

# LOGICAL ENCODING OF PROGRAMS

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ABSTRACT. These notes describe the process of encoding program executions as a formula in first-order logic. This allows us to apply various forms of automated verification by checking satisfiability of the encodings.

## 1. LANGUAGE

Recall the simple imperative language we used to present operational semantics in class. For now, we will use a subset of that language that does not involve while loops.

**Definition 1.1** (Language Syntax). A program  $P$  is defined as follows:

$$\begin{array}{ll} P ::= x \leftarrow a & \text{assignment} \\ \quad | \text{ if } b \text{ then } P_1 \text{ else } P_2 & \text{conditional} \\ \quad | P_1; P_2 & \text{sequential composition} \end{array}$$

where  $a$  is an arithmetic (integer) expression over program variables, and  $b$  is a Boolean expression over program variables. We shall use  $V$  to denote the set of all program variables. All variables  $v \in V$  are assumed to be integer-typed ( $\mathbb{Z}$ ).

**Definition 1.2** (Language Semantics). Recall that a *state*  $s : V \rightarrow \mathbb{Z}$  of a program  $P$  is a map from variables  $V$  to integer values. Given a program  $P$ , the operational semantics define a relation  $\rightarrow$  describing the execution of  $P$  beginning at some state  $s$  and ending in state  $s'$ , denoted as follows:

$$\langle P, s \rangle \rightarrow s'$$

## 2. TRANSITION RELATIONS

We now define *transition relations*, which are relations defining the operational semantics of a program. We will later show how to define transition relations in first-order logic. Given a program  $P$ , we will define its transition relation  $trans(V, V')$  over two sets of variables, the program variables  $V$  and a copy of program variables  $V'$ . The idea is that the variables  $V$  hold the initial state  $s$  of the program, and  $V'$  hold the final state  $s'$  after the program has completed execution. This is best seen through an example:

**Example 2.1.** Consider the simple program  $P$  defined as a single statement:

$$x \leftarrow x + 1$$

The set of variables  $V$  of  $P$  is the singleton set  $\{x\}$ . The set  $V'$  is  $\{x'\}$ . Therefore the transition relation  $trans(x, x')$  is over two variables,  $x$  and  $x'$ . Concretely,  $trans$  is defined as follows:

$$trans = \{(n, n + 1) \mid n \in \mathbb{Z}\}$$

That is, for any number  $n$ , the pair  $(n, n + 1)$  is in the transition relation, denoting that if we start executing the program with  $x = n$ , we end up with  $x' = n + 1$ .

Observe how there is a one-to-one correspondence between elements of the transition relation and pairs of states  $s, s'$  such that  $\langle P, s \rangle \rightarrow s'$ .

### 3. FIRST-ORDER THEORY

Recall the first-order theories we discussed in class. To encode the relation *trans*, we will use the theory of *linear integer arithmetic* (LIA). LIA allows formulas to contain integer-valued variables, equality, inequality, addition, and *no multiplication* (multiplication will only be to replace addition, i.e.,  $x + x$  will be written as  $2x$ ). Checking satisfiability of formulas in LIA is decidable.

**Definition 3.1** (Linear Integer Arithmetic). Formally, an LIA formula  $\varphi$  is of the following form:

$$\begin{aligned} \varphi ::= & a_1 = a_2 \\ & | a_1 \leq a_2 \\ & | a_1 < a_2 \\ & | \varphi \wedge \varphi \\ & | \varphi \vee \varphi \\ & | \neg \varphi \\ & | \exists x. \varphi \\ & | \forall x. \varphi \end{aligned}$$

where  $a_1, a_2$  are arithmetic expressions of the form  $c_1x_1 + \dots + c_nx_n$ , where  $c_i \in \mathbb{Z}$  and  $x_i$  are first-order variables. For instance,  $2x + 3y$ . Note that  $\Rightarrow$  and  $\Leftarrow$  can be written using  $\wedge, \neg$ .

A model  $m$  for a formula  $\varphi$ , denoted  $m \models \varphi$ , is a mapping from the free variables of  $\varphi$ , denoted  $fv(\varphi)$ , to integers, that satisfies the formula. For example, consider  $x + y > 0$ . Let  $m = \{x \mapsto 1, y \mapsto 0\}$ . We have  $m \models x + y > 0$

### 4. ENCODING TRANSITION RELATIONS

**Single assignments** Let us now consider how we would encode a transition relation of a single assignment. Let the assignment be of the form

$$x \leftarrow a$$

We simply transform this into a formula  $\varphi$  defined as follows:

$$\varphi \equiv x' = a \wedge \bigwedge_{y \neq x, y \in V} y' = y$$

Notice that the variable  $x$  on the lhs of the assignment is encoded as  $x'$ , denoting the final value of  $x$  after the assignment is performed. Notice also that the final state of every variable  $y$  other than  $x$  is the same as its initial value, since it is not modified by the assignment statement.

**Example 4.1.** Consider the assignment

$$x \leftarrow x + y$$

This is encoded as the transition relation

$$\text{trans}(x, y, x', y') \equiv x' = x + y \wedge y' = y$$

assuming  $V = \{x, y\}$

**Loop-free Programs** Now that we have discussed how to construct *trans* for a simple program comprised of a single assignment, we can define the rules for full (loop-free) programs.

**Definition 4.2** (Transition-Relation Encoding).

$$\begin{aligned} \text{enc}(x \leftarrow a) &\triangleq x' = a \wedge \bigwedge_{y \neq x, y \in V} y' = y \\ \text{enc}(\text{if } b \text{ then } P_1 \text{ else } P_2) &\triangleq (b \Rightarrow \text{enc}(P_1)) \wedge (\neg b \Rightarrow \text{enc}(P_2)) \\ \text{enc}(P_1; P_2) &\triangleq \exists V''. \text{trans}_1(V, V'') \wedge \text{trans}_2(V'', V') \end{aligned}$$

$$\text{where } \text{trans}_1(V, V') \equiv \text{enc}(P_1)$$

$$\text{trans}_2(V, V') \equiv \text{enc}(P_2)$$

To illustrate the encoding, let us consider some examples:

**Example 4.3.** Consider the following program  $P$

$$\text{if } x > 0 \text{ then } x \leftarrow x + 1 \text{ else } x \leftarrow y$$

The encoding  $\text{enc}(P)$  is a formula over  $V$  and  $V'$  defined as follows:

$$(x > 0 \Rightarrow x' = x + 1 \wedge y' = y) \wedge (x \leq 0 \Rightarrow x' = y \wedge y' = y)$$

The left conjunct defines the transition relation of the *then* branch; the right conjunct defines the *else* branch.

**Example 4.4.** Now consider the following program  $P$ :

$$x \leftarrow x + 1; y \leftarrow y + 1$$

The function  $\text{enc}$  encodes this program one instruction at a time, and combines the results. First, we encode  $x \leftarrow x + 1$  as follows:

$$\text{trans}_1(x, y, x', y') \equiv \text{enc}(x \leftarrow x + 1) \equiv x' = x + 1 \wedge y' = y$$

Then, we encode  $y \leftarrow y + 1$ :

$$\text{trans}_2(x, y, x', y') \equiv \text{enc}(y \leftarrow y + 1) \equiv y' = y + 1 \wedge x' = x$$

We now simply conjoin the two transition relations; however, we have to be careful about the variable names: the output variables of  $\text{trans}_1$  need be the same as the input variables of  $\text{trans}_2$ . Therefore we conjoin them as follows:

$$\text{trans}_1(x, y, x'', y'') \wedge \text{trans}_2(x'', y'', x', y')$$

Notice that we have renamed the outputs of  $\text{trans}_1$  and inputs of  $\text{trans}_2$  so that they actually match; these variables are  $V'' = \{x'', y''\}$ . Intuitively,  $V''$  defines the state of the program after executing the first instruction; but since we only care about the final state, we *quantify the variables  $V''$  away*. Finally, we arrive at the following encoding

$$\exists x'', y''. (x'' = x + 1 \wedge y'' = y) \wedge (y' = y'' + 1 \wedge x' = x'')$$

The first conjunct is  $trans_1(x, y, x'', y'')$ , and the second is  $trans_2(x'', y'', x', y')$ . Notice that the free variables of this formula are  $x, y$  and  $x', y'$ , defining the initial states and final states, respectively.

## 5. SOUNDNESS AND COMPLETENESS

We need to show that our encoding is sound and complete. Soundness ensures that the transition relation does not over-approximate the operational semantics relation  $\rightarrow$ . Completeness, on the other hand, ensures that every element of  $\rightarrow$  is also in the encoding.

**Theorem 5.1** (Soundness). *Fix a program  $P$  with variables  $V$ . Let  $m \models \text{enc}(P)$ . Let*

$$\begin{aligned} s &= \{v \mapsto m(v) \mid v \in V\} \\ s' &= \{v' \mapsto m(v') \mid v' \in V'\} \end{aligned}$$

*Then,  $\langle P, s \rangle \rightarrow s'$ .*

**Theorem 5.2** (Completeness). *Fix a program  $P$  with variables  $V$ . Let  $s, s'$  be such that  $\langle P, s \rangle \rightarrow s'$ . Let*

$$m = \{v \mapsto s(v) \mid v \in V\} \cup \{v' \mapsto s'(v') \mid v' \in V'\}$$

*Then,  $m \models \text{enc}(P)$ .*

*Proof.* Both proofs proceed by structural induction on the program.  $\square$

## 6. VERIFICATION

Now that we have defined the encoding, we can use it to check if a Hoare triple holds. Suppose we are given a Hoare triple  $\{\phi\}P\{\psi\}$ , where  $\phi$  and  $\psi$  are LIA formulas over program variables. We would like to check if the Hoare triple is valid; informally, for any state  $s$  satisfying  $\phi$ , for any state  $s'$  such that  $\langle P, s \rangle \rightarrow s'$ , we want to make sure that  $s'$  satisfies  $\psi$ .

To automatically check if the Hoare triple is valid, we encode *all* executions starting at  $\phi$  and check whether they end up in  $\psi$ . Formally, we check validity of the following formula:

$$\begin{aligned} (\phi \wedge \text{enc}(P)) \Rightarrow \psi' \text{ is VALID} \\ \text{iff} \\ \{\phi\}P\{\psi\} \text{ is VALID} \end{aligned}$$

Intuitively,  $\phi \wedge \text{enc}(P)$  defines the set executions of  $P$  constrained to the ones starting at  $\phi$ . The implication ensures that all final states are contained in  $\psi'$ . Notice that we use a primed version of  $\psi$ , since final states in the encoding are over primed variables.

**Example 6.1.** Let us consider a simple example. To check validity of

$$\{x > 0\}x \leftarrow x + 1\{x > 1\}$$

we check validity of the following formula:

$$(x > 0 \wedge x' = x + 1) \Rightarrow x' > 1$$

which is valid.

**Example 6.2.** Here is another example, but this time the Hoare triple is invalid:

$$\{x > 0\}x \leftarrow x + y\{x > 1\}$$

The formula  $\Psi$

$$\Psi \equiv (x > 0 \wedge x' = x + y \wedge y' = y) \Rightarrow x' > 1$$

is not valid. Here is a counterexample; i.e., a model  $m$  for the negation of the formula,  $\neg\Psi$ :

$$m = \{x \mapsto 0, y \mapsto 0, x' \mapsto 0, y' \mapsto 0\}$$

In other words,  $m$  says that if  $x = y = 0$  in the initial state, the final state will be such that  $x = 0$ , therefore invalidating the postcondition, which specifies the  $x > 1$  when the program terminates.

## 7. BOUNDED VERIFICATION

We will now enrich our programming language to include while loops. For simplicity, we shall assume a program  $P$  contains a single while loop; that is,  $P$  is of the form:

$$P_{pre}; \text{while } b \text{ do } P_{body}$$

where  $P_{pre}$  and  $P_{body}$  are loop-free programs.

Suppose we want to check validity of a Hoare triple  $\{\phi\}P\{\psi\}$  where  $P$  contains a while loop. We will now show how to check that the Hoare triple is valid assuming  $P$  can only take a bounded number of loop iterations, e.g., 3 loop iterations. In the literature, this process is known as *bounded verification*, *bounded model checking*, or *symbolic execution*.

The first step is to encode executions that take  $n$  loop steps in  $P$ . We define this using the function  $\text{enc}_n(P)$  as follows, where  $n \in [0, \infty)$ .

$$\text{enc}_n(P) \triangleq \text{trans}_{pre}(V, V^1) \wedge \left( \bigwedge_{i=1}^n b_i \wedge \text{trans}_{body}(V^i, V^{i+1}) \right) \wedge \neg b^{n+1}$$

where  $\text{trans}_{pre} \equiv \text{enc}(P_{pre})$  and  $\text{trans}_{body} \equiv \text{enc}(P_{body})$ . Notice how we rename the variables such that we have  $n$  copies of the transition relation of the loop body, where iteration  $i$  starts with variables  $V^i$  and ends with variables  $V^{i+1}$ . Also, note that at the end we ensure that the loop-exit condition is true:  $\neg b^{n+1}$ .

Now that we know how to encode  $n$  loop iterations, we can check if a Hoare triple is valid for loop  $\leq n$  loop iterations by checking validity of the following formula:

$$\bigwedge_{i=1}^n (\phi \wedge \text{enc}_i(P) \Rightarrow \psi^{i+1})$$

Note that each conjunct  $i$  ensures that executions that start in  $\phi$  and run for  $i$  loop iterations end in a state satisfying  $\psi$ .