

Problem 9 Design of Experiments (DOE) Interactive Seminar

E326 – Lean Manufacturing & Six Sigma

SCHOOL OF **ENGINEERING**











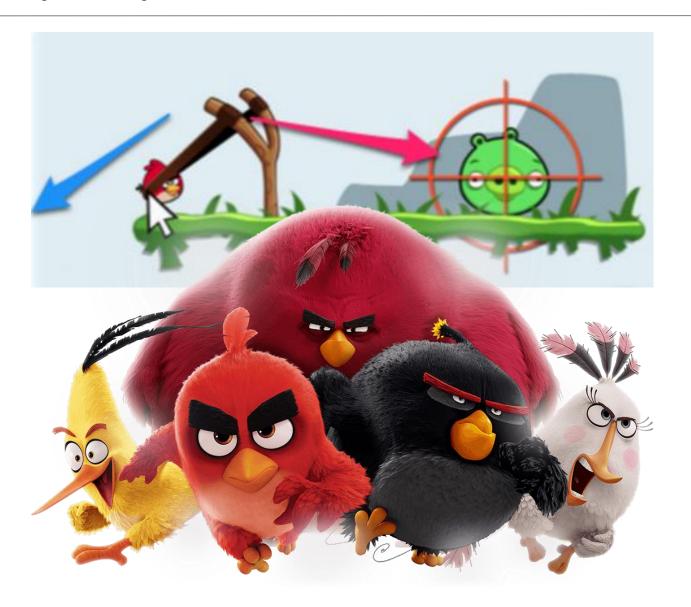






Now you try it...





Today's Catapult



Steps:

- 1. Define the objective of the experiment
 - To determine the optimum settings to use in order to hit the Target distance, e.g. 58 +/- 3 cm
- 2. Identify the response and input factors
 - Response factor = Distance travelled by the ball
 - Input factors = (i) Start Angle, (ii) Stop Position, (iii) Hook Position.
- 3. Determine the resources required
 - Catapult set, ball, measuring tape
 - Three replications of experiment

Today's Problem



- 4. Select experiments design matrix and analysis strategy
 - 2-level, 3 factors full factorial design (2³):
 - 3 factors (Start Angle, Stop Position, Hook Position)
 - o 2 Levels (160/180, 2/4, 2/4)
- 5. Conduct the experiments and record data
 - Use Minitab to generate all the experimental runs in the worksheet in a randomized manner.
 - Conduct the experiments to get the observation value at each treatment.
- 6. Analyze data, draw conclusions and perform confirmation runs.
 - Analyze Custom Factorial Design

2^k Factorial Level



You may use either the Coded or Uncoded Design Matrix to solve this problem. However, in this problem, we will focus on using the Uncoded Design Matrix.

Uncoded levels

| Factors | Low Setting | High Setting |
|---------------|-------------|--------------|
| Hook Position | 2 | 4 |
| Stop Position | 2 | 4 |
| Start Angle | 160 | 180 |

Coded levels

| Factors | Low setting | High setting |
|---------------|-------------|--------------|
| Hook Position | -1 | +1 |
| Stop Position | -1 | +1 |
| Start Angle | -1 | +1 |

2^k Factorial Test Matrix (in Yates Order)



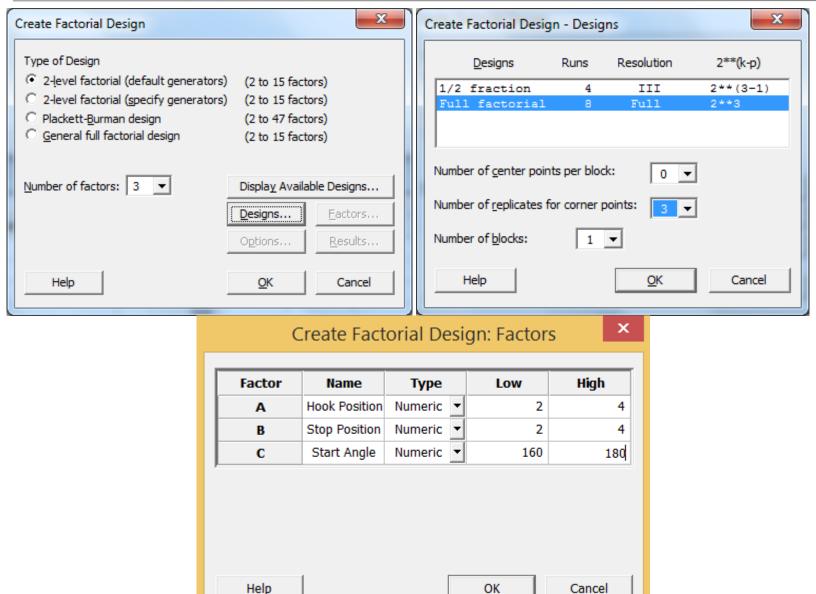
| Un-coded Design Matrix | | | | | | | |
|------------------------|-----------------------|-------------------------|--|--|--|--|--|
| Hook Position (level) | Stop Position (level) | Start Angle (degree) | | | | | |
| 2 | 2 | 160 | | | | | |
| 4 | 2 | 160 | | | | | |
| 2 | 4 | 160 | | | | | |
| 4 | 4 | 160 | | | | | |
| 2 | 2 | 180 | | | | | |
| 4 | 2 | 180 | | | | | |
| 2 | 4 | 180 | | | | | |
| 4 | 4 | 180 | | | | | |

| Coded Matrix | | | | | | |
|--------------|----|----|--|--|--|--|
| А | В | С | | | | |
| -1 | -1 | -1 | | | | |
| 1 | -1 | -1 | | | | |
| -1 | 1 | -1 | | | | |
| 1 | 1 | -1 | | | | |
| -1 | -1 | 1 | | | | |
| 1 | -1 | 1 | | | | |
| -1 | 1 | 1 | | | | |
| 1 | 1 | 1 | | | | |

Note: 2^k means Two levels, K factors

Setting up the DOE in Minitab





2³ Full Factorial Design (Uncoded) with

3 Replicates

Key in all the responses collected



| + | C1 | C2 | C3 | C4 | C5 | C6 | C7 | C8 🗾 | C9 🛮 | |
|----|----------|----------|----------|--------|----------------------|---------------|-------------|-----------------|-----------------|---|
| | StdOrder | RunOrder | CenterPt | Blocks | Hook Position | Stop Position | Start Angle | Dist-Heavy-Ball | Dist-Light-Ball | |
| 1 | 1 | 1 | 1 | 1 | 2 | 2 | 160 | 33.0 | 40.0 | |
| 2 | 2 | 2 | 1 | 1 | 4 | 2 | 160 | 16.5 | 24.0 | |
| 3 | 3 | 3 | 1 | 1 | 2 | 4 | 160 | 62.0 | 73.0 | 4 |
| 4 | 4 | 4 | 1 | 1 | 4 | 4 | 160 | 42.5 | 55.0 | 1 |
| 5 | 5 | 5 | 1 | 1 | 2 | 2 | 180 | 73.0 | 89.0 | |
| 6 | 6 | 6 | 1 | 1 | 4 | 2 | 180 | 37.0 | 53.0 | |
| 7 | 7 | 7 | 1 | 1 | 2 | 4 | 180 | 89.0 | 93.0 | |
| 8 | 8 | 8 | 1 | 1 | 4 | 4 | 180 | 50.0 | 64.0 | |
| 9 | 9 | 9 | 1 | 1 | 2 | 2 | 160 | 32.0 | 42.0 | |
| 10 | 10 | 10 | 1 | 1 | 4 | 2 | 160 | 16.0 | 24.5 | |
| 11 | 11 | 11 | 1 | 1 | 2 | 4 | 160 | 62.0 | 71.0 | |
| 12 | 12 | 12 | 1 | 1 | 4 | 4 | 160 | 43.0 | 54.0 | 2 |
| 13 | 13 | 13 | 1 | 1 | 2 | 2 | 180 | 74.0 | 89.0 | ۷ |
| 14 | 14 | 14 | 1 | 1 | 4 | 2 | 180 | 37.0 | 53.0 | |
| 15 | 15 | 15 | 1 | 1 | 2 | 4 | 180 | 89.0 | 94.0 | |
| 16 | 16 | 16 | 1 | 1 | 4 | 4 | 180 | 51.0 | 64.5 | |
| 17 | 17 | 17 | 1 | 1 | 2 | 2 | 160 | 33.0 | 41.0 | |
| 18 | 18 | 18 | 1 | 1 | 4 | 2 | 160 | 17.0 | 25.0 | |
| 19 | 19 | 19 | 1 | 1 | 2 | 4 | 160 | 62.5 | 72.0 | |
| 20 | 20 | 20 | 1 | 1 | 4 | 4 | 160 | 42.5 | 53.5 | 2 |
| 21 | 21 | 21 | 1 | 1 | 2 | 2 | 180 | 74.0 | 89.0 | 3 |
| 22 | 22 | 22 | 1 | 1 | 4 | 2 | 180 | 37.5 | 53.0 | |
| 23 | 23 | 23 | 1 | 1 | 2 | 4 | 180 | 89.5 | 93.5 | |
| 24 | 24 | 24 | 1 | 1 | 4 | 4 | 180 | 50.0 | 65.0 | |
| | | | | | 1 | 1 | | | | |

1st replicate

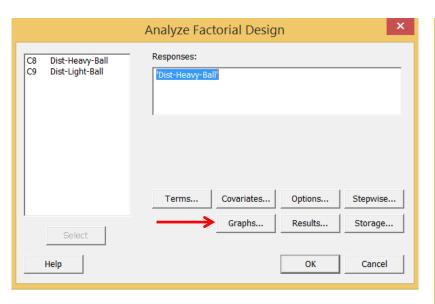
 2^{nd} replicate

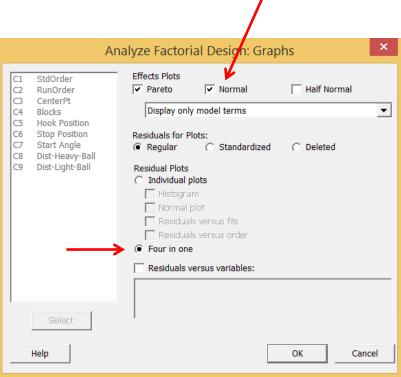
3rd replicate

Results and Analysis (Identifying insignificant terms)



Minitab > Stat > DOE > Factorial > Analyse Factorial Design...>Graphs)





Results and Analysis (Identifying insignificant terms)



Factorial Regression: Dist-Heavy-Ball versus Hook Position, Stop Position, Start Angle

Analysis of Variance

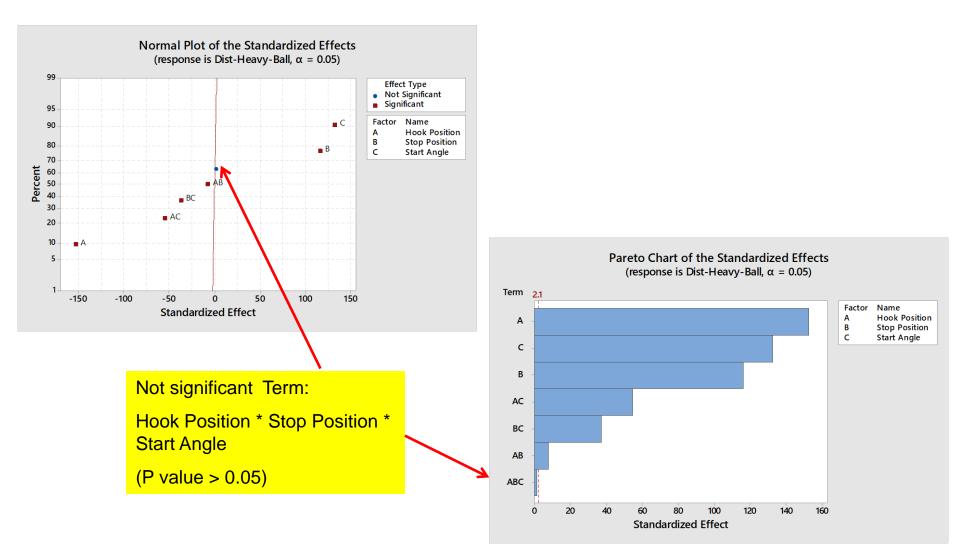
| Source | DF | Adj SS | Adj MS | F-Value | P-Value | |
|---|----|---------|---------|----------|---------|-------------------------------------|
| Model | 7 | 11643.3 | 1663.33 | 8404.18 | 0.000 | |
| Linear | 3 | 10767.5 | 3589.15 | 18134.67 | 0.000 | |
| Hook Position | 1 | 4620.4 | 4620.38 | 23345.05 | 0.000 | |
| Stop Position | 1 | 2667.0 | 2667.04 | 13475.58 | 0.000 | |
| Start Angle | 1 | 3480.0 | 3480.04 | 17583.37 | 0.000 | ` |
| 2-Way Interactions | 3 | 875.5 | 291.82 | 1474.46 | 0.000 | |
| Hook Position*Stop Position | 1 | 12.0 | 12.04 | 60.84 | 0.000 | Significant |
| Hook Position*Start Angle | 1 | 590.0 | 590.04 | 2981.26 | 0.000 | (P-value < 0.05) |
| Stop Position*Start Angle | 1 | 273.4 | 273.38 | 1381.26 | 0.000 | (1 -value < 0.03) |
| 3-Way Interactions | 1 | 0.4 | 0.37 | 1.89 | 0.188 | _ |
| Hook Position*Stop Position*Start Angle | 1 | 0.4 | 0.37 | 1.89 | 0.188 | |
| Error | 16 | 3.2 | 0.20 | | | |
| Total | 23 | 11646.5 | | | | Not significant (P value > 0.05) |

Model Summary

```
S R-sq R-sq(adj) R-sq(pred)
0.444878 99.97% 99.96% 99.94%
```

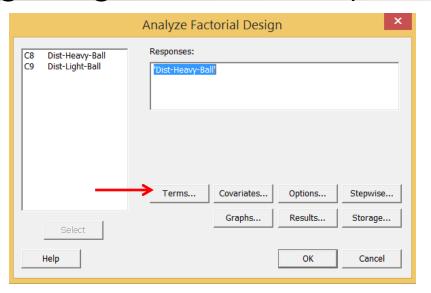
Results and Analysis (Identifying insignificant terms)

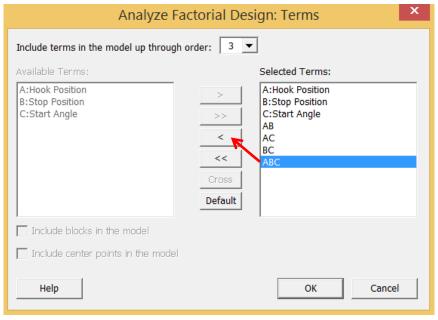


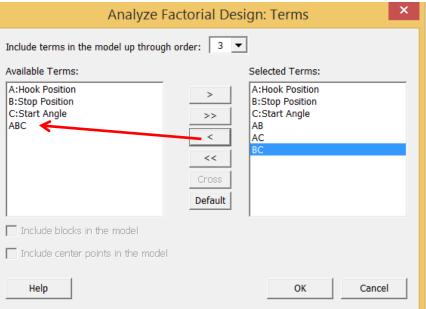


Results and Analysis (Removing insignificant terms)









Results and Analysis (After removing insignificant terms)

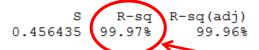


Factorial Regression: Dist-Heavy-Ball versus Hook Position, Stop Position, Start Angle

Analysis of Variance

| Source | DF | Adj SS | Adj MS | F-Value | P-Value |
|-----------------------------|----|---------|---------|----------|---------|
| Model | 6 | 11642.9 | 1940.49 | 9314.33 | 0.000 |
| Linear | 3 | 10767.5 | 3589.15 | 17227.93 | 0.000 |
| Hook Position | 1 | 4620.4 | 4620.37 | 22177.80 | 0.000 |
| Stop Position | 1 | 2667.0 | 2667.04 | 12801.80 | 0.000 |
| Start Angle | 1 | 3480.0 | 3480.04 | 16704.20 | 0.000 |
| 2-Way Interactions | 3 | 875.5 | 291.82 | 1400.73 | 0.000 |
| Hook Position*Stop Position | 1 | 12.0 | 12.04 | 57.80 | 0.000 |
| Hook Position*Start Angle | 1 | 590.0 | 590.04 | 2832.20 | 0.000 |
| Stop Position*Start Angle | 1 | 273.4 | 273.37 | 1312.20 | 0.000 |
| Error | 17 | 3.5 | 0.21 | | |
| Lack-of-Fit | 1 | 0.4 | 0.37 | 1.89 | (0.188) |
| Pure Error | 16 | 3.2 | 0.20 | | |
| Total | 23 | 11646.5 | | | |

Model Summary



Coded Coefficients

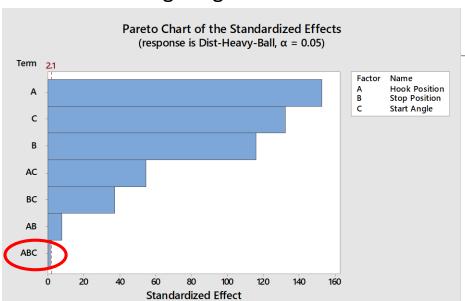
The ANOVA table includes a lack-of-fit test. The null hypothesis is that this model fits the experimental response data adequately. Since p value > level of significance, we do not reject the null hypothesis. Model is therefore a good fit with the observed data.

R-sq(pred) 99.94%

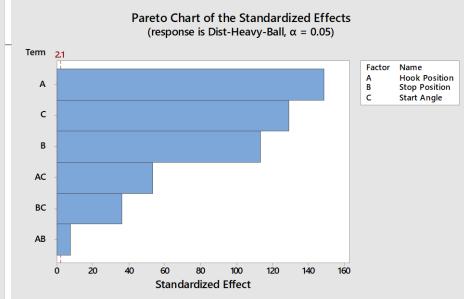
 R^2 = proportion of variation in the response that can be explained by the model equation. It has 99.93% > 80% which indicates that the model is good.

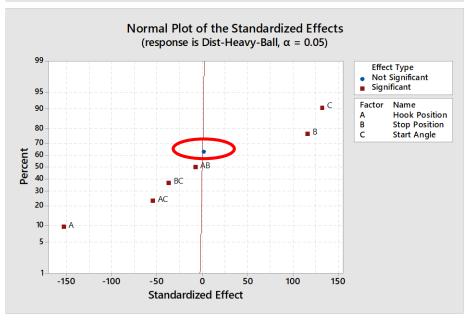
| Term | Effect | Coef | SE Coef | T-Value | P-Value | VIF |
|-----------------------------|----------|----------|---------|---------|---------|------|
| Constant | | 50.5417 | 0.0932 | 542.47 | 0.000 | |
| Hook Position | -27.7500 | -13.8750 | 0.0932 | -148.92 | 0.000 | 1.00 |
| Stop Position | 21.0833 | 10.5417 | 0.0932 | 113.15 | 0.000 | 1.00 |
| Start Angle | 24.0833 | 12.0417 | 0.0932 | 129.24 | 0.000 | 1.00 |
| Hook Position*Stop Position | -1.4167 | -0.7083 | 0.0932 | -7.60 | 0.000 | 1.00 |
| Hook Position*Start Angle | -9.9167 | -4.9583 | 0.0932 | -53.22 | 0.000 | 1.00 |
| Stop Position*Start Angle | -6.7500 | -3.3750 | 0.0932 | -36.22 | 0.000 | 1.00 |

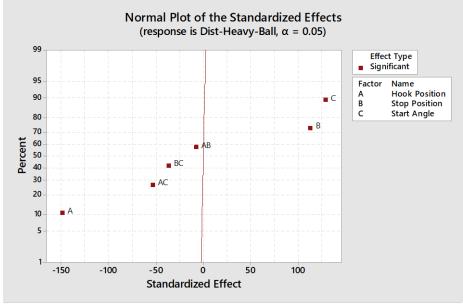
Before removing insignificant terms



After removing insignificant terms







Prediction Model



Before removing insignificant terms

Coded Coefficients

| Term | Effect | Coef | SE Coef | T-Value | P-Value | VIF |
|---|----------|----------|---------|---------|---------|------|
| Constant | | 50.5417 | 0.0908 | 556.56 | 0.000 | |
| Hook Position | -27.7500 | -13.8750 | 0.0908 | -152.79 | 0.000 | 1.00 |
| Stop Position | 21.0833 | 10.5417 | 0.0908 | 116.08 | 0.000 | 1.00 |
| Start Angle | 24.0833 | 12.0417 | 0.0908 | 132.60 | 0.000 | 1.00 |
| Hook Position*Stop Position | -1.4167 | -0.7083 | 0.0908 | -7.80 | 0.000 | 1.00 |
| Hook Position*Start Angle | -9.9167 | -4.9583 | 0.0908 | -54.60 | 0.000 | 1.00 |
| Stop Position*Start Angle | -6.7500 | -3.3750 | 0.0908 | -37.17 | 0.000 | 1.00 |
| Hook Position*Stop Position*Start Angle | 0.2500 | 0.1250 | 0.0908 | 1.38 | 0.188 | 1.00 |

Regression Equation in Uncoded Units

Distance = -594.7 + 78.92 Hook Position + 76.42 Stop Position + 3.8167 Start Angle - 2.83 Hook Position*Stop Position - 0.5333 Hook Position*Start Angle - 0.3750 Stop Position*Start Angle

+ 0.01250 Hook Position*Stop Position*Start Angle

After removing insignificant terms

Coded Coefficients

| Term | Effect | Coef | SE Coef | T-Value | P-Value | VIF |
|-----------------------------|----------|----------|---------|---------|---------|------|
| Constant | | 50.5417 | 0.0932 | 542.47 | 0.000 | |
| Hook Position | -27.7500 | -13.8750 | 0.0932 | -148.92 | 0.000 | 1.00 |
| Stop Position | 21.0833 | 10.5417 | 0.0932 | 113.15 | 0.000 | 1.00 |
| Start Angle | 24.0833 | 12.0417 | 0.0932 | 129.24 | 0.000 | 1.00 |
| Hook Position*Stop Position | -1.4167 | -0.7083 | 0.0932 | -7.60 | 0.000 | 1.00 |
| Hook Position*Start Angle | -9.9167 | -4.9583 | 0.0932 | -53.22 | 0.000 | 1.00 |
| Stop Position*Start Angle | -6.7500 | -3.3750 | 0.0932 | -36.22 | 0.000 | 1.00 |

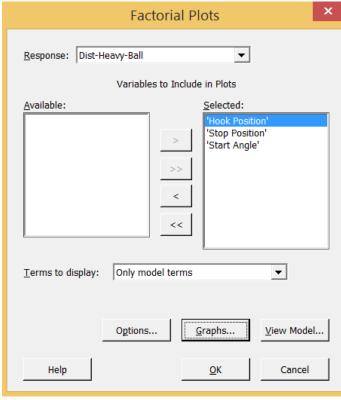
Prediction Model is based on 'uncoded units', i.e. hook position = 2, 4, instead of -1, 1

Regression Equation in Uncoded Units

Dist-Heavy-Ball = -575.54 + 72.54 Hook Position + 70.04 Stop Position + 3.7042 Start Angle - 0.7083 Hook Position*Stop Position - 0.49583 Hook Position*Start Angle - 0.33750 Stop Position*Start Angle

Main Effects Plots





Factorial Plots: Graphs

Main effects plot

Interaction plot
Display lower left matrix
Display full matrix

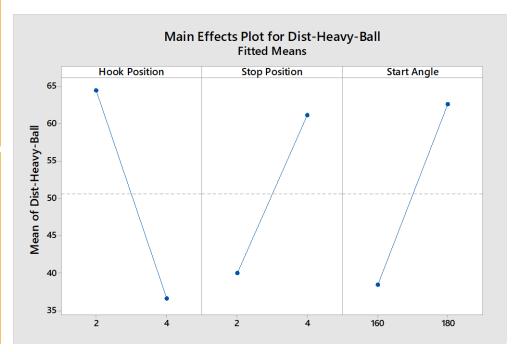
Help

OK

Cancel

A main effect occurs when the mean response changes across the levels of a factor. You can use main effects plots to compare the relative strength of the effects across factors.

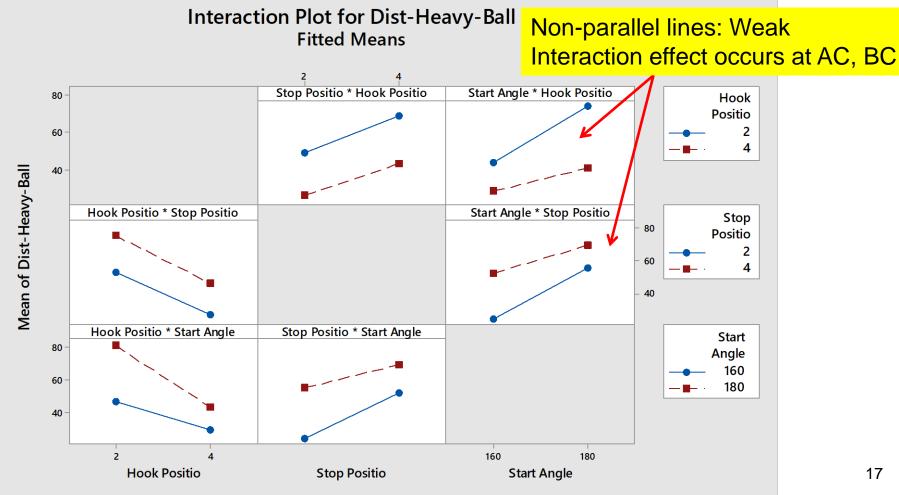
(MINITAB > Stat > DOE > Factorial > Factorial Plots...)



Interaction Plots



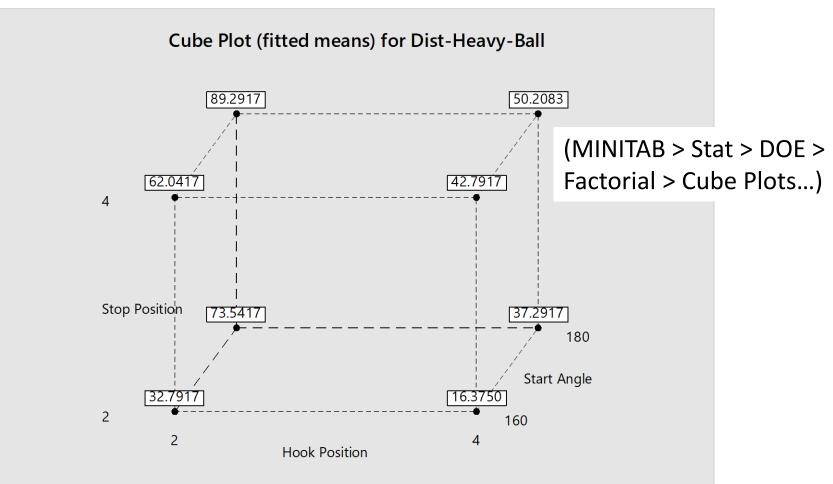
An interaction between factors occurs when the change in response from the low level to the high level of one factor is not the same as the change in response at the same two levels of a second factor. That is, the effect of one factor is dependent upon a second factor. You can use interactions plots to compare the relative strength of the effects across factors.



Cube Plot



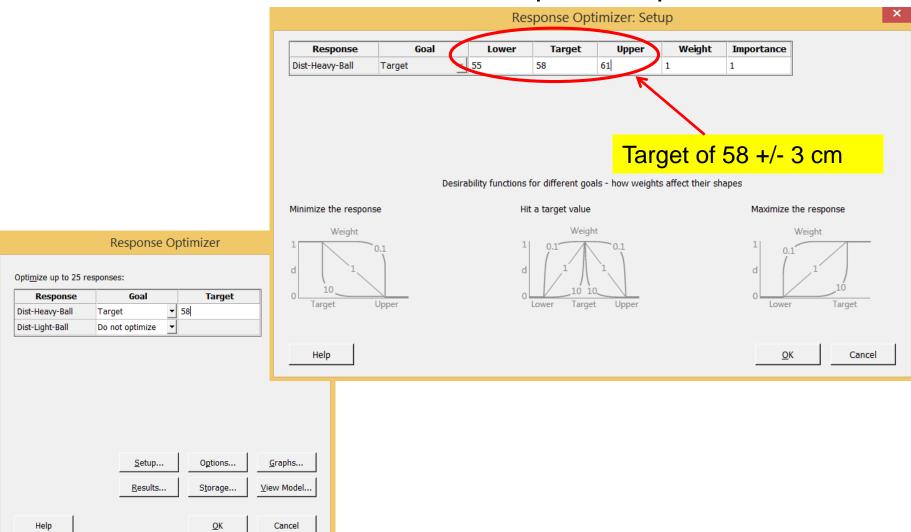
Showing the <u>Mean Distance data</u> collected from experiment at each treatment (level combination)



Response Optimizer: Target at 58cm



Minitab>Stat>DOE>Factorial>Response Optimizer



Response Optimizer: Target at 58cm



Response Optimization: Dist-Heavy-Ball

Parameters

Response Goal Lower Target Upper Weight Importance Dist-Heavy-Ball Target 55 58 61 1 1

Solution

Hook Stop Start Dist-Heavy-Ball Composite Solution Position Position Angle Fit Desirability 1 2.03614 3.74699 160 58 1

Multiple Response Prediction

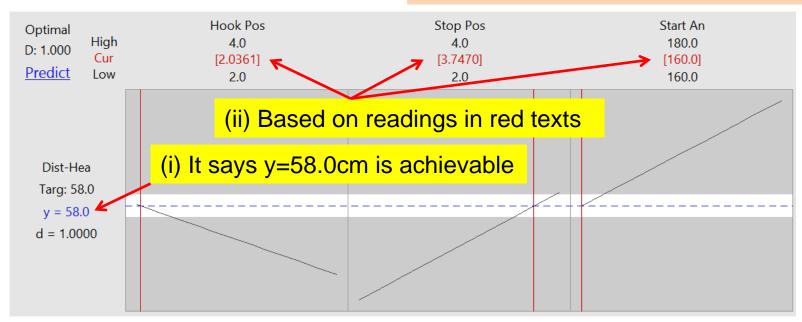
Variable Setting Hook Position 2.03614 Stop Position 3.74699 Start Angle 160

Response Fit SE Fit 95% CI 95% PI Dist-Heavy-Ball 58.000 0.218 (57.539, 58.461) (56.932, 59.068)

In order to hit a target at 58cm distance, one optimized catapult setting is:

- Hook Position 2.03614
- Stop Position 3.74699
- Start Angle 160 deg

It's however not possible to set Hook Position and Stop Position at decimal places. So go Response Optimizer / Options... to add constraints to 'Hook Position', 'Stop Position'.



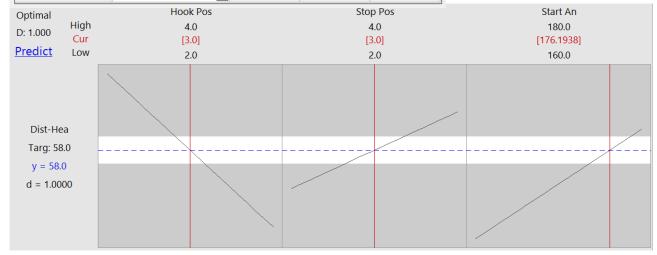




Variable Setting
Hook Position 3
Stop Position 4
Start Angle 166.442deg

Constraints

| Variable | Constraint | | Hold Value | Lower | Upper |
|-----------------|----------------|---|------------|-------|-------|
| 'Hook Position' | Hold at value | • | 3 | | |
| 'Stop Position' | Hold at value | • | 3 | | |
| 'Start Angle' | No constraints | • | | | |



Variable Setting
Hook Position 3
Stop Position 3
Start Angle 176.194deg

Limitations of Prediction Model



The prediction model does not take into account other factors, such as:

- Stability of the frame of the catapult set
- Direction of cup releasing the ball
- Energy losses due to friction
- Presence of strong wind
- Surface friction



Conclusions



- From the DOE, all 3 main effects, Hook Position, Stop Position, Start Angle are significant factors.
- In addition, the interaction between "Hook Position" & "Stop Position", "Hook Position" & "Start Angle", "Stop Position" & "Start Angle" are also significant.
- 3-way interaction, Hook Position * Stop Position * Start Angle is <u>NOT</u> significant.
- To reach a target distance, e.g. 58cm, one of the optimized settings are Hook Position 3, Stop Position 3, Start Angle 176deg.

Learning Objectives



- Explain Design of Experiments (DOE) and their uses in Improve Phase of Lean Six Sigma project
- Apply factorial experiments to practical problem solving
- Distinguish between One-Factor-At-a-Time (OFAT) and Factorial experiment

Going Further: Fractional Factorial Designs



- A fractional factorial design is an experimental design consisting of a subset (fraction) of the factorial design.
- Typically, the fraction is simple proportional of the full set of possible treatment combinations. For example, half-fractions, quarter-fractions, and so forth are common. While fractional factorial designs require fewer runs, certain information cannot be separated.

Example: Fractional factorial for a three factors, with 2-level experiment:

- Pressure (10,20)
- Speed (50,100)
- o Time (45,65)

| RunOrder | Pressure | Speed | Temp |
|----------|----------|-------|------|
| 1 | 20 | 100 | 65 |
| 2 | 10 | 100 | 45 |
| 3 | 10 | 50 | 65 |
| 4 | 20 | 50 | 45 |

Overview of E326 Lean Manufacturing and Six Sigma



