

Table of Contents						
74,576	Page					
1. GENERAL DESCRIPTION	2					
2. FEATURES						
3. BLOCK DIAGRAM						
4. PIN DESCRIPTION						
	6					
5. SPI COMMAND DESCRIPTION						
5.1 "3-Wire" Serial Port Interface	8					
5.2 "4-Wire" Serial Port Interface	9					
6. SPI CONTROL REGISTERS:	10					
6.1 Register Table						
7. ELECTRICAL SPECIFICATIONS						
7.1 Absolute Maximum Rating						
7.2 Digital DC Characteristic						
7.3 Analog DC Characteristics						
7.4 AC Characteristics						
8. REVISION HISTORY						
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All-in-one driver with TCON for Color application

1. GENERAL DESCRIPTION

This driver is an all-in-one driver with timing controller for color application. The outputs have 1-bit white/black and 1-bit red resolution output per pixel. The timing controller provides control signals for the source driver and gate drivers.

The DC-DC controller allows to generate the source output voltage VSH/VSL (+/-2.4V~+/-11V). The chip also includes an output buffer for the supply of the common electrode (VCOMAC or VCOMDC). The system is configurable through a 3-wire/4-wire (SPI) serial.

2. FEATURES

- System-on-chip (SOC) for color application
- Timing controller support several all resolution (maximum resolution 320x300)
- Support source & gate driver function:
 - 320 Outputs source driver with 1-bit white black & 1-bit red per pixel
 - Output dynamic range: \(\structure{\str

VSHR +/24++/11//(programmable, red)

- Output deviation: 0.1V
- Left and Right shift capability

300 Output gate driver:

- Output dynamic range: VGH and VGL: +16V, -15V
- Up and Down shift capability
- Common electrode level
 - AC-VCOM and DC-VCOM
 - Support sensing function (6-bit digital status)
 - Support LUT
- Charge Pump: On-chip booster and regulator
- Built in Frame memory maximum: (320 x 300 x 1 bit) x 2 SRAM
- Built in temperature sensor:
 - On-Chip: On-Chip: $-25\sim50$ °C ± 2.0 °C / 8-bit status
 - Off-Chip: $-55\sim125^{\circ}\text{C} \pm 2.0^{\circ}\text{C} / 11$ -bit status ($I^{2}\text{C/LM75}$)
- Support LPD, Low Power detection (VDD<2.5V)
- OCS : On-chip RC oscillator

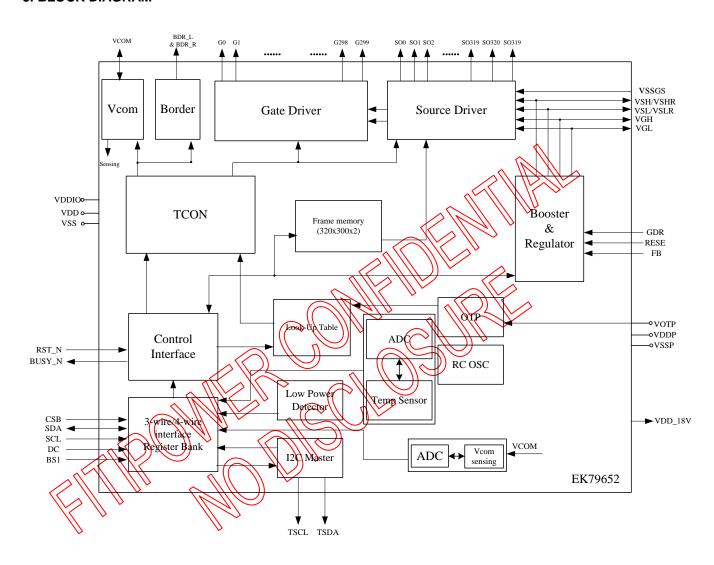
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- 3-wire/4-wire (SPI) serial interface for system configuration: Clock rate up to 20MHz
- Digital supply voltage: 2.3~3.6V
- Support cascade





3. BLOCK DIAGRAM





4.1 Pin define

Pin Name	Pin Type	I/O Structure	Description
		Seria	Communication Interface
CSB		Type 2	Serial communication chip select.
SDA	I/O	Type 4	Serial communication data input.
SCL	I	Type 3	Serial communication clock input.
DC	I	Type 2	Serial communication Command/Data; input L: Command H: data (default)
			Control Interface
RST_N	I	Type 2	Global reset pin. Low reset. (normal pull high) When RST_N become low, driver will reset. All register will reset to default value, all driver function will disable. SD output and VCOM will base on previous condition. It may have two conditions, over floating.
BUSY_N	0	Type1	This pin indicates the driver status, BUSY_N="0": Driver is busy, data/VCOM is transforming. BUSY_N="1": non-busy. Host side can send command/data to driver.
BS	1	Type 5	Input interface setting. Select 3 wire/ 4 wire SPI interface L: 4-wire IF H:3-wire IF (Default)
TSCL		Type1	If Clock for external temperature sensor
TSDA	(VO)	Туре	V ² C data for external temperature sensor
MS	_ (//	Type 5	Master/Slave selection for cascade mode Low: Slave High: Master In single-chip mode, MS should be connect to VDD
Output Driver			3 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 - 1 -
S[0,319]	0	-	Source driver output signals.
G[0,299]	0	-	Gate driver output signals
			Border
BDR_L, BDR_R	0	-	Border output pins. It outputs black WF.
VCOM GENERATO	R		
VCOM_PASSR/ VCOM PASSL	I/O		VCOM Internal Pass Line
VCOM	0	Type 1	VCOM output. VCOM has follow four voltage state: 1. (VSH-VCM_DC) v 2. (-VCM_DC) v 3. (VSL-VCM_DC) v. 4. Floating
			Power Circuit
GDR	0	-	This pin is N-MOS gate control.
RESE	Р	-	Current sense input for control loop.
FB	P	<u> </u>	Keep open
VGH	Р	Type 4	Positive gate voltage
VGL	Р	Type 4	Negative gate voltage.

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Pin Name	Pin Type	I/O Structure	Description
VSH	Р	Type 4	Positive source voltage
VSL	Р	Type 4	Negative source voltage.
VSHR	Р	Type 4	Positive source voltage for Red
VSLR	Р	Type 4	negative source voltage for Red
			Power Supply
VSSP	Р	-	DCDC Ground
VDDP	Р	-	DCDC power input
VDD	Р	-	Digital/Analog power.
VSS	Р	-	Digital ground
VSSA	Р		Analog Ground
VDDIO	Р	-	IO voltage supply
VDD_18V	Р	-	1.8V voltage input &output
VOTP	Р	-	OTP program power (7.5½)
VSSGS	Р		Driver Ground
Reserved Pins			
TP[66:0]	I/O	-	Leave it floating
			Cascade direction
MS_LR	I	Type 5	0 (Master(right side output) > Slave(left side input)
		(1	> Slave (right side input) < master (left side output)
VSYNC_R	I/O	Type 4	Cascade right side Vsync
VSYNC_L	I/O	Type A	Cascade left side Vsync)
SYNCM_R	I/O	Type 4	Cascade master right side state sync
SYNCM_L	I/O 🔬	Type 4	Cascade master left side state sync
SYNCS_R	NO	Type 4	Cascade slave right side state sync
SYNCS_L		Type 4	Cascade slave left side state sync
CLK_L		Type 4	Cascade left side reference clock pin
CLK_R /\\	N S	Type 4	Cascade right side reference clock pin
HSYNG(L)	/// I/O	Type 4	Cascade left side system clock pin
HSYNC_R \\) I/O (\\ T ype 4	Cascade right side system clock pin
ENZZ \	I/O	Type 4	Cascade left side enable pin
EN_R	I/O	√ Type 4	Cascade right side enable pin
DT_Ľ	I/O	Type 4	Cascade left side data pin for temperature data
DT_R	I/O	Type 4	Cascade right side data pin for temperature data

Note: I: Input, O: Output, P: Power, D: Dummy, S: Shorted line, M: Mark, PI: Power input, PO: Power output, I/O: Input / Output. PS: Power Setting, C: Capacitor pin.

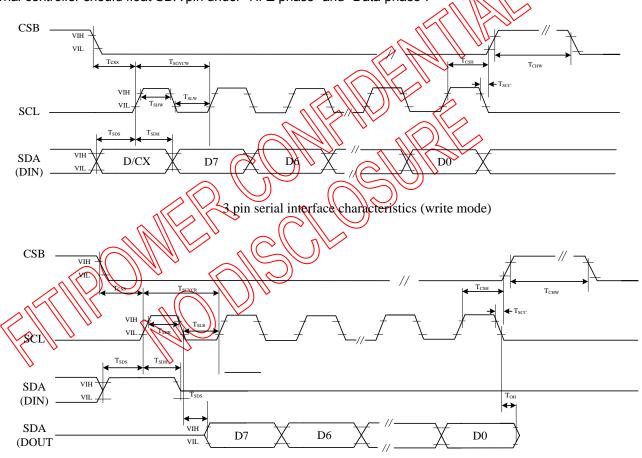


5. SPI COMMAND DESCRIPTION

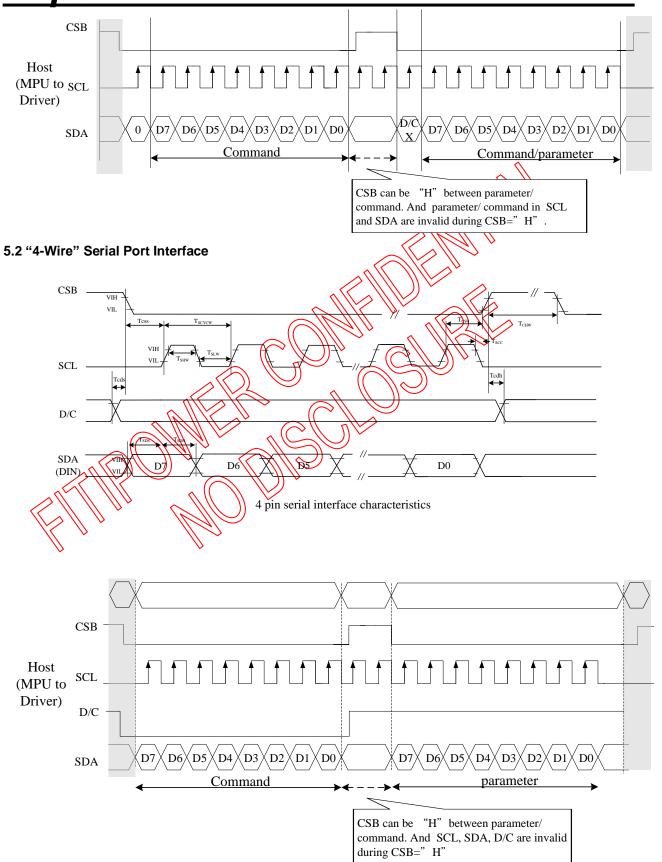
5.1 "3-Wire" Serial Port Interface

EK79652 use the 3-wire serial port as communication interface for all the function and command setting. 3-Wire communication can be bi-directional controlled by the "R/W" bit in address field. EK79652 3-Wire engine act as a "slave mode" for all the time, and will not issue any command to the 3-Wire bus itself.

Under read mode, 3-Wire engine will return the data during "Data phase". The returned data should be latched at the rising edge of SCL by external controller. Data in the "Hi-Z phase" will be ignored by 3-Wire engine during write operation, and should be ignored during read operation also. Quring read operation, external controller should float SDA pin under "Hi-Z phase" and "Data phase".



3 pin serial interface characteristics (read mode)





6. SPI CONTROL REGISTERS:

6.1 Register Table

Following table list all the SPI control registers and bit name definition for EK79652. Refer to the next section for detail register function description.

section for detail register function description.												
Address	command	DAM	D/CV	D7	DC	Dr.	Bit	Da	Do	D4	Do	Code
		R/W	D/CX		D6	D5	D4	D3	D2	D1	D0	Code
R00H	Panel setting (PSR)	W	0	0	0	0	0	0	0	0	0	00H
		W	1	RES[1]	RES[0]	REG_EN	BWR	UD	SHL	SHD_N	RST_N	07h
		W	1	-	-	-	-	-	- A	VOHL LV	VDG_EN VGHL_LV	03h
Double	D " (DMD)	W	1			-	-	-	VCOM_HW		[0]	00h
R01H	Power setting (PWR)	W	1			VSH [5]	VSH [4]	VSH [3]	(VSHV2)	VSHMI	VSH [0]	26h
		W	1			VSL [5]	VSL [4]	AST [3]/	VS L [2]	VSL [1]	VSL [0]	26h
Doold	D 055(D05)	W	1		VSHR [6]	VSHR [5]	VSHR [4]	VSHRIST	VSHR [2]	VSHR [1]	VSHR [0]	03h
R02H	Power OFF(POF)	W	0	0	0	0		0	0	1	0	02H
R03H	Power off Sequence	W	0	0	0	0 T_VD\$_OFF	TVDS OF	100	0	1	1	03H
	Setting(PFS)	W	1	-	-	1/1/	V64/)				00h
R04H	Power ON (PON)	W	0	0	0	1/18/21	87	2	1/1	0	0	04H
R05H	Power ON Measure (PMES)	W	0	0		11/00	0 0	19		0	1	05H
		W	0	0 ((0	<i>)</i>)		0)	0	1	1	06H
R06H	Booster Soft Start	W	1	BT_RHA7	ВТ_РНА6	BT_PHA5	BT PHA4	BT_PHA3	BT_PHA2	BT_PHA1	BT_PHA0	03h
. 100. 1	(BTST)	W		BT_PHB7	вт_РНВ6	BT_PHB5	BT_AND		BT_PHB2	BT_PHB1	BT_PHB0	00h
		W	\mathbb{W}	1/1-0	- (BT_PHC5	BT PHC4	BT_PHC3	BT_PHC2	BT_PHC1	BT_PHC0	26h
R07H	Deep Sleep(DSLP)	11 W	///0//	∕ 8		91	> 0	0	1	1	1	07H
	, , ,	W	1/1/1	1 (16		0	0	1	0	1	A5h
R10H	Data Start transmission1	(W)	<u>)</u> 0		11100)) 0	1	0	0	0	0	10H
(DTM1)	*	1	#	// *//	#	#	#	#	#	#	00H	
R11H	Data Stop (DSP)	W	70(10	0	0	1	0	0	0	1	11H
141111		R	////	Data_flag	-	-	-	-	-	-	-	00h
R12H	Display Refresh (DRF)	w	1/24/	0	0	0	1	0	0	0	1	12H
R13H	Data Start transmission	W	B	0	0	0	1	0	0	0	0	13H
KISH	2(DTM2)	W	1	#	#	#	#	#	#	#	#	00H
Daoli		W	0	0	0	1	1	0	0	0	0	30H
R30H	OSC control (OSC)	W	1	-	SEL_	DIV[1:0]			SEL_F[4:0]		3Ch	
	Tama anatoni Occio	W	0	0	1	0	0	0	0	0	0	40H
R40H	Temperature Sensor Command (TSC)	R	1	D10/TS[7]	D9/TS[6]	D8/TS[5]	D7/TS[4]	D6/TS[3]	D5/TS[2]	D4/TS[1]	D3/TS[0]	
	30	R	1	D2	D1	D0	-	-	-	-	-	
R41H	Temperature Sensor	W	0	0	1	0	0	0	0	0	1	41H
134111	Calibration (TSE)	W	1	TSE	-	-	-	TO[3]	TO[2]	TO[1]	TO0]	
		W	0	0	1	0	0	0	0	1	0	42H
R42H	Temperature Sensor	W	1	WATTR[7]	WATTR[6]	WATTR[5]	WATTR[4]	WATTR[3]	WATTR[2]	WATTR[1]	WATTR[0]	00h
	Write (TSW)	W	1	WMSB[7]	WMSB[6]	WMSB[5]	WMSB[4]	WMSB[3]	WMSB[2]	WMSB[1]	WMSB[0]	00h
		W	1	WLSB[7]	WLSB[6]	WLSB[5]	WLSB[4]	WLSB[3]	WLSB[2]	WLSB[1]	WLSB[0]	00h
	Temperature Sensor	W	0	0	1	0	0	0	0	0	1	43H
R43H	Read (TSR)	W	1	RMSB[7]	RMSB[6]	RMSB[5]	RMSB[4]	RMSB[3]	RMSB[2]	RMSB[1]	RMSB[0]	
		W	1	RLSB[7]	RLSB[6]	RLSB[5]	RLSB[4]	RLSB[3]	RLSB[2]	RLSB[1]	RLSB[0]	
R50H	VCOM and DATA	W	0	0	1	0	1	0	0	0	0	50H
	interval setting (CDI)	W	1	VBD[1]	VBD[0]	DDX[1]	DDX[0]	CDI[3]	CDI[2]	CDI[1]	CDI[0]	D7h
R51H	Lower Power	W	0	0	1	0	1	0	0	0	1	51H
ПІСЯ	Detection (LPD)	R	1	-	-	-	-	-	-	-	LPD	

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R60H	TCON setting	W	0	0	1	1	0	0	0	0	0	60H
110011	(TCON)	W	1	S2G[3]	S2G[2]	S2G[1]-	S2G[0]	G2S[3]	G2S[2]	G2S[1]	G2S[0]	22h
		W	0	0	1	1	0	0	0	0	1	61H
	Description.	W	1								HRES(8)	00h
R61H	Resolution setting(TRES)	W	1	HRES(7)	HRES(6)	HRES(5)	HRES(4)	HRES(3)	HRES(2)	HRES(1)	-	00h
	Johnning (TTCE)	W	1								VRES(8)	00h
		W	1	VRES(7)	VRES(6)	VRES(5)	VRES(4)	VRES(3)	VRES(2)	VRES(1)	VRES(0)	
		W	0	0	1	1	0	0	0	1	0	
		W	1								S_start [8]	
R62H	Source & gate start setting	W	1	S_start (7)	S_start (6)	S_start (5)	S_start (4)	S_start (3)	S_start (2)	(\$_ start (1)	S_start (0)	
	Setting	W	1				gscan		A R		G_start [8]	
		W	1	G_start (7)	G_start (6)	G_start (6)	G_start (4)	G_start (3)	G_start (2)	G_Start (1)	G_start (0)	
D 701.1	DEVICION (DEV)	W	0	0	1	1	1	0 (110/1	\ ŏ	0	70H
R70H	REVISION (REV)	R	1	REV[7]	REV[6]	REV[5]	REV[4]	NEW 31	REW[2]	REV[1]	REV[0]	001
		W	0	0	1	1	1 (20/	0	0	1	71H
R71H	Status register(FLG)	R	1	-	PTL_flag	I ² C_ERR	BUSYN	Data_flag	PON	POF	BUSY_N	02h
DOOLI	Auto Measure Vcom	W	0	1	0	8/	11/4	0	/9	0	0	80 I
R80H	(AMV)	W	1	-	-	AMYTIN	AMINTO	XON	AMVŞ	AMV	AMVE	10h
R81H	\/aam \/alua (\/\)	W	0	1	2	1/16/11	O	76	100	0	1	81H
коіп	Vcom Value (VV)	R	1	-	V V [6]	[5]VV[1]	VV[4] ^	/k//3/	WYE	VV[1]	VV[0]	001
R82H	Vcom_DC Setting	W	0	1 ((~ 4/)) 8	€ \(\)		0	1	0	82H
Ko∠⊓	register(VDCS)	W	1	$\langle \rangle$	VCDS[6]	VCDS[5]	VCDS [4]	Acda [3]	VCDS [2]	VCDS [1]	VCDS [0]	001
RE0H	CASCADE setting	W	92)	1 (19/0	り 。	0	0	0	EOH
KEUN	(CCSET)	W	1/1		- /		\bigcirc	cce_sel	cce_lr	TSFIX	CCEIN	001
RE5H Force Tempera	Force Temporature	w M	1101		1	1	0	0	1	0	1	E5H
	Force remperature		MY	TS_SET[7]	TS SET[6]	TS_SE [5]	TS_SET[4]	TS_SET[3]	TS_SET[2]	TS_SET[1]	TS_SET[0]	001
RE5H	Force Temperature	''	1	TS_SET[7]	TS SETIGI	TS_SE [5]				_		Τ[0]



7. ELECTRICAL SPECIFICATIONS

7.1 Absolute Maximum Rating

Parameter	Symbol	Min.	Max.	Unit
Logic supply voltage	VDD, AVDD, VDDIO, VDD1, VPP	-0.3	+6.0	V
Digital input voltage	VI	-0.3	TBD	V
Supply range	VGH-VGL	VGL-0.3	VGH+0.3	V
Analog supply	VSH	+2.4	+11	V
Analog supply	VSL	-11,	-24	V
Analog supply	VSHR	15-N/ //	+11	
Supply voltage	VGH		+16	V
Supply voltage	VGL)\\-Y5	-	V
Storage temperature	T _{STG}	-55	125	$^{\circ}\!\mathbb{C}$

Note:

Absolute Maximum Ratings are stress ratings. Stresses in excess of these ratings can cause permanent damage to the device. Functional operation of the device at these or any other conditions beyond those indicated in the operational sections of this data sheet is not implied.

Exposing device to the absolute maximum ratings in a long period of time may degrade the device and affect its reliability.



7.2 Digital DC Characteristic

DC electrical characteristics

Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
IO Supply Voltage	VDDIO	2.3	3.3	3.6	V	Cornainon
Digital/Analog supply voltage	VDD	2.3	3.3	3.6	V	
DCDC power input voltage	AVDD	2.3	3.3	3.6	V	
1.8V output voltage	VDDDO	1.62	1.8	1.98		
1.8V input voltage	VDDD	1.62	1.8	1.98		
OTP program power	VPP	7.25	7.5	7.75		
Digital ground	VSS		0		1	
DCDC ground	AVSS		0		1, 11	10
Low Level Input Voltage	Vil	GND	-	0.3xVDD	W.	Digital input pins
High Level Input Voltage	Vih	0.7xVIO	-	MO	$\sqrt{\Lambda}$	Digital input pins
High Level Output Voltage	Voh	VIO-0.4	-/>	111 -111	V	Digital output pins; IOH = 400µA
High Level Output Voltage	Vohd	VDD1-0.4				Digital output pins; IOH = 400μA ØRVD, DRVU
Low Level Output Voltage	Vol	GND		V GND+0.♥		Digital output pins; IOL = -400μA
Input Leakage Current	lin	1.0		FD.0	ŲΑ	Ďigital input pins, except pull-up, pull-down pin
Pull-up/down impedance	Rin	9	200K		ohm	
Digital Stand-by Current (power off mode)	IstVDD*) B	0.1	uA	All stopped
Digital Operating Current	/WDD*	- (0.5	2.0	mΑ	
IO Stand-by Current (power off mode)	IStVIO*		0.4	1.0	uA	All stopped
IO Operating Current	IVIO*		1	0.2	mΑ	No load
DCDC Stand-by Current (power off mode)	IstVDD1*		0	0.01	uA	All stopped
DCDC Operating Current	IXDD4*		-	0.05	mΑ	fdcdc=250kHz, No load
DCDC Operating Current	IVDD1*	-	0.5	1.0		fdcdc=250kHz, External cap: PMOS=415pF, NMOS=340pF
Operating temperature	T op	-30	-	85	$^{\circ}\!\mathbb{C}$	

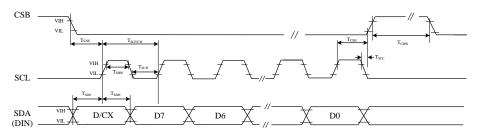
NOTE: typ. and max. values to be confirmed by design



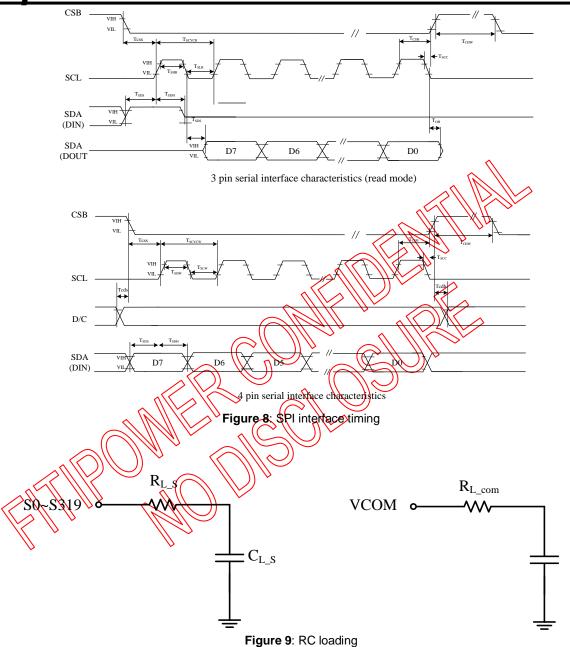
Davamatan	Comple al	N Alice	Т	Mari	1 1-2:4	Condition
Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
Positive Source voltage	VSH		10			For source driver/VCOM
Positive Source voltage dev	d VSH	-300	0	+300	mV	
Negative Source voltage	VSL		-10		V	For source driver/VCOM
Negative Source voltage dev	d VSL	-300	-	+300	mV	
Positive Source voltage for Red	VSHR					
Negative Source voltage for Red	VSLR					
Analog Operating Current	ldd		TBD		mA\	No load
Voltage Deviation of Outputs	Vvd		±20	±35 <	\m\\	
Dynamic Range of Output	Vdr	0.1	-	VSH-0.1	$// \vee //$	70
Voltage Range of VGH - VGL	VGH-VGL	4.8	-	31	W	
Negative Source voltage	VGL	-15		(\ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \ \	<u>></u> ∧	For gate driver
Negative Source voltage dev	dVGL	-400	0	\\\+400°	mγ	
Positive Source voltage	VGH	13		16	N/	For gate driver
Positive Source voltage dev	dVGH	-400	1/8/1/	+400	mA	
Positive HV Stand-by Current (power off mode)	IstVGH*	\approx		0:01	(UA)	Include VSH power With load
Positive HV Operating Current	,₩GH*		AZ N	1.1	mA	Include VDPS power With load all SD=L VCOM external resistor divider not included
Positive HV Operating Current	IVDPG*		0.8	1.2		Include VDPS power With load all SD=H VCOM external resistor divider not included
Negative HV Stand-by Current (power off mode)	IstXDNG*	-	0	0.01	•	Include VDPNS power With load
Negative HV Operating Current	IVDNG*	-	0.8	1.2	mA	Include VDNS power With load all SD=L
Negative HV Operating Current	IVDNG*	-	0.9-	1.3	mA	Include VDNS power With load all SD=H
VINT1 Stand-by Current (power off mode)	IstVINT1*		0	0.01	μΑ	
VINT1 Operating Current	IVINT1*			0.3	mΑ	



Parameter	Symbol	Min.	Тур.	Max.	Unit	Condition
SERIAL COMMUNICATION						
	tCSS	60			ns	Chip select setup time
CSB	tCSH	65			ns	Chip select hold time
COB	tSCC	20			ns	Chip select CSB setup time
	tCHW	150			ns	Chip select setup time
	tSCYCW	100			ns	Serial clock cycle (Write)
	TSHW	35	-) Ale	SCL "H" pulse width (Write)
001	tSLW	35	-	n ^C	//ns//	SCL "L" pulse width (Write)
SCL	tSCYCR	150	-	120	ηę	Serial clock cycle (Read)
	TSHR	60			nš	SCL "H" pulse width (Read)
	tSLR	60	^<<	111/2/1	ns	SCL "L" pulse width (Read)
	tSDS	30			Ŋs	Data setup time
SDA	tSDH	30			ns	Data hold time
(DIN)	tACC	10) NS	Access time
(DOUT)	tOH	45 ((11110		06	Output disable time
D/C	Tcds	20 ฏ			>	DC setup time
D/C	Todh	20	-1			DC hold time
RC loading		. (
Source driver output loading	NAT &		13.36K		Ω	
Source driver output loading	///ci_s		39.19		pf	
Gate driver output loading	RL_S		7 12.32K		Ω	
Cate driver output dading	CLS		32.09		pf	
VCOW output loading	RL com		61.26		Ω	
vectivi datpat reading	CL COM		3365.7		pf	
Driver \\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\						
Source driver rise time	trS		5		us	99% final value
Source driver fall time	tFS		5		us	
Gate driver rise time	TrG		5		us	99% final value
Gate driver fall time	tFG		5		us	
VCOM rise time	trCOM		1		ms	99% final value
VCOM fall time	tFCOM		1		ms	



3 pin serial interface characteristics (white mode)





Revision	Content	Page	Date
0.1	1.new issue		2015/10/27

