Assignment - 4

Ultrasonic sensor simulation in Wokwi

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Maximum Marks	2 Marks

Question-1:

Write a code and connections in wokwi for the ultrasonic sensor. Whenever the distance is less than 100cms send an "Alert" to IBM cloud and display in the device recent events.

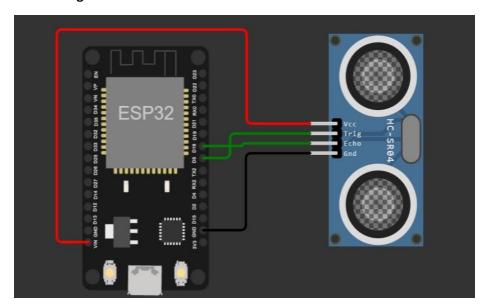
Code:

```
#include <WiFi.h>
#include <PubSubClient.h>
void callback(char* subscribetopic, byte* payload, unsigned int
payloadLength);
//----credentials of IBM Accounts-----
#define ORG "ytluse"//IBM ORGANITION ID
#define DEVICE TYPE "2702"//Device type mentioned in ibm watson IOT Platform
#define DEVICE_ID "12345"//Device ID mentioned in ibm watson IOT Platform
#define TOKEN "O+n)Eh+lNX0y3?rG!8" //Token
String data3;
char server[] = ORG ".messaging.internetofthings.ibmcloud.com";
char publishTopic[] = "iot-2/evt/Data/fmt/json";
char subscribetopic[] = "iot-2/cmd/test/fmt/String";
char authMethod[] = "use-token-auth";
char token[] = TOKEN;
char clientId[] = "d:" ORG ":" DEVICE_TYPE ":" DEVICE_ID;
WiFiClient;
PubSubClient client(server, 1883, callback ,wifiClient);
const int trigPin = 5;
const int echoPin = 18;
#define SOUND_SPEED 0.034
long duration;
float distance;
void setup() {
 Serial.begin(115200);
 pinMode(trigPin, OUTPUT);
 pinMode(echoPin, INPUT);
```

```
wificonnect();
  mqttconnect();
void loop()
  digitalWrite(trigPin, LOW);
  delayMicroseconds(2);
  digitalWrite(trigPin, HIGH);
  delayMicroseconds(10);
  digitalWrite(trigPin, LOW);
  duration = pulseIn(echoPin, HIGH);
  distance = duration * SOUND_SPEED/2;
  Serial.print("Distance (cm): ");
  Serial.println(distance);
  if(distance<100)</pre>
    Serial.println("ALERT!!");
    delay(1000);
    PublishData(distance);
    delay(1000);
    if (!client.loop()) {
      mqttconnect();
    }
  delay(1000);
void PublishData(float dist) {
  mqttconnect();
  String payload = "{\"Distance\":";
  payload += dist;
  payload += ",\"ALERT!!\":""\"Distance less than 100cms\"";
  payload += "}";
  Serial.print("Sending payload: ");
  Serial.println(payload);
  if (client.publish(publishTopic, (char*) payload.c_str())) {
   Serial.println("Publish ok");
  } else {
    Serial.println("Publish failed");
```

```
void mqttconnect() {
  if (!client.connected()) {
    Serial.print("Reconnecting client to ");
    Serial.println(server);
    while (!!!client.connect(clientId, authMethod, token)) {
      Serial.print(".");
      delay(500);
     initManagedDevice();
     Serial.println();
void wificonnect()
  Serial.println();
  Serial.print("Connecting to ");
  WiFi.begin("Wokwi-GUEST", "", 6);
  while (WiFi.status() != WL_CONNECTED) {
    delay(500);
    Serial.print(".");
  Serial.println("");
  Serial.println("WiFi connected");
  Serial.println("IP address: ");
  Serial.println(WiFi.localIP());
void initManagedDevice() {
  if (client.subscribe(subscribetopic)) {
    Serial.println((subscribetopic));
    Serial.println("subscribe to cmd OK");
  } else {
    Serial.println("subscribe to cmd FAILED");
void callback(char* subscribetopic, byte* payload, unsigned int payloadLength)
{
  Serial.print("callback invoked for topic: ");
  Serial.println(subscribetopic);
  for (int i = 0; i < payloadLength; i++) {</pre>
    //Serial.print((char)payload[i]);
    data3 += (char)payload[i];
Serial.println("data: "+ data3);
data3="";
```

Circuit Diagram:

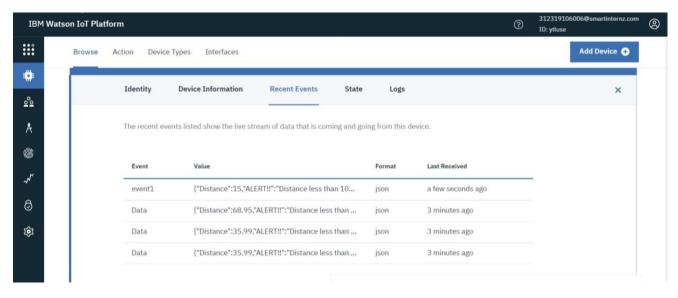


Output:

Wokwi output:

```
Connecting to ...
WiFi connected
IP address:
10.10.0.2
Reconnecting client to ytluse.messaging.internetofthings.ibmcloud.com
iot-2/cmd/test/fmt/String
subscribe to cmd OK
Distance (cm): 35.99
ALERT!!
Sending payload: {"Distance":35.99,"ALERT!!":"Distance less than 100cms"}
Publish ok
Distance (cm): 35.99
ALERT!!
Sending payload: {"Distance":35.99, "ALERT!!": "Distance less than 100cms"}
Publish ok
Distance (cm): 68.95
ALERT!!
Sending payload: {"Distance":68.95,"ALERT!!":"Distance less than 100cms"}
Publish ok
```

IBM cloud output:



Wokwi simulation link:

https://wokwi.com/projects/346236324918854227