

Z

3-Axis FORCE Sensor

Benefits:

- Multi axis force measurement
- High resolution
- Highly adaptable product design
- Dust and water proof (IP65)
- High overload range
- Mechanical shock resistant
- Cost efficient solution
- Easy integration

OMD-20-FE-200N

Description:

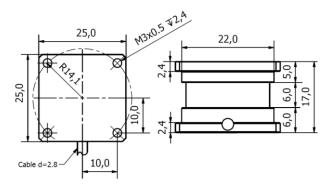
OptoForce 3D sensors measure the magnitude and the direction of Fx, Fy, and Fz forces based purely on **optical principles**. Depending on the application, **semi-spherical** and **flat top** versions are available. We advise these sensors for low budget research programs and for measurements where torque sensing is unnecessary. Semi-spherical sensors are ideal as sensitive **fingertips** for humanoid robot hands, industrial **grippers**, harvesting robots, and due to its **high durability** there are various applications in the field of **medical robotics** (rehabilitation) and **advanced robotics** (e.g. exoskeletons) as well.

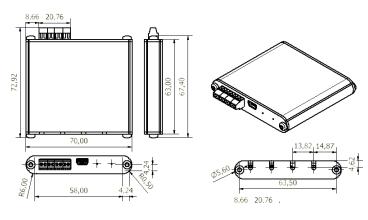
	Nominal Capacity	Typical Deformation
Fxy	± 20 N	± 1.5 mm
Fz – compression	200 N	1.2 mm
Fz – tension	100 N	1 mm

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^{*:} For F/T sensing kindly see our 6 axis datasheets







Sensor

DAQ (Non-Detachable)



SPECIFICATIONS

Sensor Type	3 Axis Force Sensor		
Dimensions	Height x width x length		17 x 25 x 25 mm
Weight	With 1 m cable (without)		23 g (14 g)
	Fz Compression	Fz Tension	Fxy
Nominal Capacity (N.C)	200 N	100 N	20 N
Single axis overload	200 %	200 %	200 %
Full scale nonlinearity	2 %	2 %	2 %
Resolution	12.5 mN	12.5 mN	2.1 mN
Single axis deformation at N.C	1.2 mm	1 mm	±1.5 mm
Crosstalk (typical)	< 5%		
Hysteresis (measured on Fz axis, typical)	< 2 %		
Working temperature range			-40 °C - +80 °C
Power requirement	In continuous operation		10 mA



INTERFACE TYPES



USB	CAN	UART		
Maximum sampling frequency 1000 Hz				
Supported systems Windows; Linux; ROS; UR				

info@optoforce.com