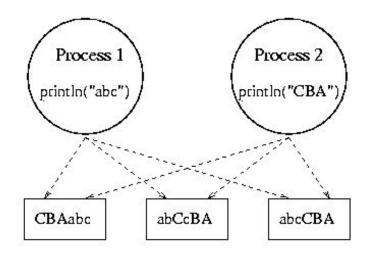
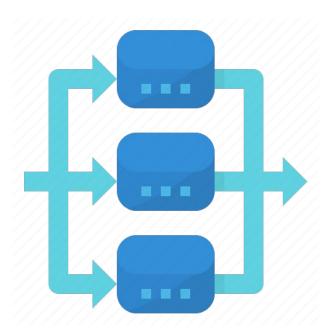
CENG 322 LAB 7

Synchronization

- Two types of processes in terms of synchronization:
 - Independent Process: Execution of one process does not affects the execution of other processes.
 - Cooperative Process: Execution of one process affects the execution of other processes.
- Cooperating processes share resources and may cause inconsistency in processes data therefore process synchronization is required for consistency of data.



Why do we permit processes to **cooperate**?



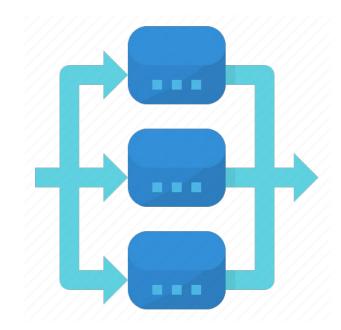
Why do we permit processes to **cooperate**?

Want to **share resources**:

- One computer, many users.
- One database of checking account records, many tellers.

Want to do things **faster:**

- Read next block while processing current one.
- Divide job into sub-jobs, execute in parallel.



Assume that:

```
A = 1
```

$$B = 3$$

Process 1

$$A = B + 1$$

Process 2

$$B = B * 2$$

Result:
$$A = ?$$
 and $B = ?$

Assume that:

A = 1

B = 3

Process 1

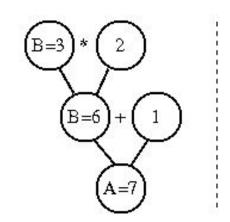
A = B + 1

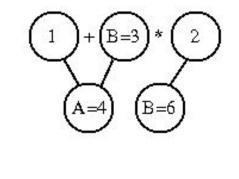
Process 2

B = B * 2

Inconsistent!

Non-deterministic!





Race Condition

Race condition mostly **occurs** when two or more processes (or threads) try to **read**, **write** and possibly **make the decisions** based on the memory that they are accessing concurrently.

- Multiple processes
- Executing same code
- Accessing the same memory
- Using shared variable

Race Condition Example

counter++ could be implemented as

```
register1 = counter
register1 = register1 + 1
counter = register1
```

counter-- could be implemented as

```
register2 = counter
register2 = register2 - 1
counter = register2
```

Consider this execution interleaving with "count = 5" initially:

```
S0: producer execute register1 = counter

S1: producer execute register1 = register1 + 1

S2: consumer execute register2 = counter

S3: consumer execute register2 = register2 - 1

S4: producer execute counter = register1

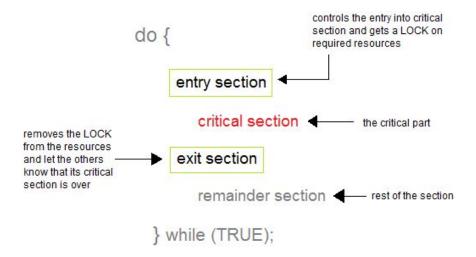
S5: consumer execute counter = register2

(counter = 6)

(counter = 4)
```

Critical Section

A **Critical Section** is a code segment that accesses **shared variables** and has to be executed as an **atomic action**.



It may cause race conditions.

Solutions of Critical Section Problem

Any solution must satisfy these requirements:

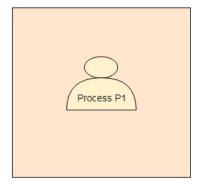
- Mutual Exclusion: At most one process in the critical section.
- Progress: If process P1 is outside the critical section, then P1 cannot prevent process P2 from entering the critical section.
- Bounded Buffer: Every process will get a chance to enter its critical section without waiting indefinitely.





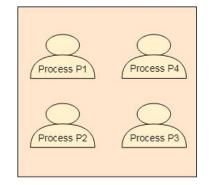


Critical Section





Critical Section





Peterson's Solution in C

Check **synchronization_1.c**!

```
do
   Flag[i] = TRUE;
   Turn = j;
   while(flag[j] && turn = = j)
      Critical Section
   Flag[i] = FALSE;
      Remainder section
}while(TRUE);
```

```
void lock(int self)
   // Acquire lock
   flag[self] = 1;
   // Give the other thread the chance
   //to acquire lock
   turn = 1-self;
   // Wait
   while (flag[1-self]==1 && turn==1-self) ;
void unlock(int self)
   flag[self] = 0;
```

Peterson's Solution in C

```
Thread 2 - 1
Thread 1 - 0
                                                  flag[1] = 1;
flag[0] = 1;
                                                  turn = 0;
turn = 1;
                                                  // Wait
// Wait
                                                  while (flag[0]==1 && turn==0);
while (flag[1]==1 && turn==1);
                                                  Case 2: Thread 2 first
Case 1: Thread 1 first
                                                  flag[0] = 0;
flag[0] = 1;
flag[1] = 0;
                                                  flag[1] = 1;
```

Bakery Algorithm in C

- It is also called Lamport's bakery algorithm.
- Solution for N threads (or processes).
- Assign numbers to the processes then support FCFS.

Assign:

```
(ticket number, process(or thread) id)
```

Waiting condition:

```
while (tickets[other] != 0 &&
  (tickets[other] < tickets[thread]
  ||(tickets[other] == tickets[thread]
  && other < thread)))</pre>
```



Mutual Exclusion (Mutex) in C

- A mutex lock is an object that only one thread at a given time can obtain it while the others must wait
 until the lock owner thread release it.
- We can implement mutex with pthread library:
- Create new mutex object:

```
#include <pthread.h>
pthread_mutex_t new_mutex;
```

• **Init** the mutex (pointer of mutex, attribute of the mutex):

```
pthread mutex_init(&new mutex, NULL);
```

Mutual Exclusion (Mutex) in C

Lock and unlock the mutex object:

```
pthread_mutex_lock(&new_mutex);
pthread_mutex_unlock(&new_mutex);
```

Destroy the mutex object:

```
pthread_mutex_destroy(&new_mutex);
```

Check **synchronization_3.c**!

Conditional Variables in C

Busy-waiting in application is a bad idea due to:

- Thread consumes CPU even when can't make progress.
- Unnecessarily slows other threads and processes.

Better to inform scheduler of **which threads can run**, typically done with condition variables:

```
// Initialize
void cond_init (cond t *, ...);
// Atomically unlock m and sleep until c signaled
// Then re-acquire m and resume executing
void cond_wait (cond t *c, mutex t *m);
// Wake one/all threads waiting on c
void cond_signal (cond t *c);
void cond_broadcast (cond t *c);
```

Semaphore in C

- Sometimes you need multiple threads to enter critical section at the same time i.e.: reader-writer problem.
- Semaphores allow you to define the # threads that can be allowed

```
Library:
              #include <semaphore.h>
Initialization:
              sem t:
              sem init(sem t *sem, int pshared, unsigned int value)
Usage:
              sem destroy(sem t *sem)
              sem wait(sem t *sem)
              sem post(sem t *sem)
```