

# Effect of Decoherence During Gates

Ben Criger

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## 1 Introduction

The purpose of this note is to determine the effect of biased (read: mostly dephasing) noise during the operation of certain gates. I'm going to start with the  $Y_{90}$  gate, implemented by a nice square pulse. There are two limits that can be handled succinctly, the perfectly-Markovian limit (where we can't decrease the error rate without a quantum error-correcting code), and the 'unknown constant Hamiltonian' limit, where we can apply pulse sequences, reversing the effect of the unknown Hamiltonian for  $\sim 1/2$  the pulse duration. I begin with the Markovian limit, as I'm not so familiar with DD pulse sequences.

## 2 Helpful Math

Let's vectorize the density matrix, in the Pauli basis:

$$\rho = \frac{\hat{1}}{2} + \rho_x \sigma_x + \rho_y \sigma_y + \rho_z \sigma_z \quad (1)$$

To express the equation of motion in this basis, I calculate a few commutators and dissipators.

$$\mathcal{D}[A](B) = ABA^\dagger - \frac{1}{2} \{A^\dagger A, B\} \quad (2)$$

$$\mathcal{D}[A](\hat{1}) = A\hat{1}A^\dagger - \frac{1}{2} \{A^\dagger A, \hat{1}\} = [A, A^\dagger] \quad (3)$$

$$\therefore \mathcal{D}[\sigma_z](\hat{1}) = [\sigma_z, \sigma_z] = 0 \quad (4)$$

$$\mathcal{D}[\sigma_z](\sigma_z) = 0 \quad (5)$$

$$\mathcal{D}[\sigma_z](\sigma_{x,y}) = -2\sigma_{x,y} \quad (6)$$

$$[\sigma_y, \sigma_x] = -2i\sigma_z \quad [\sigma_y, \sigma_z] = 2i\sigma_x \quad (7)$$

With these in hand, we can start expressing the equation of motion for a noisy  $Y_{90}$  in this operator basis.

## 3 $Y_{90}$ with Markovian Noise

A simple master equation for a  $Y_{90}$ , subject to dephasing is:

$$\dot{\rho} = -i\frac{\omega}{2} [\sigma_y, \rho] + \frac{\gamma}{2} \mathcal{D}[\sigma_z](\rho), \quad (8)$$

where the factors of two are included to make the matrix description look nice, as we will see in a minute. I express the commutator and dissipator in matrix form:

$$\frac{\gamma}{2} \mathcal{D}[\sigma_z](\cdot) = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -\gamma & 0 & 0 \\ 0 & 0 & -\gamma & 0 \\ 0 & 0 & 0 & 0 \end{bmatrix} - i\frac{\omega}{2} [\sigma_y, \cdot] = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & 0 & 0 & \omega \\ 0 & 0 & 0 & 0 \\ 0 & -\omega & 0 & 0 \end{bmatrix}. \quad (9)$$

The Lindbladian is just the sum of these two terms:

$$\dot{\vec{\rho}} = \begin{bmatrix} 0 & 0 & 0 & 0 \\ 0 & -\gamma & 0 & \omega \\ 0 & 0 & -\gamma & 0 \\ 0 & -\omega & 0 & 0 \end{bmatrix} \vec{\rho} = \hat{L}\vec{\rho} \quad (10)$$

We take the matrix exponent  $\exp(\hat{L}t)$  to get the superoperator  $S$ :

$$S = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & e^{-\frac{\gamma t}{2}} \left( \cosh(\beta t/2) - \frac{\gamma}{\beta} \sinh(\beta t/2) \right) & 0 & -\frac{2\omega}{\beta} e^{-\frac{\gamma t}{2}} \sinh(\beta t/2) \\ 0 & 0 & e^{-\frac{\gamma t}{2}} & 0 \\ 0 & \frac{2\omega}{\beta} e^{-\frac{\gamma t}{2}} \sinh(\beta t/2) & 0 & e^{-\frac{\gamma t}{2}} \left( \cosh(\beta t/2) + \frac{\gamma}{\beta} \sinh(\beta t/2) \right) \end{bmatrix} \quad (11)$$

where  $\beta = \sqrt{\gamma^2 - 4\omega^2}$ .

If  $\omega$  is large, and  $\gamma$  is small (as we hope will be the case in low-noise systems), then  $\beta$  will be imaginary, and the hyperbolic functions will become regular trigonometric functions:

$$\beta \equiv i\nu \quad (12)$$

$$\cosh\left(\frac{\beta t}{2}\right) = \cos\left(\frac{\nu t}{2}\right) \quad (13)$$

$$\frac{\sinh(\frac{\beta t}{2})}{\beta} = \frac{\sin(\frac{\nu t}{2})}{\nu} \quad (14)$$

$$S \mapsto \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & e^{-\frac{\gamma t}{2}} \left( \cos(\nu t/2) - \frac{\gamma}{\nu} \sin(\nu t/2) \right) & 0 & -\frac{2\omega}{\nu} e^{-\frac{\gamma t}{2}} \sin(\nu t/2) \\ 0 & 0 & e^{-\frac{\gamma t}{2}} & 0 \\ 0 & \frac{2\omega}{\nu} e^{-\frac{\gamma t}{2}} \sin(\nu t/2) & 0 & e^{-\frac{\gamma t}{2}} \left( \cos(\nu t/2) + \frac{\gamma}{\nu} \sin(\nu t/2) \right) \end{bmatrix} \quad (15)$$

We have control over  $t$ , and we'd like to determine how to set it in order to obtain the maximum-fidelity  $Y_{90}$ . To separate the noise from the gate we'd like to perform, we express the total superoperator as the product of a desired  $Y_{90}$  superoperator and a noise operator:

$$S = S_{\text{Noise}} S_{\text{Id}} \quad (16)$$

$$\therefore S_{\text{Noise}} = S_{\text{Id}}^{-1} S \quad (17)$$

$$S_{\text{Id}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 0 & 0 & 1 \\ 0 & 0 & 1 & 0 \\ 0 & -1 & 0 & 0 \end{bmatrix} \quad (18)$$

$$\therefore S_{\text{Noise}} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \frac{2\omega}{\nu} \exp(-\frac{\gamma t}{2}) \sin(\frac{\nu t}{2}) & 0 & \exp(-\frac{\gamma t}{2}) \left( \frac{\gamma}{\nu} \sin(\frac{\nu t}{2}) - \cos(\frac{\nu t}{2}) \right) \\ 0 & 0 & \exp(-\gamma t) & 0 \\ 0 & \exp(-\frac{\gamma t}{2}) \left( \frac{\gamma}{\nu} \sin(\frac{\nu t}{2}) + \cos(\frac{\nu t}{2}) \right) & 0 & \frac{2\omega}{\nu} \exp(-\frac{\gamma t}{2}) \sin(\frac{\nu t}{2}) \end{bmatrix} \quad (19)$$

To find the channel fidelity  $F_\Lambda = \langle \Omega | \Lambda \otimes \hat{1} (|\Omega\rangle\langle\Omega|) | \Omega \rangle$  (where  $|\Omega\rangle$  is a Bell state), we take the trace of this superoperator and divide by 4 (I won't prove this here, but leave it as an exercise):

$$F_{S_{\text{Noise}}} = \frac{1}{4} \left[ 1 + \frac{4\omega}{\nu} \exp\left(-\frac{\gamma t}{2}\right) \sin\left(\frac{\nu t}{2}\right) + \exp(-\gamma t) \right] \quad (20)$$

To find out how long to leave the Hamiltonian on, we try to optimize this fidelity over  $t$ :

$$\frac{dF_{S_{\text{Noise}}}}{dt} = \frac{1}{2} \omega \cos\left(\frac{1}{2} \nu t\right) e^{(-\frac{1}{2} \gamma t)} - \frac{\gamma \omega e^{(-\frac{1}{2} \gamma t)} \sin\left(\frac{1}{2} \nu t\right)}{2 \nu} - \frac{1}{4} \gamma e^{(-\gamma t)} = 0 \quad (21)$$

$$\therefore \sin\left(\frac{1}{2} \nu t\right) = \frac{\left(2 \nu \omega \cos\left(\frac{1}{2} \nu t\right) e^{(\gamma t)} - \gamma \nu e^{(\frac{1}{2} \gamma t)}\right) e^{(-\gamma t)}}{2 \gamma \omega} \quad (22)$$

This formula is not analytically soluble, so we just set  $t = \frac{\pi}{\nu}$ , to get the following (ridiculously good-looking) superoperator:

$$\begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & -\frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{\nu} & 0 & \frac{2\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} \\ 0 & 0 & e(-\frac{\pi\gamma}{\nu}) & 0 \\ 0 & -\frac{2\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} & 0 & \frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{\nu} \end{bmatrix} \quad (23)$$

We subtract off a term  $2\frac{\omega}{\nu} \exp(-\frac{\pi\gamma}{2\nu}) Y_{90}$  to obtain the remaining diagonal part of the superoperator:

$$\begin{bmatrix} -\frac{2\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} + 1 & 0 & 0 & 0 \\ 0 & -\frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{\nu} & 0 & 0 \\ 0 & 0 & -\frac{2\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} + e(-\frac{\pi\gamma}{\nu}) & 0 \\ 0 & 0 & 0 & \frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{\nu} \end{bmatrix} \quad (24)$$

This is equivalent to a Pauli map with the following probabilities:

$$\begin{aligned} p_I &= -\frac{\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} + \frac{1}{4} e(-\frac{\pi\gamma}{\nu}) + \frac{1}{4} & p_X &= -\frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{2\nu} - \frac{1}{4} e(-\frac{\pi\gamma}{\nu}) + \frac{1}{4} \\ p_Y &= -\frac{\omega e(-\frac{\pi\gamma}{2\nu})}{\nu} + \frac{1}{4} e(-\frac{\pi\gamma}{\nu}) + \frac{1}{4} & p_Z &= \frac{\gamma e(-\frac{\pi\gamma}{2\nu})}{2\nu} - \frac{1}{4} e(-\frac{\pi\gamma}{\nu}) + \frac{1}{4} \end{aligned} \quad (25)$$

These probabilities approach 0 in the small  $\gamma$  limit and approach  $\frac{1}{4}$  in the large  $\gamma$  limit. I'm willing to bet that they are always between 0 and 1.

## 4 Amplitude Damping

We'd also like, if possible, to consider the effect of amplitude damping (or  $T_1$  noise) on the  $Y_{90}$  gate. It will likely not be possible to express this noise as a mixed-Clifford channel, given that it is non-unital. There are two approaches to coping with this; either we obtain a mixed-Clifford channel which optimally approximates the gate, or we fold the noisy  $Y_{90}$  into the nearest state-preparation or measurement location, modeling the effect of  $T_1$  on a mixture of  $|0\rangle\langle 0|$  and  $|1\rangle\langle 1|$  rather than superpositions. This second approach ought to be easier (analytically soluble, rather than requiring an SDP), and apply most of the time (since syndrome extraction from a CSS code usually only uses  $H/Y_{90}$  gates to prepare superposition states and rotate measurement bases), so I'll try that first.

We calculate the effect of a  $\sigma_-$  dissipator in the Pauli basis:

$$\mathcal{D}[\sigma_-](\hat{1}) = [\sigma_-, \sigma_+] = \sigma_z \quad (26)$$

$$\mathcal{D}[\sigma_-](\sigma_x) = \sigma_- \sigma_x \sigma_+ - \frac{1}{2} \{\sigma_+ \sigma_-, \sigma_x\} = |0\rangle\langle 1| \sigma_x |1\rangle\langle 0| - \frac{1}{2} \{|1\rangle\langle 1|, \sigma_x\} = -\frac{1}{2} \sigma_x \quad (27)$$

$$\mathcal{D}[\sigma_-](\sigma_y) = -\frac{1}{2} \sigma_y \quad (28)$$

$$\mathcal{D}[\sigma_-](\sigma_z) = |0\rangle\langle 1| \sigma_z |1\rangle\langle 0| - \frac{1}{2} \{|1\rangle\langle 1|, \sigma_z\} = -\sigma_z \quad (29)$$

This allows us to express the new Lindbladian in matrix form (note that I mess with coefficient definitions to try to get the matrix to look nice, your coefficients may vary):

$$\dot{\rho} = -i\frac{\omega}{2} [\sigma_y, \rho] + \frac{\gamma\phi}{2} \mathcal{D}[\sigma_z](\rho) + \gamma_- \mathcal{D}[\sigma_-](\rho) \quad (30)$$

$$\dot{\vec{\rho}} = \begin{bmatrix} 0 & 0 & 0 & -\gamma_- \\ 0 & -\gamma\phi - \frac{1}{2}\gamma_- & 0 & \omega \\ 0 & 0 & -\gamma\phi - \frac{1}{2}\gamma_- & 0 \\ \gamma_- & -\omega & 0 & 0 \end{bmatrix} \vec{\rho} = \hat{L}\vec{\rho} \quad (31)$$

## 5 Questions

1. Show that "shorting" the gate time optimally (maximizing the channel fidelity) doesn't appreciably raise the fidelity over just setting  $\omega t = \frac{\pi}{\nu}$ .

2. How does all this change when we add amplitude damping?