CENG 216 - NUMERICAL COMPUTATION

LEAST SQUARES - PART II

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SLIDE CREDITS

Slides are based on material from the main textbook:

"Numerical Analysis", The new international edition, 2ed, by Timothy Sauer

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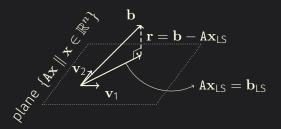
PREVIOUSLY ON CENG 216

Inconsistent Systems and the Normal Equations

 $\mathtt{A}\mathbf{x}=\mathbf{b}$ with no solutions \rightarrow Equations are inconsistent.

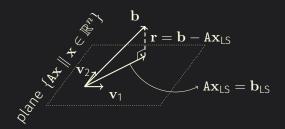
INCONSISTENT SYSTEMS AND THE NORMAL EQUATIONS

 $\mathbf{A}\mathbf{x} = \mathbf{b}$ with no solutions \rightarrow Equations are inconsistent.



INCONSISTENT SYSTEMS AND THE NORMAL EQUATIONS

 $\mathbf{A}\mathbf{x} = \mathbf{b}$ with no solutions \rightarrow Equations are inconsistent.



$$(\mathbf{b} - \mathtt{A}\mathbf{x}_{\mathsf{LS}}) \perp \{\mathtt{A}\mathbf{x} \parallel \mathbf{x} \in \mathbb{R}^n\} \implies \mathtt{A}^{\top}\mathtt{A}\mathbf{x}_{\mathsf{LS}} = \mathtt{A}^{\top}\mathbf{b} \quad \text{(Normal Equations)}$$

SUMMARY OF REDUCED QR FACTORIZATION WITH GRAM-SCHMIDT

Input:
$$\mathbf{A}_{m \times n} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix}$$
 with linearly independent columns.

$$\begin{array}{c|c} \text{for } j \leftarrow 1 \text{ to } n \text{ do} \\ & \mathbf{y} = \mathbf{a}_j \\ & \text{for } i \leftarrow 1 \text{ to } j - 1 \\ & \text{do} \\ & \mid r_{ij} = \mathbf{q}_i^\top \mathbf{a}_j \\ & \mid \mathbf{y} = \mathbf{y} - r_{ij} \mathbf{q}_i \\ & \text{end} \\ & r_{jj} = \|\mathbf{y}\| \\ & \mathbf{q}_j = \frac{\mathbf{y}}{r_{jj}} \\ & \text{end} \end{array}$$

Output: $Q_{m\times n}$ and $R_{n\times n}$ such that

$$\mathbf{A}_{m \times n} = \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 & \dots & \mathbf{q}_n \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & \dots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & r_{nn} \end{bmatrix}$$
$$= \mathbf{Q}_{m \times n} \mathbf{R}_{n \times n}$$

Modified Gram-Schmidt

Modified Gram-Schmidt Algorithm

Input:
$$\mathbf{A}_{m \times n} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix}$$
 with linearly independent columns.

Classical Gram-Schmidt:

$$\begin{array}{c|c} \text{for } j \leftarrow 1 \text{ to } n \text{ do} \\ \mathbf{y} = \mathbf{a}_j \\ \text{for } i \leftarrow 1 \text{ to } j - 1 \text{ do} \\ & r_{ij} = \mathbf{q}_i^\top \mathbf{a}_j \\ & \mathbf{y} = \mathbf{y} - r_{ij} \mathbf{q}_i \\ \text{end} \\ & r_{jj} = \|\mathbf{y}\| \\ & \mathbf{q}_j = \frac{\mathbf{y}}{r_{jj}} \\ \text{end} \end{array}$$

Modified Gram-Schmidt:

for
$$j \leftarrow 1$$
 to n do $\mathbf{y} = \mathbf{a}_j$ for $i \leftarrow 1$ to $j - 1$ do $r_{ij} = \mathbf{q}_i^{\top} \mathbf{y}$ $\mathbf{y} = \mathbf{y} - r_{ij} \mathbf{q}_i$ end $r_{jj} = \|\mathbf{y}\|$ $\mathbf{q}_j = \frac{\mathbf{y}}{r_{jj}}$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix} \text{ with } \delta = 10^{-10}.$$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta = 10^{-10}$.

to
$$\begin{bmatrix} \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with δ

$$\mathbf{y}_1 = \mathbf{a}_1 = egin{bmatrix} 1 \ \delta \ 0 \ 0 \end{bmatrix}$$

Apply classical Gram-Schmidt to $\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$ with $\delta = 10^{-10}$.

$$\mathbf{y}_1 = \mathbf{a}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} \implies \mathbf{q}_1 = \frac{1}{\underbrace{\sqrt{1 + \delta^2}}_{\approx 1 \text{ since } \delta^2 = 10^{-20}}} \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}$$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta = 10^{-10}$.

$$\mathbf{q}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix},$$

$$\mathbf{y}_2 = \begin{bmatrix} 1 \\ 0 \\ \delta \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} \mathbf{q}_1^{\mathsf{T}} \mathbf{a}_2 = \begin{bmatrix} 0 \\ -\delta \\ \delta \\ 0 \end{bmatrix}$$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta=10^{-10}$.

$$\mathbf{q}_{1} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix},$$

$$\mathbf{y}_{2} = \begin{bmatrix} 1 \\ 0 \\ \delta \\ 0 \end{bmatrix} - \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} \underbrace{\mathbf{q}_{1}^{\top} \mathbf{a}_{2}}_{1} = \begin{bmatrix} 0 \\ -\delta \\ \delta \\ 0 \end{bmatrix} \implies \mathbf{q}_{2} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$$

Apply classical Gram-Schmidt to $\begin{vmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{vmatrix}$ with $\delta = 10^{-10}$.

$$\mathbf{q}_{1} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_{2} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix},$$

$$\mathbf{y}_{3} = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \delta \end{bmatrix} - \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} \underbrace{\mathbf{q}_{1}^{\top} \mathbf{a}_{3}}_{1} - \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \underbrace{\mathbf{q}_{2}^{\top} \mathbf{a}_{3}}_{0} = \begin{bmatrix} 0 \\ -\delta \\ 0 \\ \delta \end{bmatrix}$$

Apply classical Gram-Schmidt to $\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$ with $\delta = 10^{-10}$.

$$\mathbf{q}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_2 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix},$$

$$\mathbf{y}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \\ \delta \end{bmatrix} - \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix} \underbrace{\mathbf{q}_1^{\top} \mathbf{a}_3}_{1} - \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \underbrace{\mathbf{q}_2^{\top} \mathbf{a}_3}_{0} = \begin{bmatrix} 0 \\ -\delta \\ 0 \\ \delta \end{bmatrix} \implies \mathbf{q}_3 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix}$$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta=10^{-10}$.

$$\mathbf{q}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_2 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \mathbf{q}_3 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix},$$

Apply classical Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta=10^{-10}$.

$$\mathbf{q}_{1} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_{2} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \mathbf{q}_{3} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix},$$

$$\Rightarrow \mathbf{q}_{2}^{\mathsf{T}} \mathbf{q}_{3} = \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ 0 \\ \frac{1}{\sqrt{2}} \end{bmatrix} = \frac{1}{2} \quad \text{(Not orthogonal!)}$$

Apply modified Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix} \text{ with } \delta = 10^{-10}.$$

Apply modified Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta=10^{-10}$.

$$\mathbf{q}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_2 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix} \text{ (Same as before)},$$

$$\mathbf{y} = egin{bmatrix} 1 \ 0 \ 0 \ \delta \end{bmatrix} - egin{bmatrix} 1 \ \delta \ 0 \ 0 \end{bmatrix} \mathbf{q}_1^{\mathsf{T}} \mathbf{a}_3 = egin{bmatrix} 0 \ -\delta \ 0 \ \delta \end{bmatrix},$$

Apply modified Gram-Schmidt to
$$\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$$
 with $\delta = 10^{-10}$.

$$\mathbf{q}_1 = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_2 = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}$$
 (Same as before),

$$\mathbf{y} = \begin{bmatrix} 1\\0\\0\\\delta \end{bmatrix} - \begin{bmatrix} 1\\\delta\\0\\0 \end{bmatrix} \underbrace{\mathbf{q}_{1}^{\top} \mathbf{a}_{3}}_{1} = \begin{bmatrix} 0\\-\delta\\0\\\delta \end{bmatrix}, \ \mathbf{y}_{3} = \mathbf{y} - \begin{bmatrix} 0\\-\frac{1}{\sqrt{2}}\\\frac{1}{\sqrt{2}}\\0 \end{bmatrix} \underbrace{\mathbf{q}_{2}^{\top} \mathbf{y}}_{\frac{\delta}{\sqrt{2}}} = \begin{bmatrix} 0\\-\frac{\delta}{2}\\-\frac{\delta}{2}\\\delta \end{bmatrix} \implies \mathbf{q}_{3} = \begin{bmatrix} 0\\-\frac{1}{\sqrt{6}}\\-\frac{1}{\sqrt{6}}\\-\frac{2}{\sqrt{6}} \end{bmatrix}$$

Apply modified Gram-Schmidt to $\begin{bmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{bmatrix}$ with $\delta = 10^{-10}$.

$$\mathbf{q}_{1} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_{2} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \mathbf{q}_{3} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \end{bmatrix},$$

Apply modified Gram-Schmidt to $\begin{vmatrix} 1 & 1 & 1 \\ \delta & 0 & 0 \\ 0 & \delta & 0 \\ 0 & 0 & \delta \end{vmatrix}$ with $\delta=10^{-10}$.

$$\mathbf{q}_{1} = \begin{bmatrix} 1 \\ \delta \\ 0 \\ 0 \end{bmatrix}, \mathbf{q}_{2} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{2}} \\ \frac{1}{\sqrt{2}} \\ 0 \end{bmatrix}, \mathbf{q}_{3} = \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \end{bmatrix},$$

$$\implies \mathbf{q}_{2}^{\mathsf{T}} \mathbf{q}_{3} = \begin{bmatrix} 0 & -\frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \end{bmatrix} \begin{bmatrix} 0 \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ -\frac{1}{\sqrt{6}} \\ -\frac{2}{\sqrt{6}} \end{bmatrix} = \mathbf{0} \quad \text{(Orthogonal)}$$

THE FULL QR FACTORIZATION

THE FULL QR FACTORIZATION

Given the n < m columns of an $m \times n$ matrix A, add m - n extra independent vectors to $\{a_j\}$ and compute \mathbf{q}_1 to \mathbf{q}_m .

$$\underbrace{\begin{bmatrix} \mathbf{a}_1 & \cdots & \mathbf{a}_n \end{bmatrix}}_{\mathbf{A}_{m \times n}} = \underbrace{\begin{bmatrix} \mathbf{q}_1 & \cdots & \mathbf{q}_n & \mathbf{q}_{n+1} & \cdots & \mathbf{q}_m \end{bmatrix}}_{\mathbf{Q}_{m \times m}} = \underbrace{\begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ 0 & r_{22} & \cdots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & r_{nn} \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix}}_{\mathbf{R}_{m \times n}}$$

Find the full QR factorization of
$$A = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$$
.

Find the full QR factorization of $A = \begin{bmatrix} 1 & -\overline{4} \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$.

Previously, we computed $\mathbf{q}_1 = \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix}$ and $\mathbf{q}_2 = \begin{bmatrix} -\frac{14}{15} \\ \frac{1}{3} \\ \frac{2}{15} \end{bmatrix}$ from \mathbf{a}_1

and
$$\mathbf{a}_2$$
. Add $\mathbf{a}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

Find the full QR factorization of $\mathbf{A} = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$.

Previously, we computed $\mathbf{q}_1 = \begin{bmatrix} \frac{1}{3} \\ \frac{2}{3} \\ \frac{2}{3} \end{bmatrix}$ and $\mathbf{q}_2 = \begin{bmatrix} -\frac{14}{15} \\ \frac{1}{3} \\ \frac{2}{15} \end{bmatrix}$ from \mathbf{a}_1

and \mathbf{a}_2 . Add $\mathbf{a}_3 = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix}$.

$$\mathbf{y}_3 = \mathbf{a}_3 - \mathbf{q}_1 \underbrace{\mathbf{q}_1^{\mathsf{T}} \mathbf{a}_3}_{\frac{1}{3}} - \mathbf{q}_2 \underbrace{\mathbf{q}_2^{\mathsf{T}} \mathbf{a}_3}_{-\frac{14}{15}} = \frac{2}{225} \begin{bmatrix} 2 \\ 10 \\ -11 \end{bmatrix}, \quad \mathbf{q}_3 = \begin{bmatrix} \frac{2}{15} \\ \frac{10}{15} \\ -\frac{11}{15} \end{bmatrix}$$

Find the full QR factorization of $A = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$.

$$\begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} = \frac{1}{15} \begin{bmatrix} 5 & -14 & 2 \\ 10 & 5 & 10 \\ 10 & 2 & -11 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix}$$
 (Full QR)

Find the full QR factorization of $A = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$.

$$\begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} = \frac{1}{15} \begin{bmatrix} 5 & -14 & 2 \\ 10 & 5 & 10 \\ 10 & 2 & -11 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix}$$
 (Full QR)
$$= \frac{1}{15} \begin{bmatrix} 5 & -14 \\ 10 & 5 \\ 10 & 2 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & 5 \end{bmatrix}$$
 (Reduced QR)

SUMMARY OF FULL QR FACTORIZATION WITH MODIFIED GRAM-SCHMIDT

Input: $\mathbf{A}_{m \times n} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots & \mathbf{a}_n \end{bmatrix}$ with linearly independent columns and m-n extra linearly independent vectors.

$$\begin{array}{c|c} \text{for } j \leftarrow 1 \text{ to } m \text{ do} \\ & \mathbf{y} = \mathbf{a}_j \\ & \text{for } i \leftarrow 1 \text{ to } j - 1 \\ & \text{do} \\ & & r_{ij} = \mathbf{q}_i^\top \mathbf{y} \\ & & \mathbf{y} = \mathbf{y} - r_{ij} \mathbf{q}_i \\ & \text{end} \\ & r_{jj} = \|\mathbf{y}\| \\ & \mathbf{q}_j = \frac{\mathbf{y}}{r_{jj}} \\ & \text{end} \end{array}$$

Output: $\mathbf{Q}_{m imes m}$ and $\mathbf{R}_{m imes n}$ such that

$$\mathbf{A}_{m \times n} = \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 & \dots & \mathbf{q}_m \end{bmatrix} \begin{bmatrix} r_{11} & r_{12} & \dots & r_{1n} \\ 0 & r_{22} & \dots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & r_{nn} \\ 0 & 0 & \dots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \dots & 0 \end{bmatrix}$$

 $= Q_{m \times m} R_{m \times m}$

LEAST SQUARES BY QR FACTORIZATION

Def: A square matrix Q is orthogonal if $Q^{-1} = Q^{T}$.

$$\mathbf{Q}^{\top}\mathbf{Q} = \mathbf{I} \implies \begin{bmatrix} \mathbf{q}_1^{\top} \\ \mathbf{q}_2^{\top} \\ \vdots \\ \mathbf{q}_m^{\top} \end{bmatrix} \begin{bmatrix} \mathbf{q}_1 & \mathbf{q}_2 & \cdots & \mathbf{q}_m \end{bmatrix} = \begin{bmatrix} \mathbf{q}_1^{\top}\mathbf{q}_1 & \mathbf{q}_1^{\top}\mathbf{q}_2 & \cdots & \mathbf{q}_1^{\top}\mathbf{q}_m \\ \mathbf{q}_2^{\top}\mathbf{q}_1 & \mathbf{q}_2^{\top}\mathbf{q}_2 & \cdots & \mathbf{q}_2^{\top}\mathbf{q}_m \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{q}_n^{\top}\mathbf{q}_1 & \mathbf{q}_n^{\top}\mathbf{q}_2 & \cdots & \mathbf{q}_n^{\top}\mathbf{q}_m \end{bmatrix}$$

Def: A square matrix Q is **orthogonal** if $Q^{-1} = Q^{T}$.

$$\mathbf{Q}^{\top}\mathbf{Q} = \mathbf{I} \implies \begin{bmatrix} \mathbf{q}_{1}^{\top} \\ \mathbf{q}_{2}^{\top} \\ \vdots \\ \mathbf{q}_{m}^{\top} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{1} & \mathbf{q}_{2} & \cdots & \mathbf{q}_{m} \end{bmatrix} = \begin{bmatrix} \mathbf{q}_{1}^{\top}\mathbf{q}_{1} & \mathbf{q}_{1}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{1}^{\top}\mathbf{q}_{m} \\ \mathbf{q}_{2}^{\top}\mathbf{q}_{1} & \mathbf{q}_{2}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{2}^{\top}\mathbf{q}_{m} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{q}_{n}^{\top}\mathbf{q}_{1} & \mathbf{q}_{n}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{n}^{\top}\mathbf{q}_{m} \end{bmatrix}$$

$$\implies \mathbf{q}_{j}^{\top}\mathbf{q}_{j} = 1 \text{ and } \mathbf{q}_{i}^{\top}\mathbf{q}_{j} = 0 \quad \forall i \neq j.$$

Def: A square matrix Q is **orthogonal** if $Q^{-1} = Q^{T}$.

$$\mathbf{Q}^{\top}\mathbf{Q} = \mathbf{I} \implies \begin{bmatrix} \mathbf{q}_{1}^{\top} \\ \mathbf{q}_{2}^{\top} \\ \vdots \\ \mathbf{q}_{m}^{\top} \end{bmatrix} \begin{bmatrix} \mathbf{q}_{1} & \mathbf{q}_{2} & \cdots & \mathbf{q}_{m} \end{bmatrix} = \begin{bmatrix} \mathbf{q}_{1}^{\top}\mathbf{q}_{1} & \mathbf{q}_{1}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{1}^{\top}\mathbf{q}_{m} \\ \mathbf{q}_{2}^{\top}\mathbf{q}_{1} & \mathbf{q}_{2}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{2}^{\top}\mathbf{q}_{m} \\ \vdots & \vdots & \ddots & \vdots \\ \mathbf{q}_{n}^{\top}\mathbf{q}_{1} & \mathbf{q}_{n}^{\top}\mathbf{q}_{2} & \cdots & \mathbf{q}_{n}^{\top}\mathbf{q}_{m} \end{bmatrix}$$

$$\implies \mathbf{q}_{j}^{\top}\mathbf{q}_{j} = 1 \text{ and } \mathbf{q}_{i}^{\top}\mathbf{q}_{j} = 0 \quad \forall i \neq j.$$

A set of vectors satisfying the above conditions is called an **orthonormal** set of vectors.

Lemma: If ${\bf Q}$ is an orthogonal $m \times m$ matrix and ${\bf x}$ is an m dimensional vector,

 $\|\mathbf{Q}\mathbf{x}\|^2$

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Lemma: If ${\bf Q}$ is an orthogonal $m \times m$ matrix and ${\bf x}$ is an m dimensional vector,

$$\|\mathbf{Q}\mathbf{x}\|^2 = (\mathbf{Q}\mathbf{x})^\top\,\mathbf{Q}\mathbf{x} = \mathbf{x}^\top\mathbf{Q}^\top\mathbf{Q}\mathbf{x}$$

Lemma: If ${\bf Q}$ is an orthogonal $m \times m$ matrix and ${\bf x}$ is an m dimensional vector,

$$\|\mathbf{Q}\mathbf{x}\|^2 = (\mathbf{Q}\mathbf{x})^\top \, \mathbf{Q}\mathbf{x} = \mathbf{x}^\top \mathbf{Q}^\top \mathbf{Q}\mathbf{x} = \mathbf{x}^\top \mathbf{x} = \|\mathbf{x}\|^2 \,.$$

Lemma: If ${\bf Q}$ is an orthogonal $m \times m$ matrix and ${\bf x}$ is an m dimensional vector,

$$\|\mathbf{Q}\mathbf{x}\|^2 = (\mathbf{Q}\mathbf{x})^\top\,\mathbf{Q}\mathbf{x} = \mathbf{x}^\top\mathbf{Q}^\top\mathbf{Q}\mathbf{x} = \mathbf{x}^\top\mathbf{x} = \|\mathbf{x}\|^2\,.$$

Lemma: If Q_1 and Q_2 are orthogonal then the result of the matrix multiplications Q_1Q_2 and Q_2Q_1 are also orthogonal.

$$\|\mathbf{r}\| = \|\mathtt{A}\mathbf{x} - \mathbf{b}\| = \|\mathtt{Q}\mathtt{R}\mathbf{x} - \mathbf{b}\|$$

$$\|\mathbf{r}\| = \|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}^{\mathsf{T}}\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{Q}^{\mathsf{T}}\mathbf{b}\|$$

Given $m \times n$ inconsistent system $\mathbf{A}\mathbf{x} = \mathbf{b}$, find $\mathbf{A} = \mathbf{Q}\mathbf{R}$, the full QR factorization of \mathbf{A} .

$$\|\mathbf{r}\| = \|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{Q}^{\top}\mathbf{b}\| = \|\mathbf{R}\mathbf{x} - \mathbf{\underline{Q}}^{\top}\mathbf{\underline{b}}\|$$

$$\|\mathbf{r}\| = \|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{Q}^{\top}\mathbf{b}\| = \|\mathbf{R}\mathbf{x} - \mathbf{Q}^{\top}\mathbf{b}\|$$

$$\|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \\ e_{n+1} \\ \vdots \\ e_m \end{bmatrix}$$

$$\|\mathbf{r}\| = \|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}^{\top}\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{Q}^{\top}\mathbf{b}\| = \|\mathbf{R}\mathbf{x} - \underbrace{\mathbf{Q}^{\top}\mathbf{b}}_{\mathbf{d}}\|$$

$$\|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \\ e_{n+1} \\ \vdots \\ e_m \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ 0 & r_{22} & \cdots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & r_{nn} \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} - \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \\ d_{n+1} \\ \vdots \\ d_m \end{bmatrix}$$

$$\|\mathbf{r}\| = \|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{b}\| = \|\mathbf{Q}^{\mathsf{T}}\mathbf{Q}\mathbf{R}\mathbf{x} - \mathbf{Q}^{\mathsf{T}}\mathbf{b}\| = \|\mathbf{R}\mathbf{x} - \mathbf{Q}^{\mathsf{T}}\mathbf{b}\|$$

$$\|\mathbf{A}\mathbf{x} - \mathbf{b}\| = \begin{bmatrix} e_1 \\ e_2 \\ \vdots \\ e_n \\ e_{n+1} \\ \vdots \\ e_m \end{bmatrix} = \begin{bmatrix} r_{11} & r_{12} & \cdots & r_{1n} \\ 0 & r_{22} & \cdots & r_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & r_{nn} \\ 0 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & \cdots & 0 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix} - \begin{bmatrix} d_1 \\ d_2 \\ \vdots \\ d_n \\ d_{n+1} \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \\ \vdots \\ 0 \\ -d_{n+1} \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{e}} \\ \mathbf{e}' \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{e}} \\ \mathbf{e}' \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{k}} \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{k}} \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{k}} \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} \hat{\mathbf{d}} \\ \mathbf{d}' \end{bmatrix}$$

$$\mathbf{if } \mathbf{x} = \mathbf{x}_{LS}$$

$$\hat{\mathbf{k}} \mathbf{x}_{LS} = \hat{\mathbf{d}}$$

Use QR factorization to solve
$$\begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix} \mathbf{x} = \begin{bmatrix} -3 \\ 15 \\ 9 \end{bmatrix}.$$

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$$\|\mathbf{r}\|^2 = (-0.4)^2 + (-2)^2 + 2.2^2 = 9 = 3^2.$$

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- We will cover Householder reflections, see the book for Givens rotations in case you are curious.

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Look for an orthogonal matrix ${\tt H}$ that reflects ${\bf x}$ to ${\bf w}$ by ${\tt H}{\bf x}={\bf w}$. Lemma: Assume that ${\bf x}$ and ${\bf w}$ are of the same length. Then ${\bf w}-{\bf x}$ and ${\bf w}+{\bf x}$ are perpendicular.

$$(\mathbf{w} - \mathbf{x})^{\mathsf{T}}(\mathbf{w} + \mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{w} + \mathbf{w}^{\mathsf{T}}\mathbf{x} - \mathbf{x}^{\mathsf{T}}\mathbf{w} - \mathbf{x}^{\mathsf{T}}\mathbf{x} = \|\mathbf{w}\|^2 - \|\mathbf{x}\|^2 = 0.$$

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$$(\mathbf{w} - \mathbf{x})^{\top}(\mathbf{w} + \mathbf{x}) = \mathbf{w}^{\top}\mathbf{w} + \mathbf{w}^{\top}\mathbf{x} - \mathbf{x}^{\top}\mathbf{w} - \mathbf{x}^{\top}\mathbf{x} = \|\mathbf{w}\|^2 - \|\mathbf{x}\|^2 = 0.$$
Def: Let $P = \frac{\mathbf{v}\mathbf{v}^{\top}}{\mathbf{v}^{\top}\mathbf{v}}$ then

$$P^2 = \frac{\mathbf{v}\mathbf{v}^{\top}\mathbf{v}\mathbf{v}^{\top}}{(\mathbf{v}^{\top}\mathbf{v})^2} = \frac{\mathbf{v}^{\top}\mathbf{v}}{\mathbf{v}^{\top}\mathbf{v}}\frac{\mathbf{v}\mathbf{v}^{\top}}{\mathbf{v}^{\top}\mathbf{v}} = P = P^{\top}.$$

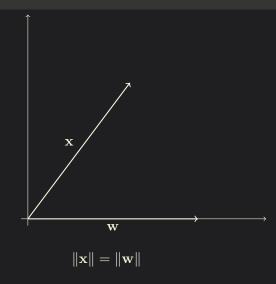
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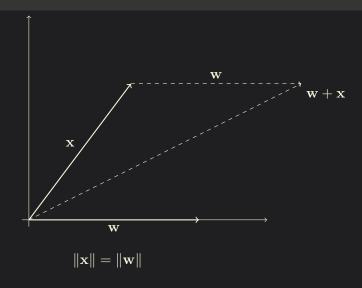
$$(\mathbf{w} - \mathbf{x})^{\mathsf{T}}(\mathbf{w} + \mathbf{x}) = \mathbf{w}^{\mathsf{T}}\mathbf{w} + \mathbf{w}^{\mathsf{T}}\mathbf{x} - \mathbf{x}^{\mathsf{T}}\mathbf{w} - \mathbf{x}^{\mathsf{T}}\mathbf{x} = \|\mathbf{w}\|^2 - \|\mathbf{x}\|^2 = 0.$$

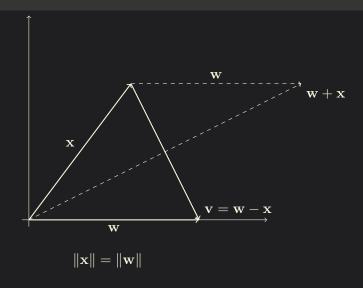
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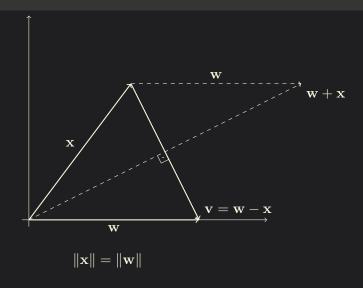
$$P^2 = \frac{\mathbf{v}\mathbf{v}^{\top}\mathbf{v}\mathbf{v}^{\top}}{(\mathbf{v}^{\top}\mathbf{v})^2} = \frac{\mathbf{v}^{\top}\mathbf{v}}{\mathbf{v}^{\top}\mathbf{v}}\frac{\mathbf{v}\mathbf{v}^{\top}}{\mathbf{v}^{\top}\mathbf{v}} = P = P^{\top}.$$

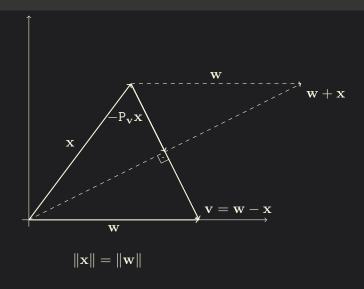
P is a symmetric projection matrix with $P\mathbf{v} = \mathbf{v}$ and $P\mathbf{u}$ is the projection of \mathbf{u} onto \mathbf{v} .

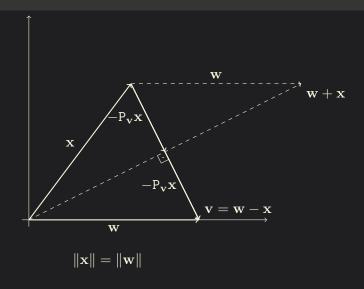


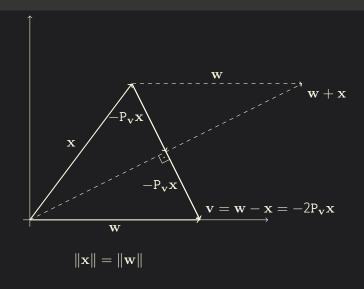


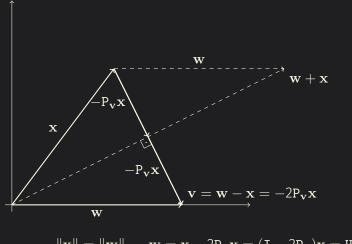






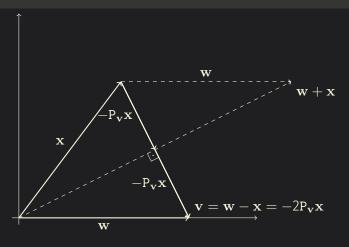






$$\|\mathbf{x}\| = \|\mathbf{w}\|, \quad \mathbf{w} = \mathbf{x} - 2P_{\mathbf{v}}\mathbf{x} = (\mathbf{I} - 2P_{\mathbf{v}})\mathbf{x} = \mathbf{H}\mathbf{x}$$

HOUSEHOLDER REFLECTIONS: THE GEOMETRY



$$\begin{split} \|\mathbf{x}\| &= \|\mathbf{w}\| \,, \quad \mathbf{w} = \mathbf{x} - 2P_{\mathbf{v}}\mathbf{x} = (\mathbf{I} - 2P_{\mathbf{v}})\mathbf{x} = H\mathbf{x} \\ H^{\top}H &= (\mathbf{I} - 2P_{\mathbf{v}})^{\top}(\mathbf{I} - 2P_{\mathbf{v}}) = (\mathbf{I} - 2P_{\mathbf{v}})(\mathbf{I} - 2P_{\mathbf{v}}) \\ &= \mathbf{I} - 2P_{\mathbf{v}} - 2P_{\mathbf{v}} + 4P_{\mathbf{v}}^2 = \mathbf{I}. \end{split}$$

Let
$$\mathbf{x} = \begin{bmatrix} 3 \\ 4 \end{bmatrix}$$
 and $\mathbf{w} = \begin{bmatrix} 5 \\ 0 \end{bmatrix}$, find \mathbf{H} s.t. $\mathbf{H}\mathbf{x} = \mathbf{w}$.
$$\mathbf{v} = \mathbf{w} - \mathbf{x} = \begin{bmatrix} 5 \\ 0 \end{bmatrix} - \begin{bmatrix} 3 \\ 4 \end{bmatrix} = \begin{bmatrix} 2 \\ -4 \end{bmatrix},$$

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$$P_{\mathbf{v}} = \frac{\mathbf{v}\mathbf{v}^{\top}}{\mathbf{v}^{\top}\mathbf{v}} = \frac{\begin{bmatrix} 4 & -8 \\ -8 & 16 \end{bmatrix}}{20} = \begin{bmatrix} 0.2 & -0.4 \\ -0.4 & 0.8 \end{bmatrix},$$

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$$\mathbf{H} = \mathbf{I} - 2P_{\mathbf{v}} = \begin{bmatrix} 0.6 & 0.8 \\ 0.8 & -0.6 \end{bmatrix},$$

$$\mathbf{H}\mathbf{x} = \begin{bmatrix} 1.8 + 3.2 \\ 2.4 - 2.4 \end{bmatrix} = \begin{bmatrix} 5 \\ 0 \end{bmatrix} = \mathbf{w}.$$

Given
$$\mathbf{A} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots, \mathbf{a}_n \end{bmatrix}$$
, take $\mathbf{x}_1 = \mathbf{a}_1$ and $\mathbf{w} = \pm \begin{bmatrix} \|\mathbf{x}_1\| \\ 0 \\ \vdots \\ 0 \end{bmatrix}$.

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Take the sign to be equal to the opposite sign of the first component of \mathbf{x}_1 for numerical stability.

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$$\mathtt{H}_1\mathtt{A} = \mathtt{H}_1 \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} = \begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}$$

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$$\begin{split} H_1 A &= H_1 \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} = \begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix} \\ H_2 H_1 A &= \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & \mathbf{\hat{H}}_2 \\ 0 & & \end{bmatrix}}_{H_2} \underbrace{\begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}}_{H_1 A} = \underbrace{\begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & 0 & \times \end{bmatrix}}_{R} \end{split}$$

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$$\mathbf{A} = \begin{bmatrix} \mathbf{a}_1 & \mathbf{a}_2 & \cdots, \mathbf{a}_n \end{bmatrix}$$
, take $\mathbf{x}_1 = \mathbf{a}_1$ and $\mathbf{w} = \pm \begin{bmatrix} \|\mathbf{x}_1\| \\ 0 \\ \vdots \\ 0 \end{bmatrix}$.

Take the sign to be equal to the opposite sign of the first component of \mathbf{x}_1 for numerical stability.

$$H_{1}A = H_{1} \begin{bmatrix} \times & \times & \times \\ \times & \times & \times \\ \times & \times & \times \end{bmatrix} = \begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}$$

$$H_{2}H_{1}A = \underbrace{\begin{bmatrix} 1 & 0 & 0 \\ 0 & \hat{H}_{2} \\ 0 & \end{bmatrix}}_{H_{2}} \underbrace{\begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & \times & \times \end{bmatrix}}_{H_{1}A} = \underbrace{\begin{bmatrix} \times & \times & \times \\ 0 & \times & \times \\ 0 & 0 & \times \end{bmatrix}}_{R}$$

$$A = H_{1}H_{2}R \quad (H_{i}^{-1} = H_{i})$$

Find the QR factorization of
$$\mathbf{A} = \begin{bmatrix} 1 & -4 \\ 2 & 3 \\ 2 & 2 \end{bmatrix}$$
.

$$\mathbf{x}_1 = \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{w}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix}, \mathbf{H}_1 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix}$$

$$\begin{aligned} \mathbf{x}_1 &= \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{w}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix}, H_1 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix} \\ H_1 \mathbf{A} &= \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix}, \mathbf{\hat{x}}_2 = \begin{bmatrix} -3 \\ -4 \end{bmatrix}, \mathbf{\hat{w}}_2 = \begin{bmatrix} 5 \\ 0 \end{bmatrix}, H_2 = \begin{bmatrix} -0.6 & -0.8 \\ -0.8 & 0.6 \end{bmatrix} \end{aligned}$$

$$\begin{split} \mathbf{x}_1 &= \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{w}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix}, H_1 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix} \\ H_1 \mathbf{A} &= \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix}, \mathbf{\hat{x}}_2 = \begin{bmatrix} -3 \\ -4 \end{bmatrix}, \mathbf{\hat{w}}_2 = \begin{bmatrix} 5 \\ 0 \end{bmatrix}, H_2 = \begin{bmatrix} -0.6 & -0.8 \\ -0.8 & 0.6 \end{bmatrix} \\ H_2 H_1 \mathbf{A} &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix} = \mathbf{R}, \end{split}$$

$$\begin{split} \mathbf{x}_1 &= \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}, \mathbf{w}_1 = \begin{bmatrix} 3 \\ 0 \\ 0 \end{bmatrix}, \mathbf{v} = \begin{bmatrix} 2 \\ -2 \\ -2 \end{bmatrix}, H_1 = \begin{bmatrix} \frac{1}{3} & \frac{2}{3} & \frac{2}{3} \\ \frac{2}{3} & \frac{1}{3} & -\frac{2}{3} \\ \frac{2}{3} & -\frac{2}{3} & \frac{1}{3} \end{bmatrix} \\ H_1 A &= \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix}, \hat{\mathbf{x}}_2 = \begin{bmatrix} -3 \\ -4 \end{bmatrix}, \hat{\mathbf{w}}_2 = \begin{bmatrix} 5 \\ 0 \end{bmatrix}, H_2 = \begin{bmatrix} -0.6 & -0.8 \\ -0.8 & 0.6 \end{bmatrix} \\ H_2 H_1 A &= \begin{bmatrix} 1 & 0 & 0 \\ 0 & -0.6 & -0.8 \\ 0 & -0.8 & 0.6 \end{bmatrix} \begin{bmatrix} 3 & 2 \\ 0 & -3 \\ 0 & -4 \end{bmatrix} = \begin{bmatrix} 3 & 2 \\ 0 & 5 \\ 0 & 0 \end{bmatrix} = R, \\ Q &= H_1 H_2 = \frac{1}{15} \begin{bmatrix} 5 & -14 & -2 \\ 10 & 5 & -10 \\ 10 & 2 & 11 \end{bmatrix} \end{split}$$

Uniqueness of QR Factorization

QR factorization is not unique since if $\mathtt{D} = \mathrm{diag}(d_1,\ldots,d_m)$ with $d_i = \pm 1$ then

$$\mathtt{A} = \mathtt{QR} = \underbrace{\mathtt{QD}}_{\mathtt{Q'}} \underbrace{\mathtt{DR}}_{\mathtt{R'}}$$

since

$$\mathtt{D}^2=\mathtt{I}$$