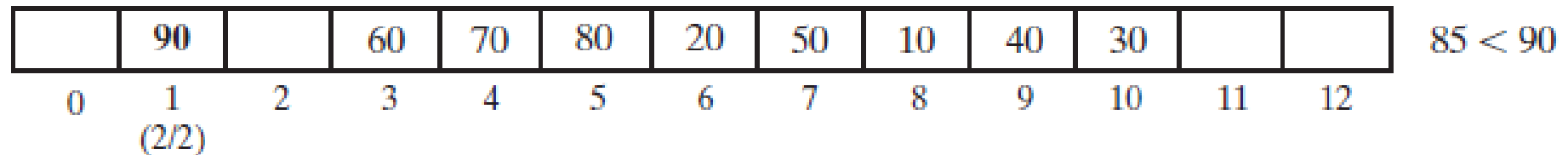
Adding an Entry

(5/2)

(d)



(e)



(f)

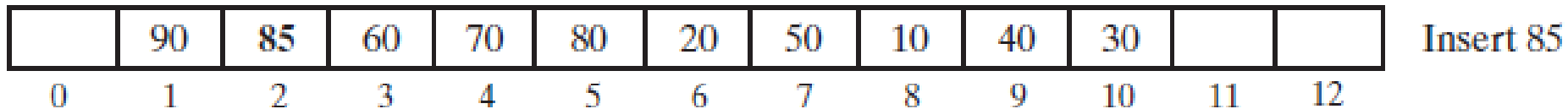


FIGURE 26-4 An array representation of the steps in Figure 26-3

Adding an Entry

Algorithm add(newEntry)

// Precondition: The array heap has room for another entry.

newIndex = *index of next available array location*

parentIndex = newIndex/2 *// Index of parent of available location*

while (parentIndex > 0 and newEntry > heap[parentIndex])

{

 heap[newIndex] = heap[parentIndex] *// Move parent to available location*

// Update indices

 newIndex = parentIndex

 parentIndex = newIndex/2

}

heap[newIndex] = newEntry

// Place new entry in correct location

if (the array heap is full)

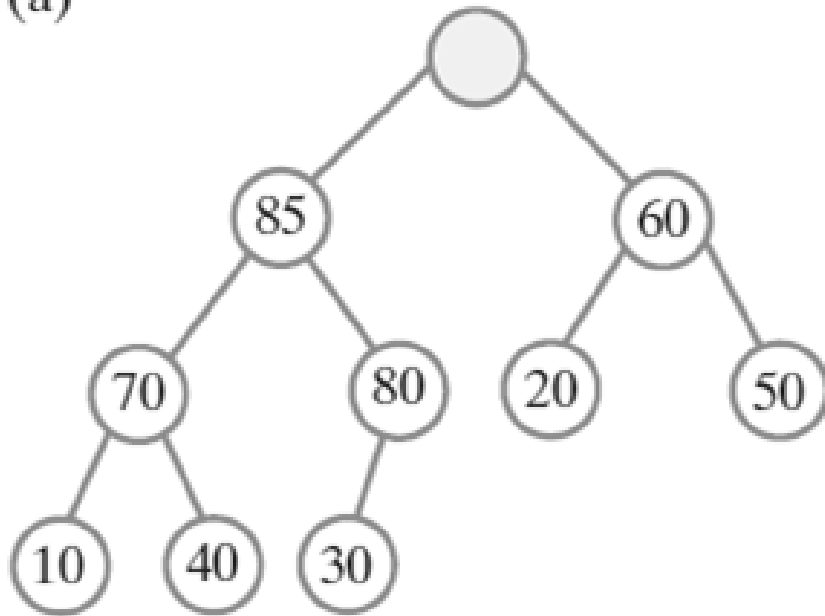
Double the size of the array

Adding an Entry

```
public void add(T newEntry)
{
    checkInitialization();           // Ensure initialization of data fields
    int newIndex = lastIndex + 1;
    int parentIndex = newIndex / 2;
    while ( (parentIndex > 0) && newEntry.compareTo(heap[parentIndex]) > 0)
    {
        heap[newIndex] = heap[parentIndex];
        newIndex = parentIndex;
        parentIndex = newIndex / 2;
    } // end while
    heap[newIndex] = newEntry;
    lastIndex++;
    ensureCapacity();
} // end add
```

Removing the Root

(a)



(b)

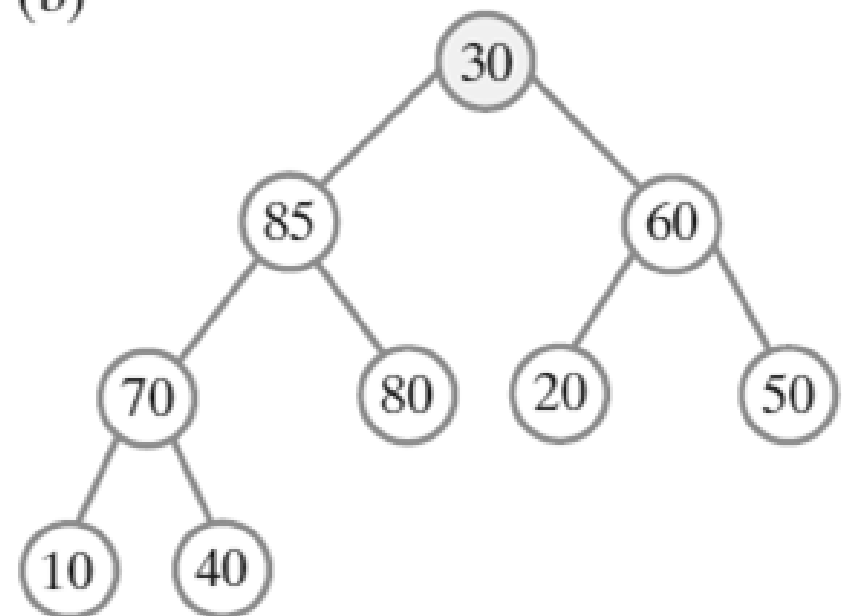
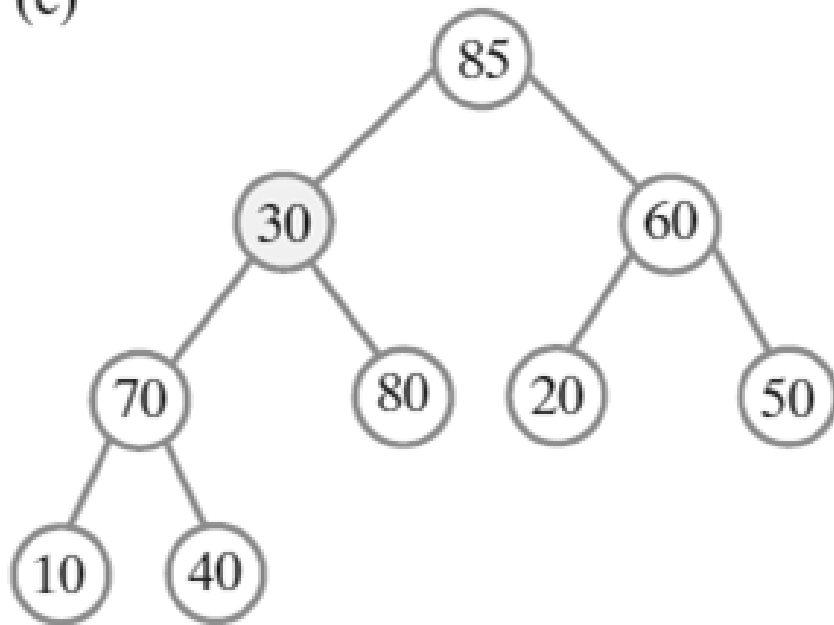


FIGURE 26-5 The steps to remove the entry in the root of the maxheap in Figure 26-3d

Removing the Root

(c)



(d)

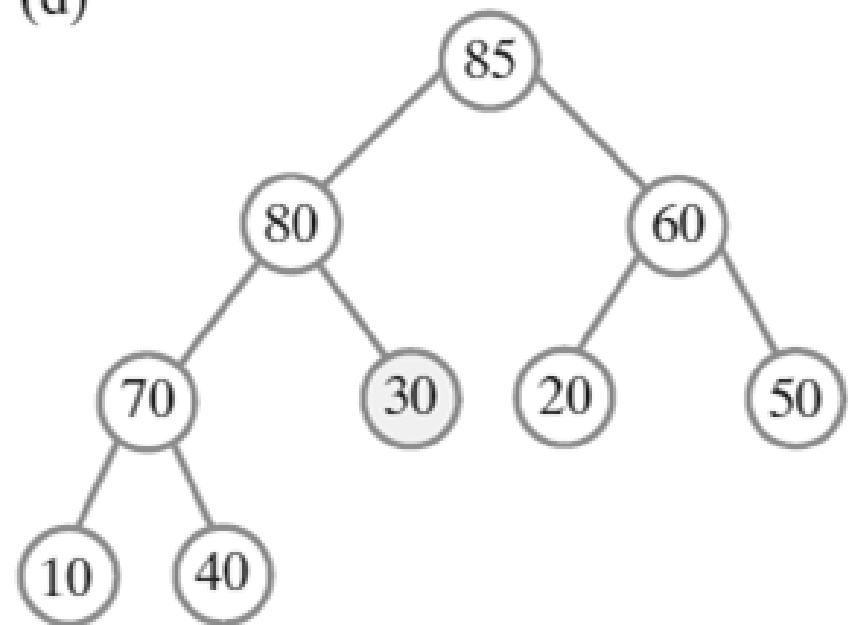


FIGURE 26-5 The steps to remove the entry in the root of the maxheap in Figure 26-3d

Removing the Root

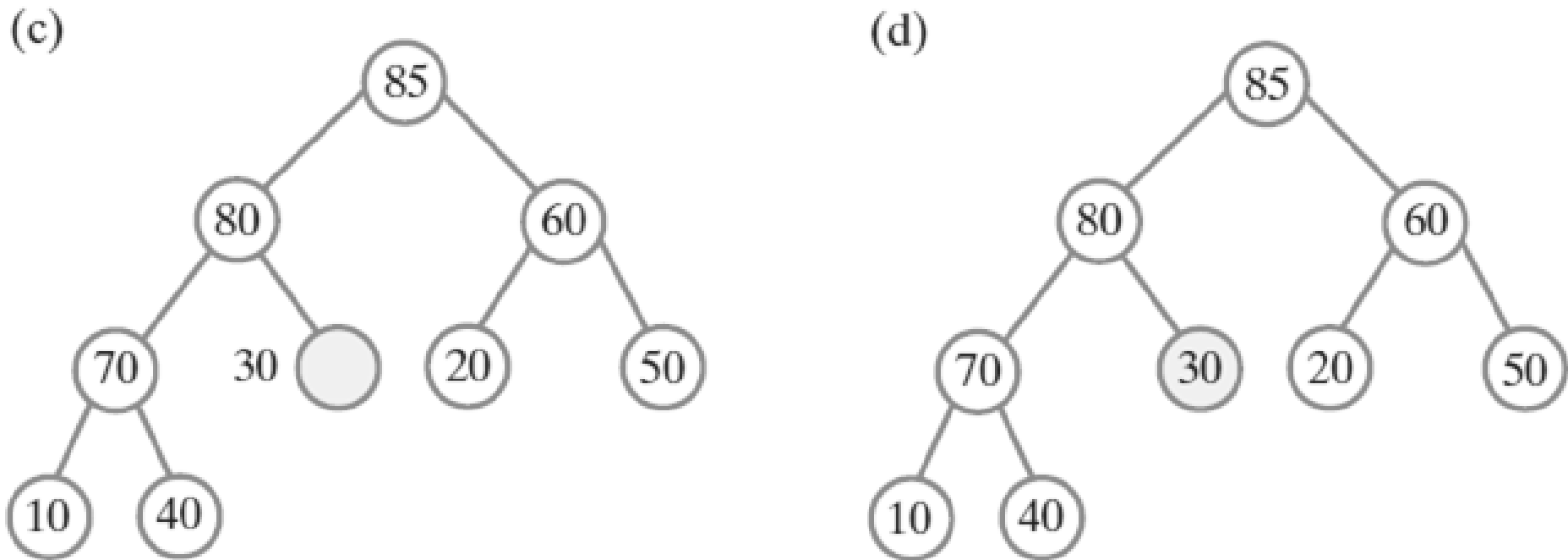


FIGURE 26-6 The steps that transform a semiheap into a heap without swaps

Removing the Root

Algorithm reheap(rootIndex)

// Transforms the semiheap rooted at rootIndex into a heap

done = false

orphan = heap[rootIndex]

while (!done *and* heap[rootIndex] *has a child*)

{

 largerChildIndex = *index of the larger child of* heap[rootIndex]

 if (orphan < heap[largerChildIndex])

 {

 heap[rootIndex] = heap[largerChildIndex]

 rootIndex = largerChildIndex

 }

 else

 done = true

}

heap[rootIndex] = orphan

Algorithm to transform a semiheap to a heap

Removing the Root

```
public T removeMax()
{
    checkInitialization();           // Ensure initialization of data fields
    T root = null;
    if (!isEmpty())
    {
        root = heap[1];              // Return value
        heap[1] = heap[lastIndex];  // Form a semiheap
        lastIndex--;                 // Decrease size
        reheap(1);                   // Transform to a heap
    } // end if
    return root;
} // end removeMax
```

Removing the Root

```
private void reheap(int rootIndex)
{
    boolean done = false;
    T orphan = heap[rootIndex];
    int leftChildIndex = 2 * rootIndex;
    while (!done && (leftChildIndex <= lastIndex) )
    {
        int largerChildIndex = leftChildIndex; // Assume larger
        int rightChildIndex = leftChildIndex + 1;
        if ( (rightChildIndex <= lastIndex) &&
            heap[rightChildIndex].compareTo(heap[largerChildIndex]) > 0)
        {
            largerChildIndex = rightChildIndex;
        } // end if
        if (orphan.compareTo(heap[largerChildIndex]) < 0)
```

Implementation of the **reheap** algorithm
as a private method

Removing the Root

```
} // end if  
if (orphan.compareTo(heap[largerChildIndex]) < 0)  
{  
    heap[rootIndex] = heap[largerChildIndex];  
    rootIndex = largerChildIndex;  
    leftChildIndex = 2 * rootIndex;  
}  
else  
    done = true;  
} // end while  
heap[rootIndex] = orphan;  
} // end reheap
```

Implementation of the **reheap** algorithm
as a private method

Creating a Heap

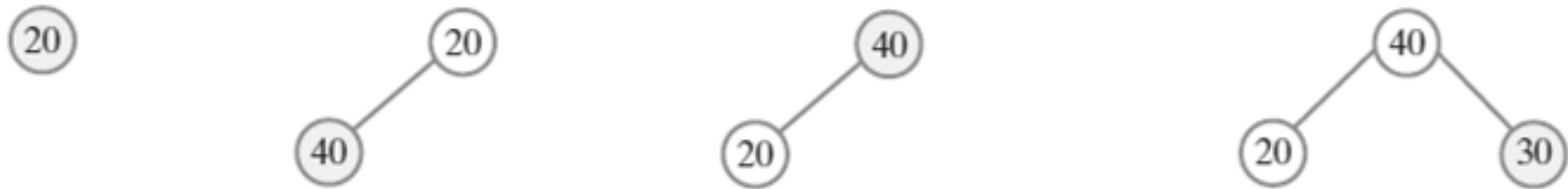


FIGURE 26-7 The steps in adding 20, 40, 30, 10, 90, and 70 to an initially empty heap

Creating a Heap

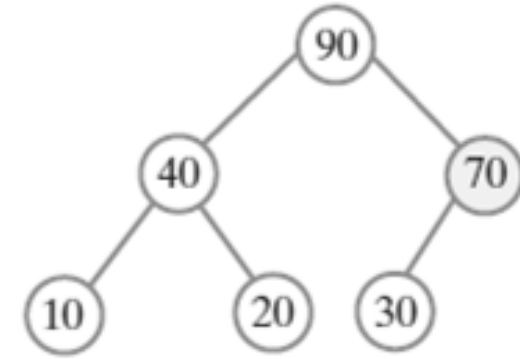
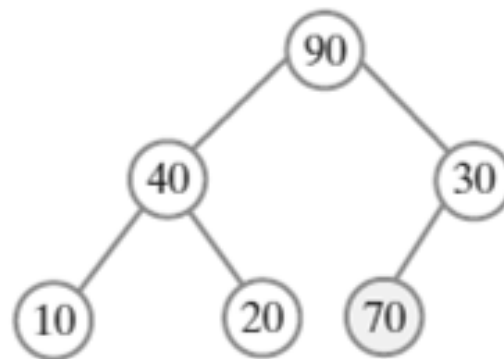
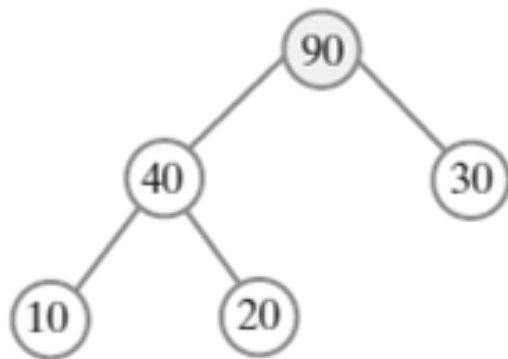
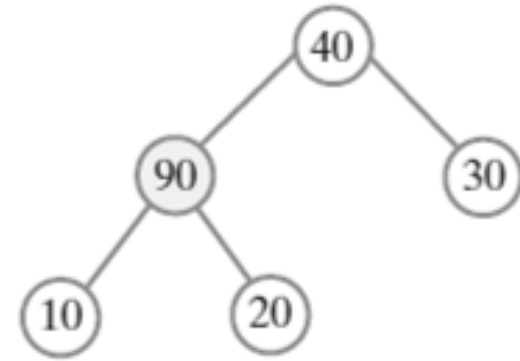
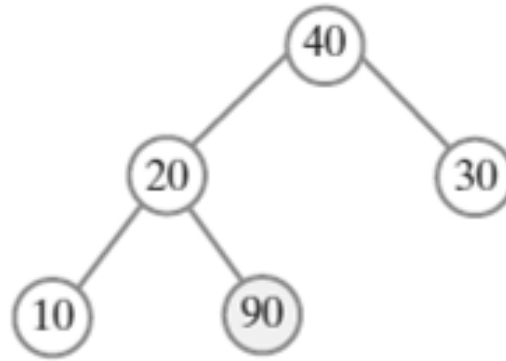
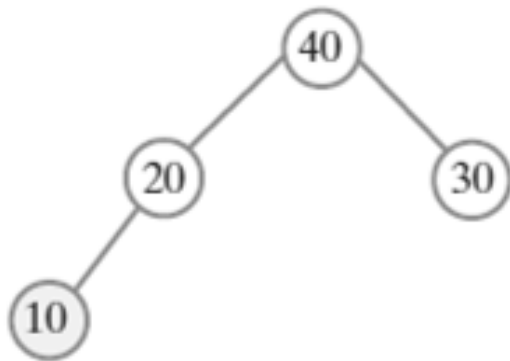
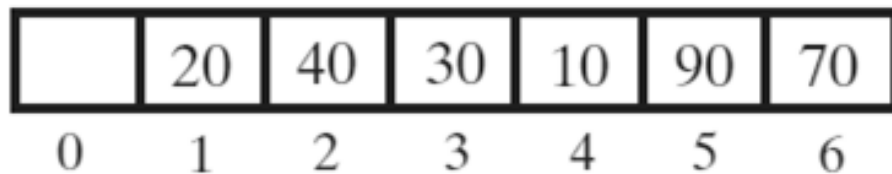


FIGURE 26-7 The steps in adding 20, 40, 30, 10, 90, and 70 to an initially empty heap

Creating a Heap

(a) An array of entries



(b) The complete tree that the array represents

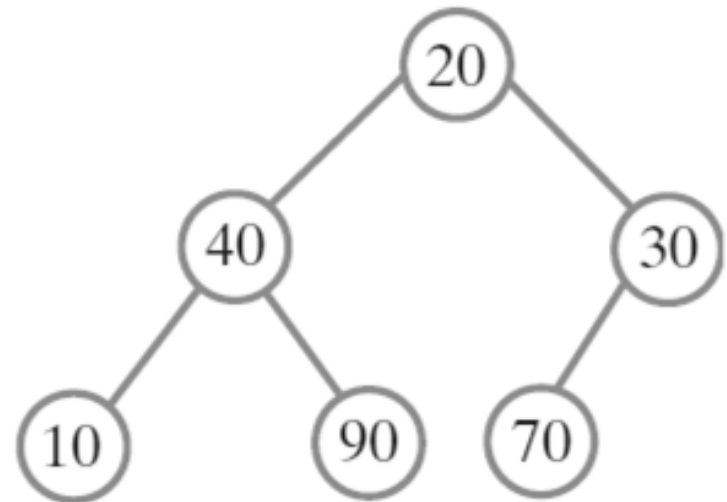
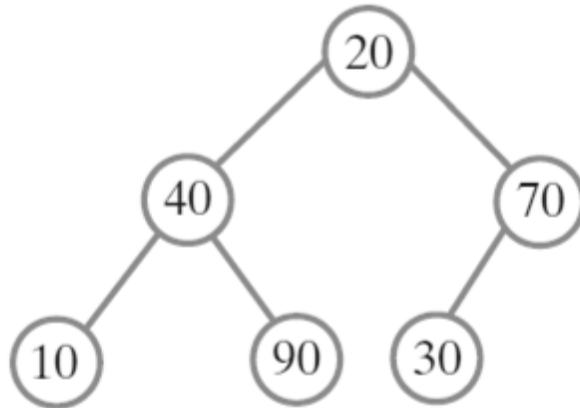
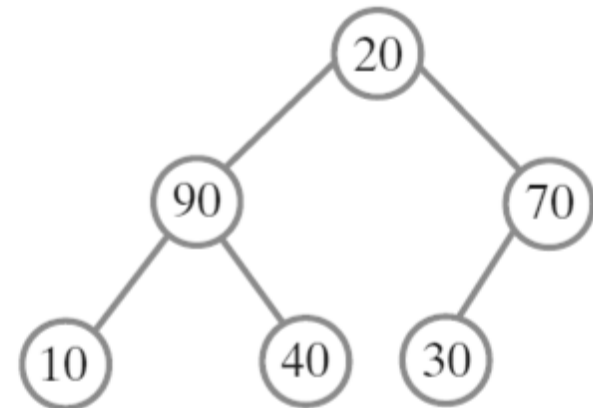


FIGURE 26-8 The steps in creating a heap of the entries 20, 40, 30, 10, 90, and 70 by using **reheap**

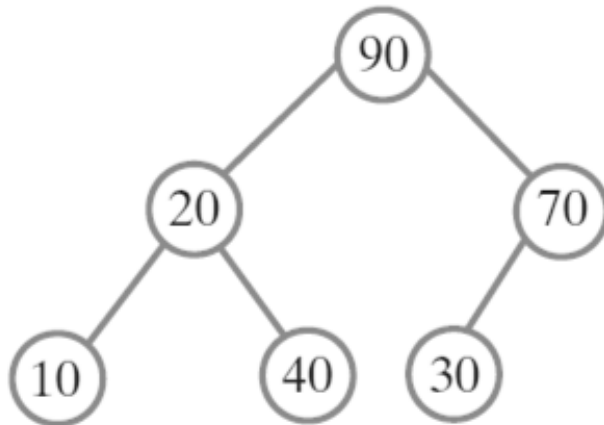
(c) After reheap(3)



(d) After reheap(2)



(e) During reheap(1)



(f) After reheap(1)

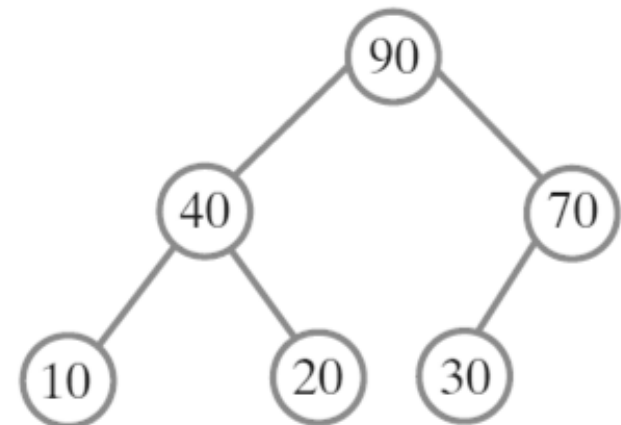


FIGURE 26-8 The steps in creating a heap of the entries 20, 40, 30, 10, 90, and 70 by using **reheap**

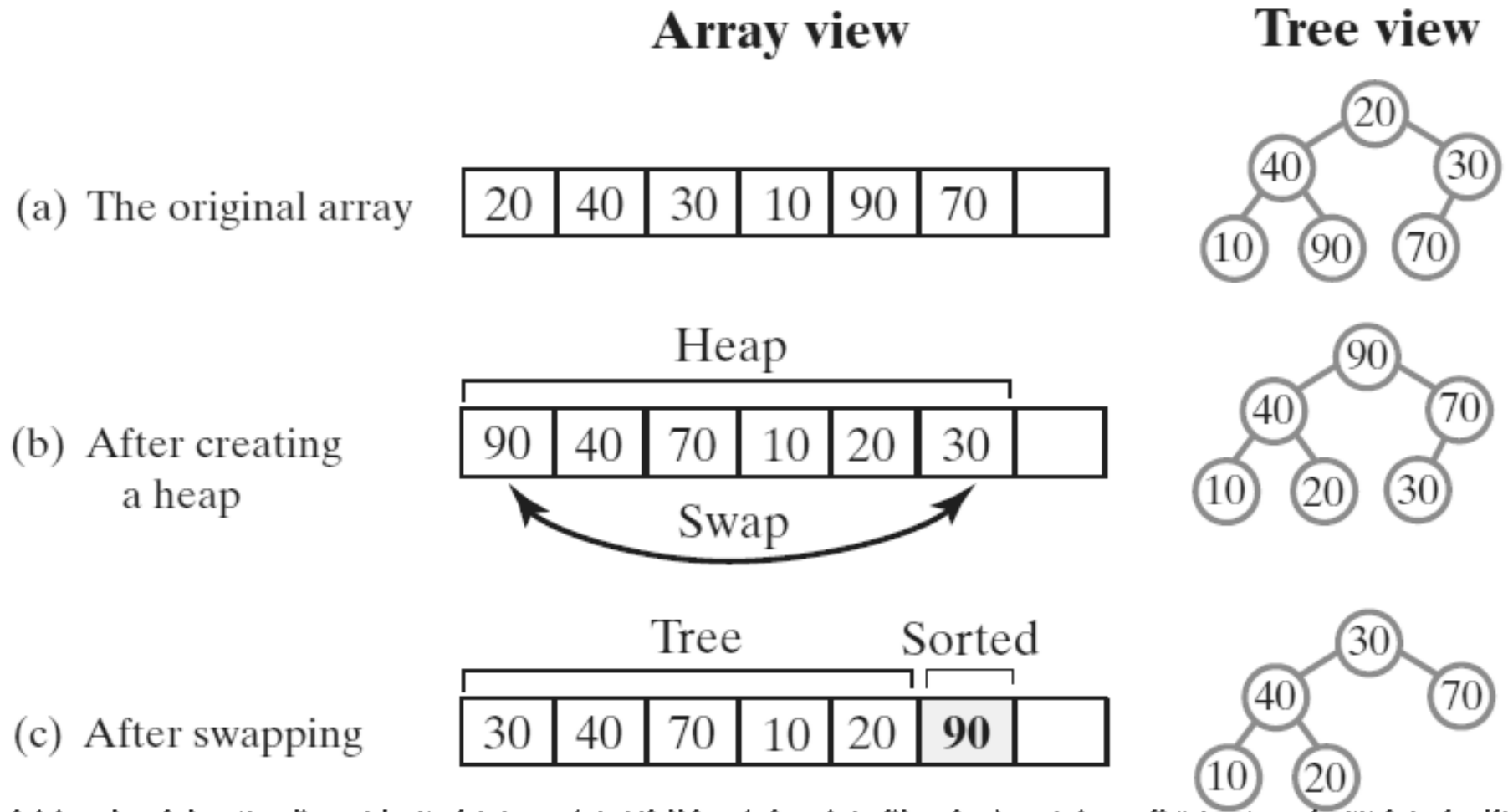
Creating a Heap

```
public MaxHeap(T[] entries)
{
    this(entries.length); // Call other constructor
    assert initialized = true;

    // Copy given array to data field
    for (int index = 0; index < entries.length; index++)
        heap[index + 1] = entries[index];

    // Create heap
    for (int rootIndex = lastIndex / 2; rootIndex > 0; rootIndex--)
        reheap(rootIndex);
} // end constructor
```

Heap Sort



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FIGURE 26-9 A trace of heap sort

Heap Sort

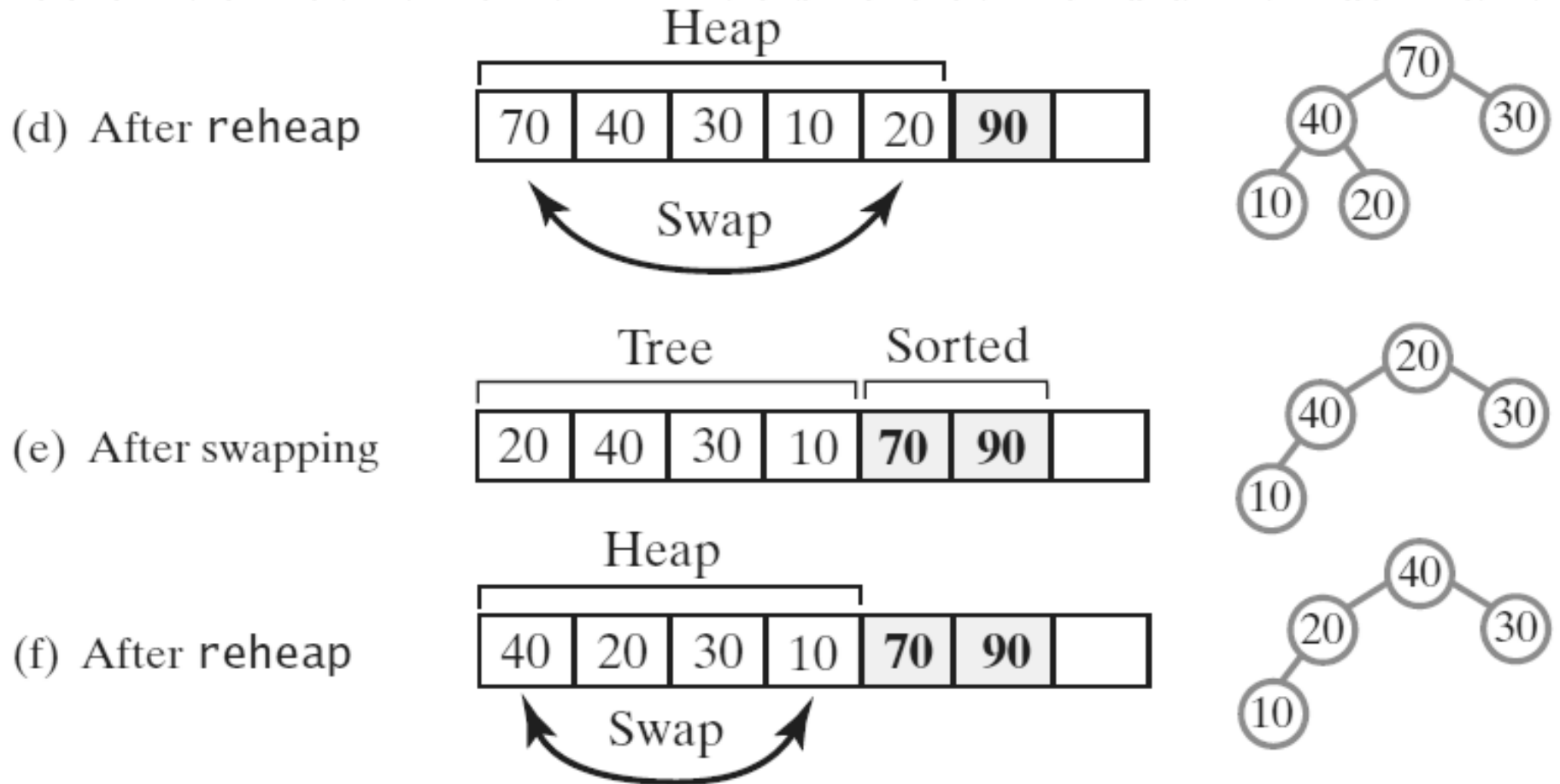


FIGURE 26-9 A trace of heap sort

Heap Sort

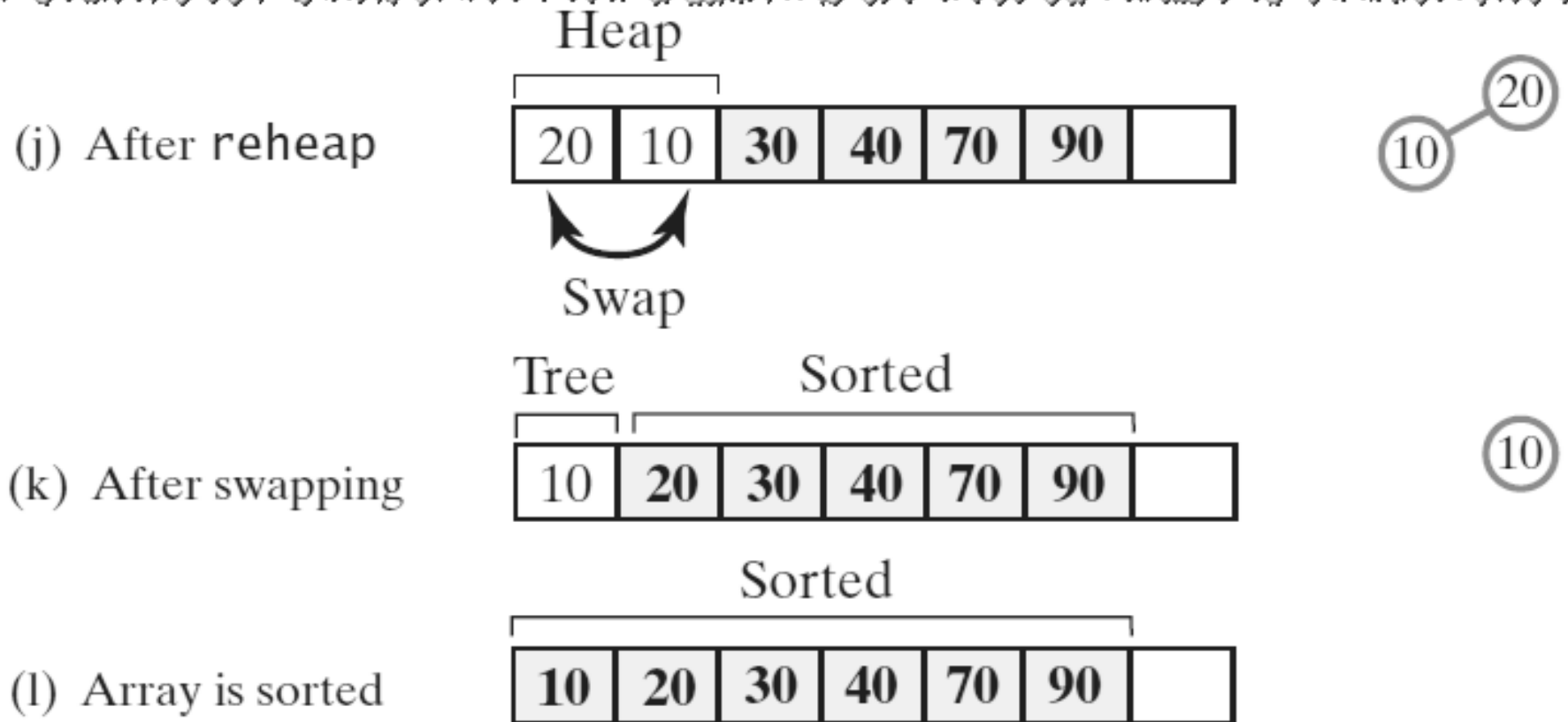


FIGURE 26-9 A trace of heap sort

Heap Sort

```
public static <T extends Comparable<? super T>> void heapSort(T[] array, int n)
{
    // Create first heap
    for (int rootIndex = n / 2 - 1; rootIndex >= 0; rootIndex--)
        reheap(array, rootIndex, n - 1);
    swap(array, 0, n - 1);
    for (int lastIndex = n - 2; lastIndex > 0; lastIndex--)
    {
        reheap(array, 0, lastIndex);
        swap(array, 0, lastIndex);
    } // end for
} // end heapSort
```

The **heapSort** method
Time efficiency is $O(n \log n)$

Heap Sort

```
private static <T extends Comparable<? super T>>
    void reheap(T[] heap, int rootIndex, int lastIndex)
{
    boolean done = false;
    T orphan = heap[rootIndex];
    int leftChildIndex = 2 * rootIndex + 1;

    while (!done && (leftChildIndex <= lastIndex))
    {
        int largerChildIndex = leftChildIndex;
        int rightChildIndex = leftChildIndex + 1;
        if ( (rightChildIndex <= lastIndex) &&
            heap[rightChildIndex].compareTo(heap[largerChildIndex]) > 0)
        {
            largerChildIndex = rightChildIndex;
        } // end if
    }
}
```

Heap Sort

```
        heap[rightChildIndex].compareTo(heap[largerChildIndex]) > 0)
    {
        largerChildIndex = rightChildIndex;
    } // end if

    if (orphan.compareTo(heap[largerChildIndex]) < 0)
    {
        heap[rootIndex] = heap[largerChildIndex];
        rootIndex = largerChildIndex;
        leftChildIndex = 2 * rootIndex + 1;
    }
    else
        done = true;
} // end while

heap[rootIndex] = orphan;
} // end reheap
```

End

Chapter 26