1. a) the optimal policy should get to state 3 as soon as possible and pay less cost to reach state I and 2. But if both state I and 2 aim directly to state 3, it has law probability and large cost. It can try action B in state I and action A in state 2, it's a bother way of cost.

事1.5%

u = (-1, -2,0), P + (b,b)

 $u_1 = -1 + 0.2 u_3 + 0.8 u_1$, $u_2 = -2 + 0.2 u_3 + 0.8 u_2$, $u_3 = 0$ $u_4 = -5$, $u_2 = -10$

In state 1: $\S T (1,a;j) U_j = 0.6 \times (-10) + 0.4 \times (-5) = -8$ $\S T (1,b,j) U_j = 0.2 \times 0 + 0.8 \times -5 = -4$ action B is perfered

In state 2: $\sum_{j} T(1,a,j) u_{j} = 0.6 \times (-5) + 0.4 \times (-10) = -7$ $\sum_{j} T(1,b,j) v_{j} = 0.2 \times 0 + 0.8 \times (-10) = -8$ action a is perfered

now $u_1^2 - 5$ and $u_2 = -2 + 0.6 u_1 + 0.4 u_2$, $u_3 = 0$ $0.6 u_2 = -2 + 0.6 \times (-5)$

UL= -8.3

now state 1: $\frac{1}{3}T(1,\alpha,j)u_j = 0.6 \times -8.3 + 0.4 \times -5 = -6.98$ $\frac{1}{3}T(1,b,j)u_j = 0.2 \times 0 + 0.8 \times (-5) = -4$

action b is still perfered

State 2: \(\frac{1}{5}T(1,a,j) \(U_j = 0.6 \times (-5) + 0.4 \times (-8.3) = -6.3 \)
\(\frac{5}{5}T(1,b,j) \(U_j = 0.2 \times 0.8 \times (-8.3) = -6.64 \)

action a is still perfered

so state 2 move to state 1 and in state 1 to move to state 3

C) It will change the form to: $u_1 = -1 + 0.4 u_1 + 0.6 u_2$ $u_2 = -2 + 0.6 u_1 + 0.24 u_2$ $u_3 = 0$

We can solve this function of U1, U2
the value will tend to -00

the discounting will not help. The discount factor will affect the policy and routs.

It will cause we can choose action b in state 2. The discount short-torm ast will outweights the discount long-term cost of action b, and it will finally repeatedly leaveing the agent in state 2.

Alexant: numbers of parameters: 61M parameters
training and test times: separate from different computers

reference: 40 epochs trained for 6 days on two 67x 580 APU

performance: first use of Relu, heavy data augmentation, dropout 0.5,

8 layers, 16.4 scare on Imagenet board, more than 75% accuracy

V6167: numbers of parameters: 138 million parameters.

training and test times: for respect 50 runs to 76% + top 1 accuracy on 90 epochs in roughly 7.3 hours on a vx-8 TPU device.

performance: Ind in classification, 1 st in localization, has better feature generalization, 19 layers, 73 scores, around 70% accurage but large operations. and parameters

Resnet: numbers of parameters: 11 million parameters.

training and test times: never training time of the seconds with validation

performance: ultra-deep in Imagine net 152-layer nets, the deeper networks achieve lower training error, 75% accuracy, with 152 layers

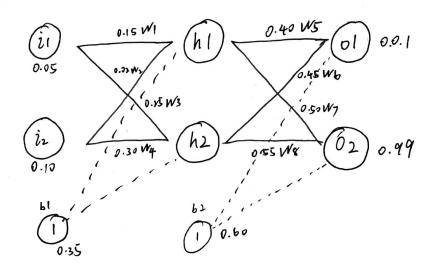
googlenet: number of parameters: 7 million parameters!

training and test times: close with the time as VGB, it needs to train 22 layors which more than vgg 16

performance: 22 layers, 6.7 score in imagenet scale, 70% lover accuracy, less parameters and operations, is most efficient network architecture.

To find a best neural architecture, we need to find it in different use. A basic neural network need a input layer, a first hidden layer and second hidden layer. Each layer tormed a different representation of input and different levels of abstraction usually we can use three layers to form a simple task but when meet more complex tasks, we need maybe various layers to learn the complex concepts. For more efficient, we expect compact representation to result in better generalization performance. Also, for a class of deep network and target functions, one needs a substantially smaller number of nodes to achieve a predefind accuracy compared to a shallow one. So, the way to find a best neural network is base on the problem we need to solve. We should choose a network with appronte layers, efficient parameters and quick runing time.

4.



first, forward pass

The net input for hi is calculated as the sum of the product of each weight value and input value and bias value

net input
$$h_1 = W_1 \times i_1 + W_2 \times i_2 + b_1 \times 1$$

= 0.15 x 0.05 + 0.2 x 0.1 + 0-35 y 1 = 0.3775

then use sigmoid function to calculate the output of h_1 out $h_1 = \frac{1}{1 + e^{-net}h_1} = \frac{1}{1 + e^{-net}h_1} = 0.5933$

So input
$$h_2 = 0.25 \times 0.05 + 0.30 \times 0.1 + 0.35 \times 1 = 0.3925$$

Out $h_2 = \frac{1}{1 + e^{-0.3915}} = 0.59688$

input
$$0_1 = W_5 \times \text{out } h_1 + W_6 \times \text{out } h_2 + b_2 \times 1$$

 $= 0.4 \times 0.5933 + 0.45 \times 0.59688 + 0.6 \times 1 = 1.10591$
out $0_1 = \frac{1}{1 + o^{-\text{net } 01}} = \frac{1}{1 + o^{-1.10591}} = 0.7514$

Same inato = 0.5 x 0.5933 + 0.55 x 0.59688 + 0.6x 1 = 1.2249

Then calculate error $E + 0.01 = 5 \pm (target - autput)^2$ $E_0, = \frac{1}{2}(0.01 - 0.75^{13b})^2 = 0.2748$ $E_0, = \frac{1}{2}(0.99 - 0.77293)^2 = 0.0235b$ $E + 0.01 = E_0, + E_0 = 0.27481 + 0.0235b = 0.29837$

Use the back propagation to update each weight in the network. finally update W5 = W5 - nx (2 E total) the rate of change error Altotal = DEfatel x dout 01 y 2 net 01

Dout 01 x 2 not 01 2 out 01 (1-0001) = 0.751365 × (1-0.751365) = 0.18682 <u> Inet 01</u> = 1x and h 1 x Ws (1-1) + 0 + 0 = out h 1 = 0.59326 = 25total = 0.741365 x 0.18682 x 0.59326 = 0.082167 update W5 = 0.4-0.5× 0.08×167 = 0.35892 as the same level backward. $W_b^* = 0.408666$ then go to next nevel layer, start with wi $W_{i}^{*} = W_{i} - n \times \underbrace{(\partial E botal)}_{\partial W_{i}}$ $\underbrace{\partial E botal}_{\partial W_{i}} = \underbrace{\frac{\partial E botal}{\partial adh_{i}}}_{\partial adh_{i}} \times \underbrace{\frac{\partial outh_{i}}{\partial neth_{i}}}_{\partial neth_{i}} \times \underbrace{\frac{\partial nebh_{i}}{\partial W_{i}}}_{\partial W_{i}}$ $\frac{\partial E t \circ tal}{\partial \theta h h_1} = \frac{\partial E O_1}{\partial o v h_1} + \frac{\partial E O_2}{\partial o v t h_1} = \frac{\partial E O_1}{\partial n e t O_1} \times \frac{\partial n e t O_1}{\partial o v t h_1} \times \frac{\partial E O_1}{\partial n e t O_1} \times \frac{\partial n e t O_1}{\partial o v t h_1}$ = 0.741365 x 0.1868 15 + 0.1384985 x 0.40 = 61380x 900 7500 399999 3-05539945+1-0.019049) = 0.83635 3neth1 = outh1(1-outh1)= 0.593269(1-0.59327)=0.2413 dneth1 = 1 = 2, = 0.05 :. W, * = W, - n x = \frac{3\text{Etotal}}{3W} = 0.15 - 0.5 \times 0.03 635 x 0.2413 x 0.05 =0.15 -0.5 × 0.000 4385 = 0.14978 as the same W1 = 0.1995 6143 W* = 0.24975114

W # = 0->9950229

addition: $W_7^* = W_7 - n \times \left(\frac{\partial E b o bal}{\partial W_7}\right)$ $\frac{\partial E total}{\partial W_7} = \frac{\partial E total}{\partial out \partial_2} \times \frac{\partial Out \partial_2}{\partial net \partial_1} \times \frac{\partial net \partial_2}{\partial W_7}$ $\frac{\partial E + tal}{\partial u + 0} = -\left(target \ 02 - out \ 02\right) = -\left(0.99 - 0.77293\right)^{\frac{2}{2}} = -0.21707$ 3 outor = outor (1-outor) = 0.77293 (1-0.77293) = 0.17551 Anetor = 1x out h, x W, (1-1)+0+0 = out h, = 0.59327 $W_7^* = 0.5 - 0.5 \times (-0.21707 \times 0.1755 (\times 0.59327) = 0.511301$ $W_3^{\dagger} = W_3 - n \times \frac{\partial E \text{ total}}{\partial W_2}$ DEtatal = DEtatal X Douth 2 X Anoths X Douths a outher britain of the $= \frac{\partial E O_1}{\partial \text{ out his}} + \frac{\partial E O_2}{\partial \text{ out his}}$ = $\frac{\partial E O I}{\partial net O Z} \times \frac{\partial net O Z}{\partial outh_{Z}} + \frac{\partial E O_{Z}}{\partial Aet O_{Z}} \times \frac{\partial net O Z}{\partial Aet h_{x}}$ $= \frac{\partial E \circ I}{\partial outh_{2}} \times \frac{\partial outh_{1}}{\partial net \partial z} \times \frac{\partial net \partial z}{\partial outh_{2}} + \frac{\partial E \partial z}{\partial outh_{3}} \times \frac{\partial outh_{2}}{\partial net \partial z} \times \frac{\partial net \partial z}{\partial outh_{3}}$ = -0.21707X 0.1755 | X 0.55 + AA-0-4707 x 0.1755 | X 0.55 = 0.04137 | 3 outhz = Outhz [1-outhz] = [0.59688] x (1-0.59688) = 0.240614

 $\frac{2 net h 2}{3 w_3} = \overline{z}_1 = 0.05$ $\frac{1}{3} = 0.05 - 0.5 \times 0.041371 \times 0.240614 \times 0.05 = 0.24975114$