

Data Structures: Lists

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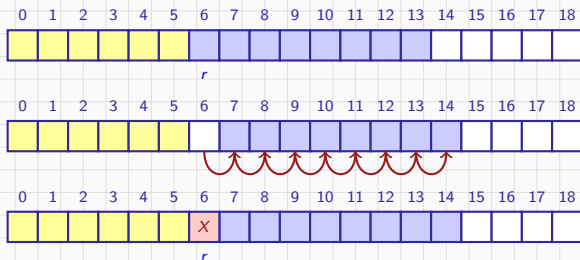
Linked Lists

Introduction

Array: successive items locate a fixed distance

👉 Disadvantages:

- data movements during insertion and deletion
- waste space in storing n ordered lists of varying size



Nonsequential List-Representation

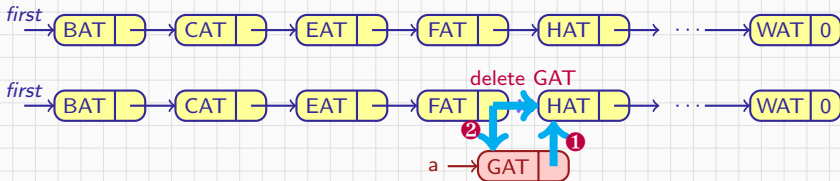
Insert "GAT" at Position 5

	1	2	3	4	5	6	7	8	9	10	11
<i>first</i> → 8	HAT		CAT	EAT			WAT	BAT	FAT		VAT
	11		4	9			0	3	1		7

	1	2	3	4	5	6	7	8	9	10	11
<i>first</i> → 8	HAT		CAT	EAT	GAT		WAT	BAT	FAT		VAT
	11		4	9	1		0	3	5		7

A Linked List

1. Get a node **a**
2. Set the "data" field of a to "GAT"
3. Set the "link" field of a to point to the node after FAT, which contains HAT
4. Set the "link" field of the node containing FAT to a

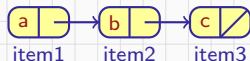
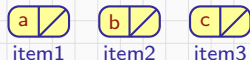
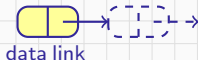


Representations

Self-Referential Structures

One or more of its components is a pointer to itself.

```
typedef struct list{  
    char data;  
    struct list *link;  
} list;  
  
list item1, item2, item3;  
item1.data = 'a';  
item2.data = 'b';  
item3.data = 'c';  
item1.link = item2.link = item3.link = NULL;  
  
item1.link = &item2;  
item2.link = &item3;
```



List of Words

- A node:

```
typedef struct listNode *listPointer;  
typedef struct listNode {  
    char data[4];  
    listPointer link;  
};
```

- Creation

```
listPointer first = NULL;
```

- Testing

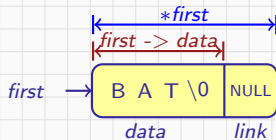
```
#define IS_EMPTY(first) (!(first))
```

- Structure member: `(*e).name` OR `e->name`

- Copy

```
strcpy(first->data, "BAT");
```

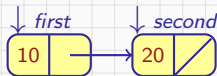
```
first->link = NULL;
```



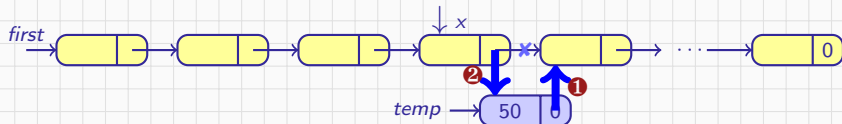
Two-Node Linked List

Create a two-node list

```
typedef struct listNode *listPointer;  
typedef struct listNode {  
    int data;  
    listPointer link;  
} listNode;  
listPointer first = NULL;  
listPointer create2( ) {  
    listPointer first, second;  
    MALLOC(first, sizeof(listNode));  
    MALLOC(second, sizeof(listNode));  
    second->link = NULL;  
    second->data = 20;  
    first->data = 10;  
    first->link = second;  
    return first;  
}
```



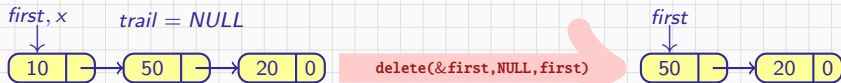
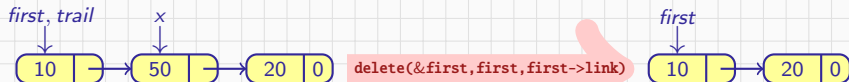
Singly Linked Lists: Insertion



```
void insert(listPointer *first, listPointer x)
{ /*Insert a node after node x
  listPointer temp;
  MALLOC(temp, sizeof(*temp));
  temp->data = 50;
  if (*first) {
    temp->link = x->link;
    x->link = temp;
  }
  else {
    temp->link = NULL;
    *first = temp;
  }
}
```

insert(&first, x);

Singly Linked Lists: Deletion



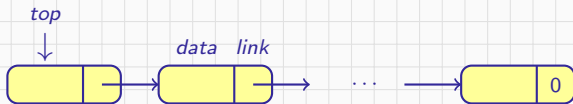
```
void delete(listPointer *first, listPointer trail, listPointer x)
{
    /*Delete node x
    if (trail) /*Delete a node other than the first node
        trail->link = x->link;
    else /*Delete the first node
        *first = (*first)->link;
    free(x);
}
```

Printing out a List

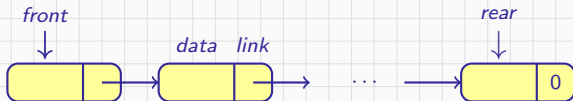
```
void printList(listPointer first)
{
    printf("The list contains: ")
    for (; first; first = first->link)
        printf("%4d", first->data);
    printf("\n");
}
```

Linked Stacks and Queues

*Linked stack:



*Linked queue:



Multiple Stacks

```
#define MAX_STACKS 10
typedef struct element {
    int key;
    /* other fields */
} element;
typedef struct stack *stackPointer;
typedef struct stack {
    element data;
    stackPointer link;
} stack;
stackPointer top[MAX_STACKS];
```

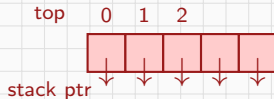
```
void push(int i, element item)
{
    stackPointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->data = item;
    temp->link = top[i];
    top[i] = temp;
}
```

Initial condition:

$\text{top}[i] = \text{NULL}, 0 \leq i < \text{MAX}$

Boundary condition:

$\text{top}[i] = \text{NULL} \Leftrightarrow \text{ith stack is empty}$



```
element pop(int i)
{
    stackPointer temp = top[i];
    element item;
    if (!temp)
        return stackEmpty();
    item = temp->data;
    top[i] = temp->link;
    free(temp);
    return item;
}
```

Multiple Queues

```
#define MAX_QUEUES 10
typedef struct queue
*queuePointer;
typedef struct queue {
    element data;
    queuePointer link;
} queue;
queuePointer front[MAX_QUEUES],
rear[MAX_QUEUES];
```

```
void addq(int i, element item)
{
    queuePointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->data = item;
    temp->link = NULL;
    if (front[i])
        rear[i] ->link = temp;
    else
        front[i] = temp;
    rear[i] = temp;
}
```

Initial condition:

$\text{front}[i] = \text{NULL}, 0 \leq i < \text{MAX}$

Boundary condition:

$\text{front}[i] = \text{NULL} \Leftrightarrow \text{ith queue is empty}$

```
element deleteq(int i)
{
    queuePointer temp = front[i];
    element item;
    if (!temp)
        return queueEmpty();
    item = temp->data;
    front[i] = temp->link;
    free(temp);
    return item;
}
```

Polynomials

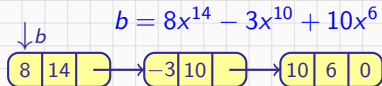
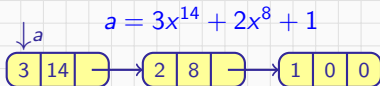
Polynomial Representation

- $A(x) = a_{m-1}x^{e_{m-1}} + \dots + a_0x^{e_0}$
where $a_i \neq 0$ for all i and $e_{m-1} > \dots \geq 0$
- Assume that $a_i \in \mathbb{Z}^+$

```
typedef struct polyNode
*polyPointer;
typedef struct polyNode {
    int coef;
    int expon;
    polyPointer link;
} polyNode;
polyPointer a,b;
```

coef	expon	link
------	-------	------

Example



```

polyPointer padd(polyPointer a, polyPointer b)
{
    polyPointer c, rear, temp;
    int sum;
    MALLOC(rear, sizeof(*rear));
    c = rear;
    while (a && b)
        switch (COMPARE(a->expon,b->expon)) {
            case -1: /* a->expon < b->expon */
                attach(b->coef,b->expon,&rear);
                b = b->link;
                break;
            case 0: /* a->expon = b->expon */
                sum = a->coef + b->coef;
                if (sum) attach(sum,a->expon,&rear);
                a = a->link; b = b->link; break;
            case 1: /* a->expon > b->expon */
                attach(a->coef,a->expon,&rear);
                a = a->link;
        }
    for (; a; a = a->link) attach(a->coef,a->expon,&rear);
    for (; b; b = b->link) attach(b->coef,b->expon,&rear);
    rear->link = NULL;
    temp = c; c = c->link; free(temp);
    return c;
}

```

Attach a Node

```
void attach(float coefficient, int exponent, polyPointer *ptr)
{
    polyPointer temp;
    MALLOC(temp, sizeof(*temp));
    temp->coef = coefficient;
    temp->expon = exponent;
    (*ptr)->link = temp;
    *ptr = temp;
}
```

Analysis of padd

- There are three cost measures
 1. coefficient additions
 2. exponent comparisons
 3. creation of new nodes for c
- Assume that each of these operations takes a single unit of time if done once. And

$$A(x) = a_{m-1}x^{e_{m-1}} + \dots + a_0x^{e_0} \quad \text{and}$$

$$B(x) = b_{n-1}x^{f_{n-1}} + \dots + b_0x^{f_0}$$

$$\Rightarrow 0 \leq \# \text{ of coefficient additions} \leq \min\{m, n\}$$

- We make one comp on each iteration of the while loop. On each iteration, either a or b or both move to the next term.
An extreme case: $e_{m-1} > f_{n-1} > e_{m-2} > f_{n-2} > \dots > e_0 > f_0$
 $\Rightarrow \# \text{ of exponent comparisons} \leq m + n - 1$
- In summary, the max $\#$ of the executions $\Rightarrow O(m + n)$

Erasing Polynomials

- **Example:**

$$e(x) = a(x) * b(x) + d(x)$$

```
polyPointer a,b,d,temp;  
a = readPoly();  
b = readPoly();  
d = readPoly();  
temp = pmult(a,b);  
e = padd(temp,d);
```

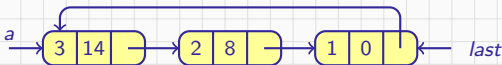
Return the nodes of temp(x)!!!

```
void erase(polyPointer *ptr)  
{  
    polyPointer temp;  
    while (*ptr) {  
        temp = *ptr;  
        *ptr = (*ptr) ->link;  
        free(temp);  
    }  
}
```

Circular Representation of Polynomials

- We can free all the nodes of a polynomial more efficiently if we modify our list structure to a **circular** list. (not a chain)

EX: $3x^{14} + 2x^8 + 1$



- We free nodes that are no longer in use. But we may reuse some nodes later.
 - ⇒ Collect the "freed" space to **the avail list**
 - ⇒ Only when the list is empty do we need to use "MALLOC" to
create a new node.

Maintaining an Available List

Constant time:

Independent of # of nodes in a list $\Rightarrow O(1)$.

```
void retNode(polyPointer node)
{
    node->link = avail;
    avail = node;
}
```

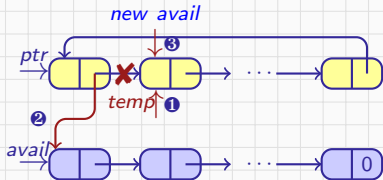
Initially, avail = NULL

```
polyPointer getNode(void)
{
    polyPointer node;
    if (avail) {
        node = avail;
        avail = avail ->link;
    }
    else
        MALLOC(node, sizeof(*node));
    return node;
}
```

Erasing a Circular List

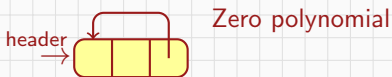
- We may erase a circular list in a fixed amount of time
constant time!

```
void cerase(polyPointer *ptr)
{
    polyPointer temp;
    if (*ptr) {
        temp = (*ptr)->link; ①
        (*ptr)->link = avail; ②
        avail = temp; ③
        *ptr = NULL;
    }
}
```

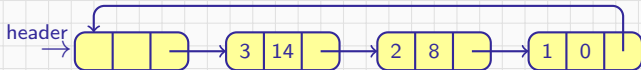


A Header Node

- Note: we have to handle **the zero polynomial** as a special case!
- A possible solution ➡ header nodes
Each polynomial, zero or nonzero, contains a one additional node.



$$3x^{14} + 2x^8 + 1$$



```

polyPointer cpadd(polyPointer a, polyPointer b)
{
    polyPointer startA, c, lastC;
    int sum, done = FALSE;
    startA = a; a = a->link; b = b->link;
    c = getNode(); c->expon = -1; lastC = c;
    do {
        switch (COMPARE(a->expon, b->expon)) {
            case -1: /* a->expon < b->expon */
                attach(b->coef, b->expon, &lastC);
                b = b->link;
                break;
            case 0: /* a->expon = b->expon */
                if (startA == a) done = TRUE;
                else {
                    sum = a->coef + b->coef;
                    if (sum) attach(sum, a->expon, &lastC);
                    a = a->link; b = b->link;
                }
                break;
            case 1: /* a->expon > b->expon */
                attach(a->coef, a->expon, &lastC);
                a = a->link;
        }
    } while (!done);
    lastC->link = c; return c;
}

```

Additional Operations

Inverting for Chains

- Chain: A singly linked list in which the last node has a null link

```
listPointer invert (listPointer lead)
{
    listPointer middle, trail;
    middle = NULL;
    while (lead){
        trail = middle;
        middle = lead;
        lead = lead->link;
        middle->link = trail;
    }
    return middle;
}
```

$O(\text{length})$

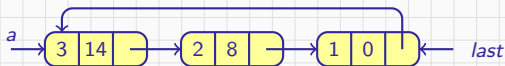
Concatenating Two Chains

- Concatenates two chains, ptr1 and ptr2.
- Assign the list ptr1 followed by the list ptr2.

```
listPointer concatenate (listPointer ptr1, listPointer  
ptr2)  
{  
    listPointer temp;  
    if (!ptr1) return ptr2;  
    if (!ptr2) return ptr1;  
    for (temp = ptr1; temp->link; temp = temp->link) ;  
    temp->link = ptr2;  
}
```

Inserting at the Front of a Circularly List

- $3x^{14} + 2x^8 + 1$



```
void insertFront (listPointer *last, listPointer node)
{
    if (!(*last)) {
        *last = node;
        node->link = node;
    }
    else {
        node->link = (*last)->link;
        (*last)->link = node;
    }
}
```

Finding the Length of a Circular List

```
int length (listPointer last)
{   listPointer temp;
    int count = 0;
    if (last) {
        temp = last;
        do {
            count++;
            temp = temp->link;
        } while (temp != last);
    }
    return count;
}
```

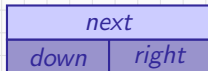
Sparse Matrices

Data Structures of Sparse Matrices

- Sequential representation of sparse matrix suffered from the same inadequacies as the similar representation of Polynomial.
- In Chapter 2, $\langle \text{row}, \text{column}, \text{value} \rangle$
- Here we study a circular linked list representation of a sparse matrix.

Two types of nodes:

- head node: tag, down, right, and next
- entry node: tag, down, row, col, right, and value



a head node

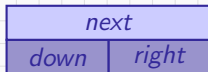


an entry node

Head Nodes for Sparse Matrices

Head node i is the head node for both row i and column i .

- Each head node involves three lists: a row list, a column list, and a head node list.
 - *down*: link into a column list
 - *right*: link into a row list
 - *next*: link into the head node together
- The total number of head nodes is $\max\{\# \text{ of rows}, \# \text{ of cloumns}\}$.



a head node

Entry Nodes for Sparse Matrices

If $a_{ij} \neq 0$, there is a node with

tag field \leftarrow entry, value $\leftarrow a_{ij}$, row $\leftarrow i$, col $\leftarrow j$

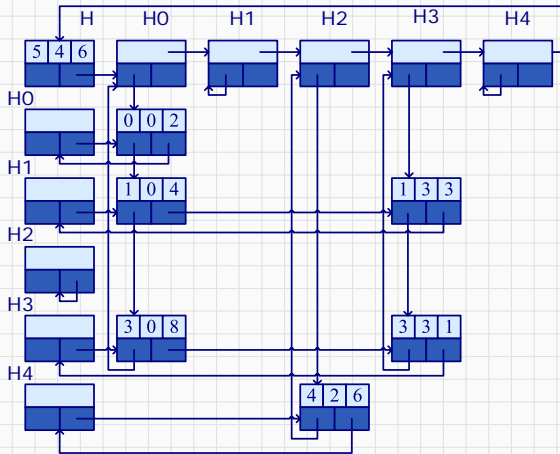
- Link this node into the circular linked list for row i and column j
 - *down*: link into the next nonzero term in the same col
 - *right*: link into the next nonzero term in the same row
- For an $n \times m$ sparse matrix with r nonzero terms, the number of nodes needed is $\max\{n, m\} + r + 1$.

<i>row</i>	<i>col</i>	<i>value</i>
<i>down</i>	<i>right</i>	

an entry node

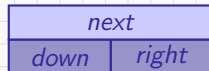
An Example

$$\begin{bmatrix} 2 & 0 & 0 & 0 \\ 4 & 0 & 0 & 3 \\ 0 & 0 & 0 & 0 \\ 8 & 0 & 0 & 1 \\ 0 & 0 & 6 & 0 \end{bmatrix}$$

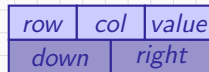


Structures of Sparse Matrices

```
#define MAX_SIZE 50
typedef enum {head, entry} tagfield;
typedef struct matrixNode *matrixPointer;
typedef struct entryNode {
    int row;
    int col;
    int value;
}
typedef struct matrixNode {
    matrixPointer down;
    matrixPointer right;
    tagfield tag;
    union {
        matrixPointer next;
        entryNode entry;
    } u;
};
matrixPointer hdnode[MAX_SIZE];
```



a head node



an entry node

Reading in a Matrix

- Assume: input $\langle \text{row}, \text{col}, \text{value} \rangle$

	0	1	2	
0	5	4	6	$\rightarrow \text{hdnode}$
1	0	0	2	$\text{hdnode}[i]$ points to i th row and i th column
2	1	0	4	
3	1	3	3	
4	3	0	8	
5	3	3	1	
6	4	2	6	

- Procedure `mread` reads in a sparse matrix.

$$O(\max\{\text{numRows}, \text{numCols}\} + \text{numTerms}) = O(\text{numRows} + \text{numCols} + \text{numTerms})$$

Erasing a Matrix

```
void merase(matrixPoiner *node)
{
    matrixPointer x, y, head=(*node)->right;
    int i;
    for(i=0; i < (*node)->u.entry.row; i++) {
        y = head->right;
        while(y!=head) {
            x =y; y = y->right; free(x);
        }
        x = head; head = head->u.next; free(x);
    };
    y= head;
    while(y != *node){
        x =y; y = y->u.next; free(x);
    }
    free(*node); *node = NULL;
}
```

$O(\text{numRows} + \text{numCols} + \text{numTerms})$

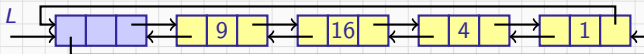
Doubly Linked Lists

- Singly linked list (in one direction only)
- Move in forward and backward direction.
How to get the preceding node during deletion or insertion?

➡ Using 2 pointers

- A node in doubly linked list

```
typedef struct node *nodePointer;  
typedef struct node {  
    nodePointer llink;  
    element data;  
    nodePointer rlink;  
} node;
```

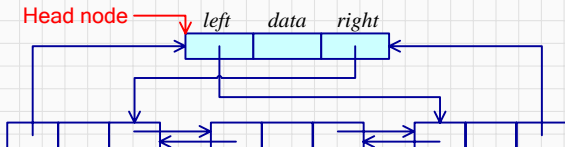


A Head Node

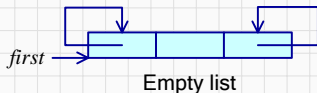
- A head node allows us to implement our operations easily.
data: no information
- Suppose *ptr* points to any node in a doubly linked list

$$ptr = ptr \rightarrow llink \rightarrow rlink = ptr \rightarrow rlink \rightarrow llink$$

- Back or forth with equal ease

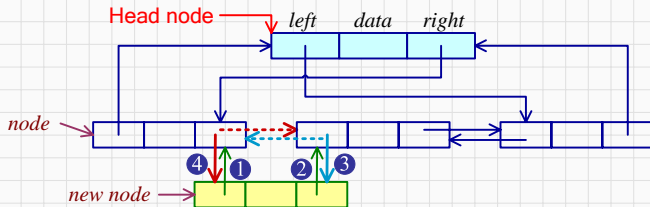


- Emptylist



Insertion

```
void dininsert(nodePointer node, nodePointer newnode)
{ /* insert newnode to the right of node
  newnode->llink = node  ①;
  newnode->rlink = node->rlink  ②;
  node->rlink->llink = newnode  ③;
  node->rlink = newnode  ④;
}
```



Deletion

```
void ddelete(nodePointer node, nodePointer deleted)
{ /* delete from the doubly linked list
  if (node==deleted)
    printf("Deletion of head node not permitted. \n");
  else {
    deleted->llink->rlink = deleted->rlink; ①
    deleted->rlink->llink = deleted->llink; ②
    free(deleted);
  }
}
```

