PatchCore

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Towards Total Recall in Industrial Anomaly Detection.

Paper https://arxiv.org/abs/2106.08265.

class

```
anomalib.models.image.patchcore.lightning_model.Patchcore(backbone='wide_resnet50_2',
layers=('layer2', 'layer3'), pre_trained=True, coreset_sampling_ratio=0.1,
num_neighbors=9)
```

```
Bases: MemoryBankMixin, AnomalyModule
```

PatchcoreLightning Module to train PatchCore algorithm.

Parameters:

- **backbone** (*str*) Backbone CNN network Defaults to wide_resnet50_2.
- **layers** (*list[str]*) Layers to extract features from the backbone CNN Defaults to ["layer2", "layer3"].
- **pre_trained** (*bool, optional*) Boolean to check whether to use a pre_trained backbone. Defaults to True.
- **coreset_sampling_ratio** (*float, optional*) Coreset sampling ratio to subsample embedding. Defaults to 0.1.
- num_neighbors (int, optional) Number of nearest neighbors. Defaults to [9].

configure_optimizers()

Configure optimizers.

Returns:

Do not set optimizers by returning None.

Return type:

None

configure_transforms(image_size=None)

Default transform for Padim.

Return type:

Transform

fit()

Apply subsampling to the embedding collected from the training set.

Return type:

None

property learning_type: LearningType

Return the learning type of the model.

Returns:

Learning type of the model.

Return type:

LearningType

property trainer_arguments: dict[str, Any]

Return Patchcore trainer arguments.

```
training_step(batch, *args, **kwargs)
```

Generate feature embedding of the batch.

Parameters:

- batch (dict[str, str | torch.Tensor]) Batch containing image filename, image, label and mask
- args Additional arguments.
- **kwargs** Additional keyword arguments.

Returns:

Embedding Vector

Return type:

dict[str, np.ndarray]

validation_step(batch, *args, **kwargs)

Get batch of anomaly maps from input image batch.

Parameters:

- batch (dict[str, str | torch.Tensor]) Batch containing image filename, image, label and mask
- args Additional arguments.
- **kwargs** Additional keyword arguments.

Returns:

Image filenames, test images, GT and predicted label/masks

Return type:

dict[str, Any]

PyTorch model for the PatchCore model implementation.

```
class anomalib.models.image.patchcore.torch_model.PatchcoreModel(layers,
backbone='wide_resnet50_2', pre_trained=True, num_neighbors=9)

Bases: DynamicBufferMixin, Module
```

Patchcore Module.

Parameters:

- layers (list[str]) Layers used for feature extraction
- **backbone** (*str, optional*) Pre-trained model backbone. Defaults to [resnet18].
- **pre_trained** (*bool, optional*) Boolean to check whether to use a pre_trained backbone. Defaults to True.
- **num_neighbors** (*int, optional*) Number of nearest neighbors. Defaults to [9].

```
compute_anomaly_score(patch_scores, locations, embedding)
```

Compute Image-Level Anomaly Score.

Parameters:

- patch_scores (torch.Tensor) Patch-level anomaly scores
- **locations** (Tensor) Memory bank locations of the nearest neighbor for each patch location
- embedding (Tensor) The feature embeddings that generated the patch scores

Returns:

Image-level anomaly scores

Return type:

Tensor

static euclidean_dist(x, y)

Calculate pair-wise distance between row vectors in x and those in y.

Replaces torch cdist with p=2, as cdist is not properly exported to onnx and openvino format. Resulting matrix is indexed by x vectors in rows and y vectors in columns.

Parameters:

- x (Tensor) input tensor 1
- y (Tensor) input tensor 2

Return type:

Tensor

Returns:

Matrix of distances between row vectors in x and y.

forward(input_tensor)

Return Embedding during training, or a tuple of anomaly map and anomaly score during testing.

Steps performed: 1. Get features from a CNN. 2. Generate embedding based on the features. 3. Compute anomaly map in test mode.

Parameters:

```
input_tensor (torch.Tensor) - Input tensor
```

Returns:

Embedding for training, anomaly map and anomaly score for testing.

Return type:

Tensor | dict[str, torch.Tensor]

generate_embedding(features)

Generate embedding from hierarchical feature map.

Parameters:

- **features** (dict [str], Tensor]) Hierarchical feature map from a CNN (ResNet18 or WideResnet)
- **features** dict[str:Tensor]:

Return type:

Tensor

Returns:

Embedding vector

nearest_neighbors(embedding, n_neighbors)

Nearest Neighbours using brute force method and euclidean norm.

Parameters:

- **embedding** (*torch.Tensor*) Features to compare the distance with the memory bank.
- **n_neighbors** (*int*) Number of neighbors to look at

Returns:

Patch scores. Tensor: Locations of the nearest neighbor(s).

Return type:

Tensor

static reshape_embedding(embedding)

Reshape Embedding.

Reshapes Embedding to the following format:

[Batch, Embedding, Patch, Patch] to [Batch*Patch*Patch, Embedding]

Parameters:

embedding (torch.Tensor) – Embedding tensor extracted from CNN features.

Returns:

Reshaped embedding tensor.

Return type:

Tensor

subsample_embedding(embedding, sampling_ratio)

Subsample embedding based on coreset sampling and store to memory.

Parameters:

- embedding (np.ndarray) Embedding tensor from the CNN
- **sampling_ratio** (*float*) Coreset sampling ratio

Return type:

None

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