Members		Attended (Y/N)	Tasks(Rescue Robot)	Comment
			Tasks	
Saikot Das	**Joy**	**Y**	(1) Final Requirement diagram	
			(2) Final Use case diagram	
			(3) Subsystem refinement and Architecture	done together with Manoj Luitel
			(4) Initial wheel designs (hydrolic wheels & spring suspension)	Finally not added to the final design due to dimension problem to fit to the main robot body
			(5) Final wheel design & assembly	done together with Manoj Luitel
			(6)Fully working all programming tasks with wavefront approach(indicated as primary approach)	Manoj helped me to complete this task. The task was uploaded to github and sent to professor by email as well.
			(7) Final Documentation	All team members worked together
			(8) Preparation of ppt slides	All team member worked together
Patrick Stephen	**Eteng**	**Y**	(1) Activity Diagram	The diagram was completed and approved by the Professor
			(2) Subsystem and Component Architecture Pattern	Hieracchical Control Pattern was employed here
			(3) Designing of Jet Ski Propeller and Rudder	Done together with Evrard
			(4) Final Jet Ski Assembly	Done together with Evrard
			(5) Programming Algorithm Secondary Approach	Done together with Aditya and Moaz
			(6) Final Documentaion Compilation	All team members worked together
			(7) Preparation of ppt slides	All team members worked together
Muhammad Moaz	**Amin**	**Y**	(1) Constraint Diagram	
			(2) Initial Robotic Arm design	Not added due to mating problems and scaling issue
			(3) Final Robotic Arm	Done by watching Youtube tutorials and dimensioning it according to our scale with different mating relationships.
			(4) Programming Algorithm Secondary Approach	I and Stephen helped Aditiya in his Algorithm(Secondary).
			(5) Final Documentaion Compilation	All team members worked together
			(6) Preparation of ppt slides	All team members worked together
Aditya	**Kumar**	**Y**	(1) Developed Block diagram by researching in the filed of system engineering	The task was completed and present to the professor.
			(2) Worked on development the main fraim of the robot and the chassis.	The task was very tedious as we were very inexperience in solid works and we had to make many versions
			(3) Developed the Cassis.The final version is 5th attempt on the development of the body.	The task was completed and presented to professor.
			(4) Worked and assembled the final assembly of the robot.	The task was completed and presented to professor.
			(4) Worked on the second algorithm based on quadrant system. Task1, Task 2, Task 3, Task 4.	Worked with Moaz and Stepen of the algo. The tasked was completed and presented to professor.
			(5) Final Documentaion Compilation	The task was completed and present to the professor.
			(6) Preparation of ppt slides	The task was completed and presented to professor.
Manoj	**Luitel**	**Y**	(1) Requirement Diagram: initial	Finally updated later for improvement
			(2) Block definition Diagram	
			(3) Subsystem refinement and Architecture	Together with Saikot Das Joy
			(4) 3D Parts Design: Motor, Wheel and Assembly	Together with Saikot Das Joy
			(5) Programming Algorithm Primary Approach	Together with Saikot Das Joy
			(6) Documentation: Requirement Specification, Motor-wheel and Programming	Worked Together with all the group members
			(7) Slides for final Presentation	Worked Together with all the group members
Evrard	**Leuteu Feukeu**	**Y**	(1) Initial Use-case diagram	Not considered because it was too similar to the Activity diagram
			(2) Robot concept idea and initial design prototype	Done on Thinkercard but not considered because it was too complicated to print in 3D
			(3) Designing Jet-ski propeller and Rudder (Solid woks)	Together with patrick
			(4) Final Assembly	Together with patrick
			(5) Final IEEE documentation	All team members worked on it
			(6) preparation of ppt slides	All team members worked on it