```
float x,y,z,temp;
void setup()
{
 pinMode(8, INPUT);
 pinMode(5, OUTPUT);
 pinMode(6, OUTPUT);
 pinMode(A5, INPUT);
 pinMode(A4, INPUT);
Serial.begin(9600);
}
void loop()
{
x= digitalRead(8);
y= analogRead(A5);
z= analogRead(A4);
Serial.println(x);
Serial.println(y);
Serial.println(z);
temp = (double)z / 1024;
temp = temp * 5;
temp = temp - 0.5;
 temp = temp * 100;
if ((x>0))
  if ((y<550)&&(temp>30))
   digitalWrite(5, HIGH);
   digitalWrite(6, HIGH);
  }
  else if((y<550)&&(temp<30))
  {
```

```
digitalWrite(5, HIGH);
   digitalWrite(6, LOW);
  }
  else if((y>550)&&(temp>30))
  {
   digitalWrite(5, LOW);
   digitalWrite(6, HIGH);
  }
  else if((y>550)&&(temp<30))
  {
   digitalWrite(5, LOW);
   digitalWrite(6, LOW);
  }
}
 else
 {
  digitalWrite(5, LOW);
  digitalWrite(6, LOW);
}
}
```