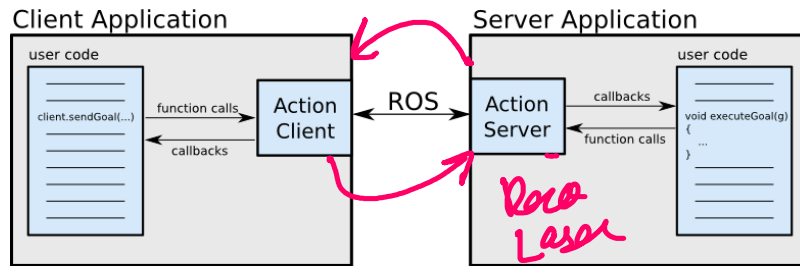


S#3 Move Base Action Server for Go to Goal

Monday, 25 October 2021 9:18 AM



<https://wiki.ros.org/actionlib>

Message

Nodes

```
client = actionlib.SimpleActionClient('move_base', MoveBaseAction)
client.wait_for_server()
argv = sys.argv[1:]
goal = MoveBaseGoal()
goal.target_pose.header.frame_id = "map"
goal.target_pose.header.stamp = rospy.Time.now()
goal.target_pose.pose.position.x = float(argv[0])
goal.target_pose.pose.position.y = float(argv[1])
goal.target_pose.pose.position.z = 0.000

goal.target_pose.pose.orientation.w = 0.19012465928
goal.target_pose.pose.orientation.z = 0.998917586
```

