# CENG 216 - NUMERICAL COMPUTATION

# SOLVING EQUATIONS

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### **SLIDE CREDITS**

Slides are based on material from the main textbook:

"Numerical Analysis", The new international edition, 2ed, by Timothy Sauer

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# Introduction

$$f(x) = g(x) \to f(x) - g(x) = 0$$

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  - · As opposed to analytic (closed-form) solution
  - · Computer Algebra Systems (CAS)

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  - · Complexity: Evaluation of  $f(x_i)$  and possibly  $f'(x_i), f''(x_i), \dots$

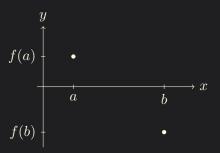
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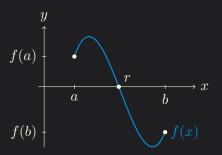
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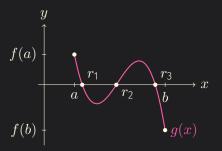
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· Search in an address book

• Search in an address book  $\rightarrow$  Binary Search

end

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$$\frac{(b-a)}{2} > TOL$$
 do  $c = \frac{(a+b)}{2}$ 

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while \frac{(b-a)}{2} > TOL do
    c = \frac{(a+b)}{2}
    if f(c) = 0 then
         stop
    end
```

end

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$$\begin{array}{l} \text{while } \frac{(b-a)}{2} > \textit{TOL} \, \operatorname{do} \\ & c = \frac{(a+b)}{2} \\ & \text{if } f(c) = 0 \text{ then} \\ & | \, \operatorname{stop} \\ & \text{end} \\ & \text{if } f(a)f(c) < 0 \text{ then} \\ & | \, b = c \\ & | \, a = c \\ & | \, \text{end} \\ & \text{end} \\ & \text{end} \end{array}$$

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while \frac{(b-a)}{2} > TOL do
   c = \frac{(a+b)}{2}
   if f(c) = 0 then
       stop
    end
    if f(a)f(c) < 0 then
    b = c
    else
     a = c
    end
```

### end

The final interval [a, b] contains the root, which is approximately at  $\frac{a+b}{2}$ .

a	f(a)	b	f(b)	c	f(c)	(b - a)/2

i	a	f(a)	b	f(b)	c	f(c)	(b - a)/2
0	0.00000	-1.00000	1.00000	1.00000	0.50000	-0.37500	0.50000

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0	0.00000	-1.00000	1.00000	1.00000	0.50000	-0.37500	0.50000
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1	0.50000	-0.37500	1.00000	1.00000	0.75000	0.17187	0.25000
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2	0.50000	-0.37500	0.75000	0.17187		-0.13086	0.12500
3		-0.13086	0.75000	0.17187	0.68750	0.01245	0.06250

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2	0.50000	-0.37500	0.75000	0.17187	0.62500	-0.13086	0.12500
3	0.62500	-0.13086	0.75000	0.17187	0.68750	0.01245	0.06250
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4	0.62500	-0.13086	0.68750	0.01245	0.65625	-0.06113	0.03125
5	0.65625	-0.06113	0.68750	0.01245		-0.02483	0.01562
6		-0.02483	0.68750	0.01245	0.67969	-0.00631	0.00781

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6	0.67187	-0.02483	0.68750	0.01245		-0.00631	0.00781
7		-0.00631	0.68750	0.01245	0.68359	0.00304	0.00391

Find the root of the function  $f(x) = x^3 + x - 1$  in [0,1].

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5	0.65625	-0.06113	0.68750	0.01245	0.67187	-0.02483	0.01562
6	0.67187	-0.02483	0.68750	0.01245	0.67969	-0.00631	0.00781
7	0.67969	-0.00631	0.68750	0.01245		0.00304	0.00391
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5	0.65625	-0.06113	0.68750	0.01245	0.67187	-0.02483	0.01562
6	0.67187	-0.02483	0.68750	0.01245	0.67969	-0.00631	0.00781
7	0.67969	-0.00631	0.68750	0.01245	0.68359	0.00304	0.00391
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$$r_c = 0.682617$$
, max. error =  $\pm 0.000977$ 

Reminder: Absolute Error =  $|x_c - r|$ , where  $x_c$  is the computed root.

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- At i=n: Absolute Error  $< \frac{b-a}{2^{n+1}}$
- Number of required function evaluations is n + 2.
- **Def:** A solution is correct to p decimal places if the error is less than  $0.5 \cdot 10^{-p}$ .

$$\frac{1}{2^{n+1}} < 0.5 \cdot 10^{-6}$$

$$\frac{1}{2^{n+1}} < 0.5 \cdot 10^{-6} \to n > \frac{6}{\log_{10} 2}$$

$$\frac{1}{2^{n+1}} < 0.5 \cdot 10^{-6} \to n > \frac{6}{\log_{10} 2} \approx \frac{6}{0.301} \approx 19.9$$

Find the number of iterations of the bisection method required to compute a root of the function  $f(x) = \cos x - x$  in [0,1] to six correct decimal places.

$$\frac{1}{2^{n+1}} < 0.5 \cdot 10^{-6} \to n > \frac{6}{\log_{10} 2} \approx \frac{6}{0.301} \approx 19.9$$

Take n = 20.

# FIXED POINT ITERATIONS

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- Fixed point iterations:

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$$y = \sqrt[3]{1.0 - y} = q(y)$$

$$0 = z^{3} + z - 1.0$$

$$z = 1 - z^{3}$$

$$3z^{3} + z = 1 + 2z^{3}$$

$$(3z^{2} + 1)z = 1 + 2z^{3}$$

$$z = \frac{1 + 2z^{3}}{3z^{2} + 1} = r(z)$$

i	$x_i = p(x_{i-1})$	$y_i = q(y_{i-1})$	$z_i = r(z_{i-1})$
0	0.50000000	0.50000000	0.50000000

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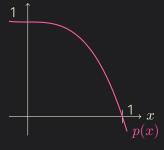
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6	0.00337606	0.65900615	0.68232780
7	0.99999996	0.69863261	0.68232780

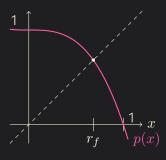
i	$x_i = p(x_{i-1})$	$y_i = q(y_{i-1})$	$z_i = r(z_{i-1})$
0	0.50000000	0.50000000	0.50000000
1	0.87500000	0.79370053	0.71428571
2	0.33007813	0.59088011	0.68317972
3	0.96403747	0.74236393	0.68232842
4	0.10405419	0.63631020	0.68232780
5	0.99887338	0.71380081	0.68232780
6	0.00337606	0.65900615	0.68232780
7	0.99999996	0.69863261	0.68232780
8	0.00000012	0.67044850	0.68232780

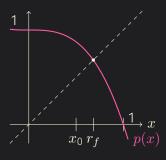
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9	1.00000000	0.69072912	0.68232780
10	0.00000000	0.67625892	0.68232780
11	1.00000000	0.68664554	0.68232780
12	0.00000000	0.67922234	0.68232780

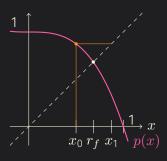
## **ROOT FINDING EXAMPLE**

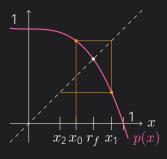
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12	0.00000000	0.67922234	0.68232780
24	0.00000000	0.68227157	0.68232780
25	1.00000000	0.68236807	0.68232780

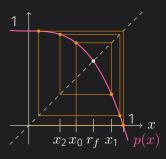


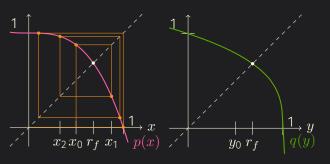


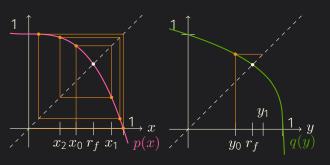


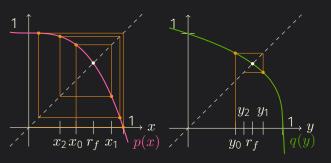


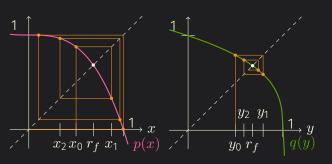


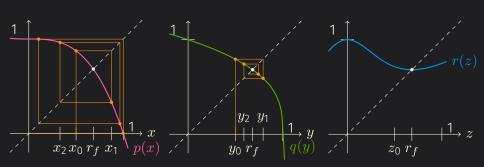


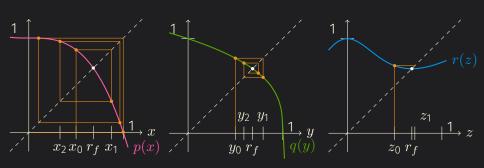


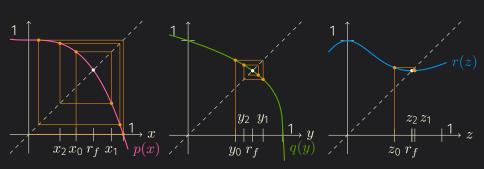


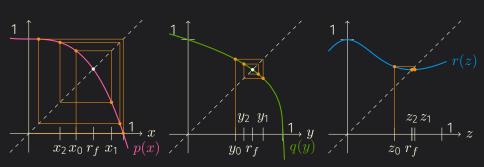












#### LINEAR CONVERGENCE OF FIXED POINT ITERATIONS

• **Def:** Let  $e_i = |x_i - r|$  be the error at step i. If

$$\lim_{i \to \infty} \frac{e_{i+1}}{e_i} = s < 1$$

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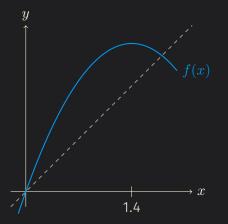
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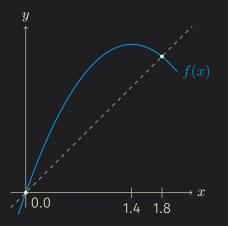
$$f(x) = \cos x, f'(x) = -\sin x, f'(0.739085133215) \approx -0.67.$$

Find the fixed points of  $2.8x - x^2 = f(x)$ .

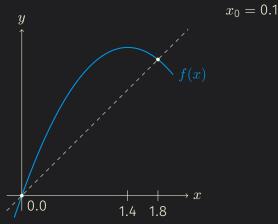
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Find the fixed points of  $2.8x - \overline{x^2 = f(x)}$ .

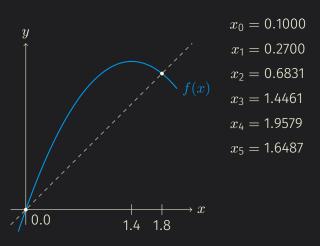


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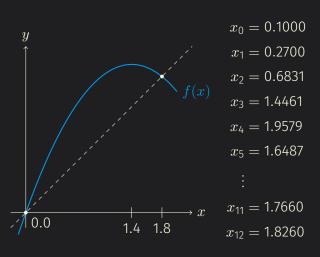


 $x_0 = 0.1000$ 

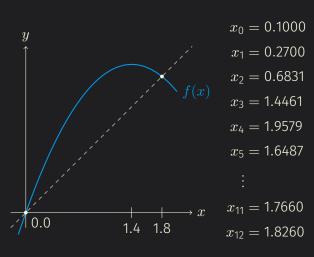
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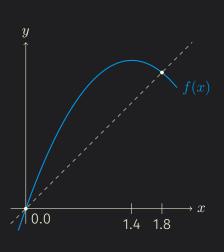


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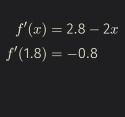
f'(x) = 2.8 - 2x

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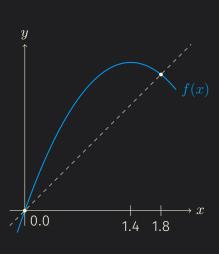


$$x_0 = 0.1000$$
  
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 $x_2 = 0.6831$   
 $x_3 = 1.4461$   
 $x_4 = 1.9579$   
 $x_5 = 1.6487$   
 $\vdots$   
 $x_{11} = 1.7660$ 

 $\overline{x_{12}} = 1.8260$ 

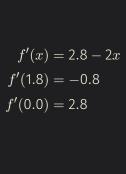


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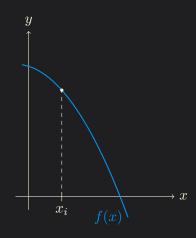
$$\begin{aligned} |x_{i+1} - x_i| &< \textit{TOL} \\ \frac{|x_{i+1} - x_i|}{|x_{i+1}|} &< \textit{TOL} \end{aligned}$$

#### STOPPING CRITERIA

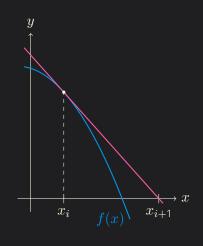
$$\begin{aligned} |x_{i+1}-x_i| &< TOL \\ \frac{|x_{i+1}-x_i|}{|x_{i+1}|} &< TOL \\ \frac{|x_{i+1}-x_i|}{\max\left(|x_{i+1}|,\theta\right)} &< TOL, \text{ with } \theta > 0.0 \end{aligned}$$

**NEWTON'S METHOD** 

## Newton-Raphson Approach

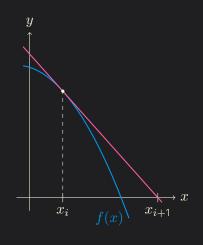


## **NEWTON-RAPHSON APPROACH**



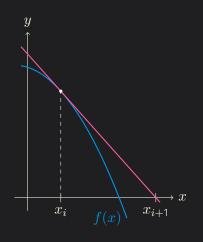
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#### **NEWTON-RAPHSON APPROACH**



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Alternatively,

$$0=f\overbrace{(x_i+\Delta x_i)}^{x_{i+1}}$$
 $0=f(x_i)+\Delta x_if'(x_i)+ ext{H.O.T}$ 
 $\Delta x_ipprox -rac{f(x_i)}{f'(x_i)}$ 

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$$x_{0} = -0.7$$

$$x_{1} = 0.12712551$$

$$\vdots$$

$$x_{6} = 0.68232780$$

$$x_{7} = 0.68232780$$

# QUADRATIC CONCERGENCE OF NEWTON'S METHOD

• Def: Iterations are quadratically convergent if

$$M = \lim_{i \to \infty} \frac{e_{i+1}}{e_i^2} < \infty$$

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- If f'(r) = 0, which happens in case of double roots, convergence is linear. See Modified Newton's Method in the textbook.

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Apply Newton's Method to  $f(x)=4x^4-6x^2-\frac{11}{4}$  starting at  $x_0=\frac{1}{2}$ 

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#### **EXAMPLE OF NON-CONVERGENCE**

Apply Newton's Method to 
$$f(x)=4x^4-6x^2-\frac{11}{4}$$
 starting at  $x_0=\frac12$  
$$x_{i+1}=x_i-\frac{4x_i^4-6x_i^2-\frac{11}{4}}{16x_i^3-12x_i}$$
 
$$x_1=-\frac12 \text{ and } x_2=\frac12$$

# **LIMITS OF ACCURACY**

Use Bisection Method to find the root of  $f(x)=x^3-2x^2+\frac{4}{3}-\frac{8}{27}$  to within six correct digits.

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Due to rounding errors f(0.6666641)=0 so Bisection terminates with r=0.6666641 which is close in y but not in x.

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 $x_a = 0.6666641 \rightarrow \text{backward error} \approx \epsilon_{\text{mach}}, \text{ forward error} \approx 10^{-5}.$ 

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$$W(x) = (x - 1)(x - 2) \cdots (x - 20)$$
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$$x_0 = 16.0$$

$$x_a = 16.01468\dots$$

$$r \to f(x) = 0$$
 
$$r + \Delta r \to f(x) + \epsilon g(x) = 0$$

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$$\Delta r \approx \frac{-\epsilon g(r)}{f'(r) + \epsilon g'(r)} \approx -\epsilon \frac{g(r)}{f'(r)} \quad \epsilon \ll f'(r), f'(r) \neq 0$$

$$P(x) = (x-1)(x-2)(x-3)(x-4)(x-5)(x-6) - 10^{-6}x^{7}.$$

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Largest root of  $f(x) = 6$ .

$$\Delta r \approx -\frac{\epsilon 6'}{5!} = -2332.6\epsilon \implies r + \Delta r = 6.0023328$$

$$error magnification factor = \frac{relative forward error}{relative backward error}$$

· Def:

error magnification factor 
$$= \frac{\text{relative forward error}}{\text{relative backward error}}$$
  
 $= \left| \frac{\Delta r/r}{\epsilon g(r)/g(r)} \right| = \frac{|g(r)|}{|rf'(r)|}$ 

 Def: Condition number is the maximum error magnification factor over all input changes.

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- We will revisit conditioning for different numerical problems throughout the course.

- A ball throwing robot arm throws a ball with initial velocity  $V_0$  at an angle  $\theta$  from the ground. Assuming that the robot arm is at x=0, the ball will hit the ground at  $x_f=\frac{V_0^2\sin2\theta}{g}$ , where  $g=9.8~\mathrm{m/s^2}$  is the gravitational constant.

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- The robot design constrains the speed to be  $V_0=k(1+\cos\theta)$ , where k=0.75 is a design parameter.
- Solve for  $\theta$  in the interval  $[0^{\circ}, 40^{\circ}]$  and calculate the required  $V_0$ .

· Writing  $V_0 = k(\mathbf{1} + \cos \theta)$  into the equation for  $x_f$ , we have

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- After 20 iterations  $\theta \approx$  28.53°,  $f(\theta) \approx$  6.76 · 10<sup>-8</sup>, and  $V_0 \approx$  1.41 m/s.