Parallel RLC forced response with nonzero initial conditions
$$I = i_c + i_L + i_R$$

$$I = i_C + i_L + i_R$$

$$I = 24mA$$

$$I =$$

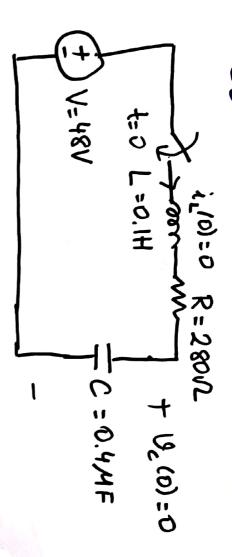
CL
$$\frac{di_L}{dt^2}$$
 + i_L + $\frac{di_L}{R}$ = $\frac{1}{dt}$ = $\frac{1}{LC}$ forced \leq natural response $\frac{di_L}{dt^2}$ + $\frac{1}{RC}\frac{di_L}{dt}$ + $\frac{i_L}{LC}$ = $\frac{1}{LC}$ $i_L(t)$ = $\frac{1}{LC}$ + $\frac{1}{LC}$ Depending on ∞ , $\frac{di_L}{dt^2}$ + $\frac{1}{RC}\frac{di_L}{dt}$ + $\frac{i_L}{LC}$ = $\frac{1}{LC}$ Steady-state

 $M = \frac{1}{2RC} = \frac{1}{2*500 \times 25 \times 10^{-9}} = \frac{10^6}{25} \text{ yr} \text{ lines in the last raise}$
 $M_0 = \frac{1}{1} = \frac{1}{2*500 \times 25 \times 10^{-9}} = \frac{1}{25 \times 10^{-9}} = \frac{1}{15 \times$

x_L(+) = 24 + 2.2 te -4000t i(+) = 24×10-3 + D, te- «+ + Dze x=wo = aitically damped i_(0) = 24×10-3+ b2 = 29mA = 29x10-3A = D2 = 5x10-3A dt 1t=0 D1-4×104×5×10-3 = 10,00) = 50 = 50 = D1-2200 A/s = D, (ext + + base o) + D2 (-a)e-at = D, -aD2 + 5e +000t

(0)

Series RLC forced response



$$w_0 = \frac{1}{\sqrt{10.1 \times 0.4 \times 10^{-6}}} = \frac{1}{\sqrt{0.1 \times 0.4 \times 10^{-6}}}$$

$$\frac{dw_{c}(o)}{dt} = \frac{i_{c}(o)}{c}$$

$$y_{c}(t) = 48V + B_{1} e^{-\alpha t} \cos \omega_{d}t + B_{2} e^{-\alpha t} \sin \omega_{d}t
y_{c}(0) = 48 + B_{1} = 0 \Rightarrow B_{1} = -48V
\frac{dv_{c}(0)}{dt} = \frac{i_{L}(0)}{C} = 0
\frac{dv_{c}(t)}{dt} \Big|_{t=0} = B_{1} \Big(-\alpha e^{-\alpha t} \cos \omega_{d}t \Big) + B_{2} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t} \Big(-\alpha t^{-\alpha t} \cos \omega_{d}t \Big) + e^{-\alpha t}$$

Find DE in terms of V64)

$$V_{c} = C \quad V_{c}(4) \quad V_{c} = R I_{o} + V_{o} = 0$$

$$V_{c} = R I_{o} + V_{o} = R C \frac{dV_{o}}{dt} + C \frac{dV_{o}}{dt}$$

$$I_{c} = C \frac{dV_{c}}{dt} = R C^{2} \frac{d^{2}V_{o}}{dt^{2}} + C \frac{dV_{o}}{dt}$$

$$-V_{i}^{2} + R(I_{c} + I_{o}) + V_{c} = 0$$

$$R(Rc^{2} \frac{d^{2}V_{o}}{dt^{2}} + C \frac{dV_{o}}{dt} + C \frac{dV_{o}}{dt}) + RC \frac{dV_{o}}{dt} + V_{o} = V_{i}^{2}$$

$$R^{2}C^{2} \frac{d^{2}V_{o}}{dt^{2}} + 3RC \frac{dV_{o}}{dt} + V_{o} = V_{i}^{2}$$

$$R^{2}C^{2} \frac{d^{2}V_{0}}{dt^{2}} + 3RC \frac{dV_{0}}{dt} + V_{0} = V_{1}$$

$$\frac{d^{2}V_{0}}{dt^{2}} + \frac{3}{RC} \frac{dV_{0}}{dt} + \frac{V_{0}}{R^{2}C^{2}} = \frac{V_{1}}{R^{2}C^{2}}$$
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