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Supplementary Material

Particle Swarm Optimization for Efficiently Evolving Deep Convolutional Neural Networks Using an Autoencoder-based Encoding Strategy

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S-I. THE INFLUENCE OF POPULATION SIZES ON PARTICLE SWARM OPTIMIZATION (PSO)

In EAEPSO, the block structures are evolved by PSO. The population size is an essential parameter of PSO, affecting the consumed time and the performance of the final block structure. The section further investigates the influence of different population sizes on the CIFAR-10 dataset. The searched block structure's prediction accuracy on the evaluation dataset, and the computational cost of the PSO process (measured by GPU-days) are shown in Table S-I.

TABLE S-I
THE SEARCHED BLOCK STRUCTURE'S PERFORMANCE AND THE
COMPUTATIONAL COST USING DIFFERENT POPULATION SIZES.

| Population Size | Accuracy | GPU-Days |
|-----------------|----------|----------|
| 10 | 74.09% | 0.8 |
| 30 | 74.44% | 2.0 |
| 50 | 75.06% | 4.2 |

It is clearly shown that both the predictive accuracy and the GPU-days increase along with the increased population size. In the proposed EAEPSO, the particle size is set to be 30, which is a trade-off between the prediction performance and the consumed computational time. The population size can be set to be larger or smaller, considering the users' preference and available computing resources.

S-II. THE RATIONAL EXPLORATION OF STACKING THE BLOCKS

In EAEPSO, PSO searches for a good dense block structure, and then different blocks that share the same structure are stacked together to determine the best number of blocks. In this section, we design experiments to show if the whole network's performance is closely related to the performance of one block. Specifically, five different dense block structures are randomly generated first. For each one, at most four blocks are stacked together to test the performance on the CIFAR-10 dataset considering the size of the input. Fig. S-I shows the prediction error rate with different numbers of blocks. Table S-II presents the single block's performance, the network's best performance, and the number of blocks of the best networks.

From Fig. S-I, we can see the prediction error rate decreases along with the number of blocks increasing when the number is smaller than four. From Table S-II, we can see that *Structure* 5 has the lowest error rate when the network is composed

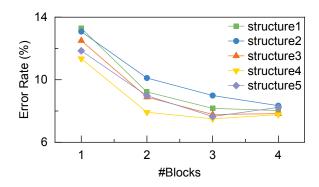


Fig. S-I. The prediciton error rates of networks stacked by different number of blocks, and there are five different block structures.

TABLE S-II
DIFFERENT SINGLE BLOCKS' PREDICTION ERROR RATES, BEST
NETWORKS' PREDICTION ERROR RATES, AND THE CORRESPONDING
NUMBERS OF BLOCKS.

| Structure | Single Block Error Rate | Lowest Network Error Rate | Corresponding Number of Blocks |
|-----------|----------------------------|------------------------------|-----------------------------------|
| 1 | 13.30% | 8.03% | 4 |
| 2 | 13.08% | 8.34% | 4 |
| 3 | 12.50% | 7.78% | 3 |
| 4 | 11.85% | 7.65% | 3 |
| 5 | 11.35% | 7.50% | 3 |

of a single block, and it also achieves the best performance when consisting of 3 blocks. Generally, the network's best performance is consistent with the single block's performance. It is reasonable to select the best-performed block structure and then stack the blocks.

S-III. USING PSO TO EVOLVE DENSE BLOCKS

PSO is usually used for addressing continuous optimization problems, and each particle, representing a potential solution, has velocity and position vectors [1]. In PSO, each particle's velocity and position are updated according to Equation (1) and Equation (2), where v_i is a vector representing the velocity of the i-th particle, and p_i expresses the position of the i-th particle. w is inertia weight, and c_1 and c_2 are two positive constants, which can be used to fine-tune the performance of PSO. r_1 and r_2 represent random numbers between 0 and 1, and p_p and p_g denotes the positions of $pBest_i$ and $gBest_i$, respectively.

$$v_i = w \cdot v_i + c_1 \cdot r_1 \cdot (p_p - p_i) + c_2 \cdot r_2 \cdot (p_g - p_i)$$
 (1)

$$p_i = p_i + v_i \tag{2}$$

Algorithm S-1 shows the procedures of evolving dense block with the two fitness evaluation methods, which can be divided into three parts, i.e., the initialization part (lines 1-7), the basic fitness evaluation guided evolution part (lines 8-22), and the progressive fitness evaluation guided evolution part (lines 23-39). In the initialization part, the population is initialized according to Algorithm 2 first (line 1). After that, all the particles' velocities are initialized (line 3), and the fitness is evaluated based on the proposed basic fitness evaluation method (presented in Algorithm 3) to get their basic fitness (line 4). Then pBest of each particle and qBestfor the population are determined (lines 5-7). After that, the basic fitness evaluation is used to guide the evolution (lines 8-22) and all particles are updated according to Equation (1) and Equation (2) (lines 13-14). If the fitness of the gBest keeps increasing, all the particles will be evaluated by the basic fitness evaluation method and updated repeatedly (lines 10-15). On the contrary, if qBest's fitness has not increased for five consecutive iterations, the current evolution is considered sufficient, and the particles will be evaluated by the proposed progressive fitness evaluation method (lines 23-39). Please note that n deep training dataset proportions are provided. Specifically, for each given training data proportion r_{prog} , the progressive fitness evaluation method (presented in Algorithm 4) is used to evaluate the fitness (line 27), and then the particles are updated (lines 28-29), and pBest and the gBest are updated based on the basic fitness and progressive fitness respectively (lines 28-32). Similarly, particles will be repeatedly evaluated and updated until gBest has not been updated for five consecutive iterations. Finally, qBest is selected and decoded to the network structure as the evolved dense block.

S-IV. ADDITIONAL PERFORMANCE TEST FOR EAEPSO

A. Overall Performance on SVHN

The Street View House Number (SVHN) dataset [2] is built based on the images of numbers collected from Google street view. The images are provided as the size of 32×32 . There are 73,257 digits in the training set and 26,032 digits in the test set. EAEPSO is performed on SVHN, and Table S-III presents the comparison results with six peer competitors regarding the model scale and the test error rate.

EAEPSO ranks the second in terms of the error rate, which is 0.05% less accurate than DenseNet (k=12) [8]. However, EAEPSO's model scale is only 46.4% of DenseNet(k=12) [8]. From the overall performance, we can say EAEPSO achieves very competitive performance on the SVHN dataset.

B. EAEPSO using ConvNeXt

To further examine the effectiveness and efficiency of the proposed method, we further change the backbone structure and build the search space based on ConvNeXt [9],

Algorithm S-1: Evolving block structure using PSO

```
Input: The population size N, the proportions of the
            progressive training data [r_{prog1},..., r_{progn}].
   Output: The best block structure.
 1 P_0 \leftarrow Initialize population according to Algorithm 2;
 2 for i = 1; i \le N; i \leftarrow i + 1 do
        v_i \leftarrow randomly initialize the velocity;
        fitb_i \leftarrow \text{ evaluate basic fitness using } Algorithm 3;
       pBest_i \leftarrow p_i;
 6 end
 7 Select gBest;
 8 times \leftarrow 0;
 9 while times < 5 do
        for i = 1; i \le N; i \leftarrow i + 1 do
10
            fitb_i \leftarrow Evaluate basic fitness using
11
              Algorithm 3;
            Update pBest_i;
12
            v_i \leftarrow \text{Update velocity using Equation (1)};
13
            p_i \leftarrow \text{Update position using Equation (2)};
14
15
        end
        Update gBest;
16
        if gBest changes then
17
            times \leftarrow 0
18
19
        else
            times \leftarrow times + 1
20
21
        end
22 end
23 for k = 1; k \le n; k \leftarrow k + 1 do
        times \leftarrow 0;
24
        while times < 5 do
25
            for i = 1; i \le N; i \leftarrow i + 1 do
26
                Evaluate basic fitness fitb_i and progressive
27
                  fitness fitp_i using Algorithm 4 with
                  proportion r_{progk};
                 v_i \leftarrow \text{Update velocity using Equation (1)};
28
                p_i \leftarrow \text{Update position using Equation (2)};
29
                update pbest_i based on fitb_i;
30
31
            Update gbest based on fitp;
32
33
            if gbest changes then
                times \leftarrow 0
34
            else
35
                times \leftarrow times + 1
36
            end
37
38
        end
   end
   Decode qbest to dense block structure;
```

41 **Return** The evolved dense block structure.

TABLE S-III
PERFORMANCE COMPARISON WITH PEER COMPETITORS ON THE SVHN
DATASET.

| Method | Number of Parameters | Error rate |
|---------------------------|----------------------|------------|
| Network in Network [3] | _ | 2.35% |
| Deeply Supervised Net [4] | _ | 1.92% |
| FractalNet [5] | 38.6M | 2.01% |
| Wide ResNet [6] | 11.0M | 1.85% |
| ResNet [7] | 1.7M | 2.01% |
| DenseNet(k=12) [8] | 7.0M | 1.67% |
| EAEPSO | 3.05M | 1.72% |

which achieves excellent performance on ImageNet. However, considering our available computational resources, we perform EAEPSO using ConvNeXt backbone, termed as EAEPSO(Conv), on the CIFAR-10 dataset [10].

1) Search space and encoding strategy:

ConvNeXt is composed of a number of blocks. In EAEPSO(Conv), PSO searches for the depth of the whole network and the convolutional layer's kernel size of each ConvNeXt block. We use a string composed of 20 integers to represent the network structure that has at most 20 blocks; each integer represents the kernel size of a ConvNeXt block, and 0 is employed to represent the corresponding block is no-existing (the total number of blocks can be smaller than 20s).

2) The performance on CIFAR-10:

The performance of EAEPSO(Conv) on CIFAR-10 is shown in Table S-IV. EAEPSO(Conv) achieves an error rate of 3.08%, a model size of 3.2M, and a computational cost of 2.4 GPU-days. The error rate is smaller than 22 competitors and is slightly larger than six peer competitors, and the reason may be the backbone structure prefers larger datasets (such as ImageNet [11]), but the data volumes of CIFAR-10 and ImageNet are vastly different. However, the model size and the computational cost are relatively small. The results show EAEPSO(Conv) is a very competitive method.

S-V. EFFECTIVENESS OF THE PROPOSED AUTOENCODER

In order to examine the effectiveness of the proposed autoencoder, three different particle representation methods are compared in the proposed method, i.e., the representation without autoencoder transforming (NAE), the representation using a comparative autoencoder which only considers the reconstruction loss (CAE), and the representation transformed by the proposed autoencoder (EAE). The parameters are set to be the same for the three experiments: the population size is 30, and the number of generations is 20. For a fair comparison, we employ a standard fitness evaluation method instead the proposed hierarchical evaluation method. The fitness of the global best particle of the 10th generation and the 20th generation are presented in Table S-V.

EAE achieves the highest fitness in both the 10th generation, and the 20th generation, and NAE's performance is worse than CAE and EAE. The use of the autoencoder greatly affects the performance, and the proposed autoencoder can improve the performance compared with a vanilla autoencoder.

TABLE S-IV PERFORMANCE COMPARISON WITH PEER COMPETITORS ON CIFAR-10.

| Model | #Parameters | Error Rate | GPU-Days |
|------------------------------|-------------|------------|----------|
| FractalNet [5] | 38.6M | 5.22% | _ |
| Maxout [12] | _ | 9.3% | _ |
| ResNet-101 [13] | 1.7M | 6.43% | _ |
| DenseNet $(k=24)$ [8] | 27.2M | 3.74% | _ |
| Highway Network [14] | | 7.72% | _ |
| VGG [15] | 20.04M | 6.66% | _ |
| CGP-CNN [16] | 2.64M | 5.98% | 27 |
| NAS [17] | 2.5M | 6.01% | 22,400 |
| Large-scale Evolution [18] | 5.4M | 5.4% | 2,750 |
| Block-QNN-S [19] | 6.1M | 4.38% | 90 |
| MetaQNN [20] | _ | 6.92% | 100 |
| EIGEN [21] | 2.6M | 5.4% | 2 |
| CNN-GA [22] | 2.9M | 4.78% | 35 |
| PNASNet-5 [23] | 3.2M | 3.41% | 150 |
| AmoebaNet-B [24] | 34.9M | 2.98% | 3,150 |
| EAS [25] | 23.4M | 4.23% | <10 |
| NASNET-A [26] | 27.6M | 2.97% | 2,000 |
| AECNN [27] | 2.0M | 4.3% | 27 |
| DENSER [28] | 10.81M | 5.87% | _ |
| GeNet from WRN [29] | _ | 5.39% | 100 |
| CoDeepNEAT [30] | _ | 7.3% | _ |
| Hier. repr-n, evolution [31] | _ | 3.63% | 300 |
| EffPnet [32] | 2.68M | 3.58% | <3 |
| DARTS [33] | 3.4M | 2.82% | 1 |
| NSGA-Net [34] | 3.3 M | 2.75% | 4 |
| LEMONADE [35] | 13.1M | 2.58% | 90 |
| NSGANetV1-A1 [36] | 0.5M | 3.49% | 27 |
| Proxyless NAS [37] | 5.7M | 2.08% | 1,500 |
| EAEPSO(Conv) | 3.2M | 3.08% | 2.4 |

TABLE S-V
PERFORMANCE COMPARISON OF DEFFERENT PARTICLE
REPRESENTATIONS.

| Method | gbest (10th generation) | gbest (20th generation) |
|--------|-------------------------|-------------------------|
| NAE | 0.7853 | 0.7867 |
| CAE | 0.7876 | 0.7885 |
| EAE | 0.7888 | 0.7901 |

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