

/home/rishchou/catkin
_ws/src/xPLOER/include
/xplorer/obstacleDetector.hpp

```
graph TD; A["/home/rishchou/catkin_ws/src/xPLOER/include/xplorer/obstacleDetector.hpp"] --> B[iostream]; A --> C[ros/ros.h]; A --> D[sensor_msgs/LaserScan.h]; A --> E[std_msgs/Float64.h];
```

iostream

ros/ros.h

sensor_msgs/LaserScan.h

std_msgs/Float64.h